

Short Circuit Protection Inrush Current Protection **Drive Overtemperature Protection** Undervoltage Protection Regeneration Protection

Still Air: 45°C (113°F) Operating Temperature

Moving Air: 50°C (122°F) Minimum: 0°C (32°F)

-40°C - 85°C (-40°F - 185°F) Storage Temperature:

Humidity:

0 - 95%, non-condensing



# Troubleshooting

Commonly used status commands (binary status bits are numbered 1 to n, from left to right):

TERRLG Error log reports the last 10 error conditions

(cleared with CERRLG).

TAS General report, including fault conditions. TASX

Additional report of conditions not covered with

TIN

If TASX bit #7 or bit #28 is set, you can identify TCS

the cause with TCS.

TINO Bit #6 indicates status of Enable input ("1" = OK to enable drive)

Status of digital inputs, including end-of-travel

Status of digital outputs.

You must configure all motor parameters. Be sure to follow the drive configuration procedure (see Chapter 2 Installation).

Any fault condition causes the drive to shut down.

The drive can not be enabled (DRIVE1) unless the Enable input is grounded and the Reset input is not grounded.

Use one of three methods to reset the drive (all command settings are remembered after reset): Issue the RESET command

Momentarily close the Reset input. Cycle power to the drive.

# **Quick Reference** Guide



# **Gemini GT6 Series Digital Stepper** Controller/Drive

**Compumotor Division Parker Hannifin Corporation p/n 88-018375-01 A** (effective December 17, 1999)



RS-232/485 Connector – Configuration Port

To configure all drive parameters, connect a PC or HPC to this port. Use Motion Planner or Pocket Motion Planner for drive configuration.

