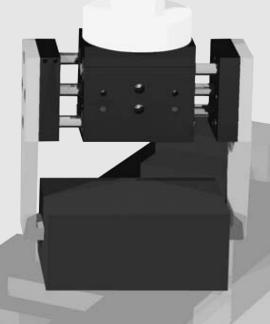
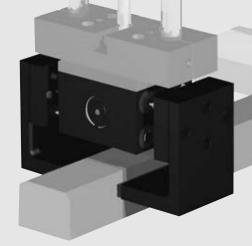
# Parallel Grippers-Wide Body Series





Machining applications:

Sealed design repels chips and other particulate from the internal drive mechanism.

Long gripper fingers:

Jaw support thru the length of the body allows for long fingers to be attached to the jaws.

Large or wide parts:

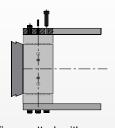
Wide body design provides secure gripping of large & wide parts.

• Non synchronous motion:

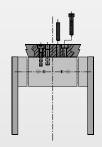
The unit can be made non-synchronous providing independent jaw motion allowing the gripper to pick or place at a point other than it's center.

#### **Mounting Information:**

#### Grippers can be mounted & operated in any orientation

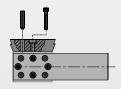


Fingers attach with screws and locate on jaws with dowel pins









Body mounts on top or on side with screws and locates with slip fit dowel pin holes for accuracy

#### **Technical Specifications:**

**Pneumatic Specifications** Imperial Metric Pressure Operating Range 40-100 psi 3-7 bar **Dual Double Acting** Cylinder Type **Internally Lubricated Buna-N** Dynamic Seals Valve Required 4-way, 2-position

**Air Quality Requirements** 

40 Micron or Better Air Filtration Air Lubrication **Not Necessary\* Low Moisture Content (dry)** Air Humidity

**Temperature Operating Range** 

Buna-N Seals (standard) -30°~180° F -35°~80° C -30°~150° C -20°~300° F Viton® Seals (optional)

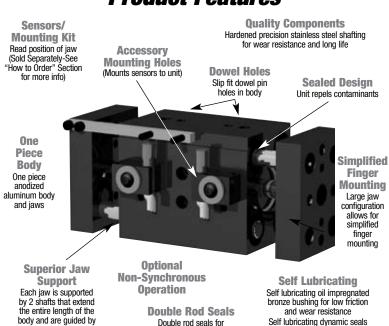
#### Maintenance Specifications<sup>†</sup>

**Expected Life** 

Normal Application 5 million cycles w/ Preventative Maintenance 10+ million cycles\* Field Repairable Yes Seal Repair Kits Available Yes

\*Addition of lubrication will greatly increase service life †See Maintenance Section

## **Product Features**

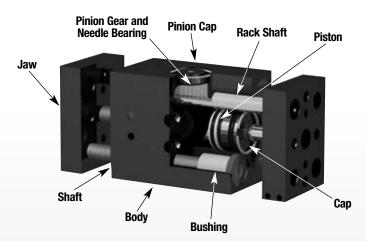


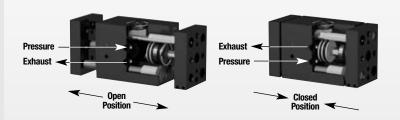
# **Operating Principle**

longer life

2 bronze bushings

per shaft





- Two shafts, one with a rack cut into it, are securely fastened to each of the jaws and are supported through the length of the body.
- Two double acting opposed pistons provide power to the jaws.
- The rack shafts of each jaw slide in opposite directions of one another and are synchronized by a pinion gear.
- This gripper is suitable for internal or external gripping.

# U.S. Patent # 5,163,729 Designed and manufactured in the USA

# Style-RPW Parallel Gripper Size -625M-1 Stroke: 625-1 625M-1 50.8 mm

Stroke: 2.00 in. 50.8 mm Grip Force: 240 lb 1068 N Weight: 6.5 lb 2.95 Kg



See **1.216** Page **1.216** 

# **Style-RPW Parallel Gripper**

Size -625M-2 Stroke: 3.50 in. 88.9 mm Grip Force: 240 lb Weight: 7.8 lb 3.55 Kg



See **1.217** 

## **Style-RPW Parallel Gripper**

Size -750M Stroke: 4.50 in. 114.3 mm Grip Force: 470 lb 2091 N Weight: 14 lb 6.36 Kg



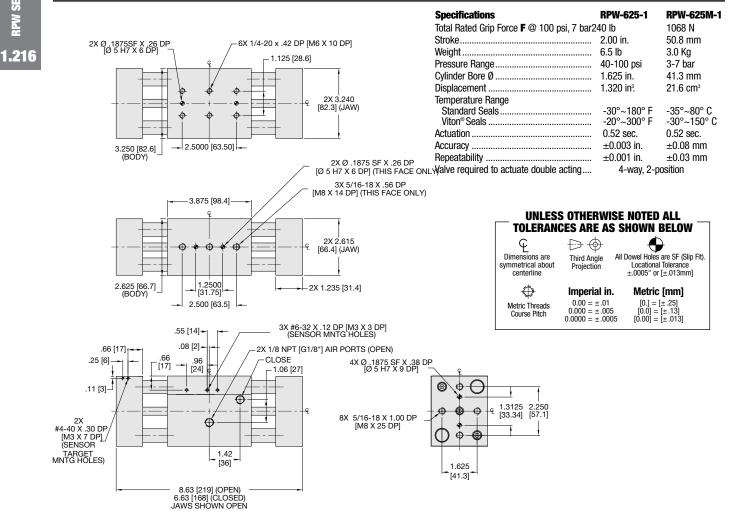
See **1.218** Page **1.218** 

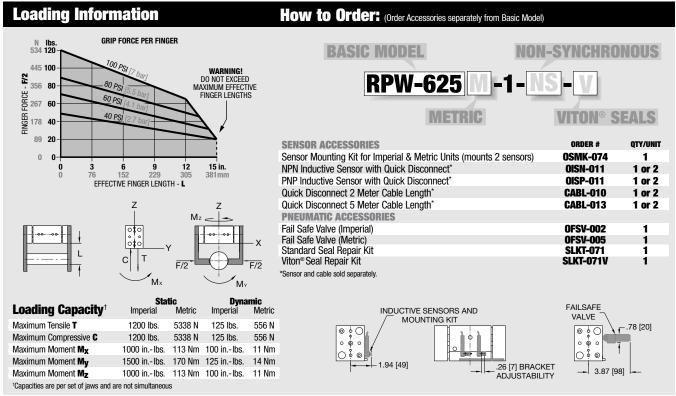
**Note:** Please refer to the New DPW series for sizes of RPW-250 through RPW-500-2 on pages 1.196 to 1.209. The RPW series information on these sizes is still available on our website and are available for sale. We encourage you to consider the new DPW design for new projects.

(Buna-N only)

#### **PARALLEL GRIPPER RPW-625M-1** WIDE BODY SERIES

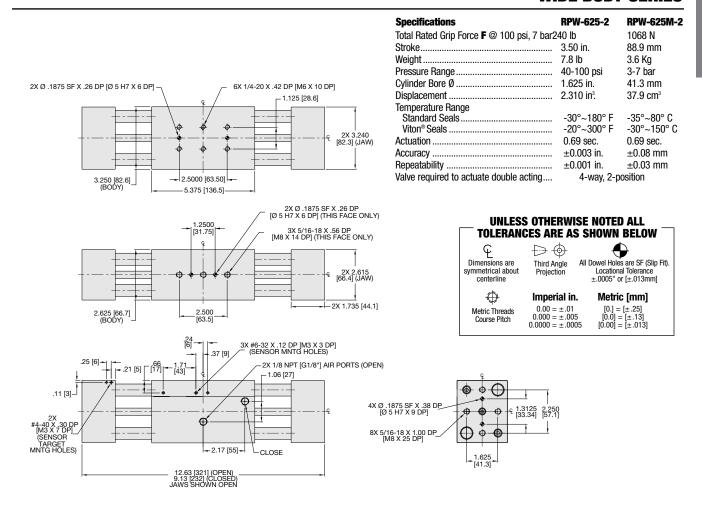


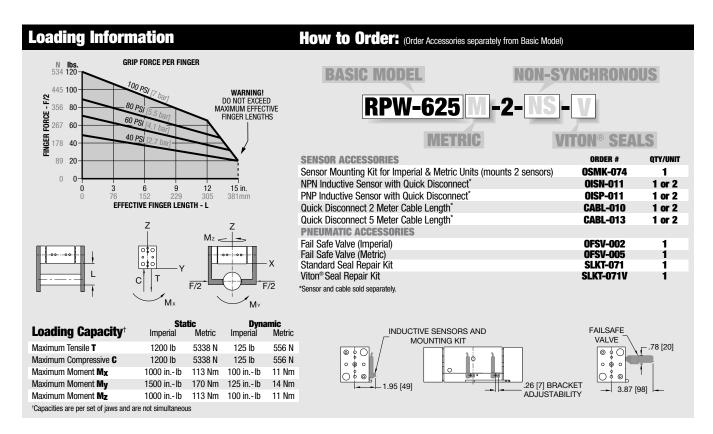






#### PARALLEL GRIPPER RPW-625M-2 WIDE BODY SERIES

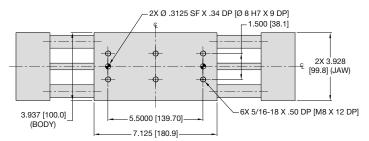




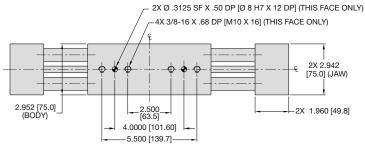
1.218

# PARALLEL GRIPPER RPW-750M WIDE BODY SERIES

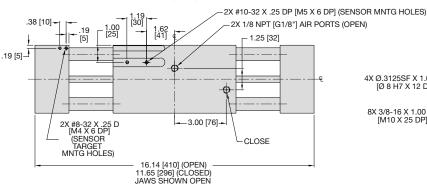


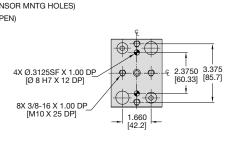


Specifications	RPW-750	RPW-750M
Total Rated Grip Force F @ 100 psi, 7 bar4	2091 N	
Stroke	4.50 in.	114.3 mm
Weight	14 lb	6.4 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	2.000 in.	50.8 mm
Displacement	14.200 in <sup>3</sup> .	232.7 cm <sup>3</sup>
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation	1.00 sec.	1.00 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-p	osition



#### **UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW** All Dowel Holes are SF (Slip Fit). Dimensions are Third Angle Projection symmetrical about Locational Tolerance ±.0005" or [±.013mm] centerline Metric [mm] 0 Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ Metric Threads Course Pitch

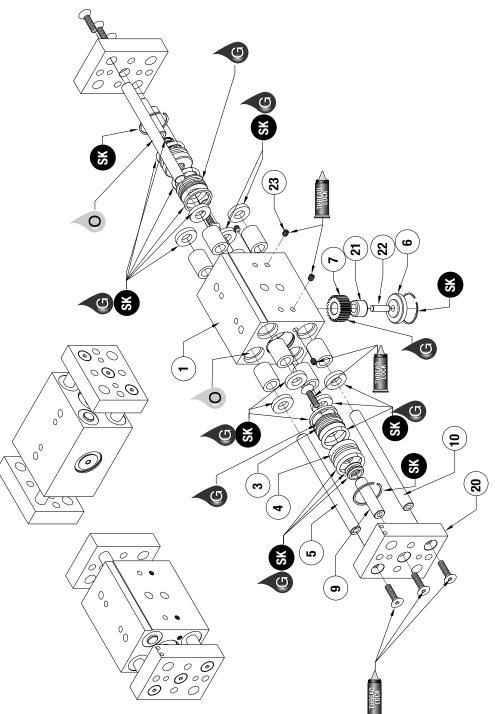




#### **Loading Information** How to Order: (Order Accessories separately from Basic Model) GRIP FORCE PER FINGER N lbs 1113 250 **BASIC MODEL NON-SYNCHRONOUS ≥** 890 200 WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE **RPW-750** 80 PSI FORCE 668 150 FINGER LENGTHS 60 PSI FINGER **METRIC** VITON® SEALS SENSOR ACCESSORIES ORDER # QTY/UNIT Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors) **OSMK-014** 1 NPN Inductive Sensor with Quick Disconnect\* **OISN-011** 1 or 2 12 16 PNP Inductive Sensor with Quick Disconnect\* **OISP-011** 1 or 2 **EFFECTIVE FINGER LENGTH - L** Quick Disconnect 2 Meter Cable Length\* CABL-010 1 or 2 Quick Disconnect 5 Meter Cable Length\* **CABL-013** 1 or 2 **PNEUMATIC ACCESSORIES** Fail Safe Valve (Imperial) **OFSV-002** 1 **OFSV-005** Fail Safe Valve (Metric) **SLKT-060** Standard Seal Repair Kit 1 Viton® Seal Repair Kit SLKT-060V Т F/2 F/2 \*Sensor and cable sold separately. М× M INDUCTIVE SENSORS AND FAILSAFE Static **Dynamic** MOUNTING KIT VALVE Loading Capacity<sup>†</sup> Metric Metric Imperial Imperial -.88 [22] @ **\$** C @ **\$** O Maximum Tensile T 2500 lb 1112 N 11121 N 250 lb 0 0 Maximum Compressive C 2500 lb 11121 N 250 lb 1112 N 0 0 Maximum Moment Mx 2000 in.-lb 226 Nm 200 in.-lb 22 Nm 0 |○ \$ ⊚ | Maximum Moment My 3000 in.-lb 339 Nm 250 in.-lb 28 Nm 4.04 [103] .36 [9] BRACKET -2.20 [56] Maximum Moment Mz ADJUSTABILITY 2000 in.-lb 226 Nm 200 in.-lb 22 Nm †Capacities are per set of jaws and are not simultaneous

## **RPW Series Exploded View**





ltem	Qty	Name
0.4		5 1
<u>01</u>	_1	Body
03	2	Piston
04	2	Cap
05	2	Shaft
06	1	Gear Cover
07	1	Gear
09	2	Shaft, Piston
10	2	Shaft,Gear
20	2	Block, End W/ Target Holes
21	1	Bearing, Needle
22	1	Dowel Pin
23	1	Ball

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

#### **Assembly Procedure**

- 1) Lubricate and install seals.
- 2) Install pistons and shafts.\*
- 3) Place piston caps and retaining rings into body
- 4) Install tooling plates and shafts
- 5) Place bearing, shaft, and gear\*\* into body and install cap and retaining ring for sync. version:
- a) For disassembly, use magnet to pull gear out of body.
- b) Install 2 rack shafts with teeth facing syncing gear.

#### **Non-Synchronous Procedure**

- Take RPW synchronous gripper and remove the retainer ring and gear cover.
- 2) Slide out dowel pin and bearing.
- 3) Remove gear from gripper. (a magnet is often very helpful in removing the gear.)
- Replace the dowel pin, gear cover, and retainer ring. The gripper is now non-synchronous.
- SK Seal Repair Kit Order #'s See Product Data Sheets









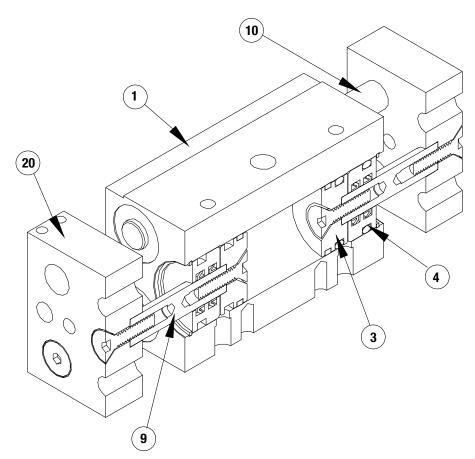








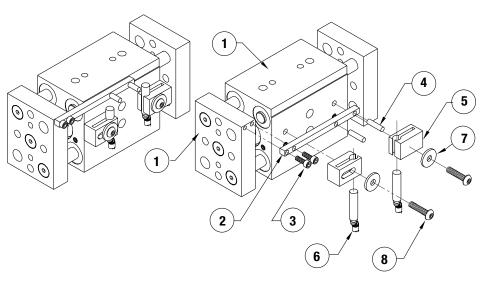




Item	Qty	Name
<u>01</u>	1	Body
03	2	Piston
04	2	Cap
05	2	Shaft
06	1	Gear Cover
07	1	Gear
09	2	Shaft, Piston
10	2	Shaft,Gear
20	2	Block, End W/ Target Holes
21	1	Bearing, Needle
22	1	Dowel Pin
23	1	Ball

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

## **Accessory Installation & Adjustment Instructions**



Install target as shown, install sensors as shown, adjust for proper end of stroke sensing.













