Parallel Grippers-DPG DIRECTCONNECT** Modular Series











- Sense up to four positions: Up to four jaw positions can be sensed to allow open, closed, part present, or variable part size sensing.
- Shielded to repel contaminate: Design repels chips and particulate. Closed jaw position spacing eliminates "chip compactor" effect.
- Longer finger applications: Rigid design and full body support of jaw allows for longer finger lengths.
- Spring assist, spring return: Cylinders can be double acting, double acting spring assist, failsafe, or single acting in either open or closed direction.
- Non-synchronous motion: Non-synchronous motion option provides independent jaw motion allowing the gripper to pick or place at a point other than it's center.
- Single jaw motion with fixed jaw: This option locks one jaw in a fixed position while the other jaw is free to move.

Mounting Information:

are available.

• Multiple mounting locations: DIRECTCONNECT™ mounting on top and back of

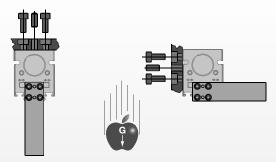
• Multiple air port positions: Tapped air ports

on front and both sides are standard. Top air

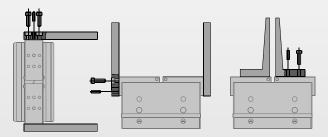
ports with counterbores for o-ring manifolded operation and threads for screw-in type fittings

body. Fingers mount to sides or bottom of jaws.

Grippers can be mounted & operated in any orientation



Body mounts with screws and locates with slip fit dowel pins for accuracy



Fingers attach with screws and locate on jaws by keying or dowel pin holes

Technical Specifications:

Pneumatic Specifications Imperial Metric Pressure Operating Range 40-100 psi 3-7 bar **Double Acting** Cylinder Type or Single Acting Spring Return or Double Acting Spring Assist **Dynamic Seals Internally Lubricated Buna-N** Valve Required 4-way, 2-position for Double Acting to Operate or 3-way, 2-position for Single Acting

Air Quality Requirements

Air Filtration 40 Micron or Better Not Necessary* Air Lubrication **Low Moisture Content (dry)** Air Humidity

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F -35°~80° C Viton® Seals (optional) -20°~300° F -30°~150° C

Maintenance Specifications[†]

Expected Life

Normal Application 5 million cycles w/ Preventative Maintenance 10+ million cycles* Field Repairable Yes Seal Repair Kits Available Yes

Application Restrictions

Applications where mechanism lubricant could cause contamination

*Addition of lubrication will greatly increase service life See Maintenance Section

Product Features

High Temperature

Optional Viton® seals are available for

high temperature applications

Hard Coat Anodize

The body and jaws have hard-coat anodize 60RC with Teflon® impregnation

Sensor Mounting Slots

Standard mounting slots for magneto resistive and inductive sensors (sensors sold separately)

One Piece Body Sensor Targets

One piece lightweight aircraft quality aluminum body **DIRECTCONNECT** Magnets come standard in pistons for magneto resistive sensors Four inductive sensor targets on sides

Mounting Patterns 2 DIRECTCONNECT™ mounting surfaces on top and back of body

Multiple Air Port

Locations

3 standard airport locations

(front & both sides)

Optional top airports available

Superior Jaw Support

Jaws are supported throughout the length of the body

Versatile Finger Mounting

2 finger mounting surfaces on each jaw

Extremely Compact & Robust Design

Self-Lubricating Seals Self lubricating dynamic seals (Buna-N only)

Shielded Design

Shielded design repels

of jaws

Dowel Holes

Slip fit dowel

pin holes in

body and jaws

Multiple Sensor Capabilities

Capable of sensing both jaws in the open and closed positions (up to 4 sensors can be used for multi-position sensing)

Optional Features

- Top air ports eliminating the need for airlines
- · Fixed jaw configurations · Spring assist for open or close stroke
- Non-synchronous version

Style -DPG-10M Parallel Gripper

Size -1

Style: D Stroke: 0.25 in. Grip Force: 50 lbs. 6.4 mm 222 N Weight: 0.39 lbs. 0.17 Kg





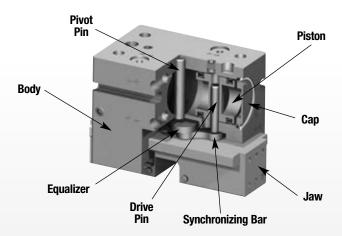
Style -DPG-10M Parallel Gripper

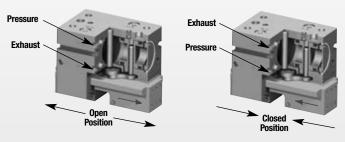
Size -2

Style: D Stroke: 0.50 in. Grip Force: 50 lbs. DPG-10M-2 12.7 mm 222 N 0.53 lbs 0.24 Kg



Operating Principle





- · Dual double acting opposed pistons, connected to both a jaw and a synchronizing bar by a drive pin, actuate in opposite directions.
- The synchronizing bars are connected to the equalizer which synchronizes the motion.
- · Suitable for internal or external gripping.
- The synchronizing elements can be removed for non-synchronous operation.

Designed and manufactured in the USA

Style -DPG-10M Parallel Gripper

Size -3

Grip Force: 50 lbs.
Weight: 0.68 lbs. 19.1 mm 222 N



See **1.128** Page **1.128**

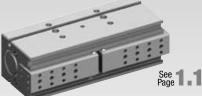
Style -DPG-10M Parallel Gripper

Size -4

Style: Stroke: DPG-10M-4 Stroke: 1.00 in. Grip Force: 50 lbs. Weight:

0.81 lbs.

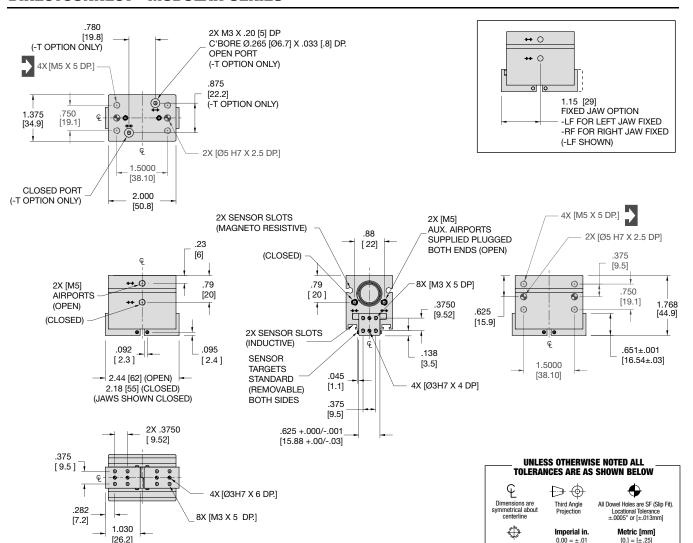
222 N 0.36 Kg





PARALLEL GRIPPER DPG-10M-1 DIRECTCONNECT™ MODULAR SERIES





NOTE: DIRECTCONNECT $^{\!\scriptscriptstyle{\mathsf{M}}}$ DIMENSIONS ARE SHOWN IN BLUE

How to Order: (Order Accessories separately from Basic Model) **SENSOR ACCESSORIES BASIC MODEL SPRING TOP PORTING** Inductive Sensor Mounting Kit (Mounts 2 Sensors) OSMK-097 1 or 2 NPN Inductive Sensor with Qk. Disconnect* **OISN-019** 1,2,3, or 4 **DPG-10M** -PNP Inductive Sensor with Qk. Disconnect* **OISP-019** 1,2,3, or 4 NPN Magneto Resistive Sensor w/Qk. Disconnect* **OHSN-017** 1,2,3, or 4 **OHSP-017** PNP Magneto Resistive Sensor w/Qk. Disconnect* **JAW SYNC VITON® SEALS** 1,2,3, or 4 **OHSN-011** NPN Magneto Resistive Sensor (90°) w/Qk. Disconnect* (See Below) 1,2,3, or 4 PNP Magneto Resistive Sensor (90°) w/Qk. Disconnect* OHSP-011 1,2,3, or 4 Spring Open Spring Closed Leave Blank. No Spring Option (standard) **SPRING DIRECTION** Quick Disconnect Cable (2 meters long)* CABL-010 1,2,3, or 4 Č Quick Disconnect Cable (5 meters long)³ CABL-013 1,2,3, or 4 CABL-015 Quick Disconnect Cable Extension Cord (1 meter long)* 1,2,3, or 4 JAW SYNCHRONIZATION Left Jaw Fixed CABL-016 Quick Disconnect Cable Extension Cord (2 meters long)* 1,2,3, or 4 Right Jaw Fixed Non-synchronous Jaws Leave Blank for Synchronous (standard) **CONFIGURATION** RF NS **PNEUMATIC ACCESSORIES** ORDER # QTY/UNIT Standard Seal Repair Kit **SLKT-183** 1 Viton® Seal Repair Kit SLKT-183V -T Option Plumbing Fitting - M3 male to 3mm OD Tube Push-in Style PLFT-021 1 or 2 -T Option Plumbing Fitting - M3 male to 2mm ID Tube Barb Style PLFT-022 1 or 2 **OFSV-004** Fail Safe Valve - M5 (Metric) 1 Adjustable Flow Control (Metric) **VLVF-008** 1 or 2 Top Port Manifold Seal Kit SLKT-184V *Sensor and cable sold separately **SAMPLE ORDER: DPG-10M-1-C-V** Ex: DPG-10M Gripper, Metric, Size 1, Spring Close, Viton® Seals

Metric Threads Course Pitch

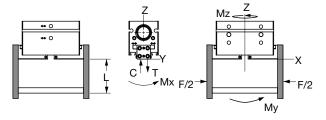


GRIP FORCE PER FINGER WARNING! 112 25 100 PSI [7 bar] DO NOT EXCEED MAXIMUM EFFECTIVE 89 20 FINGER LENGTHS [5.5 bar FINGER FORCE -67 15 45 10 0 PSI [2 23 5 0 0 2.5 3.5 in. Ō 13 25 38 51 64 76 89mm

Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open		26 N 49 N	9 lbs. 6 lbs.	40 N 26 N

EFFECTIVE FINGER LENGTH - L

Specifications	DPG-10M	-1
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	0.25 in.	6.4 mm
Weight	0.39 lbs.	0.17 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.688 in.	17.5 mm
Displacement	0.076 in ³ .	1.2 cm ³



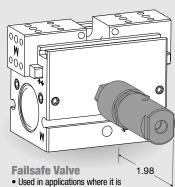
PARALLEL GRIPPER DPG-10M-1 DIRECTCONNECT™ MODULAR SERIES

Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	175 lbs. [778 N]	20 lbs. [89 N]
Maximum Compressive C	400 lbs. [1779 N]	20 lbs. [89 N]
Maximum Moment Mx	150 in1bs. [17 Nm]	20 in1bs. [2 Nm]
Maximum Moment My	175 in1bs. [20 Nm]	30 in1bs. [3 Nm]
Maximum Moment Mz	150 in1bs. [17 Nm]	20 in1bs. [2 Nm]

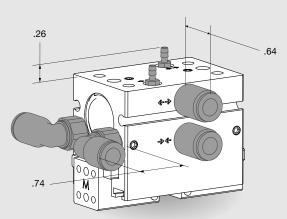
†Capacities are per set of jaws and are not simultaneous

Specifications (cont.)	DPG-10M-1	
Temperature Range: Standard SealsViton® Seals	-30°~180° F -20°~300° F	
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate	4-way, 2-p	oosition

Accessory Mounting Technical Data

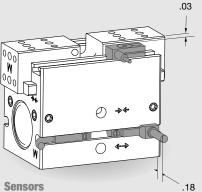


- critical that the part being gripped not be dropped if air pressure is lost
- Mounts directly to gripper
- M5 air port

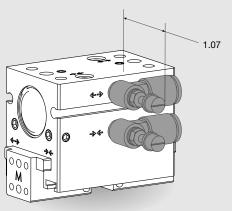


Multiple Air Port Locations

- 3 standard air port locations (front and both sides)
- Optional top ports are tapped for M3 fittings
- Consult factory for plumbing fitting part numbers



- · Choose from magneto resistive and inductive prox
- · Capable of sensing 4 positions open and closed on both jaws
- PNP and NPN available
- · Magneto resistive sensors are slot mounted, no mounting
- Threaded quick disconnect with built-in led output
- · Sensors mount on either side of gripper

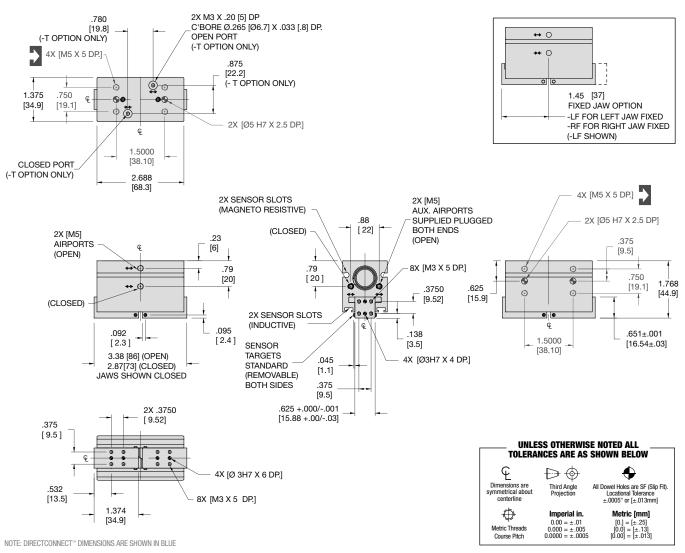


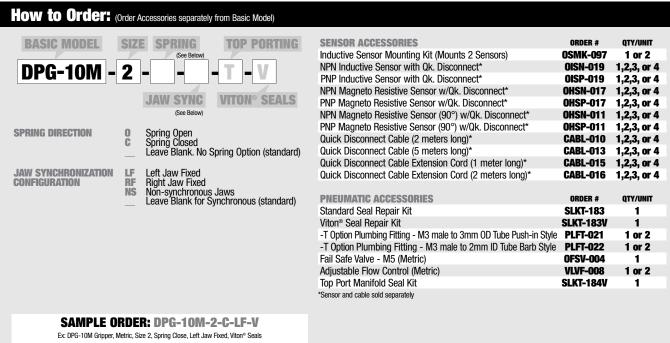
- Thumb screw adjust with locking nut for adjusting actuation time
- · Available for 5mm OD tubing

PARALLEL GRIPPER DPG-10M-2 DIRECTCONNECT™ MODULAR SERIES

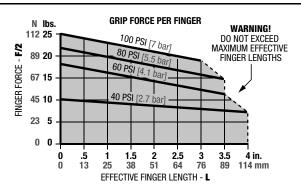






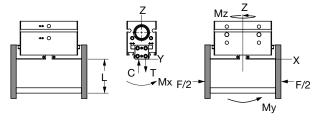






Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open		26 N	14 lbs.	62 N
@ Full Close		66 N	6 lbs.	26 N

Specifications	DPG-10	M-2
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	0.50 in.	12.7 mm
Weight	0.53 lbs.	0.24 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.688 in.	17.5 mm
Displacement	0.153 in ³ .	2.5 cm ³



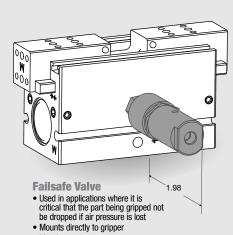
PARALLEL GRIPPER DPG-10M-2 DIRECTCONNECT™ MODULAR SERIES

Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	200 lbs. [890 N]	25 lbs. [111 N]
Maximum Compressive C	425 lbs. [1890 N]	25 lbs. [111 N]
Maximum Moment M _X	175 in1bs. [20 Nm]	25 in1bs. [3 Nm]
Maximum Moment My	200 in1bs. [23 Nm]	35 in1bs. [4 Nm]
Maximum Moment Mz	175 in1bs. [20 Nm]	25 in1bs. [3 Nm]

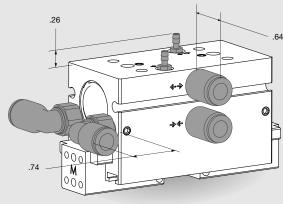
†Capacities are per set of jaws and are not simultaneous

Specifications (cont.)	DPG-10M-2	
Temperature Range: Standard SealsViton® Seals		
Actuation	0.19 sec.	0.19 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate	. 4-way, 2-position	

Accessory Mounting Technical Data

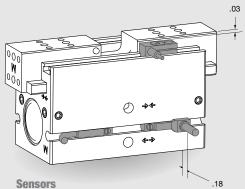


• M5 air port

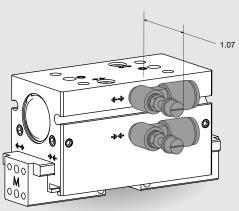


Multiple Air Port Locations

- 3 standard air port locations (front and both sides)
- Optional top ports are tapped for M3 fittings
- Consult factory for plumbing fitting part numbers



- Choose from magneto resistive and inductive prox
- · Capable of sensing 4 positions open and closed on both jaws
- PNP and NPN available
- · Magneto resistive sensors are slot mounted, no mounting
- Threaded quick disconnect with built-in led output
- · Sensors mount on either side of gripper

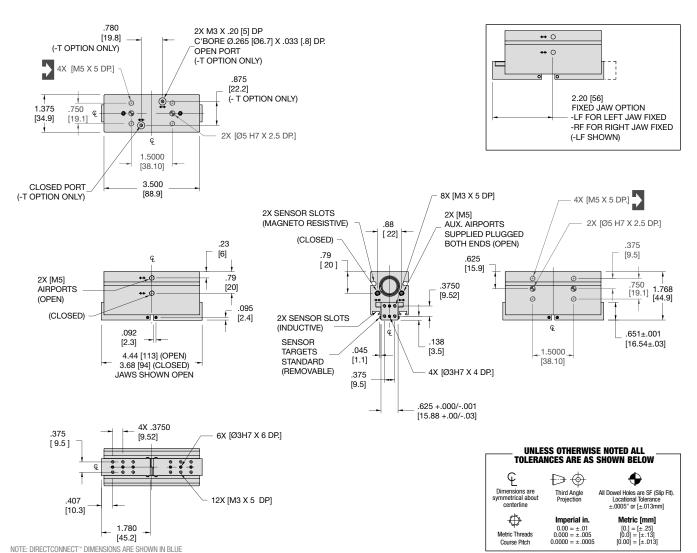


- . Thumb screw adjust with locking nut for adjusting actuation time
- Available for 5mm 0D tubing

PARALLEL GRIPPER DPG-10M-3 **DIRECTCONNECT™ MODULAR SERIES**









TOP PORTING DPG-10M -**VITON® SEALS JAW SYNC** (See Below)

SPRING DIRECTION

0

Spring Open Spring Closed Leave Blank. No Spring Option (standard)

JAW SYNCHRONIZATION **CONFIGURATION**

Left Jaw Fixed RF NS

Right Jaw Fixed Non-Synchronous Jaws Leave Blank for Synchronous (standard)

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
Inductive Sensor Mounting Kit (Mounts 2 Sensors)	OSMK-097	1 or 2
NPN Inductive Sensor with Qk. Disconnect*	OISN-019	1,2,3, or 4
PNP Inductive Sensor with Qk. Disconnect*	OISP-019	1,2,3, or 4
NPN Magneto Resistive Sensor w/Qk. Disconnect*	OHSN-017	1,2,3, or 4
PNP Magneto Resistive Sensor w/Qk. Disconnect*	OHSP-017	1,2,3, or 4
NPN Magneto Resistive Sensor (90°) w/Qk. Disconnect*	OHSN-011	1,2,3, or 4
PNP Magneto Resistive Sensor (90°) w/Qk. Disconnect*	OHSP-011	1,2,3, or 4
Quick Disconnect Cable (2 meters long)*	CABL-010	1,2,3, or 4
Quick Disconnect Cable (5 meters long)*	CABL-013	1,2,3, or 4
Quick Disconnect Cable Extension Cord (1 meter long)*	CABL-015	1,2,3, or 4
Quick Disconnect Cable Extension Cord (2 meters long)*	CABL-016	1,2,3, or 4

PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
Standard Seal Repair Kit	SLKT-183	1
Viton® Seal Repair Kit	SLKT-183V	1
-T Option Plumbing Fitting - M3 male to 3mm OD Tube Push-in Style	PLFT-021	1 or 2
-T Option Plumbing Fitting - M3 male to 2mm ID Tube Barb Style	PLFT-022	1 or 2
Fail Safe Valve - M5 (Metric)	OFSV-004	1
Adjustable Flow Control (Metric)	VLVF-008	1 or 2
Top Port Manifold Seal Kit	SLKT-184V	1
*Conser and public cold congrately		

SAMPLE ORDER: DPG-10M-3-C-RF-V

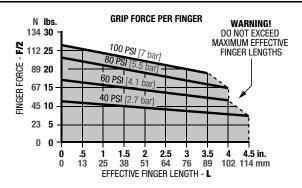
Ex: DPG-10M Gripper, Metric, Size 3, Spring Close, Right Jaw Fixed, Viton® Seals



Cylinder Bore Ø

Displacement

PARALLEL GRIPPER DPG-10M-3 DIRECTCONNECT™ **MODULAR SERIES**



Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open	6 lbs.	26 N	15 lbs.	66 N
@ Full Close		102 N	6 lbs.	26 N

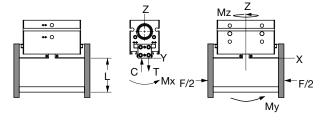
Specifications	DPG-10	DM-3
Total Rated Grip Force F @ 100 psi, 7 bar		222 N
Stroke	0.75 in.	19.1 mm
Weight	0.68 lbs.	0.30 Kg
Pressure Range	40-100 psi	3-7 bar

0.688 in.

0.230 in³.

17.5 mm

3.8 cm³

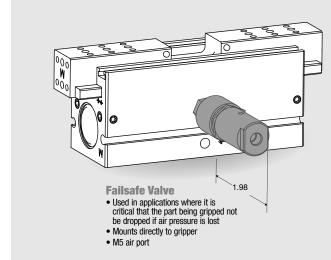


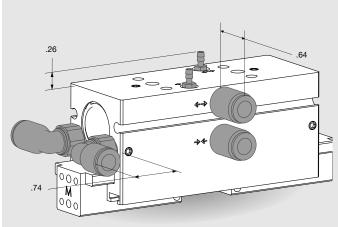
Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	225 lbs. [1001 N]	30 lbs. [133 N]
Maximum Compressive C	450 lbs. [2002 N]	30 lbs. [133 N]
Maximum Moment M _X	200 in1bs. [23 Nm]	30 in1bs. [3 Nm]
Maximum Moment My	225 in1bs. [25 Nm]	40 in1bs. [5 Nm]
Maximum Moment Mz	200 in1bs. [23 Nm]	30 in1bs. [3 Nm]

†Capacities are per set of jaws and are not simultaneous

Specifications (cont.)	DPG-10M-3	
Temperature Range: Standard Seals		
Viton® Seals	-20°~300° F 0.29 sec.	-30°~150° C 0.29 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate	4-way, 2-p	osition

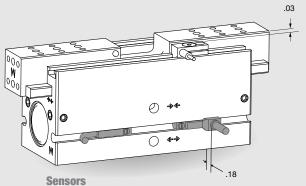
Accessory Mounting Technical Data



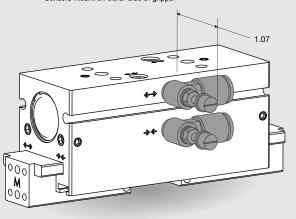


Multiple Air Port Locations

- 3 standard air port locations (front and both sides)
- Optional top ports are tapped for M3 fittings
- Consult factory for plumbing fitting part numbers



- Choose from magneto resistive and inductive prox
- · Capable of sensing 4 positions open and closed on both jaws
- PNP and NPN available
- · Magneto resistive sensors are slot mounted, no mounting
- Threaded quick disconnect with built-in led output
- · Sensors mount on either side of gripper

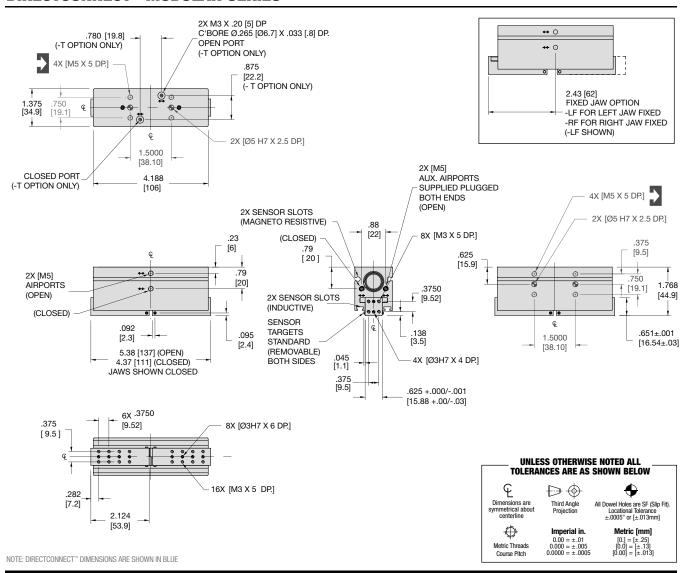


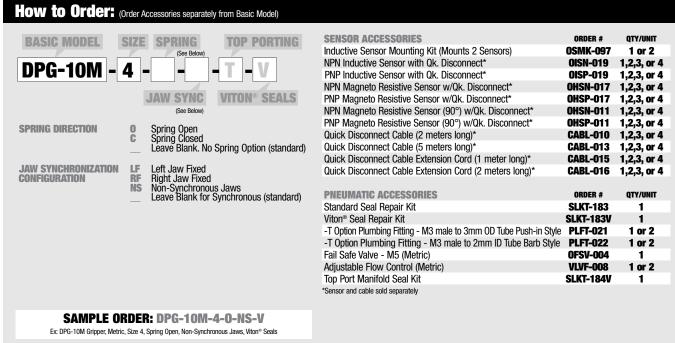
- Thumb screw adjust with locking nut for adjusting actuation time
- · Available for 5mm OD tubing

PARALLEL GRIPPER DPG-10M-4 DIRECTCONNECT™ MODULAR SERIES



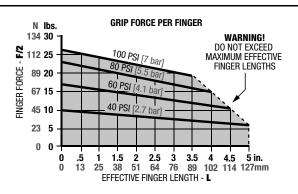






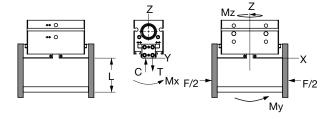


PARALLEL GRIPPER DPG-10M-4 DIRECTCONNECT™ **MODULAR SERIES**



Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open@ Full Close		26 N 97 N	15 lbs. 6 lbs.	66 N 26 N

Specifications	DPG-10	M-4
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	1.00 in.	25.4 mm
Weight	0.81 lbs.	0.36 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.688 in.	17.5 mm
Displacement	0.306 in ³ .	5.0 cm ³

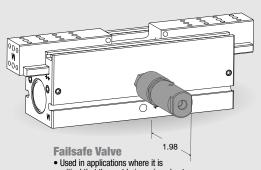


Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	250 lbs. [1112 N]	35 lbs. [156 N]
Maximum Compressive C	475 lbs. [2113 N]	35 lbs. [156 N]
Maximum Moment M _X	225 in1bs. [25 Nm]	35 in1bs. [4 Nm]
Maximum Moment My	250 in1bs. [28 Nm]	45 in1bs. [5 Nm]
Maximum Moment Mz	225 in1bs. [25 Nm]	35 in1bs. [4 Nm]

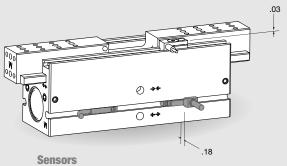
†Capacities are per set of jaws and are not simultaneous

Specifications	DPG-1	OM-4
Temperature Range: Standard SealsViton® Seals	-30°~180° F -20°~300° F	
Actuation	0.40 sec.	0.40 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate	4-way, 2-p	osition

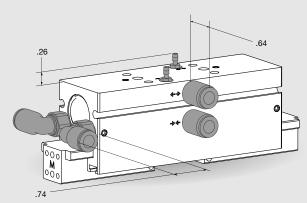
Accessory Mounting Technical Data



- critical that the part being gripped not be dropped if air pressure is lost
- Mounts directly to gripper
- M5 air port

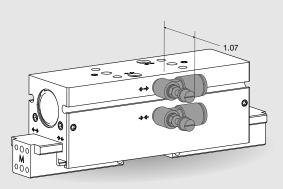


- Choose from magneto resistive and inductive prox
- Capable of sensing 4 positions open and closed on both jaws
- · PNP and NPN available
- Magneto resistive sensors are slot mounted, no mounting kits required
- Threaded quick disconnect with built-in led output
- Sensors mount on either side of gripper



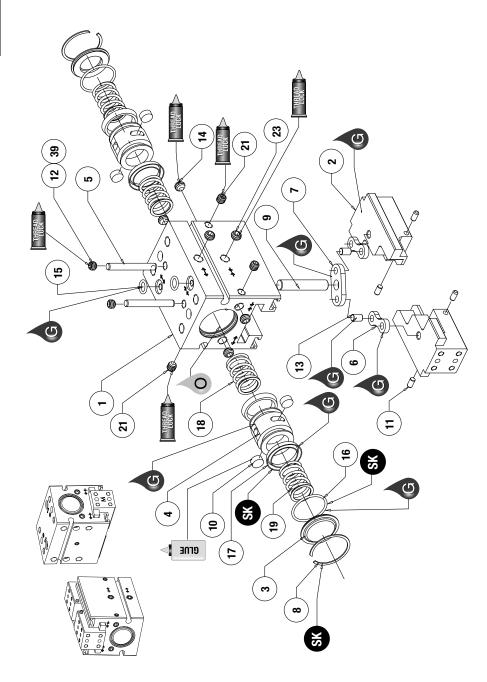
Multiple Air Port Locations

- 3 standard air port locations (front and both sides)
- . Optional top ports are tapped for M3 fittings
- Consult factory for plumbing fitting part numbers



- . Thumb screw adjust with locking nut for adjusting actuation time
- Available for 5mm 0D tubing





Item	Qty	Name
01	1	Body
02		Jaw
03	2 2 2 2 2	Cap
04	2	Piston
05	2	Drive Pin
06	2	Synchronizing Bar
07	1	Equalizer
08		Retaining Ring
09	2	Pivot Pin
10	4	Magnet
11	4	Targets for Inductive
11	4	Sensors
12	2	Set Screw - Drive Pin
12	2	
13	2	Access Plug
13	2	Equalizer/Synchronizing
14	4	Bar pivot pin Set Screw - End Port
14	4	
15	2	Plugs
15	2	O-ring - Top Porting
10	_	Manifold Seals (-T option)
16 17	2	O-ring - Cap Seals
18		U-cup - Piston Seals Springs for "-0"
18	2	Springs for "-U"
10		Spring-Open Option Springs for "-C"
19	2	
<u> </u>		Spring-Closed Option
21	3	Set Screw - Internal
		Porting Plugs
23	2	Set Screw - Side Porting
		Plugs (-T option)
39	1	Set Screw - Plug (-LF
		and -RF options only)

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



Assembly Procedure

- 1) Lubricate body.
- Plug cross ports in body.
- Press pivot pin into body.
- Insert magnets into pistons making sure magnets attract to each other.
- Lubricate and install seals onto pistons.
- Insert pistons into body aligning drive pin hole in pistons with the drive pin hole in the body.
- Press pins into equalizer.
- Assemble equalizer with synchronizing bars and place onto pivot pin in body
- making sure holes in synchronizing bars line up with holes in pistons.

 9) From top body mounting surface insert
- drive pins through the pistons and into the synchronizing bars making sure not to go through the synchronizing bars.
- 10) Place jaws into body aligning the drive pins with the hole in the jaws.
- Press drive pins into jaws.
- 12) Install drive pin plugs into body.
- Place seals onto caps and install with retaining rings.

Non-Synchronous Procedure

- Remove drive pin plugs.
 Press drive pins out of body from jaw side.
- Remove jaws from body.
- Remove equalizer and synchronizing bars from body.
- Re-install jaws into body aligning the drive pin with the hole in the jaws
- Press drive pins into jaws.
- 7) Re-install drive pin plugs into body.













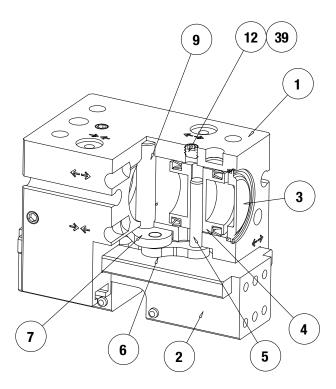






DPG SERIES ASSEMBLED VIEW

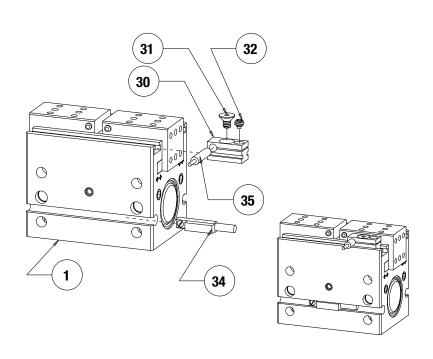




Item	Qty	Name
01	1	Body
02	2	Jaw
03	2	Cap
04	2	Piston
05	2	Drive Pin
06	2	Synchronizing Bar
07	1	Equalizer
09	1	Pivot Pin
12	2	Set Screw - Drive Pin
		Access Plug
39	1	Set Screw - Plug (-LF and
		-RF options only)

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation:

Magneto Resistive Sensors

- 1) Install sensors in profile slots of gripper body as shown.
- 2) Set sensors with integrated screw.

Inductive Sensors

- Insert sensor bracket into slot of body.
 Insert sensor into bracket and adjust
- sensor depth so that sensor light indicates on target.
- 3) Tighten sensor locking screw (#31) to hold sensor depth.
- 4) Position sensor bracket for desired stroke detection.
- 5) Tighten sensor bracket with setscrew (#32) to lock stroke detection position.

Seal Kit Items











