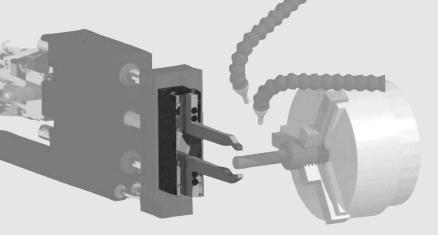
# Parallel Gripper

# **Clean Room / Harsh Environments Series**



### • Precision applications:

Preloaded "Dual-V" roller bearings eliminate side play for excellent part position repeatability.

### • Clean Room rated:

A corrosion resistant shield protects the drive and bearing mechanism. All internal components are lubricated with clean room grade lubricant. The scavenge port can be used with vacuum pressure to prevent

of particulate generated by the internal mechanism.

### Harsh environments:

All moving components are located within the stainless steel shield. The body has a purge port which can expel contaminates from the mechanism using low air pressure.

### • Repeatable grip force:

Low friction mechanism allows for consistent, repeatable gripping forces. To grip delicate parts, grip force can be easily altered by adjusting air pressure.

# **Longer finger applications:**

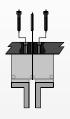
Rigid design allows for longer gripper finger lengths to be used when compared to other grippers of equal weight.

### **Non-synchronous motion:**

The unit can made non-synchronous providing independent jaw motion allowing the gripper to pick or place at a point other than it's center.

# **Mounting Information:**

### Grippers can be mounted & operated in any orientation



Body mounts with screws and locates with slip fit dowel pins for accuracy



Shields provide protection from falling debris when mounted upside down





Fingers attach to jaws with screws and locate by keying

# **Technical Specifications:**

**Pneumatic Specifications Imperial** Metric Pressure Operating Range 5-100 psi .3-7 bar Cylinder Type **Dual Double Acting** Dynamic Seals **Internally Lubricated Buna-N** Valve Required to Operate 4-way, 2-position

### **Air Quality Requirements**

Air Filtration 40 Micron or Better Air Lubrication Not Necessary\* Air Humidity **Low Moisture Content (dry)** 

# **Temperature Operating Range**

-30°~180° F Buna-N Seals (standard) -35°~80° C Viton® Seals (optional) -20°~250° F -30°~120° C

Yes

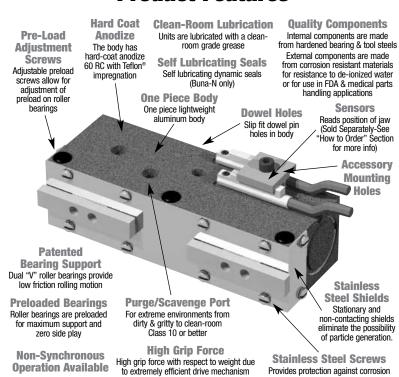
Yes

### Maintenance Specifications<sup>†</sup>

**Expected Life** Normal Application 5 million cycles w/ Preventative Maintenance 10+ million cycles\* Field Repairable Seal Repair Kits Available

\*Addition of lubrication will greatly increase service life

# **Product Features**



# Style-RPLC Parallel Gripper Size -1M Style: RPLC-1 Stroke: 0.25 in. 6.4 mm Grip Force: 26 lb 116 N Weight: 16 lb .07 Kg



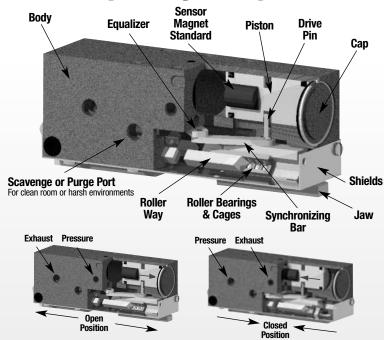
See 1.100







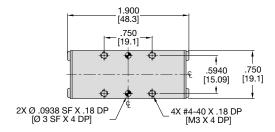
# **Operating Principle**



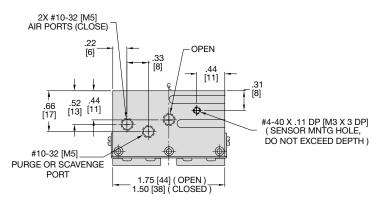
- Dual double acting opposed pistons, connected to both a jaw and a synchronizing bar by a drive pin, actuate in opposite directions.
- The synchronizing bars are connected to the equalizer which synchronizes the motion.
- The purge/scavenge port can be used to expel or retain contaminates using pressure or vacuum respectively.
- Suitable for internal or external gripping.
- The synchronizing elements can be removed for non-synchronous operation.

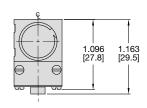
U.S. Patent # 5,529,359 Designed and manufactured in the USA

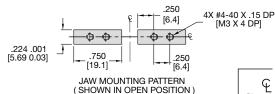




Specifications	RPLC-1	RPLC-1M
Total Rated Grip Force F @ 100 psi, 7 bar2	6 lb	116 N
Stroke	0.25 in.	6.4 mm
Weight	0.16 lb	0.07 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.438 in.	11.1 mm
Displacement	0.038 in <sup>3</sup> .	0.6 cm <sup>3</sup>
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~250° F	-30°~120° C
Actuation	0.10 sec.	0.10 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-po	osition







Dimensions are symmetrical about centerline

Third Angle Projection All Dowel Holes are SF (Slip Fit).
Locational Tolerance
±.0005" or [±.013mm]

Metric Threads Course Pitch

NON-SYNCHRONOUS

Imperial in.  $0.00 = \pm .01$   $0.000 = \pm .005$  $0.0000 = \pm .0005$ 

**VITON® SEALS** 

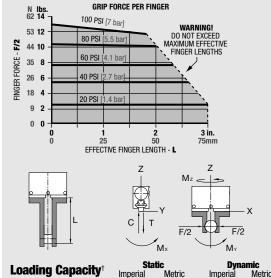
\_.30 [8] MAX

# **Loading Information**

# How to Order: (Order Accessories separately from Basic Model)

**BASIC MODEL** 

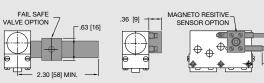
RPLC-1



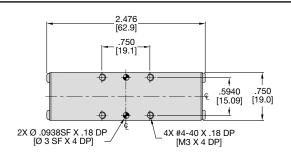
SENSOR ACCESSORIES*	ORDER #	QTY/UNIT
Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors)	<b>OSMK-008</b>	1
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-017	1 or 2
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-017	1 or 2
Quick Disconnect 2 Meter Cable Length*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable Length*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Fail Safe Valve (Imperial)	<b>OFSV-001</b>	1
Fail Safe Valve (Metric)	<b>OFSV-004</b>	1
Standard Seal Repair Kit	SLKT-010	1
Viton® Seal Repair Kit	SLKT-010V	1
*Sensor and cable sold separately †Piston magnet standard		
· · · ·		

**METRIC** 

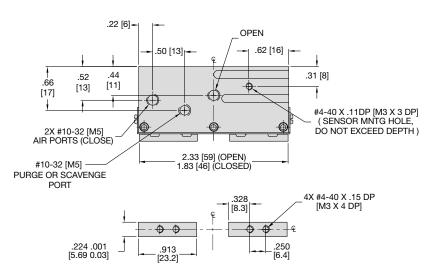
Loading Capacity <sup>†</sup>	<b>Sta</b> Imperial	<b>tic</b> Metric	<b>Dyna</b> Imperial	<b>mic</b> Metric
Maximum Tensile T	50 lbs.	222 N	15 lbs.	67 N
Maximum Compressive C	50 lbs.	222 N	15 lbs.	67 N
Maximum Moment Mx	30 inlbs.	3.4 Nm	10 inlbs.	1.1 Nm
Maximum Moment My	40 inlbs.	4.5 Nm	12 inlbs.	1.4 Nm
Maximum Moment Mz	30 inlbs.	3.4 Nm	10 inlbs.	1.1 Nm
†Capacities are per set of jaws and are not simultaneous				

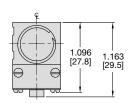


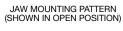
# **PARALLEL GRIPPER RPLC-2M** PRECISION DUAL "V" CLEAN ROOM SERIES



Specifications	RPLC-2	RPLC-2M
Total Rated Grip Force F @ 100 psi, 7 bar2	26 lb	116 N
Stroke	0.50 in.	12.7 mm
Weight	0.20 lb	0.09 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.438 in.	11.1 mm
Displacement	0.075 in <sup>3</sup> .	1.2 cm <sup>3</sup>
Temperature Range		
Standard Seals	-30°∼180° F	-35°~80° C
Viton® Seals	-20°~250° F	-30°~120° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition







# **UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW**

P Dimensions are symmetrical about

 $\Rightarrow \Leftrightarrow$ Third Angle Projection All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

0 Metric Threads Course Pitch

Imperial in. 0.00 = ±.01 0.000 = ±.005 0.0000 = ±.0005

WITON® GEALS

**NON-SYNCHRONOUS** 

Metric [mm]  $[0.] = [\pm .25]$   $[0.0] = [\pm .13]$   $[0.00] = [\pm .013]$ 

# **Loading Information**

Maximum Tensile T

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

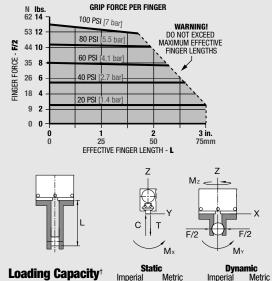
Maximum Moment Mz

†Capacities are per set of jaws and are not simultaneous

# How to Order: (Order Accessories separately from Basic Model)

**BASIC MODEL** 

RPLC-2



65 lbs.

65 lbs.

45 in.-lbs.

60 in.-lbs.

45 in.-lbs.

289 N

289 N

5.1 Nm

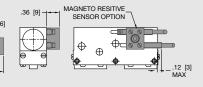
6.8 Nm

5.1 Nm

METHIO	ALLOIA	JEALS
SENSOR ACCESSORIES*	ORDER	# QTY/UNIT
Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sense	ors) <b>OSMK-0</b>	08 1
NPN Magneto Resistive Sensor with Quick Disconnect*	OHSN-0	17 1 or 2
PNP Magneto Resistive Sensor with Quick Disconnect*	OHSP-0	17 1 or 2
Quick Disconnect 2 Meter Cable Length*	CABL-0	10 1 or 2
Quick Disconnect 5 Meter Cable Length*	CABL-0	13 1 or 2
PNEUMATIC ACCESSORIES		
Fail Safe Valve (Imperial)	OFSV-0	D1 1
Fail Safe Valve (Metric)	OFSV-0	04 1
Standard Seal Repair Kit	SLKT-0	10 1
Viton® Seal Repair Kit	SLKT-01	OV 1
*Sensor and cable sold separately <sup>†</sup> Piston magnet standard		
, , ,		

METDIC

FAIL SAFE VALVE OPTION -.63 [16]



89 N

89 N

1.7 Nm

2.3 Nm

1.7 Nm

20 lb

20 lb

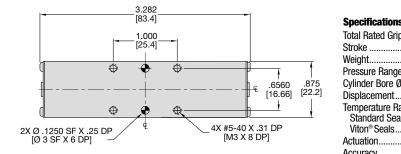
15 in.-lbs.

20 in.-lbs.

15 in.-lbs.

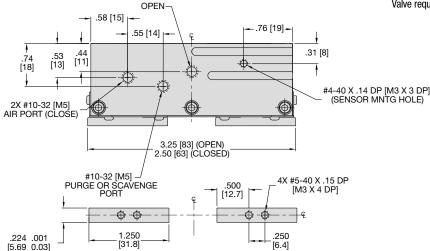


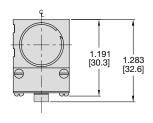
DDI C-2M



opeonications	III LU-J	III LU-JIII
Total Rated Grip Force <b>F</b> @ 100 psi, 7 bar	36 lb	160 N
Stroke	0.75 in.	19.1 mm
Weight	0.32 lb	0.15 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.500 in.	12.7 mm
Displacement	0.147 in <sup>3</sup> .	2.4 cm <sup>3</sup>
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~250° F	-30°~120° C
Actuation	0.14 sec.	0.14 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-po	osition

DDI C-2





JAW MOUNTING PATTERN (SHOWN IN OPEN POSITION)

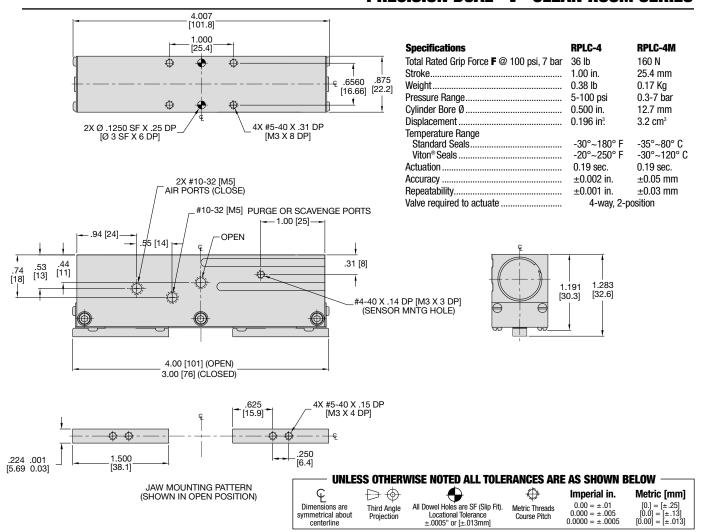
# **UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW**

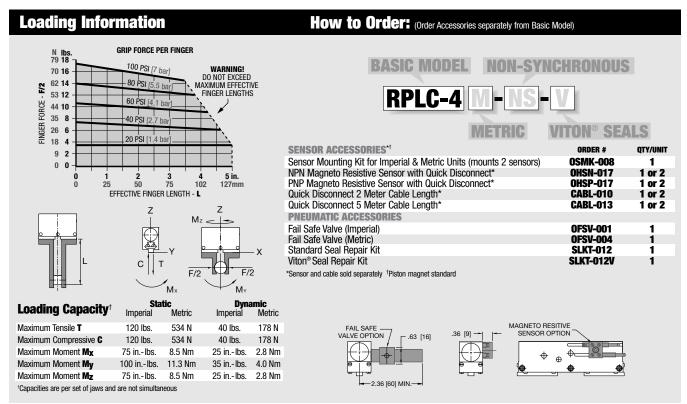
UITE	JJ UIIILIII	HIGE HOLED WEE HOLE	IIAIIULS AII	IL AJ JIIVIII D	LLUII
Ç	$\Rightarrow \phi$	<b>⊕</b>	$\bigoplus$	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$
		·			

### **Loading Information** How to Order: (Order Accessories separately from Basic Model) GRIP FORCE PER FINGER N lbs 79 18 **BASIC MODEL** 100 PSI [7 bar] WARNING 70 16 DO NOT EXCEED MAXIMUM EFFECTIVE 62 14 FINGER LENGTHS 53 12 44 10 35 8 FINGER **METRIC VITON® SEALS** 26 6 18 SENSOR ACCESSORIES\*\* ORDER # QTY/UNIT 9 2 Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors) **OSMK-008** 0 n NPN Magneto Resistive Sensor with Quick Disconnect\* **OHSN-017** 1 or 2 4 in. 102 mm PNP Magneto Resistive Sensor with Quick Disconnect\* **OHSP-017** 1 or 2 Quick Disconnect 2 Meter Cable Length\* CABL-010 1 or 2 EFFECTIVE FINGER LENGTH - L Quick Disconnect 5 Meter Cable Length\* CABL-013 1 or 2 **PNEUMATIC ACCESSORIES** Fail Safe Valve (Imperial) **OFSV-001** Fail Safe Valve (Metric) **OFSV-004** Standard Seal Repair Kit **SLKT-012** Viton® Seal Repair Kit SLKT-012V С \*Sensor and cable sold separately †Piston magnet standard F/2 M× Static **Dynamic** rial Metric **Loading Capacity**<sup>†</sup> Imperial Metric Imperial MAGNETO RESITIVE SENSOR OPTION FAIL SAFE VALVE OPTION Maximum Tensile T 400 N 133 N 90 lbs 30 lbs .36 [9] .63 [16] Maximum Compressive C 90 lbs. 400 N 30 lbs. 133 N Maximum Moment Mx Φ 60 in - lbs 6.8 Nm 20 in - lbs 2 3 Nm Ф Maximum Moment My 80 in.-lbs. 9.0 Nm 25 in.-lbs. 2.8 Nm Maximum Moment Mz 60 in.-lbs. 6.8 Nm 20 in.-lbs. 2.3 Nm -2.36 [60] MIN. †Capacities are per set of jaws and are not simultaneous

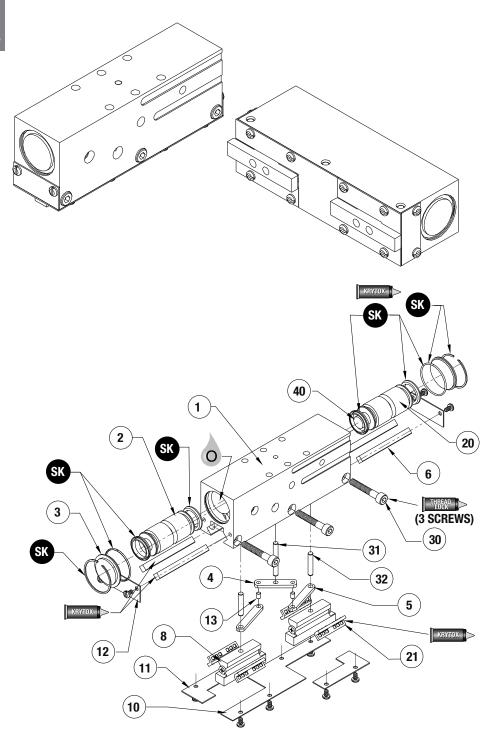


# PARALLEL GRIPPER RPLC-4M PRECISION DUAL "V" CLEAN ROOM SERIES









Item	Qty	Name
01	1	Body
02	1	Piston
03	2	Cap
04	1	Equalizer
05	2	Link
06	4	Way
80	2	Jaw
10	1	Cover, Bottom
11	2	Cover, Bottom, Corners
12	2	Cover, End
13	2	Bearing, Roller
20	1	Piston W/Magnet Slot
21	4	S'assy, Cage & Rollers
30	3	SHCS
31	1	Dowel Pin
32	2	Dowel Pin
40	2	Magnet

Note: contact the robohand sales department for a complete spare parts list with order numbers and prices.

### **Assembly procedure**

- 1) Lubricate and install seals.
- 2) Glue magnets into one piston, install pistons, caps and retaining rings.
- 3) Press dowel pin into center of body.
- 4) Place links and equalizers into body.
- 5) Press dowel pins into jaws.
- 6) Place jaws through links and into pistons.
- 7) Install cages on jaws.
  8) Place ways behind cages with flat facing out and install screws.
- 9) Adjust preload.
- 10) Install bottom cover, bottom cover corners and end covers.

# Preload adjustment procedure

- 1) Tighten center screw (#30) so that fingers preload adjustment procedure

  2) Tighten outer screws in the same fashion.
- Bind slightly.
- Cycle the gripper.
- 4) Re-adjust screws so that when you push the cage, the finger moves freely. (the finger movement should not feel gritty.)

# Non-synchronous procedure

- 1) Remove end covers, bottom cover corners, and bottom cover.
- 2) Remove preload screws (#30) and ways.
- 3) Remove cages, jaws and dowel pins.
- 4) Remove equalizer, links, and roller bearings.
- 5) Re-assemble jaws and dowel pins into pistons.
- 6) Re-install cages on jaws.
- Place ways behind cages with flat facing
- 8) Adjust preload. Install preload screws.
- 9) Re-attach bottom cover, bottom cover corners and end covers. Gripper is now non-synchronous.











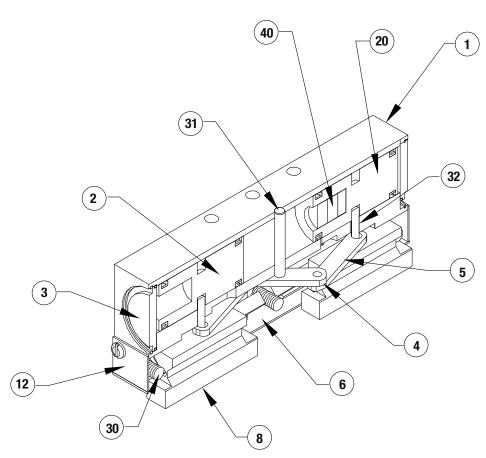








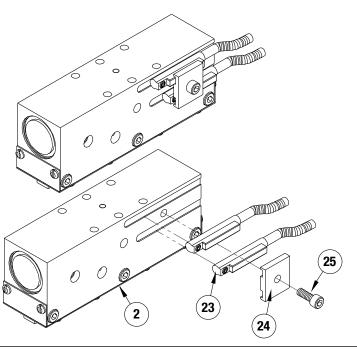




Item	Qty	Name
01	1	Body
02	1	Piston
03	2	Cap
04	1	Equalizer
05	2	Link
06	4	Way
08	2	Jaw
10	1	Cover, Bottom
11	2	Cover, Bottom, Corners
12	2	Cover, End
13	2	Bearing, Roller
20	1	Piston W/Magnet Slot
21	4	S'assy, Cage & Rollers
30	3	SHCS
31	1	Dowel Pin
32	2	Dowel Pin
40	2	Magnet

**Note:** contact the robohand sales department for a complete spare parts list with order numbers and prices.

# **Accessory Installation & Adjustment Instructions**



# Installation

- Install sensors as shown.
   Adjust for desired end of stroke detection.













