



PARALLEL GRIPPERS

ANGULAR GRIPPERS

LINEAR ACTUATORS

RS ROTARY ACTUATORS

ROBOTIC TOOLING

FEED ESCAPEMENTS





www.destaco.com Precisely positioning our customers for productivity.

DE-STA-CO OVERVIEW

Red Wing, Minnesota

Wheeling, Illinois

THE BEST PRODUCTS. UNMATCHED SERVICE. WORLDWIDE.

With a support network spanning the globe, DE-STA-CO offers consistent, comprehensive service to any location in the world. Whether your operations are localized or span multiple continents, you will always have access to the highest levels of customer service and technical support.

herland

TEAM DE-STA-CO

Charlevoix, Michigan

uburn Hills, Michiaan

Brazil

Monroe, Connecticut

Team DE-STA-CO represents our efforts to provide consistent, standard-setting service and products to every DE-STA-CO customer, regardless of geographic location. Through this commitment, we are able to draw on our extensive knowledge base to always provide the perfect solution specific to your unique applications. This progressive global approach to doing business provides a level of expertise that is unmatched in the industry.



Please see back cover for DE-STA-CO Global Locations. www.destaco.com





Automation Robohand FERGUSON CAMCO



DPE ELECTRICAL PARALLEL GRIPPERS

See page 1.8



RPR GLADIATOR PARALLEL GRIPPERS

See page 1.222



FUA FOOD SERIES ANGULAR GRIPPER





2P 2-JAW PRECISION PARALLEL GRIPPERS See page 1.40



CP 2-JAW COMPACT PARALLEL GRIPPERS See page 1.58



VULCAN HIGH TEMP ANGULAR GRIPPERS See page 2.4



RSD INDEX DRIVES



3P 3-JAW PRECISION PARALLEL GRIPPERS See page 1.252



ARV-AUTO RELEASE VENTURI VACUUM MODULE See page 6.53

Image: Non-State Parallel Grippers 1.8 DPE 1.90 RPL 1.146 DPDL 1.214 RPW 1.14 RPE 1.98 RPLC 1.158 DPL 1.222 RPR 1.20 RDH 1.106 RPM 1.176 RP-5&10 1.228 "B" Series 1.40 Precision 2P 1.114 RPMC 1.170 RP 1.230 RTH/DTH 1.58 CP 1.122 DPG 1.186 GC 1.252 Precision 3P 1.74 DPP 1.134 DDDS 1.196 DPW 1.268 PPC	1
ANGULAR GRIPPERS 2.4 RUA/VULCAN 2.22 RA-5, 6, & 10 2.32 DCT/CT 2.44 DCT-RE/CT-RE 2.56 FUA	2
ROTARY ACTUATORS 3.2 DRF 3.14 DRG 3.26 RR-18 & 28 3.32 RR-36 & 46 3.42 RR-56, 66, & 76	3
LINEAR SLIDES 4.8 DLB-B & L 4.20 DLB-TANRU 4.32 DLT-B 4.40 DLT-E&L 4.56 DLT-TANRU 4.70 DLM	4
FEED ESCAPEMENTS 5.2 RFE	5
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Terms & Conditions

GENERAL — All quotations, acceptance and orders submitted by or to and all contracts made with Destaco-Robohand shall be upon and subject to the following terms and conditions except in so far as specifically agreed to by Destaco-Robohand in writing upon or annexed to a copy thereof.

QUOTATIONS AND PRICES — Prices are subject to change without notice. Written quotations expire 30 calendar days from the date of issue and are subject to termination by notice within that period.

PURCHASE ORDER — If this quotation is accepted and Buyer's order form is used for the purpose, it is expressly understood and agreed that the terms and conditions herein set forth shall prevail, insofar as the same may in any way conflict with the terms and conditions set forth in such order form, and the issuance of such order by Buyer shall be deemed to note Buyer's assent to the foregoing.

PAYMENT — Unless expressly agreed to the contrary by Destaco-Robohand, all accounts shall be paid net within 30 days from the date of invoice. All checks and money orders should be made payable to Destaco-Robohand. Destaco-Robohand reserves the right to charge interest 1% above the base lending rate of Bank of America for the period that the account is overdue for payment and the Buyer shall reimburse Destaco-Robohand for all costs of collection including reasonable attorneys fee on all overdue amounts. In so case will the property of any of the goods pass to the Buyer until payment of the full price has been made to Destaco-Robohand. So long as any payment under this contract is overdue, Destaco-Robohand reserves the right to withhold or suspend performance of any contractual obligation.

DELIVERY — Any times quoted for delivery or dispatch are to date from the receipt by Destaco-Robohand of written order to proceed and all necessary information and drawings to enable Destaco-Robohand to put the work in hand and Destaco-Robohand's acceptance in writing of such terms. The time for delivery or dispatch shall be extended by a reasonable period if caused by any industrial dispute or by any cause beyond Destaco-Robohand's reasonable control.

TAXES — The amount of the present or future sales, revenue, excise, or other taxes applicable to the products listed herein shall be added to the purchase price and shall be paid by the Buyer or in lieu thereof the Buyer shall provide Destaco-Robohand with a tax exemption certificate acceptable to the taxing authorities.

INSTALLMENT DELIVERIES — Destaco-Robohand shall have the right to make delivery by installments of such quantities and at such intervals as it may decide and any express provisions as to installments in the contract shall be in addition to and not in derogation of this right.

GOODS LOST OR DAMAGED IN TRANSIT — Unless Destaco-Robohand receives a complaint in writing within 3 days of the receipt by the Buyer of the goods, the goods shall be deemed to be in good condition and of the quality and description invoiced or in the case of non-delivery, Buyer shall furnish written notice within such time from the date of dispatch as shall enable Destaco-Robohand to make a reasonable claim on the carrier.

DEFECTS AFTER DELIVERY — Destaco-Robohand will make good by repair or at it's option by the supply of a replacement: defects, which under proper use, appear in the goods within a period of one (1) year after the goods have been delivered and arise solely from faulty design (other than a design made, furnished, or specified by the buyer. Materials or workmanship provided that have defective parts will be returned to Destaco-Robohand if so required, Destaco-Robohand will refund the cost of carriage on such returned goods and the repaired or new parts will be delivered free of charge.

SHIPMENT — All prices are F.O.B. Our factory, Monroe, CT and route of shipment are at our discretion, unless the Buyer supplies implicit instructions. All shipments are insured at the Buyer's expense and made at the Buyer's risk. Identification of the goods to the contract shall occur as each shipment is placed in the hands of the carrier.

DRAWINGS — All descriptive and forwarding specifications, drawings and particulars of weight and dimensions submitted with Destaco-Robohand's proposal are approximate only and the descriptions and illustrations contained in Destaco-Robohand's catalogs, price list and other advertisement matter are intended merely to present a general idea of the goods described therein and none of these shall form part of a contract and any statement or representation made by or on behalf of Destaco-Robohand is executed to the extent authorized by The Misrepresentation Act, 1967.

EXCLUSIONS OF LIABILITY — Any warranties given by Destaco-Robohand in these Conditions of Sale are in lieu of all other warranties or conditions express or implied by common or statute law and Destaco-Robohand shall not be liable to the Buyer for any consequential damage or loss whatsoever nature resulting from defects in material of workmanship, except as herein provided, or from any other breaches of this contract by Destaco-Robohand whatsoever with the exception of damage or loss caused through death or personal injury resulting solely from negligence of the seller in the manufacture, supply or repair of the goods.

DESTACO-ROBOHAND'S RIGHT OF POSSESSION —

Destaco-Robohand shall have the right, in addition to all others it may possess, at any time, for credit reasons or because of Buyer's default or defaults, to withhold shipments, in whole or in part, and to recall goods in transit, retake same, and repossess all goods which may be stored with Destaco-Robohand for Buyer's account, without the necessity of taking any other proceedings, and Buyer consents that all the merchandise so recalled, retaken or repossessed shall become Destaco-Robohand's absolute property, provided that Buyer is given full credit therefor. The foregoing shall not be construed as limiting, in any manner, any of the rights or remedies available to Destaco-Robohand because of any default of Buyer under the Uniform Commercial Code as in force and effect in the State of Connecticut on the date of the signing of this agreement.

SPECIFICATIONS — Normal tolerances in specifications shall be acceptable. GOODS NOT OF DESTACO-ROBOHAND'S MANUFACTURE — Destaco-Robohand will give the Buyer a guarantee equivalent to guarantee (if any) which the supplier of such goods in respect thereof but not so as to impose on Destaco-Robohand in respect of such goods a liability greater than those contained in these Conditions of Sale.

RETURNED MATERIAL — In no case are goods to be returned without first obtaining Destaco-Robohand's permission. Only unused material as currently manufactured, which has been invoiced to Buyer within 90 days, will be considered for return.

REPAIR WORK — Quotations for repair are made on a preliminary examination of the goods to be repaired. To assure a satisfactory repair, it is frequently necessary to replace parts which on first inspection appear to be reusable and/or carry out additional work to that originally quoted for Destaco-Robohand therefore reserves the right to invoice repair work on the basis of ascertained costs. If following receipt of a quotation for the repair of goods the Buyer decides not to proceed, Destaco-Robohand reserves the right to charge for dismantling and installation.

If within 30 days from receipt of a quotation for the repair of goods the Buyer does not give any instructions, Destaco-Robohand will not therefore accept any liability for loss of or damage to any of the Buyer's property remaining in its hands.

PATENTS — In the event of any claim being made or action taken being brought against the Buyer in respect of infringement of patents by the manufactured or sale by Destaco-Robohand or goods supplied to the Buyer being goods manufactured according to the designs and specifications of Destaco-Robohand, the Buyer shall notify Destaco-Robohand immediately of any such claim being made or action being brought and Destaco-Robohand shall be at liberty with the assistance of the Buyer, if required, but at Destaco-Robohand's expense, to conduct all negotiations for the settlement of the same and/or litigations that may arise therefrom. The Buyer shall indemnify Destaco-Robohand against all costs, claims, expenses, damages, charges or liability whatsoever in respect of or arising from any claim for infringement of any patent, trademark or registered design relating to any product supplied to the design of the Buyer or following the instructions of the buyer.

LEGAL CONSTRUCTION — Unless otherwise agreed in writing, contracts shall, in all respects, be construed in accordance with the laws of the State of Connecticut and operate as a contract conforming to American law.

CONTROLLING PROVISIONS — These terms and conditions shall supersede and terms, provisions and conditions contained on any confirmation order, or other writing Buyer may give or receive and the rights of the parties shall be governed exclusively by the terms and conditions hereof. Destaco-Robohand makes no representations or warranties concerning this order except such as are expressly contained herein, and this order may not be changed or modified orally.

LIMITATION OF WARRANTY - All Destaco-Robohand products are to be free of actual defects in material and workmanship, provided any such defect be reported to Destaco-Robohand in writing within one (1) year of shipment from factory. This warranty is limited to replacing or repairing at the company's option, F.O.B. the company's factory any part which, upon company inspection, is found to have a defect in material and/or workmanship. The Company, in no event shall be liable for indirect or consequential damages arising out of the use of Destaco-Robohand products. Components purchased by the company from others for inclusion by the company shall be warranted to the extent set out and/or to the guarantee or warranty, if any, made by the supplier of said component. APART FROM THE ABOVE WARRANTY, THERE ARE NO WARRANTIES EXPRESS, WRITTEN, IMPLIED OR STATUTORY, INCLUDING, WITHOUT LIMITATION, WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, WHICH EXTENDED BEYOND THE DESCRIPTION ON THE FACE HEREOF AND ROBOHAND SHALL NOT BE LIABLE DIRECTLY OR INDIRECTLY ARISING FROM THE USE OF SUCH PRODUCTS OR FOR ANY CONSEQUENTIAL DAMAGES. Destaco-Robohand expressly reserves the right to substitute materials in the products described in the catalogs and any supplements thereto: however, this shall not apply to special order products and/or custom products where Destaco-Robohand is advised in writing of specific material requirements and agrees in writing to comply with the request for such materials.

Applications Form

Company Informatio	n:							
Company Name:			Date					
Address:								
City:			Sta	te Zip				
Phone:		Fax:		Web:				
Key Contact Informa	tion:							
Name:								
Phone: ()	Ext	Fax: ()		Email:	<u>.</u>			
What is your time fra	ame to purchase?							
□ Immediate	□ 3-6 Month	G-12 Months	□ Other:_					
What is your expecta	ations on delivery?		weeks					
What is the Quantity	Required?		pcs.					
Specifications:								
Air Pressure:	psi	Finger Length:		in. Part Weight:	lbs.			
Stroke Required:	in. Cycle T	ime: Sec	Cycle Rate:	cycles/hour Duty Cycle:	%			
Environment: 🔲 Dirt	y 🗆 Corrosive	🗆 Clean Room	🗆 High Temp	Other				

Description:

Please describe your application. Include a sketch or attach additional sheets if necessary. Please provide any photos you have available.

Paralel Grippers

Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com

1.2

Parallel Motion Gripper



- No programming or software required
- 60 parts per minute-no problem!
- · Compact, lightweight design

Preferred Market:
Global



Two Jaw Parallel

Gripper

- Shielded design deflects chips and other particulate away from the internal components
- · Large surface area of the jaws allows for use of long fingers
- All gripper sizes are available in 2 strokes sizes.

Preferred Market:
 Global

2P Series Precision Two Jaw Parallel Gripper

- Precision operation
- Cylindrical design
- Optional springs for failsafe operation or for increased gripforces
- Side or rear airports
- Tandem piston for double grip force
- · Optional Protective Boot for harsh environments
- All gripper sizes are available in 2 strokes sizes

Preferred Market: ■ EU ◆ SA

CP Series **Compact Two Jaw** Parallel Gripper

- Rugged, compact design
- · Shielded design deflects chips and other
- particulate away from the internal components Optional springs for failsafe operation
- or for increased gripforces
- Side or rear airports
- Multi-sensor capable design
- All gripper sizes are available in 2 strokes sizes

Preferred Market: EU



Precision Gripper

- Featuring our DIRECTCONNECT[™] mounting pattern
- · "Dual-V" precision roller bearing design provides zero side
- play for excellent part position repeatability
- · Optional double acting spring assist for increased force or failsafe operation

NEW

· Low friction design allows for delicate part handling · Synchronized and non-synchronized versions available

Preferred Market:
 Global



See **1** Page **1**



See **1.20**

See **1.40**

RPL/RPLC Series

- Lightweight, Compact
 Patented Dual "V" Roller Bearing System
- · Excellent accuracy and repeatability
- · Synchronized and non-synchronized versions available
- Designed for use in Class 10 clean rooms as well as in harsh environments
- Stainless Steel hardware and covers for durability
- Vacuum/Pressure port

Preferred Market:
Global



See **1.106**

RPM/RPMC Series Micro/Clean Room Gripper

- Extremely small size—as small as 5/8" wide! Compact design allows for gripping small parts
- in small spaces • Top air manifold eliminates the need for air fittings
- and allows grippers to be mounted in close array · Ultra low friction mechanism allows for consistent,
- repeatable gripping forces Shielded with purge port

Preferred Market:
 Global

DPG Series DIRECTCONNECT. **Modular Gripper**

- Multiple DIRECTCONNECT[™] mounting locations Multiple air port locations
- · Spring assisted design for failsafe operation or increased grip force
- · Shielded design repels contaminates
- · Synchronized and non-synchronized versions

Preferred Market:
 Global



DPDS & DPDL DIRECTCONNECT Modular Gripper

- Multiple DIRECTCONNECT[™] mounting locations
- Multiple air port locations
- Multiple strokes per size
- Front-to-back thru-body mounting
- Extended strokes (DPDL)
- · Purge/scavenge ports for harsh environments Optional corrosion resistant hardware, high temperature seals, and sealed jaw boot (DPDL)

Preferred Market:
 Global



Long Stroke Gripper

- · For use in confined spaces, combining long strokes with the high gripping force provided by two simultaneously acting pistons.
- Offers wide range of options and accessories (safety springs, in-line jaws, magneto resistive or inductive sensors).
- · Enclosed, shielded design repels chips and other particulate
- from internal drive mechanism

Preferred Market:
Global



See **1.134**



See **1.158**



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See **1.74**

See **1.58**

Products Overview

See **1.170**

See **1.176**

See **1.186**

RP Series Miniature Double Wedge Gripper

- Compact size, high gripping force, and extended jaw design facilitates finger attachment for smaller parts.
 High grip force to weight ratio make these grippers very
- popular on small robots. · Miniature size allows banks of grippers to be mounted in
- close proximity for multiple part picking and placing. • Internally sealed for use in hostile environments

Preferred Market:
 Global

RP Series Double Wedge Gripper

- Patented "Double Wedge Design" for extreme high grip force to size ratio
- · Internally sealed for use in hostile environments
- · Superior accuracy and repeatability
- Made from 7075-T6 aircraft quality aluminum hardcoat anodized to RC60 with Teflon® impregnation
- · Highest grip force to weight/size ratio in the industry

Preferred Market:
Global

GC Series Precision Parallel Gripper

- Precision operation
- Spring assist
 Grippers are fitted with 2 sensor holders (sensor available separately)
- Side or rear airports
- Optional 3rd sensor for part sensing, Viton[®] seals for high temperature applications, and encoder available

Preferred Market:
 Global

DPW Series DIRECTCONNECT

Wide Body Gripper

- Features our DIRECTCONNECT[®] mounting pattern
- · Excellent jaw support through the full body of the gripper
- Highly configurable gripper featuring multiple options and accessories
- Synchronized and non-synchronized versions available · Each gripper is offered in 2 different strokes

Preferred Market:
 Global

RPW Series Large Format Wide Body Gripper

- · Excellent jaw support through the full body of the gripper
- High gripping forces utilizing two opposing pistons
- · Synchronized and non-synchronized versions available
- · Superior accuracy and repeatability · Sealed design for harsh environments
- Preferred Market:
 Global





See **1.214**

RPR Gladiator Heavy Duty Parallel Gripper Gripper • Wide body, long stroke design

- · Designed for maching and foundry applications
- Rigid design and full body support of
- jaws allows for longer finger lengths • High temperature design available

Preferred Market: A NA + SA

See **1.222**

B-Series Industrial Grippers

- · For large and wide parts in machining and foundry applications
- · Heavy duty, rugged designs



RTH Series Three Jaw Centering Gripper

- Shielded design (DTH) deflects chips and other particulate away from the internal components Large surface area of the jaws allows for use
- of long fingers

Preferred Market:
Global

3P Series Precision Three Jaw Parallel Gripper

- Precision operation
- Cylindrical design
- · Optional springs for failsafe operation or for increased gripforces
- · Side or rear airports
- Tandem piston for double grip force
- Optional Protective Boot for harsh environments • All gripper sizes are available in 2 strokes sizes

Preferred Market: ■ EU ◆ SA

PPC Series Through Hole Gripper

- Unique through hole design
- 3 jaw concentric parallel gripper
 Shielded design protects internal components
- for increased life in harsh environments
- Optional safety springs, extended strokes, sensors, and high temperature seals

Preferred Market:
Global



NEW

See **1.230**

See 252



See **1.268**

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· Extremely high grip forces and moment loads

Preferred Market: A NA





NEW





Destaco-Robohand Parallel Gripper Product Selector

Model #	Two Jaws Three Jaws	0 - 0.25 ln. [0 - 6.3mm] 0.25 - 0.50 in. [6.3 - 12.7mm] 0.55 - 0.50 in. [12.7 - 19.1mm] 0.55 - 100 in. [19.1 - 25.4mm] 1.00 - 1.25 in. [25.4 - 31.8mm] 1.20 - 1.25 in. [31.8 - 34.18mm] 1.20 - 1.25 in. [31.9 - 44.5mm] 2.20 - 2.26 in. [44.5 - 60.8mm] 2.26 - 2.00 in. [44.5 - 60.8mm] 2.26 - 2.20 in. [57.1 - 63.5mm] 2.26 - 2.20 in. [63.5 - 69.8mm] 3.00+ [76.2mm+] 3.00+ [76.2mm+]	1 - 10 lbs. [0.45 - 45N] 1 - 25 lbs. [0.45 - 45N] 2 - 50 lbs. [111 - 22N] 2 - 50 lbs. [111 - 22N] 2 - 100 lbs. [222 - 445N] 100 - 500 lbs. [2225 - 13350N]	0 - 2 lin, [0 - 50.8mm] 2 - 4 lin, [50.8 - 102mm] 2 - 4 lin, [50.8 - 102mm] 2 - 4 lin, [50.8 - 102mm] 1 - 102mm] 2 - 4 lin, [25.4 - 305mm] 2 - 14lin, [305 - 355mm] 2 - 14lin, [305 - 355mm] 1 - 15 - 14lin, [305 - 406mm] 18 - 20 lin, [457 - 508mm] 2 0 lin, [457 - 508mm]	0.05 - 0.1 sec. voita - 0.5 sec. voita - 0.75 sec. 0.75 - 1 sec.	5 - 100 psi (0.3 - 7 bar) 20 - 100 psi (0.3 - 7 bar) 20 - 100 psi (1.5 - 7 bar) 40 - 100 psi (3.5 - 7 bar) 50 - 100 psi (3.5 - 7 bar)	24VDC Electric Actuation	Clean Room Environment Normal Environment HarstvDirty Environment	Failsafe Operation	Inductive Sensors Magneto Resistive Sensors	Double Acting Cylinder Single Acting/Spring Return Double Acting/Spring Assist	Non-Synchronous Option
DPE ELECTRIC	GRIPPER		_				•		•			
RPE ELECTRIC	GRIPPER					_					-	÷
RPE-100 RPE-101	÷		1				•	••	•	•		
RDH/DDH SHIE RDH-1	LDED 2 J	AW DESIGN			8	•		• •	•	• •	• • •	
RDH-1-L RDH-2	•					•	_	••	•	••	•••	_
RDH-2-L	•					•		• •	•	• •	• • •	
RDH-3 RDH-3-L	•					•		•••	•	•••	•••	
RDH-4 RDH-4-L	•					•	_	••	•	••	•••	
RDH-5	•					•		••	٠	• •	• • •	
RDH-5-L RDH-6	•					•		•••	•	•••	•••	
RDH-6-L RDH-7	•		+			•		••	•	•••	•••	
RDH-7-L	•					•		••	•	••	• • •	
RDH-8-L	•				1.3 sec.	•		•••	•	•••	•••	
2P PRECISION 6002P	DESIGN					•		••	•	•	• •	
6002P-C 8002P	•					•		••	•	•	••	
8002P-C	•					••		••	٠	•	• •	
11002P 11002P-C	•					••		•••	•	•	••	
14002P 14002P-C	•					••		••	•	•	••	
16502P	•					••		••	•	•	• •	
16502P-C 16502PGR	•				-	•••		••	•	•	••	
CP SQUARE DI CP-1	SIGN •				1			• •	•	• •	• •	
CP-1-C	•		-		<u>.</u>			••	•	••	••	
CP-2-C	•							• •	•	• •	• •	
CP-3 CP-3-C	•							••	•	•••	••	
CP-4 CP-4-C	•							••	•	••	••	
CP-5	•				-			••	•	• •	• •	
CP-5-C CP-6	•							•••	•	•••	••	
CP-6-C DIRECTCONNE	• CT PRECI	SION "DVAL-V" DESIGN						• •	•	• •	• •	
DPP-10M-06	•					•		••	•	••	• • •	•
DPP-10M-12 DPP-14M-15	•					•		•••	•	•••	•••	•
DPP-14M-25 DPP-20M-25	•					•		••	•	•••	•••	•
DPP-20M-38	•					•		••	•	• •	• • •	٠
RPL-1	•					•		•		•	•	٠
RPL-2 RPL-3	•					•		•		•	•	•
RPL-4 LOW PROFILE	• FLEAN BO	OM DESIGN				•		•		•	•	٠
RPLC-1	•					•		• • •		•	•	٠
RPLC-2 RPLC-3	•				_	•		•••		•	•	•
RPLC-4 MICRO_DESIGN	•					•		• • •		•	•	٠
RPM-1	•					•		•			•	
KPM-2 RPM-3	•					•		•			•	
MICRO CLEAN RPMC-1	ROOM DI	SIGN				•					•	
RPMC-2	•					•		• • •			•	
nr1116-3	•								Conti	uad ar	novt nort	
									JUIIII	ucu 011	пелі раде	

PARALLEL Grippers

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Destaco-Robohand Parallel Gripper Product Selector

	Two Jaws Three Jaws	0 - 0.25 in. [0 - 6.3mm] 0.25 - 0.50 in. [6.3 - 12.7mm] 0.25 - 0.50 in. [12.7 - 19.1mm] 0.75 - 1100 in. [19.1 - 5.4mm] 1.00 - 1.26 in. [25.4 - 31.8mm] 1.26 - 1.50 in. [381 - 44.5mm] 1.56 - 1.50 in. [381 - 44.5mm] 2.50 - 2.25 in. [50.8 - 57.1mm] 2.50 - 2.25 in. [50.8 - 57.1mm] 2.50 - 2.25 in. [50.8 - 57.1mm] 2.50 - 2.25 in. [63.5 - 69.8mm] 2.56 - 2.00 in. [971 - 63.5mm] 2.56 - 2.00 in. [971 - 63.5mm] 2.56 - 2.55 in. [63.5 - 69.8mm] 2.56 - 2.55 in. [63.5 - 69.8mm] 2.56 - 2.50 in. [981 - 76.2mm] 3.00+ [76.2mm+]	1 - 10 lbs. [0,45 - 454] 10 - 25 lbs. [45 - 111N] 50 - 50 lbs. [171 - 2234] 50 - 100 lbs. [222 - 445N] 100 - 500 lbs. [225 - 13350N] 500 - 3000 lbs. [225 - 13350N]	0 - 2 In. [0 - 50.8mm] 2 - 4 In. [50.8 - 102mm] 4 - 6 In. [102 - 152mm] 6 - 8 In. [152 - 203mm] 8 - 10 in. [203 - 554mm] 11 - 12 In. [205 - 554mm] 12 - 14 In. [305 - 556mm] 14 - 16 In. [355 - 406mm] 14 - 16 In. [355 - 406mm] 18 - 20 In. [457 - 508mm] 20 In. + [508mm+]	0.05 - 0.1 sec. 0.1 - 0.5 sec. 10.5 - 0.75 sec. 0.75 - 1 sec.	5 - 100 psi [0.3 - 7 bar] 20 - 100 psi [1.5 - 7 bar] 40 - 100 psi [3.5 - 7 bar] 50 - 100 psi [3.5 - 7 bar] 70 - 150 psi [5 - 7 bar]	Clean Room Environment Normal Environment Harsh/Dirty Environment	Failsafe Operation	Inductive Sensors Magneto Resistive Sensors	Double Acting Cylinder Single Acting/Spring Return Double Acting/Spring Assist Non-Synchronous Option
Model #		Stroke Range	Force Range	@ 60 PSI [4 bar]	Time	Pressure	ment			
DIRECTCONNEC DPG-10-1	T GIB DE	SIGN				•	••	•	• •	• • • •
DPG-10-2 DPG-10-3	•					•	••	•	•••	• • • •
DPG-10-4	•					•	• •	•	• •	• • • •
DPDS-047	•					•	••		•	•
DPDS-056 DPDS-088	•				-	•	•••		•	•
DPDS-125 DPDL-047	•					•	•••		•	•
DPDL-056 DPDL-088	•					•	• • •		•	•
DPDL-125	етноме	STROKE DESIGN				•	• • •		•	•
DPL-2520	•					•	• •	•	• •	• • • •
DPL-2535 DPL-3230	•					•	••	•	•••	••••
DPL-3250 DPL-4040	•					•	••	•	•••	• • • •
DPL-4070 DOUBLE WEDO	HE DESIG					•	• •	•	• •	•••
RP-5 RP-10	•					•	•	٠	•	• • •
RP-11	•				_	•	••		•	•
RP-15	•				_	•	••		•	•
RP-17 RP-18	•				-	•	•••		•	•
RP-19 PRECISION DE	• SIGN					•	••		•	•
DGC-25 DGC-45	•				1	•	••	•	•	•
DGC-65	•					•	••	•	•	•
GC-105	•					•	••	•	•	•
DIRECTCONNE DPW-250M-1	•	BODY DESIGN				•	••		• •	• •
DPW-250M-2 DPW-375M-1	•					•	••		•••	• •
DPW-375M-2 DPW-500M-1	•					•	••		•••	• •
DPW-500M-2	T WINE R					•	••		• •	• •
RPW-625-1	•					•	••		•	• •
RPW-625-2 RPW-750	·					•	••		•	• •
GLADIATOR GR RPR-57-200	RIPPER •					•	• •		•	• •
"B-SERIES" IN BPW-1600	DUSTRIA	L GRIPPERS	•							
BPW-2000	•					•	• •	•	•	• • • •
BRP-20 BRP-21	•					•	•••	•	•	•••
BRP-21-D BPG-160	•					•	••	•	•	•••
RTH/DTH SHIE RTH/DTH-1	LDED 3 J/	AW DESIGN				•	• •			
RTH/DTH-1-L	•					•	••	•	••	•••
RTH/DTH-2-L	•					•	••	•	••	•••
RTH/DTH-3 RTH/DTH-3-L	•					•	•••	•	•••	•••
RTH/DTH-4 RTH/DTH-4-L	•					•	••	•	• •	•••
RTH/DTH-5 RTH/DTH-5-L	•					•	••	•	• •	•••
RTH/DTH-6	•				=	•	••	•	••	•••
RTH/DTH-7	•					•	• •	•	••	•••
RTH/DTH-7-L RTH/DTH-8	•					•	•••	•	•••	•••
RTH/DTH-8-L	•					•	• • Continu	• ied o	••	•••

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Destaco-Robohand Parallel Gripper Product Selector

	Two Jaws Three Jaws	0 - 0.25 in [0 - 6.3mm] 0.25 - 0.50 in [6.3 - 12.7mm] 0.26 - 0.51 (127 - 19.1mm] 0.75 - 100 in [191 - 25.4mm] 1.00 - 125 in [26.4 - 13.8mm] 1.00 - 126 in [31.8 - 34.4mm] 1.25 - 1.50 in [31.8 - 34.4mm] 1.75 - 200 in [44.5 - 60.8mm] 2.76 - 200 in [67.1 - 63.5mm] 2.26 - 2.76 in [63.5 - 69.8mm] 3.304 - [76.2mm+]	1 - 10 lbs. [0.45 - 45N] 10 - 25 lbs. [45 - 111N] 25 - 50 lbs. [111 - 223N] 50 - 100 lbs. [223 - 445N] 100 - 500 lbs. [2225 - 13350N] 500 - 3000 lbs. [2225 - 13350N]	0 - 2 in. [0 - 50.8mm] 2 - 4 in. [50.8 - 102mm] 4 - 6 in. [102 - 152mm] 6 - 8 in. [152 - 203mm] 8 - 10 in. [203 - 254mm] 10 - 12 in. [254 - 305mm] 12 - 14 in. [305 - 356mm] 14 - 16 in. [365 - 406mm] 16 - 18 in. [405 - 457mm] 18 - 20 in. [508mm+] 20 in+ [508mm+]	0.05 - 0.1 sec. 0.1 - 0.5 sec. 0.5 - 0.75 sec. 0.75 - 1 sec.	5 - 100 psi [0.3 - 7 bar] 20 - 100 psi [1.5 - 7 bar] 40 - 100 psi [3.5 - 7 bar] 50 - 100 psi [3.5 - 7 bar] 70 - 150 psi [5 - 7 bar]	Clean Room Environment Normal Environment Harsh/Dirty Environment	Failsafe Operation	Inductive Sensors Magneto Resistive Sensors	Double Acting Cylinder Single Acting/Spring Return Double Acting/Spring Assist Non-Synchronous Option
Model #		Stroke Bange	Total Grip Force Bange	Maximum Finger Length	Actuation Time	Operating	Environ-			
	DECION	ou oko Haligo	roice naige		TITIC	ricodure	mont			
6003P	•					•	• •	•	• •	• • •
6003P-C	•					•	• •	•	• •	• • •
8003P	•					• •	• •	•	• •	• • •
8003P-C	•					• •	• •	٠	• •	• • •
11003P	•					• •	• •	•	• •	• • •
11003P-C	•					• •	• •	٠	• •	• • •
14003P	•					• •	• •	•	• •	• • •
14003P-C	•					• •	• •	٠	• •	• • •
16503P	•					• •	• •	•	• •	• • •
16503P-C	•					• •	• •	•	• •	• • •
PPC THROUGH	HOLE D	3SIGN							_	
PPC-12	•					•	• •	•	• •	•••
PPC-12-C	•					•	• •	•	• •	•••
PPC-25	•					•	• •	•	••	•••
PPC-25-C	•					•	• •	•	••	•••
PPC-34	•					•	••	•	••	•••
PPC-34-C	•					•	• •	•	••	• • •

1.8

DPE Parallel Gripper-Electric Gripper Series

Electrically Actuated

24 VDC, 4-wire input: power, ground, open & closed signals. 100% duty cycle for high throughput.

• "Light Switch" Simplicity

Plug and play. No programming, tuning or adjusting required. As easy as a pneumatic gripper to control and operate.

• Energy Efficient

Only 3W required. Can be driven directly by most PLC's without a separate power supply. Can be battery driven for remote applications.

• High Cycle Life

20+ million cycles with zero maintenance! High reliability eliminates down time. Lowest cost of ownership of any gripper, pneumatic or electric.

• Built-in Electronics

All electronics are sealed within the gripper. No external control board needed. 4-pin/wire control cable sold separately.

Patent Pending.

Mounting Information:

Gripper can be mounted and operated in any orientation





Long Stroke, Fast Actuation 25mm stroke for picking multiple sized parts.

Full actuation in 0.25 second. Pick up to 150 parts per minute (with reduced stroke).

• Failsafe operation

In case of a power loss, the jaws will not separate but grip force will be diminished. Finger design should include features other than just friction to retain part for critical applications.

Technical Specifications:

Product Specifications

Voltage	24 VDC
Power Max.	40 W
Operating Temperature	5° / 50° C (40° / 120°F)
Protection Class	IP54 Ó
Clean Room	100
Clean Room with Scavenge Port*	10
*Contact Tech Support.	

Maintenance Specifications Field Repairable

Yes

Application Restrictions

- Timing, power and load beyond specifications
- Suitable for external gripping only



Operating Principle



- Apply +24 VDC from the PLC to the gripper "Close" wire.
- The motor rotates a planetary gear reduction box that is connected to the drive pinion by a coupling
- The pinion drives the integral jaw racks causing the jaws to close synchronously
 Power is maintained to the closed signal to continue gripping force throughout the grip cycle.
- To open, remove signal to "Close" wire and apply +24 VDC from the PLC to the gripper "Open" wire
- Design is suitable for internal or external gripping

Patent Pending



PARALLEL GRIPPER DPE-200-25 **E-GRIPPER SERIES**





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DPE SERIES

1.10



Installation and Operation:

- 1. Mount fingers (customer supplied) to gripper jaws using dowel pins and threaded fasteners. See dimensional drawing for hole sizes. Use Loctite® 242 threadlocker or equivalent.
- 2. Mount gripper using dowel pins and threaded fasteners. Gripper can be mounted and operated in any orientation. See dimensional drawing for mounting hole pattern and sizes. Use Loctite® 242 threadlocker or equivalent.
- To operate the DPE gripper, follow the instructions below:
 Apply +24VDC to pin 1 (brown) and Ground to pin 3 (blue) to turn on the gripper. To open the fingers, apply +24VDC to pin 2 (white). To close the fingers, remove +24VDC from pin 2, and apply +24VDC to pin 4 (black). +24VDC signal must remain present on the open / close line to maintain the force output. The gripper will do nothing if a +24VDC signal is present on the open and close lines at the same time.

WARNING:

- Operating gripper outside of power voltages and can cause damage and void warranty
- · Disconnect power from gripper before performing maintenance or making adjustments.

ELECTRICAL INTERFACE



PIN OUT (LOOKING INTO HEADER CONNECTOR ON GRIPPER)

1 BROWN (+ 24 VDC)

2 WHITE 3 BLUE (OPEN GRIPPER) +24 VDC = ACTIVE (GROUND) (CLOSE GRIPPER) +24 VDC = ACTIVE 4 BLACK

CABLE # CABL-046



DPE SERIES

DPE Series Exploded View





Assembly Procedure

- 1) Clean all make details free of dirt, oil and other contaminants.
- 2) Insert # 32 motor into the # 1 body, line up the motor holes and assemble motor to the body by using # 18 screws. Make sure that the motor wires are carefully routed to the top for it's connection to the motor control board.
- 3) Assemble # 25 set screws one of the # 7 coupling hubs, but not all the way in. Assemble the coupling to the motor shaft, with flat on the motor shaft facing one of the set screws and adjust the inside face of the coupling, flat with end face of the motor shaft. Tighten the set screw on the motor shaft thru the acccess hole at set screw # 30 location.
- 4) Assemble the # 10 coupling insert into the # 7 hub, as asssembled to the motor shaft, as above.
- 5) Assemble # 8 drive pinion with it's shaft all the way into the second # 7 coupling hub and tighten the set screws. Assemble # 16 bearing and # 19 dowel pin into the drive pinion. Now install this assembly hub / insert assembly installed earlier to the motor shaft.
- 7) Assemble # 15 magnets into # 6 jaws, using lok-tite as recommended.

NRECTONNE

- 8) Lubricate the pinion, the bearing, the jaws and inside surfaces of jaw-ways with lubricant as recommended.
- 9) Install the jaws into the body, meshed with the pinion and symmetrically positioned w.r.t the pinion.

10) Install # 5 stop and # 22 dowel pins into the jaws.

- 11) Assemble # 2 cover to the body, with dowel pins # 19 and # 29 aligned to the corrosponding holes in the cover. Install fasteners # 17 to secure the cover to the body.
- 12) Install / connect the motor cable connector the motor control board. Use # 21 & # 24 fasteners and install the motor control board to the body. Note: Remove the hex nut supplied with the connector on the motor control board. This hex nut will be re-installed after # 4 cover is installed.
- 13) Install # 4 cover to the body with # 29 gasket and # 21 screws as shown.
- 14) Installed the previously removed hex nut back to the connector. Caution: Only snug tighten this hex nut.
- 15) Install # 3 cap with 0 ring and snap ring, as shown.
- 16) Install tags and labels as shown.

m	Qty	Name
	1	Body
	1	Bottom Plate
	1	Сар
	1	Cover

01

02	1	Bottom Plate
03	1	Сар
04	1	Cover
05	2	Bumper
06	2	Jaw
07	2	Coupling Pin
08	1	Drive Pin
09	1	Motor Control Board
10	1	Coupling Insert
11	2	Tag-Destaco-Robohand
12	1	Tag-Electric Pin Out
13	1	Tag-Production
14	1	Tag-VBL Collar
15	2	Magnet
16	1	Bearing
17	8	SHCS, M1.6*5mm, Alloy
18	3	SHCS, M2.5*5mm, Alloy
19	1	Dowel Pin: 1/8 Dia X 3/8
20	2	Dowel Pin: 2mm
		dia*6mm lg
21	8	Screw, Fillister HD,
		M2x6mm
22	2	Dowel Pin: 3mm
		dia*6mm lg.
23	0	Jam Nut-Ref Only (Part Of
		Motor Control Board)
24	8	Washer
25	2	Set Screw
26	0	0-Ring - Ref Only (Comes
		With Connector)
27	1	0-Ring
28	2	Set Screw
29	1	0-Ring
30	1	Set Screw
31	4	0-Ring, Buna, 70d,
		0.026 CS, .097id
32	1	Gear Motor
33	1	Ret. Ring
-		

NOTE: Contact the DE-STA-CO Customer Service for a complete spare parts list with order numbers and prices.

SK		KRYTOX	0	G	GLUE	ightarrow ightarrow
Seal Kit	Thread	Krytox™	Lightweight	Teflon [™] Based	Super	Third Angle
Items	Locker	Lubricant	Machine Oil	Grease	Bonder	Projection

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SK

Seal Kit Items THREAD >

Thread Locker



DPE Series Assembled View

ltem	Qty	Name
01	1	Body
02	2	Jaw
03	1	Motor/Gear ASM
04	1	Coupling Asm
05	1	Pinion
06	1	Bearing
07	1	Motor Control Board
84	1	End Cap

NOTE: Contact the DE-STA-CO Customer Service for a complete spare parts list with order numbers and prices.



1.13

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Lightweight Machine Oil

RYTOX

Krytox™ Lubricant G

Teflon™ Based Grease

1.1

RPE Parallel Gripper-Electric Gripper Series

- Failsafe Operation: Spring closed feature allows for full grip force during power off conditions.
- Electrically Actuated: Requires simple 24VDC pulsed signal. No programmable or expensive controller required.
- **Sensing:** Adjustable inductive proximity sensors available.
- Low System Impact: Easily integrated into current engineering and manufacturing processes.
- Miniature size:

Compact design allows for gripping small parts in small spaces.

Patent Pending. The RPE is CE marked.

Mounting Information:

Gripper can be mounted and operated in any orientation

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Body mounts with screws and locates with slip fit dowel pins for accuracy Fingers attach to jaws with screws and locate with dowel pins

Precision applications:

Preloaded "Dual-V" roller bearings eliminate side play for excellent part position repeatability.

Delicate part handling:

Low friction mechanism allows for repeatable gripping forces for holding delicate parts. Grip force is constant throughout stroke.

• Clean room suitable:

A corrosion resistant shield protects the drive and bearing mechanism. All internal components are lubricated with Krytox[™] grease.

Harsh environments:

All moving components are located within the corrosion resistant cover.

Technical Specifications:

Product Specifications

Voltage	24 VDC
Power Max.	40 W
Operating Temperature	5° / 50° C (40° / 120°F)
Protection Class	IP54
Clean Room	100
Clean Room with Scavenge Port*	10
*Contact Tech Support.	

Maintenance Specifications Field Repairable

Yes

Application Restrictions

- Timing, power and load beyond specifications
- Suitable for external gripping only

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RPE SERIES

1.15

- To open the gripper, a short power pulse to the solenoid retracts the plunger to the latched position, which opens the jaws. No power is required to maintain the open position.
- Suitable for external gripping only.

U.S. Patent # 5,529,359. Other Patents Pending.

PARALLEL GRIPPER RPE-100M/-101M **E-GRIPPER SERIES**

10.6 lbf-in [1.2 Nm]

6.6 lbf-in [0.75 Nm]

3.5 lbf-in [0.4 Nm]

9.7 lbf-in [1.1 Nm]

Maximum Moment My

Maximum Moment Mz

⁺Capacities are per set of jaws and are not simultaneous

RPE SERIES

1.16





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CUSTOMER SUPPLIED FINGERS WITH TARGET



PARALLEL GRIPPER RPE-100M/-101M **E-GRIPPER SERIES**

1.17

Installation and Operation:

- 1. Mount fingers (customer supplied) to gripper jaws using dowel pins and threaded fasteners. See dimensional drawing for hole sizes. Use Loctite® 242 threadlocker or equivalent.
- 2. Mount gripper using dowel pins and threaded fasteners. Gripper can be mounted and operated in any orientation. See dimensional drawing for mounting hole pattern and sizes. Use Loctite® 242 threadlocker or equivalent.

3. The following instructions apply to standard operation and require a 24VDC power supply: To open gripper, connect positive lead of power supply to Pin 1 of the connector and negative lead to Pin 3 of the connector. See below for pin orientation. Pulse for 50msec maximum as shown in Timing Diagram. After 50 msec pulse, allow 450msec minimum dwell time. To close gripper, connect positive lead of power supply to Pin 3 of connector and negative lead to Pin 1 of connector. Pulse for 50msec maximum as shown in Timing Diagram. After 50msec pulse, allow 450msec minimum dwell time.

WARNING:

- Operating gripper outside of power voltages and pulse times will cause damage and void warranty
- Do not insert any foreign objects (tools, body parts, etc) between gripper fingers when power is applied.
- Disconnect power from gripper before performing maintenance or making adjustments.
- Do not apply power to gripper for more than 100msec maximum. Observe 10% duty cycle at all times.





PIN ORIENTATION

TIMING DIAGRAM

NOTE: The RPE is CE marked.





Item	Qty	Name
01	1	Body
02	2	Jaw
03	1	Housing
04	1	Сар
05	1	Wedge
06	4	Way
07	2	Shield
08	1	Clevis Pin
09	1	Spacer
10	1	Solenoid
11	4	Kit, Roller Bearing
		and Cage
12	3	Preload Screw
13	6	Set Screw-Way Locating
14	4	BHCS-Shield
		Mounting Screw
15	4	BHCS Solenoid
		Mounting Screw
16	8	FHCS-Housing
		Mounting Screw
17	2	Retaining Ring
18	2	Dowel Pin

NOTE: Contact the DE-STA-CO Customer Service for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate #1 body, #5 wedge, and #11 bearings using Krytox[™] grease.
- 2) Insert #2 jaws and #5 wedge into body.
 3) Insert #6 way and #11 bearings into each end of the body.
- 4) Adjust preload by adjusting #12 preload screws. (See below for procedure)
- 5) Install #10 solenoid plunger with #8 clevis pin and #17 retaining rings.
- 6) Fasten #10 solenoid to housing. Do not tighten yet, allowing the solenoid to freely move within slots.
- Slide #9 spacer and #10 solenoid spring onto plunger.
- 8) Fasten #1 body into #3 housing. Completely fasten the two screws that are located on the same side as the #10 solenoid 3-pin connector then fasten the two remaining screws on the opposite side.
- 9) Fully open jaws and tighten #15 screws securely.
- 10) Install #7 shields to gripper.11) Fasten #10 3-pin connector.
- 12) Fasten #4 cap into housing. Completely fasten the two screws that are located on the same side as the #10 solenoid 3-pin connector then fasten the two remaining screws on the opposite side.

Preload Adjustment Procedure

- Install preload screws (12) with Loctite® 7649 primer and Loctite® 242 thread locker on threads.
- Tighten until there is no side play in the jaws.
- Cycle gripper (w/finger assembly)
- 4) Recheck for play in jaws & tighten or loosen as needed.



For more information call us at: 1.888.DESTACO or 248.836.6700 Fax: 248.836.6901 Visit us on the Internet at: www.destaco.com



RPE Series As	sembled View
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1.19

item	Qty	Name
01	1	Body
02	2	Jaw
03	1	Housing
04	1	Сар
05	1	Wedge
06	4	Way
07	2	Shield
08	1	Clevis Pin
09	1	Spacer
10	1	Solenoid
11	4	Kit, Roller Bearing
		and Cage

NOTE: Contact the DE-STA-CO Customer Service for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Flange Mounting Plate, Gang Mounting and more...



For more information call us at: 1.888.DESTACO or 248.836.6700 Fax: 248.836.6901 Visit us on the Internet at: www.destaco.com www.comoso.com

ROH SERIES

Parallel Grippers -**2-Jaw Paral** Series

Machine applications:

The 2 symmetric jaws and excellent repeatability allow for precise handling of various parts.

Harsh environments:

Shielded design repels chips and other particulate from internal drive mechanism.

Compact, robust and powerful gripper: This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Different strokes: All gripper sizes are available in 2 strokes sizes.

For long fingers applications:

The large surface area of the jaws, coupled with the encapsulated bottom case design allows for long fingers applications.

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Multi-purpose gripper: A wide range of options and accessories (extended stroke, safety springs for internal or external gripping, magneto resistive or inductive sensors) allow these grippers to be used in a wide number of applications.

Mounting Information:

Grippers can be mounted & operated in any orientation

Gripper is located using 2 dowel pins and assembled from the top with 4 screws.





Gripper can also be assembled

from the bottom with 4 through

Gripper is protected from debris when operated upside down.

Gripper can be operated utilizing top manifold air ports



Fingers are located on jaws with 2 dowel sleeves (provided) and assembled with 2 screws.

Technical Specifications:

Pneumatic Specifications	Imperial	Metric
vithout Springs	30-100 psi	2-7 bar
Cylinder Type	Double /	Acting
	or Double Acting	Spring Assist
Dynamic Seals	Internally Lubri	cated Buna-N
Valve Required to Operate:		
Double Acting Single Acting (-C or -O On	4-way, 2-	position
	uon) 3-way, 2 -	position
Air Quality Requirements		
Air Filtration	40 Micro	n or Better
Air Humidity	Low Moisture	Content (drv)
Temperature Operating Ra	nge	2E° 00° C
Viton [®] Seals (Optional)	-30 ~160 F -20°~300° F	-30°~150° C
Maintenance Specification	1S [†]	
Normal Application	5 million	cycles
w/ Preventative Maintenan	ce 10+ milli	on cycles*
Field Repairable	Yes	S
Seal Repair Kits Available	Yes	S
*Addition of lubrication will greatly increase	service life	

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PARALLEL GRIPPER RDH-1M 2-JAW PARALLEL SERIES





1.22



PARALLEL GRIPPER RDH-1M 2-JAW PARALLEL SERIES

RDH-1M Loading Information



Maximum Tensile T	134 lbs. [594 N]	17 lbs. [74 N]	
Maximum Compressive C	175 lbs. [779 N]	17 lbs. [74 N]	
Maximum Moment M_X	159 inIbs. [18 Nm]	18 inIbs. [2 Nm]	
Maximum Moment My	204 inIbs. [23 Nm]	18 inIbs. [2 Nm]	
Maximum Moment M_X	124 inIbs. [14 Nm]	18 inIbs. [2 Nm]	
Capacities are per set of jaws and are not simultaneous			

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	125 lbs.	555 N
Without Spring Assist -L	81 lbs.	361 N
With Spring Assist	156 lbs.	693 N
With Spring Assist -L	102 lbs.	452 N
Total Stroke:		
Standard	0.16 in.	4 mm
Extended -L	0.32 in.	8 mm
Weight (RDH)	0.4/0.5 lbs.	0.19/0.21 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

Accessory Mounting Technical Data



RDH-1M-L Loading Information



		∕ My
Loading Capacity ⁺	Static	Dynamic
Maximum Tensile T	121 lbs. [540 N]	11 lbs. [48 N]
Maximum Compressive C	159 lbs. [708 N]	11 lbs. [48 N]
Maximum Moment M _X	142 inlbs. [16 Nm]	9 inIbs. [1 Nm]
Maximum Moment My	168 inlbs. [19 Nm]	9 inIbs. [1 Nm]
Maximum Moment M _X	106 inlbs. [12 Nm]	9 inIbs. [1 Nm]
*Capacities are per set of jaws and are not simu	Itaneous	

Specifications (cont.)

Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	0.9 in ² .	5.8 cm ²
Displacement	0.31 in ³ .	5 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Actuation (open/close)	0.06 sec.	/0.06 sec.
Accuracy	±0.0016 in.	±0.04 mm
Repeatability	±0.001 in.	±0.02 mm
Valve required to actuate single acting	3-way, 2	2-position
Valve required to actuate double acting	4-way, 2	2-position

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PARALLEL GRIPPER RDH-2M 2-JAW PARALLEL SERIES





1.24



RDH-2M Loading Information



Loading Capacity	Static	Dynamic	
Maximum Tensile T	191 lbs. [849 N]	18 lbs. [81 N]	
Maximum Compressive C	248 lbs. [1103 N]	18 lbs. [81 N]	
Maximum Moment Mx	319 inIbs. [36 Nm]	27 inIbs. [3 Nm]	
Maximum Moment My	451 inIbs. [51 Nm]	35 inIbs. [4 Nm]	
Maximum Moment Mx	283 inlbs. [32 Nm]	35 inIbs. [4 Nm]	
Canacities are nor set of jaws and are not simultaneous			

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	170 lbs.	754 N
Without Spring Assist -L	111 lbs.	494 N
With Spring Assist	226 lbs.	1006 N
With Spring Assist -L	149 lbs.	661 N
Total Stroke:		
Standard	0.24 in.	6 mm
Extended -L	0.47 in.	12 mm
Weight (RDH)	0.86/0.93 lbs.	0.39/0.42 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	65-100 psi	4.5-7 Bar

Accessory Mounting Technical Data



Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- · Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Available with 2M Quick Disconnect mating cable
- (order separately)



2-JAW PARALLEL SERIES

PARALLEL GRIPPER RDH-2M

RDH-2M-L Loading Information



Loading Capacity[†]

Loading Capacity ⁺	Static	Dynamic
Maximum Tensile T	172 lbs. [764 N]	12 lbs. [53 N]
Maximum Compressive C	223 lbs. [993 N]	12 lbs. [53 N]
Maximum Moment Mx	283 inlbs. [32 Nm]	18 inIbs. [2 Nm]
Maximum Moment My	363 inIbs. [41 Nm]	18 inIbs. [2 Nm]
Maximum Moment Mx	230 inlbs. [26 Nm]	18 inIbs. [2 Nm]
*Capacities are per set of jaws and are not sim	ultaneous	

PLUMBING FITTING

PLFT-037

Specifications (cont.)

Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	1.24 in ² .	8 cm ²
Displacement	0.63 in ³ .	10.3 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Actuation (open/close)	0.07 sec./0	.07 sec.
Accuracy	±0.0016 in.	±0.04 mm
Repeatability	±0.001 in.	±0.02 mm
Valve required to actuate single acting	3-way, 2-p	osition
Valve required to actuate double acting	4-way, 2-p	osition

PARALLEL GRIPPER RDH-3M 2-JAW PARALLEL SERIES





Ex: RDH-3M Parallel Gripper, Metric, 16mm Extended Stroke, Spring Closed, Viton® Seals

1.26



PARALLEL GRIPPER RDH-3M 2-JAW PARALLEL SERIES

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RDH-3M Loading Information



Louding oupdoily	Juno	Dynamic	
Maximum Tensile T	289 lbs. [1284 N]	44 lbs. [196 N]	
Maximum Compressive C	374 lbs. [1665 N]	44 lbs. [196 N]	
Maximum Moment Mx	513 inlbs. [58 Nm]	62 inIbs. [7 Nm]	
Maximum Moment My	735 inlbs. [83 Nm]	97 inIbs. [11 Nm]	
Maximum Moment Mx	478 in lbs. [54 Nm]	97 inlbs. [11 Nm]	
[†] Canacities are per set of jaws and are not simultaneous			

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	296 lbs.	1317 N
Without Spring Assist -L	192 lbs.	854 N
With Spring Assist	379 lbs.	1683 N
With Spring Assist -L	246 lbs.	1094 N
Total Stroke:		
Standard	0.31 in.	8 mm
Extended -L	0.63 in.	16 mm
Weight (RDH)	1.81/1.94 lbs.	0.82/0.88 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

Accessory Mounting Technical Data



Magneto Resistive Sensors

- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting kits required
- Simple adjustment with slotted screw driver
- Built in LED for ease of positioning and troubleshooting
- Available with 2M Quick Disconnect mating cable (order separately)



RDH-3M-L Loading Information



Loading Capacity[†]

Louding oupdoily	otado	Dynamio		
Maximum Tensile T	258 lbs. [1146 N]	29 lbs. [127 N]		
Maximum Compressive C	334 lbs. [1485 N]	29 lbs. [127 N]		
Maximum Moment Mx	460 in lbs. [52 Nm]	44 inIbs. [5 Nm]		
Maximum Moment My	584 in lbs. [66 Nm]	53 inIbs. [6 Nm]		
Maximum Moment Mx	381 inIbs. [43 Nm]	53 inIbs. [6 Nm]		
*Canacities are ner set of jaws and are not simultaneous				

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Specifications (cont.)

Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	2.14 in ² .	13.8 cm ²
Displacement	1.43 in ³ .	23.4 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Actuation (open/close)	0.08 sec./0.08 sec.	
Accuracy	±0.0016 in.	±0.04 mm
Repeatability	±0.001 in.	±0.02 mm
Valve required to actuate single acting	3-way, 2-position	
Valve required to actuate double acting	4-way, 2	2-position

PLUMBING FITTING PLFT-037 0.648 [16.46] 0.764 [19.41]

Plumbing Fittings

- Adjustable flow controls:
 Have thumb screw adjust with locking nut for adjusting actuation time
- Available for 6mm 0D tubingPlumbing fittings:
- For side air port location
 Top air port are plugged as standard

1.27

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

PARALLEL GRIPPER RDH-4M 2-JAW PARALLEL SERIES





Ex: RDH-4M Parallel Gripper, Metric, 20mm Extended Stroke, Spring Closed, Viton® Seals

1.28


2-JAW PARALLEL SERIES

Dynamic

RDH-4M Loading Information



Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	352 lbs. [1564 N]	58 lbs. [259 N]
Maximum Compressive C	465 lbs. [2070 N]	58 lbs. [259 N]
Maximum Moment Mx	673 inlbs. [76 Nm]	89 inIbs. [10 Nm]
Maximum Moment My	938 inIbs. [106 Nm]	124 inIbs. [14 Nm]
Maximum Moment Mx	620 inIbs. [70 Nm]	124 inIbs. [14 Nm]
*Capacities are per set of jaws and are not s	imultaneous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	490 lbs.	2177 N
Without Spring Assist -L	318 lbs.	1414 N
With Spring Assist	628 lbs.	2789 N
With Spring Assist -L	408 lbs.	1814 N
Total Stroke:		
Standard	0.39 in.	10 mm
Extended -L	0.79 in.	20 mm
Weight (RDH)	3.15/3.33 lbs.	1.43/1.51 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

Accessory Mounting Technical Data



RDH-4M-L Loading Information



Loading Capacity[†] Static

Maximum Tensile T	313 lbs. [1394 N]	38 lbs. [168 N]	
Maximum Compressive C	415 lbs. [1845 N]	38 lbs. [168 N]	
Maximum Moment M x	602 inlbs. [68 Nm]	53 inIbs. [6 Nm]	
Maximum Moment My	743 inlbs. [84 Nm]	71 inIbs. [8 Nm]	
Maximum Moment Mx	496 inlbs. [56 Nm]	71 inIbs. [8 Nm]	
*Capacities are per set of jaws and are not simultaneous			

8 in. Hg	20 mm Hg
30 psi	2.1 Bar
3.52 in ² .	22.7 cm ²
2.90 in ³ .	47.5 cm ³
-30°~180° F	-35°~80° C
0.08 sec.	/0.08 sec.
±0.0024 in.	±0.06 mm
±0.0012 in.	±0.03 mm
3-way, 2-position	
4-way, 2-position	
	8 in. Hg 30 psi 3.52 in ² . 2.90 in ³ . -30° ~180° F 0.08 sec. ±0.0024 in. ±0.0012 in. 3-way, 2 4-way, 2

PARALLEL GRIPPER RDH-4M

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SERIES

PARALLEL GRIPPER RDH-5M 2-JAW PARALLEL SERIES





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RDH-5M Loading Information



Loading Capacity	Static	Dynamic
Maximum Tensile T	493 lbs. [2192 N]	96 lbs. [428 N]
Maximum Compressive C	657 lbs. [2923 N]	96 lbs. [428 N]
Maximum Moment Mx	929 inIbs. [105 Nm]	142 inIbs. [16 Nm]
Maximum Moment My	1310 in lbs. [148 Nm]	195 inIbs. [22 Nm]
Maximum Moment Mx	859 inIbs. [97 Nm]	195 inIbs. [22 Nm]
Capacities are per set of jaws and are not simul	taneous	

pecifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	808 lbs.	3593 N
Without Spring Assist -L	525 lbs.	2333 N
With Spring Assist	1037 lbs.	4609 N
With Spring Assist -L	675 lbs.	2999 N
Total Stroke:		
Standard	0.51 in.	13 mm
Extended -L	1.02 in.	26 mm
Weight (RDH)	6.06/6.57 lbs.	2.75/2.98 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	60-100 psi	4-7 Bar

Accessory Mounting Technical Data



PARALLEL GRIPPER RDH-5M 2-JAW PARALLEL SERIES

RDH-5M-L Loading Information



Loading Capacity[†]

Louding oupdoily	ouulo	Dynamio
Maximum Tensile T	442 lbs. [1966 N]	62 lbs. [278 N]
Maximum Compressive C	589 lbs. [2621 N]	62 lbs. [278 N]
Maximum Moment Mx	832 in lbs. [94 Nm]	89 inIbs. [10 Nm]
Maximum Moment My	1053 inlbs. [119 Nm]	115 inlbs. [13 Nm]
Maximum Moment Mx	690 inlbs. [78 Nm]	115 inlbs. [13 Nm]
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*Capacities are per set of jaws and are not simultaneous

Specifications (cont.)

Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	5.81 in ² .	37.5 cm ²
Displacement	6.22 in ³ .	102 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Actuation (open/close)	0.14 sec./0.14 sec.	
Accuracy	±0.0024 in.	±0.06 mm
Repeatability	±0.0012 in.	±0.03 mm
Valve required to actuate single acting	3-way, 2-position	
Valve required to actuate double acting	4-way, 2-position	

Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com

PARALLEL GRIPPER RDH-6M 2-JAW PARALLEL SERIES

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RDH SER

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RDH-6M Loading Information



Loading Capacity	JIAUG	Dynamic
Maximum Tensile T	779 lbs. [3463 N]	186 lbs. [827 N]
Maximum Compressive C	1045 lbs. [4649 N]	186 lbs. [827 N]
Maximum Moment Mx	1204 in lbs. [136 Nm]	248 inlbs. [28 Nm]
Maximum Moment My	1744 in lbs. [197 Nm]	363 inlbs. [41 Nm]
Maximum Moment Mx	1151 inlbs. [130 Nm]	363 inlbs. [41 Nm]
Capacities are per set of jaws and are not simul	taneous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	1406 lbs.	6250 N
Without Spring Assist -L	914 lbs.	4062 N
With Spring Assist	1944 lbs.	8640 N
With Spring Assist -L	1265 lbs.	5623 N
Total Stroke:		
Standard	0.63 in.	16 mm
Extended -L	1.26 in.	32 mm
Weight	12.72 lbs.	5.77 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	65-100 psi	4.5-7 Bar

Accessory Mounting Technical Data



PARALLEL GRIPPER RDH-6M 2-JAW PARALLEL SERIES

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RDH-6M-L Loading Information



Loading Capacity[†]

Louding oupdoily	ouuo	Dynamio
Maximum Tensile T	694 lbs. [3089 N]	121 lbs. [537 N]
Maximum Compressive C	932 lbs. [4146 N]	121 lbs. [537 N]
Maximum Moment Mx	1071 inIbs. [121 Nm]	159 in lbs. [18 Nm]
Maximum Moment My	1390 inIbs. [157 Nm]	212 in lbs. [24 Nm]
Maximum Moment Mx	912 inlbs. [103 Nm]	212 in lbs. [24 Nm]
[†] Capacities are per set of jaws and are not simu	Itaneous	

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'Capacities are per set of Jaws and are not

Specifications (cont.)		
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	10.08 in ² .	65 cm ²
Displacement	13.18 in ³ .	216 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Actuation (open/close)	0.20 sec.	/0.20 sec.
Accuracy	±0.0031 in.	±0.08 mm
Repeatability	±0.0016 in.	±0.04 mm
Valve required to actuate single acting	3-way, 2-position	
Valve required to actuate double acting	4-way, 2-position	

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PARALLEL GRIPPER RDH-7M 2-JAW PARALLEL SERIES







PARALLEL GRIPPER RDH-7M 2-JAW PARALLEL SERIES

My

Dynamic

RDH-7M Loading Information



	Static	Dynamic
Maximum Tensile T	1013 lbs. [4505 N]	236 lbs. [1048 N]
Maximum Compressive C	1335 lbs. [5938 N]	236 lbs. [1048 N]
Maximum Moment Mx	1478 inIbs. [167 Nm]	319 in lbs. [36 Nm]
Maximum Moment My	2106 in lbs. [238 Nm]	451 inIbs. [51 Nm]
Maximum Moment Mx	1425 inIbs. [161 Nm]	451 inlbs. [51 Nm]
[†] Canacities are per set of jaws and are not sin	nultaneous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	2228 lbs.	9901 N
Without Spring Assist -L	1441 lbs.	6404 N
With Spring Assist	2822 lbs.	12542 N
With Spring Assist -L	1830 lbs.	8135 N
Total Stroke:		
Standard	0.98 in.	25 mm
Extended -L	1.97 in.	50 mm
Weight	24.8 lbs.	11.25 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	60-100 psi	4-7 Bar

Accessory Mounting Technical Data



RDH-7M-L Loading Information



Loading Capacity[†]

J		•
Maximum Tensile T	879 lbs. [3911 N]	152 lbs. [678 N]
Maximum Compressive C	1159 lbs. [5155 N]	152 lbs. [678 N]
Maximum Moment Mx	1283 in lbs. [145 Nm]	204 inlbs. [23 Nm]
Maximum Moment My	1584 inIbs. [179 Nm]	257 inlbs. [29 Nm]
Maximum Moment Mx	1080 in lbs. [122 Nm]	257 inlbs. [29 Nm]

Static

[†]Capacities are per set of jaws and are not simultaneous

Specifications (cont.)

Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Surface	16.12 in ² .	104 cm ²
Displacement	32.95 in ³ .	540 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Actuation (open/close)	0.55 sec./	0.55 sec.
Accuracy	±0.0039 in.	±0.1 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate single acting	3-way, 2	2-position
Valve required to actuate double acting	4-way, 2	2-position

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PARALLEL GRIPPER RDH-8M **2-JAW PARALLEL SERIES**

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PARALLEL GRIPPER RDH-8M 2-JAW PARALLEL SERIES

F/2 Mx

8 in. Ha

35.81 in².

-30°~180° F

1.3 sec./1.3 sec.

3-way, 2-position

4-way, 2-position

30 psi

Static

1328 lbs. [5906 N]

1726 lbs. [7678 N]

2885 in.- lbs. [326 Nm]

3160 in.- lbs. [357 Nm]

1974 in.- lbs. [223 Nm]

..... 103.1 in³.

🗸 Mv

Dynamic

253 lbs. [1125 N]

253 lbs. [1125 N]

478 in.- lbs. [54 Nm]

522 in.- lbs. [59 Nm]

522 in.- lbs. [59 Nm]

20 mm Ha

2.1 Bar

231 cm²

1689 cm³

±0.1 mm

±0.05 mm

-35°~80° C

RDH-8M Loading Information



Luauning vapacity	Stauc	Dynamic
Maximum Tensile T	1543 lbs. [6863 N]	392 lbs. [1743 N]
Maximum Compressive C	2006 lbs. [8921 N]	392 lbs. [1743 N]
Maximum Moment Mx	3354 inlbs. [379 Nm]	743 inIbs. [84 Nm]
Maximum Moment My	4257 inlbs. [481 Nm]	947 inIbs. [107 Nm]
Maximum Moment Mx	2664 in lbs. [301 Nm]	947 inIbs. [107 Nm]
Capacities are per set of jaws and are not simul	taneous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	4941 lbs.	21958 N
Without Spring Assist -L	3190 lbs.	14178 N
With Spring Assist	6300 lbs.	28002 N
With Spring Assist -L	4076 lbs.	18115 N
Total Stroke:		
Standard	1.38 in.	35 mm
Extended -L	2.76 in.	70 mm
Weight	71.1 lbs.	32.3 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

Accessory Mounting Technical Data



RDH-8M-L Loading Information

Loading Capacity[†]

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mx

Specifications (cont.)

Displacement.....

*Capacities are per set of jaws and are not simultaneous

Max. Vacuum for Scavenge Port.....

Max. Pressure for Purge Port.....

Cylinder Surface.....

Temperature Range

Accuracy ±0.0039 in.

Repeatability ±0.002 in. Valve required to actuate single acting.....

Actuation (open/close)

Valve required to actuate double acting

Maximum Tensile T



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RDH Series Exploded View

SK (58

63

(57

(9

G(1

(65)

(2)

(56)

SK G 54

(4)

G(3





Item Qty Name

01	1	Body
02	1	Piston
03	1	Double wedge
04	1	Сар
05	1	Bottom Case
06	2	Jaws
07	2	Bottom Case, SS Screw
08	4	Locating sleeve
09	2	Sensing nut
50	1	Cap, O-ring
51	2	Cap, O-ring
52	3	Cap, SS screw
53	4	Cap, SHC screw
54	1	Piston, O-ring
55	1	Body, O-ring
56	4	Piston, Magnet
57	1	Piston, Pin
58	1	Bottom case, O-ring
59	1	Body, SS screw
60	2	Cap. Pin
61	1	Double wedge, HH screw
62	1	Double wedge, Seal
63	2	Bottom case. Pin
64	6	Bottom case, SHC Screw
65	4 or 8	Spring
71	2	Sensor holder
72	4	Sensor holder, SHC screw
73	2	Sensing nut, SHC screw

NOTE: Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.



- 19) Insert screws #73 into the sensing nuts #9 from the body holes
- 20) Insert locating sleeves #8 into the jaws

- Assembly Procedure
- 1) Lubricate and install seal #55 into the body #1

e

- 2) Install #59 screw with thread locker into the body #1
- 3) Sub assemble the sensing nuts #9 into the jaws #6
- 4) Sub assemble the jaws #6 on either side of the double wedge #3 with lubrication
- 5) Insert the jaws and double wedge sub assembly into the body
- 6) Install seal #58 into the bottom case #5
- 7) Insert the screws #7 into the bottom case #5
- Install bottom case #5 with pressed-in pins #63 onto the body and fasten with #64 screws with thread locker
- 9) Lubricate and install seal #54 into the piston #2
- 10) Mount magnets #56 to piston #2 with thread locker

11) For -C option, insert the springs #65 into the body #1 counterbore holes

55) G

61) THREAD

(60)

51) G

(53)

(50) G SK

(59)

(73)

(72)

(71)

(62) (SK

- 12) Insert the piston #2 with pressed-in pin #57 onto the double wedge#3 and fasten with screw #61 with thread locker and washer #62. Face mount the piston counterbore holes to the body counterbore holes for -C option.
 Opposite mount for -O option.
- 13) For -O option, insert the springs #65 into the piston #2 counterbore holes
- 14) Install the screws #52 with thread locker onto the cap #4
- 15) Install seals #50 and #51 into the cap #4
- 16) Insert the cap #4 into the body #1 and locate it using cap dowel pins #60
- 17) Fasten the cap #4 with #53 screws with thread locker
- 18) Install the sensor holders #71 onto the body and fasten with screws #72



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RDH Series Assembled View

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01	1	Body
02	1	Piston
03	1	Double wedge
04	1	Сар
05	1	Bottom Case
06	2	Jaws
07	2	Bottom Case, SS Screw
08	4	Locating sleeve
09	2	Sensing nut
50	1	Cap, O-ring
51	2	Cap, O-ring
52	3	Cap, SS screw
53	4	Cap, SHC screw
54	1	Piston, O-ring
55	1	Body, O-ring
56	4	Piston, Magnet
57	1	Piston, Pin
58	1	Bottom case, 0-ring
59	1	Body, SS screw
60	2	Cap, Pin
61	1	Double wedge, HH screw
62	1	Double wedge, Seal
63	2	Bottom case, Pin
64	6	Bottom case, SHC Screw
65	4 or 8	Spring
71	2	Sensor holder
72	4	Sensor holder, SHC screw
73	2	Sensing nut, SHC screw

NOTE: Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



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2P Parallel Gripper-2-Jaw Precision Series

Precision Gripper

Two centering jaws and very good repeatability [0.02mm] allow loading and unloading accurate cylindrical parts.

Harsh Environments

Shielded design (-E) repels chips and other particulate from internal drive mechanism depending on the chosen material of the shield.

Compact and Powerful

This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Multipurpose Gripper

A wide range of options and accessories (extended stroke, hydraulic power, safety springs for internal or external gripping, inductive sensors, tandem cylinder, Viton® seals, and protective boot) allow these grippers to be used in a number of applications.

Mounting Information:



Technical Specifications:

Pneumatic Specifications	Imperial	Metric			
Pressure Operating Range	30-100 psi	2-7 bar			
Cylinder Type	Double or double acting spring-assisted or single acting with spring				
Dynamic Seals	Buna	a-N			
Valve Required to Operate:					
Double Acting	4-way, 2-	position			
Single acting (Option RE or RI)	3-way, 2-	position			
Air Quality Requirements					
Filtration	40 Micron	or Better			
Lubrification	Not Nec	essary*			
Temperature Operating Range					
Buna-N Seals (standard)	-30°~180° F	-35°~80° C			
Viton [®] Seals (optional)	-20°~300° F	-30°~150° C			
Application Restrictions					
Expected Life					
Normal Application	5 million	cycles			
w/ Preventative Maintenance	10+ millio	n cycles*			
Field Repairable	Yes				
Seal Repair Kits Available	Ye	s			

*Addition of lubrication will greatly increase service life

6002P

10 mm

694 N

176 N

0.51 kg

8002P

13 mm

1946 N

635 N

0.84 kg

20 mm

3043 N

965 N

2.04 kg

26 mm

6232 N

2305 N

4.20 kg

16502P

30 mm

11475 N

3825 N

8.74 kg

16502PGR

30 mm

11475 N

3825 N

11.5 kg

6002P-C

16 mm

432 N

109 N

0.51 kg

8002P-C

20 mm

1256 N

410 N

0.84 kg

11002P 11002P-C

14002P 14002P-C

40 mm

4031 N

1490 N

4.20 kg

16502P-C

50 mm

6878 N

2292 N

8.74 kg

30 mm

2030 N

644 N

2.04 kg



- The rotation of the levers converts the vertical movement of the piston in a horizontal motion and synchronized two-bit gates, which are guided in grooves in «T» fitting body.
- . This gripper is suitable for internal or external gripping and can be mounted in any orientation
- Optional failsafe spring can be used to maintain gripping force if gripper looses air pressure or as a single acting return gripper.

See Page 1.52

See Pages 1.53-1.56

1. Force with spring and air at 6bar 2. Force with spring without air

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PARALLEL GRIPPER 6002P PRECISION 2P GRIPPER SERIES





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PARALLEL GRIPPER 6002P-C PRECISION 2P GRIPPER SERIES



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PARALLEL GRIPPER 8002P PRECISION 2P GRIPPER SERIES

PRECISION 2P

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Options and Accessories: See Page 1.53

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S80V

S80H

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Viton[®] Seal Repair Kit

Hydraulic Seal Repair Kit



PARALLEL GRIPPER 8002P-C PRECISION 2P GRIPPER SERIES



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PARALLEL GRIPPER 11002P PRECISION 2P GRIPPER SERIES





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PARALLEL GRIPPER 11002P-C PRECISION 2P GRIPPER SERIES



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PARALLEL GRIPPER 14002P PRECISION 2P GRIPPER SERIES





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PARALLEL GRIPPER 14002P-C PRECISION 2P GRIPPER SERIES



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PARALLEL GRIPPER 16502P PRECISION 2P GRIPPER SERIES





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PARALLEL GRIPPER 16502P-C PRECISION 2P GRIPPER SERIES



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PARALLEL GRIPPER 16502PGR PRECISION 2P GRIPPER SERIES







SUPPLY: (P) Pneumatic (H) (H80) Hydraulic

As standard, the clamp is supplied with air to a pressure of 7 bar. The clamp is fitted with Viton O-ring seals for high temperatures.

On request (contact us) the gripper can be supplied with hydraulic fluid. The clamp is fitted with seals Viton Quad-Ring.

- Choice (H) allows a hydraulic power to a pressure of 20 bar max. In this case the overall dimensions do not change. For better security the gripper must be fixed on their support before being fired. CAUTION: Hydraulic cycle times are longer.
- Choice (H80) allows a hydraulic power to a pressure of 80 bar max. In this case the total height of the gripper is increased (contact us).

The hydraulic power is incompatible with the option tandem (M).

Option (RE) or (RI): Spring Assist

The internal springs of the gripper ensures failsafe operation by retaining the component during pressure loss, to increase the gripforce, or allows the usage of the gripper in single acting operation.

Option (**RE**) for external gripping. Option (**RI**) for internal gripping.

The (RE) is incompatible with the option (RI).

Option (T): Sensor Rod

Option (**T**) is a steel rod which comes out on the rear side of the gripper. The rod is fixed with the piston and has the same stroke movement. The open end of the rod allows for mounting a cam which allows to control the position of the jaws by using inductive sensors, micro switches, etc

WARNING: when screwing on cam rod, make sure the sensor rod does not rotate to prevent twisting of the springs of options (RE) or (RI).

Model

6002P & 6002P-C

8002P & 8002P-C

11002P & 11002P-C

14002P & 14002P-C

16502P & 16502P-C

Option (T) is incompatible with option (K).



Model	A	В	C	D	Е	F
6002P & 6002P-C	35	5	30	15	M6	10
8002P & 8002P-C	35	6.5	28.5	15	M6	10
11002P & 11002P-C	35	10	25	15	M6	15
14002P & 14002P-C	55	13	42	20	M8	15
16502P & 16502P-C	53	23	30	20	M8	15

ØC

38.1

50.8

76.2

107.95

127

ØD

60

80

110

140

165

W

3

3

3

5

6

Weight (kg)

0.200

0.300

0.750

2.100

3.600

Ay

28.5

27

34

49

65

Option (M): Tandem Cylinder

The (\mathbf{M}) is a cylinder light-alloy that fits behind the bottom plate. This actuator's integral action allows to double the gripforce by using the same pressure.

The combination of tandem option tandem (M) and Option (RE) or (RI) can double the clamping forces of the spring assist option. For cycle times of the tandem option, apply a factor of 3 to the actuation time.

The (M) is incompatible with the option (H).





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Option (KT1), (KX1), (KT2), (KX2): Sensor Unit

The (**K**) is a lightweight alloy housing that fits on the back of the gripper. An integrated shaft follows the movement of the piston to provide information to the sensor attached to the side of the unit. It can control two positions of the grippers jaws. 2 types of inductive sensors (**KT**, **KX**) and 2 detection zones (**1**, **2**) are possible to allow for the combination of 2 to 4 possible positions (**KT1**, **KX1**, **KT2**, **KX2**). For **KT**, **KX** sensor specifications.







Model #	Ax	Bx	ØC	ØD	w	Weight (kg)	No. of Sensing Postions (please specify when ordering)	Information area from the open grip position (green LED) X (mm)	Area information relative to the closed grip position (yellow LED) X (mm)
6002D	22	20°	20.1	60	2	0 190	1	0 or 1 ^{+0,5}	4 ⁺⁰ _{-0,5} or 5
00026	23	30	50.1	00	3	0.100	2	0 or 2 ^{+0,5} -0	3 ⁺⁰ _{-0,5} or 5
6002P-C	23	3Uo	38.1	60	3	0 180	1	0 or 1.6 ^{+0,8}	7 ⁺⁰ _{-0,8} or 8
00021-0	20	50	50.1	00	5	0.100	2	0 or 3.2 ^{+0,8}	4.8 ⁺⁰ _{-0,8} or 8
8002D	28	3Uo	50.8	80	3	0.400	1	0 or 1 ^{+0,5}	5.5 $^{+0}_{-0,5}$ or 6,5
00021	20	50	50.0	00	5	0.400	2	0 or 2 ^{+0,5} -0	4.5 $^{+0}_{-0,5}$ or 6,5
8002P-C	28	3Uo	50.8	80	3	0.400	1	0 or 1.5 ^{+0,8}	8.5 ⁺⁰ _{-0,8} or 10
00021-0	20	50	50.0	00	5	0.400	2	0 or 3.1 ^{+0,8}	6.9 ⁺⁰ _{-0,8} or 10
11002P	36	3Uo	76.2	110	3	0 900	1	0 or 1 ^{+0,5}	9 ⁺⁰ _{-0,5} or 10
110021	50	50	70.2	110	5	0.300	2	0 or 3 ^{+0,5}	7 ⁺⁰ _{-0,5} or 10
110020-0	36	3Uo	76.2	110	3	0 900	1	0 or 1.5 ^{+0,8}	13.5 ⁺⁰ _{-0,8} or 15
110021-0	50	50	10.2	110	5	0.500	2	0 or 4.5 ^{+0,8}	10.5 ⁺⁰ _{-0,8} or 15
14002P	45 5	165°	107 95	140	5	1 670	1	0 or 2 ^{+0,5} -0	11 ⁺⁰ _{-0,5} or 13
140021	40.0	105	107.55	140	5	1.070	2	0 or 4 ^{+0,5}	9 ⁺⁰ _{-0,5} or 13
1/0020-0	15 5	165°	107.05	140	5	1 670	1	0 or 3 ^{+0,8}	17 ⁺⁰ _{-0,8} or 20
140021-0	40.0	105	107.55	140	5	1.070	2	0 or 6.2 ^{+0,8}	13.8 ⁺⁰ _{-0,8} or 20
16502P	65 5	165°	197	165	6	2 670	1	0 or 2 ^{+0,5} -0	13 ⁺⁰ _{-0,5} or 15
100021	05.5	105	121	103	0	2.070	2	0 or 4 ^{+0,5}	11 ⁺⁰ _{-0,5} or 15
165020-0	65 F	1650	107	165	6	2.670	1	0 or 3.3 ^{+0,8}	21.7 ⁺⁰ _{-0,8} or 25
100027-0	05.5	105	127	103	0	2.070	2	0 or 7 ^{+0,8}	18 ⁺⁰ _{-0,8} or 25

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Option (V): Viton[®] Seals

Gripper with Viton[®] seals allows for use in high temperature environments [-30 ° C or 150 ° C].

Accessory (E): Protective Boot

The accessory (\mathbf{E}) is a protective boot that fits over the gripper. It protects the mechanism and thus improves the life of the gripper in hostile environments. The accessory (\mathbf{E}) causes a different location of the fingers on the jaws as compared to the standard installation. Before attaching the boot, perform the following steps:

- 1. Mount gripper to machine.
- 2. Slip boot over gripper and secure in place.
- 3. Attached fingers to jaws using finger adapter.

Depending on the environment 2 types of envelopes are available:

- (E) Envelope of black or brown PVC for environmental grinding with emery presence.
- (E3) red envelope containing KEVLAR fireproof silicone environment for hot chips and weld spatter.

The accessory (E) is incompatible with the accessory (SD)

Model Code	Order #	Model	A	В	C	D	E	F	G	H	J	K	S	т	тх	v	Y
E E3	ER62P E3R62P	6002P & 6002P-C	88	98	35	13.5	8	29	29	17.5	13	_	3	M4	9	13	6
E E3	ER82P E3R82P	8002P & 8002P-C	89	110	34	13.5	10	33	30	22.3	16	_	3	M5	10	16	6
E E3	ER112P E3R112P	11002P & 11002P-C							Se	e drawi	ng						
E E3	KP-311 KP-313	14002P & 14002P-C	143	185	50	18	12	55	34	19.5	24	18	5	M8	14	_	8
E E3	KP-314 KP-316	16502P & 16502P-C	172	220	70	16	14	67	37	24 19	28	23	6	M10	19	_	8





PRECISION 2P

1.56





Accessory (SD): Inductive Sensor Mounting Kit

Allows for sensing of two positions: open and closed jaw. The accessory kit (SD) includes: 1 sensor bracket, 1 flag and screws. Sensors are not provided.

NOTES:

To be usable, the cylindrical inductive sensors selected by the customer must have tapped their bodies to a minimum depth H (see table below).

Depending on their length, the cylindrical inductive sensors can extend below the clamp, requiring provision of suitable housing in the surrounding parts. It is possible to control more than 2 positions using a second attachment (**SD**).



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RECIDESIGN NOTES 1.5 PRECISION 2P

Parallel Gripper-CP Square Jaw Series

Compact and Powerful

This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Multipurpose Gripper

A wide range of options and accessories (extended stroke, safety springs for internal or external gripping, inductive sensors and Viton® seals) allow these grippers to be used in a number of applications.

Harsh Environments

Shielded design repels chips and other particulate from internal drive mechanism depending on the chosen material of the shield.





Technical Specifications:

Pneumatic Specifications Ρ

Pressure Operating Range Cylinder Type Dynamic Seals Valve Beguired to Operate	3-10 bar Double Acting Buna-N
Double Acting Single acting (Option RE or RI)	4-way, 2-position 3-way, 2-position
Air Quality Requirements	
Air Filtration Air Lubrication	40 Micron or Better Not Necessary*
Temperature Operating Range	
Buna-N Seals (standard)	-35°~80° C
Viton [®] Seals (optional)	-30°~150° C
Application Restrictions	
Expected Life	
Normal Application w/ Preventative Maintenance	3 million cycles 6 million cycles*
Field Repairable	Yes
Seal Repair Kits Available	Yes
*Addition of lubrication will greatly increase service life	

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 A double-acting piston is connected to the piston shaft at its end with a driving groove. The piston is pre-fitted with a ring magnet for sensor detection.

Pre

Exhaust

- Levers pivot in the body about an axis of articulation. Their two heads agree precisely on one side in the groove of the small piston, the other in a groove cut in each jaw holder.
- The rotation of the levers converts the vertical movement of the piston in a horizontal motion and synchronized two-bit gates, which are guided in grooves in «T» fitting body.
- This gripper is suitable for internal or external gripping and can be mounted in any orientation
- Optional failsafe spring can be used to maintain gripping force if gripper looses air pressure or as a single acting return gripper.

Style: CP Parallel Gripper



 Model
 CP-1
 CP-1-C

 Total Stroke:
 4 mm
 6 mm

 Force at 6bar:¹
 88 N
 60 N

 Force w/o air:²
 15 N
 10 N

 Weight:
 0.09 kg
 0.09 kg

See Pages 1.60 & 1.61

Style: CP Parallel Gripper



Model	CP-2	CP-2-C
Total Stroke:	6 mm	9 mm
Force at 6bar:1	238 N	161 N
Force w/o air:2	43 N	29 N
Weight:	0.21 kg	0.20 kg

See Pages 1.62 & 1.63

Style: CP Parallel Gripper



Model	CP-3	CP-3-C
Total Stroke:	10 mm	16 mm
Force at 6bar:1	677 N	407 N
Force w/o air:2	161 N	97 N
Weight:	0.45 kg	0.47 kg

See Pages 1.64 & 1.65

Style: CP Parallel Gripper



Model	CP-4	CP-4-C
Total Stroke:	13 mm	20 mm
Force at 6bar:1	1016 N	665 N
Force w/o air:2	222 N	145 N
Weight:	0.73 kg	0.75 kg

See Pages 1.66 & 1.67

Style: CP Parallel Gripper



Style: CP Parallel Gripper



OPTIONS & ACCESSOIRES

1.59

1.72

1. Force with spring and air at 6bar 2. Force with spring without air See Page **1.72**

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CP SERIES

PARALLEL GRIPPER CP-1 COMPACT GRIPPER SERIES







S	pe	cit	fica	tion	S	
~		_				

Grip Force (F6+R) ¹ , 6 bars, Springs Mid-Way, L=0	88 N
Grip Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	15 N
Total Stoke	4 mm
Weight	0.09 kg
Pressure Range	2-10 bar
Pressure Range with Springs	2.5-10 bar
Ø Cylinder Bore	16 mm
Displacement	0.7 cm ³
Acuation (open / close)	0.06 s / 0.06 s
Repeatability	± 0.025
1. Force with spring and air at 6bar 2 Force with spring without air	

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



Loading Information

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)







SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP1	1
Viton® Seal Repair Kit	SCP1V	1
Repair Kit (screws, springs, standard seals)	KSCP1	1
Repair Kit (screws, springs, seals Viton)	KSCP1V	1
Accessories: see page 70		

* The Capacities are per set of jaws and are not simultaneous.

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PARALLEL GRIPPER CP-1-C **COMPACT GRIPPER SERIES**



Grippers are supplied with open side air ports and top manifold air ports plugged Top manifold sealing dimensions shown.

2. Force with spring without air



60 N

10 N

6 mm

Loading Information

2 x M3

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)

11

= 9 =

Ø2 E7

43.5 js11



How to Order: (Order Accessories separately from Basic Model)



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PARALLEL GRIPPER CP-2 COMPACT GRIPPER SERIES







Grip Force (F6+R) ¹ , 6 bars, Springs Mid-Way, L=0	238 N
Grip Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	43 N
Total Stoke	6 mm
Weight	0.21 kg
Pressure Range	2-10 bar
Pressure Range with Springs	2.5-10 bar
Ø Cylinder Bore	25 mm
Displacement	2.7 cm ³
Acuation (open / close)	0.06 s / 0.06 s
Repeatability	± 0.025
1. Force with spring and air at 6bar 2. Force with spring without air	

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



CP-2

Loading Information

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)





PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2	
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2	
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2	
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2	
nductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP2	1	
nductive PNP Sensor with M8 Connector	OISP-011-C	1 or 2	
nductive NPN Sensor with M8 Connector	OINP-011-C	1 or 2	
Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2	
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit	SCP2	1	
Viton® Seal Repair Kit	SCP2V	1	
Repair Kit (screws, springs, standard seals)	KSCP2	1	
Repair Kit (screws, springs, seals Viton)	KSCP2V	1	
Accessories: see page 70			

* The Capacities are per set of jaws and are not simultaneous.

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PARALLEL GRIPPER CP-2-C COMPACT GRIPPER SERIES





Open Ø 27 H10 2	.8 DP
15 js8	-
2 slots for magnetic sensors	
Specifications	CP-2-C
Grip Force (F6+R) ¹ , 6 bars, Springs Mid-Way, L=0	161 N
Grip Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	29 N
Total Stoke	9 mm
Weight	0.20 kg
Pressure Range	2-10 bar
Pressure Range with Springs	2.5-10 bar

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

Ø Cylinder Bore

Acuation (open / close)

1. Force with spring and air at 6bar

2. Force with spring without air

Displacement

Repeatability

How to Order: (Order Accessories separately from Basic Model)



KSCP2V

1

25 mm

2.7 cm[°]

0.06 s / 0.06 s

± 0.025

Loading Information



Sum of forces transmitted by the jaws on the workpiece

<u> </u>	─ ─ Mx	└─ ▼ My	
Loading Capacity*	Static	Dynamic	
Maximum Tensile T	260 N	22 N	
Maximum Compresive C	375 N	22 N	
Maximum Moment Mx	4 Nm	0.7 Nm	
Maximum Moment My	8 Nm	1.2 Nm	
Maximum Moment Mz	8 Nm	1.2 Nm	
* The Capacities are per set of jaws and are	not simultaneous.		

BASE MODEL LONG STROKE **ANGULAR JAW** CP-2 C **RE** External Gripping SPRINGS SENSOR MOUNTS **VITON® SEALS RI** Internal Gripping **SENSOR ACCESSORIES** ORDER # QTY/UNIT PNP Sensor with 0.3m Output Cable with 90° with M8 connector D1 1 or 2 NPN Sensor with 0.3m Output Cable with 90° with M8 connector D10 1 or 2 PNP Sensor with 0.3m Output Cable with M8 connector D4 1 or 2 D7 NPN Sensor with 0.3m Output Cable with M8 connector 1 or 2 Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD) SDCP2 1 Inductive PNP Sensor with M8 Connector OISP-011-C 1 or 2 Inductive NPN Sensor with M8 Connector OINP-011-C 1 or 2 Quick Disconnect 2 Meter Cable Length CABL-010 1 or 2 **PNEUMATIC ACCESSORIES** Standard Seal Repair Kit SCP2 1 Viton[®] Seal Repair Kit SCP2V 1 Repair Kit (screws, springs, standard seals) KSCP2 1

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Repair Kit (screws, springs, seals Viton)

Accessories: see page 70

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PARALLEL GRIPPER CP-3 COMPACT GRIPPER SERIES





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Specifications

Grip Force (F6+R) ¹ , 6 bars, Springs Mid-Way, L=0	677 N
Grip Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	161 N
Total Stoke	10 mm
Weight	0.45 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3-10 bar
Ø Cylinder Bore	40 mm
Displacement	11.7 cm ³
Acuation (open / close)	0.07 s / 0.07 s
Repeatability	± 0.025
1. Force with spring and air at 6bar 2. Force with spring without air	

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



CP-3

Loading Information

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)



How to Order: (Order Accessories separately from Basic Model) BASE MODEL ANGULAR JAW VITON® SEALS CP-3 - - Q - SD - V RE External Gripping RI Internal Gripping SPRINGS SENSOR MOUNTS

SENSOR ACCESSORIES	ORDER #	QTY/UNIT	
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2	
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2	
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2	
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2	
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP3	1	
Inductive PNP Sensor with M8 Connector	OISP-011-C	1 or 2	
Inductive NPN Sensor with M8 Connector	OINP-011-C	1 or 2	
Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2	
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit	SCP3	1	
Viton® Seal Repair Kit	SCP3V	1	
Repair Kit (screws, springs, standard seals)	KSCP3	1	
Repair Kit (screws, springs, seals Viton)	KSCP3V	1	
Accessories: see name 70			

* The Capacities are per set of jaws and are not simultaneous.


PARALLEL GRIPPER CP-3-C COMPACT GRIPPER SERIES

2 x M5 prof 6 (Seals Supplied)

Close

8 4 8

2 x Ø 4 H9 8 DP

Ø 43 H10 3.5 DP

θ







63



2 slots for magnetic sensors

Θ

55

44

38

ð

ଇତ

Specifications

Grip Force (F6+R) ¹ , 6 bars, Springs Mid-Way, L=0	407 N
Grip Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	97 N
Total Stoke	16 mm
Weight	0.47 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3-10 bar
Ø Cylinder Bore	40 mm
Displacement	11.7 cm ³
Acuation (open / close)	0.07 s / 0.07 s
Repeatability	± 0.025
1. Force with spring and air at 6bar 2. Force with spring without air	

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



CP-3-C

Loading Information

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)			
250 225 200 155 150 150 125 100 55 25 0 0	10 20 30 FINGER LENGTH	ar MA ar 40 50 "L" (MM)	ATTENTION : DO NOT EXCEED XXIMUM EFFECTIVE INGER LENGTHS
		F/2 —•	Z Mz F/2 My
Loading Capacity*		Static	Dynamic
Maximum Tensile T		500 N	55 N
Maximum Compresive C		675 N	55 N
Maximum Moment Mx		9 Nm	2.5 Nm
Maximum Moment My		16 Nm	4 Nm
Maximum Moment Mz		17 Nm	4 Nm
* The Capacities are per set of jaws and a	re not simultaneous.		

How to Order: (Order Accessories separately from Basic Model) BASE MODEL ANGULAR JAW LONG STROKE

	CP-3 - Q - SD -	C -	V
Ri Ri	External Gripping SPRINGS SENSOR MOUNTS	VITON® SE	ALS
	SENSOR ACCESSORIES	ORDER #	QTY/UNIT
	PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
	NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
	PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
	NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
	Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP3	1
	Inductive PNP Sensor with M8 Connector	OISP-011-C	1 or 2
	Inductive NPN Sensor with M8 Connector	OINP-011-C	1 or 2
	Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2
	PNEUMATIC ACCESSORIES		
	Standard Seal Repair Kit	SCP3	1
	Viton® Seal Repair Kit	SCP3V	1
	Repair Kit (screws, springs, standard seals)	KSCP3	1
	Repair Kit (screws, springs, seals Viton)	KSCP3V	1
	Accessories: see page 70		

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PARALLEL GRIPPER CP-4 COMPACT GRIPPER SERIES







Specifications

-	
Grip Force (F6+R) ¹ , 6 bars, Springs Mid-Way, L=0	1016 N
Grip Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	222 N
Total Stoke	13 mm
Weight	0.73 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3-10 bar
Ø Cylinder Bore	50 mm
Displacement	24.2 cm ³
Acuation (open / close)	0.07 s/0.07 s
Repeatability	± 0.025
1. Force with spring and air at 6bar 2. Force with spring without air	

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



CP-4

Loading Information

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)



How to Order: (Order Accessories separately from Basic Model)

BASE MODEL	ANGULAR JA	W VITON® SEAL	S
RE External Gripping RI Internal Gripping	RINGS	SENSOR MOUNTS	
SENSOR ACCESSORIES		ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable wi	th 90° with M8 connecto	D1	1 or 2

PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2	
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2	
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2	
VPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2	
nductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP4	1	
nductive PNP Sensor with M8 Connector	OISP-011-C	1 or 2	
nductive NPN Sensor with M8 Connector	OINP-011-C	1 or 2	
Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2	
PNEUMATIC ACCESSORIES			
Standard Seal Repair Kit	SCP4	1	
/iton® Seal Repair Kit	SCP4V	1	
Repair Kit (screws, springs, standard seals)	KSCP4	1	
Repair Kit (screws, springs, seals Viton)	KSCP4V	1	
Accessories: see page 70			

* The Capacities are per set of jaws and are not simultaneous.

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PARALLEL GRIPPER CP-4-C COMPACT GRIPPER SERIES





Specifications

•	
Grip Force (F6+R) ¹ , 6 bars, Springs Mid-Way, L=0	665 N
Grip Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	145 N
Total Stoke	20 mm
Weight	0.75 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3-10 bar
Ø Cylinder Bore	50 mm
Displacement	24.2 cm ³
Acuation (open / close)	0.07 s / 0.07 s
Repeatability	± 0.025
1. Force with spring and air at 6bar 2. Force with spring without air	

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.

How to Order: (Order Accessories separately from Basic Model)



KSCP4

KSCP4V

1

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CP-4-C

Loading Information

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke)



	BASE MODEL ANGULAR JAW LONG	STROKE	
	CP-4 Q - SD -	C -	V
RE Ri	External Gripping SPRINGS SENSOR MOUNTS	VITON® SI	EALS
	SENSOR ACCESSORIES	ORDER #	QTY/UNIT
	PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
	NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
	PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
	NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
	Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP4	1
	Inductive PNP Sensor with M8 Connector	OISP-011-C	1 or 2
	Inductive NPN Sensor with M8 Connector	OINP-011-C	1 or 2
	Quick Disconnect 2 Meter Cable Length	CABL-010	1 or 2
	PNEUMATIC ACCESSORIES		
	Standard Seal Repair Kit	SCP4	1
	Viton® Seal Benair Kit	SCP4V	1

* The Capacities are per set of jaws and are not simultaneous.

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Repair Kit (screws, springs, standard seals)

Repair Kit (screws, springs, seals Viton)

Accessories: see page 70

PARALLEL GRIPPER CP-5 COMPACT GRIPPER SERIES



1

1

1

1



How to Order: (Order Accessories separately from Basic Model)

Loading Information



* The Capacities are per set of jaws and are not simultaneous.

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PARALLEL GRIPPER CP-5-C COMPACT GRIPPER SERIES





Specifications

Specifications	CP-5-C
Grip Force (F6+R) ¹ , 6 bars, Springs Mid-Way, L=0	1081 N
Grip Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	219 N
Total Stoke	27 mm
Weight	1.27 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3-10 bar
Ø Cylinder Bore	63 mm
Displacement	53.5 cm ³
Acuation (open / close)	0.09 s / 0.09 s
Repeatability	± 0.025
1. Force with spring and air at 6bar 2. Force with spring without air	

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



Loading Information

Sum of forces transmitted by the jaws on the workpiece (Springs compressed at 50% stroke) 700 ATTENTION : DO NOT EXCEED MAXIMUM EFFECTIVE FINGER LENGTHS 600 500 (N) 400 (N) 2/3 300 200 100 0 -40 80 60 100 0 20 FINGER LENGTH "L" (MM) Mz х Ţ c F/2 F/2 Œ 🗶 Mx 🗶 My Loading Capacity* Static Dynamic Maximum Tensile T 820 N 144 N Maximum Compresive C 930 N 144 N Maximum Moment Mx 22 Nm 7 Nm 40 Nm Maximum Moment My 13 Nm 30 Nm 10 Nm Maximum Moment Mz

How to Order: (Order Accessories separately from Basic Mode	()	
BASE MODEL ANGULAR JAW LONG CP-5 Q - SD - External Gripping nternal Gripping SPRINGS SENSOR MOUNTS	STROKE C - VITON® SI	V
SENSOR ACCESSORIES	ORDER #	QTY/UNIT
PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
VPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
VPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
nductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP5	1
nductive PNP Sensor with M8 Connector	OISP-017-C	1 or 2
nductive NPN Sensor with M8 Connector	OINP-017-C	1 or 2
Quick Disconnect 2 Meter Cable Length	CABL-014	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP5	1
/iton® Seal Repair Kit	SCP5V	1
Repair Kit (screws, springs, standard seals)	KSCP5	1
Repair Kit (screws, springs, seals Viton)	KSCP5V	1

* The Capacities are per set of jaws and are not simultaneous

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Accessories: see page 70

RE RI

PARALLEL GRIPPER CP-6 COMPACT GRIPPER SERIES









Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



Loading Information



Sum of forces transmitted by the jaws on the workpiece

How to Order: (Order Accessories separately from Basic Model) BASE MODEL ANGULAR JAW VITON® SEALS CP-6 Q SD V RE External Gripping RI Internal Gripping SPRINGS SENSOR MOUNTS SENSOR ACCESSORIES ORDER # QTY/UNIT PNP Sensor with 0.3m Output Cable with 90° with M8 connector D1 1 or 2

PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP6	1
Inductive PNP Sensor with M12 Connector	OISP-017-C	1 or 2
Inductive NPN Sensor with M12 Connector	OINP-017-C	1 or 2
Quick Disconnect 2 Meter M12 Cable Length	CABL-014	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SCP6	1
Viton® Seal Repair Kit	SCP6V	1
Repair Kit (screws, springs, standard seals)	KSCP6	1
Repair Kit (screws, springs, seals Viton)	KSCP6V	1
Accessories: see nage 70		

* The Capacities are per set of jaws and are not simultaneous.

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PARALLEL GRIPPER CP-6-C COMPACT GRIPPER SERIES





Loading Information



50 js8 Open Ø 85 H10 5 DP	_
2 slots for magnetic sensors	
ecifications	CP-6-C
o Force (F6+R) ¹ , 6 bars, Springs Mid-Way, L=0	2092 N
o Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	541 N
al Otalia	00

Grip Force (F0+R) ² , 0 bars, Springs Mid-Way, L=0	541 N
Fotal Stoke	32 mm
Neight	2.56 kg
Pressure Range	2-10 bar
Pressure Range with Springs	3.5-10 bar
Ø Cylinder Bore	80 mm
Displacement	114.8 cm ³
Acuation (open / close)	0.12 s / 0.12 s
Repeatability	± 0.025
I. Force with spring and air at 6bar 2 Force with spring without air	

Grippers are supplied with open side air ports and top manifold air ports plugged. Top manifold sealing dimensions shown.



	How to Order: (Order Accessories separately from Basic Model)		
i SE	BASE MODEL ANGULAR JAW LONG CP-6 Q - SD - External Gripping Internal Gripping SPRINGS SENSOR MOUNTS	STROKE C – Viton® Se	V
	SENSOR ACCESSORIES	ORDER #	QTY/UNIT
	PNP Sensor with 0.3m Output Cable with 90° with M8 connector	D1	1 or 2
	NPN Sensor with 0.3m Output Cable with 90° with M8 connector	D10	1 or 2
	PNP Sensor with 0.3m Output Cable with M8 connector	D4	1 or 2
	NPN Sensor with 0.3m Output Cable with M8 connector	D7	1 or 2
	Inductive Sensor Mounting Kit for (mounts 2 sensors) (SD)	SDCP6	1
	Inductive PNP Sensor with M8 Connector	0ISP-017-C	1 or 2
	Inductive NPN Sensor with M8 Connector	OINP-017-C	1 or 2
	Quick Disconnect 2 Meter Cable Length	CABL-014	1 or 2
	PNEUMATIC ACCESSORIES		
	Standard Seal Repair Kit	SCP6	1
	Viton [®] Seal Repair Kit	SCP6V	1
	Repair Kit (screws, springs, standard seals)	KSCP6	1
	Repair Kit (screws, springs, seals Viton)	KSCP6V	1

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OPTIONS AND ACCESSORIES



Accessories (SD): Inductive Sensor Mounting Kit

Allows for sensing of two positions: open and closed jaw. The accessory kit (SD) includes: 1 sensor bracket, 1 flag and screws. Sensors are not provided.

NOTES:

To be usable, the cylindrical inductive sensors selected by the customer must have tapped their bodies to a minimum depth H (see table below).

Depending on their length, the cylindrical inductive sensors can extend below the clamp, requiring provision of suitable housing in the surrounding parts. It is possible to control more than 2 positions using a second attachment (**SD**).



MODELS	P1	P2	P3	P4	P5	P6	P7	P8	P9	Order #
CP-1					acce	ssory not	availabl	e		
CP-1-C					acce	ssory not	availabl	е		
CP-2	58	32	24	2	21.9	35.5	8	48	18	SDCP2
CP-2-C	58	32	24	2	21.9	35.5	8	48	18	SDCP2
CP-3	75.5	32	24	2	28.2	44	8	58	20	SDCP3
CP-3-C	75.5	32	24	2	28.2	44	8	63	24	SDCP3
CP-4	80.5	32	24	2	27	52.5	8	73	26	SDCP4
CP-4-C	80.5	32	24	2	27	52.5	8	73.5	27	SDCP4
CP-5	108	43	28	2.5	38	60	12	85	33	SDCP5
CP-5-C	108	43	28	2.5	38	60	12	85	33	SDCP5
CP-6	118	43	28	2.5	39	76.5	12	108	39	SDCP6
CP-6-C	118	43	28	2.5	39	76.5	12	108	39	SDCP6



Option (V) : Viton® Seals

Gripper with Viton[®] seals allows for use in high temperature environments [-30 ° C or 150 ° C].



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Parallel Grippers -DPP DIRECTCONNECT Precision Series

- Multiple Mounting Locations: All sizes have DIRECTCONNECT top mounting and DIRECTCONNECT thru hole mounting on back side.
- Multiple Air Port Locations: Multiple airport locations: tapped air ports on front, top and both sides are standard. Top port is also manifold ready.
- Sensing options: Magneto resistive or inductive proximity sensors available. Up to 4 positions can be sensed.
- Precision applications: Preloaded "Dual-V" roller bearings eliminate side play for excellent part position repeatability.
- Longer finger applications: Rigid design and low friction design allows for longer gripper finger lengths to be used when compared to other grippers of equal weight & size.

Mounting Information:



- Delicate part handling: Low friction mechanism allows for repeatable gripping forces for holding delicate parts. Grip force is easily adjusted by regulating air pressure.
- Non-synchronous motion: Non-synchronous option provides independent jaw motion allowing the gripper to pick or place at a point other than its center.
- Spring return: Optional double acting spring assist for increased force or fail-safe operation or operate as a single acting to open and to spring closed.



Technical Specifications:

Pneumatic Specifications	Imperial	Metric
Standard	5-100 psi	0.3-7 bar
-C Spring Closed Option	20-100 psi Double /	1.5-7 bar Acting or
oyinider type	Single Acting S	pring Return or
Dynamic Seals	Double Acting	Spring Assist
Valve Required to Operate	4-way, 2-position	for Double Acting
	C 3-way 2-nosition)r for Single Acting
	5-way, 2-position	IOI Single Acting
Air Quality Requirements		Dattau
Air Filtration	40 Micror Not Ne	Cessarv*
Air Humidity	Low Moisture	Content (dry)
Temperature Operating Rang	e	
Buna-N Seals (standard)	-30°~180° F	-35°~80° C
Viton [®] Seals (optional)	-20°~250° F	-30°~120° C
Maintenance Specifications [†]		
Normal Application	5 million	cycles
w/Preventative Maintenance	10+ millio	n cycles*
Field Repairable	Yes	S
Seal Repair Kits Available	Yes	S
Application Restrictions		
Dirty or gritty environments	e abina	
Invacrime operations generation	g criips	

- Applications where mechanism lubricant could cause contamination
- *Addition of lubrication will greatly increase service life

Grippers can be mounted & operated in any orientation



Body mounts with screws and locates with H7 dowel pins for accuracy



Fingers attach to jaws with screws and locate by key slot and/or H7 dowel pins

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Designed, manufactured and assembled in the USA

PARALLEL GRIPPERS DPP-10M-06 DIRECTCONNECT PRECISION SERIES

DPP SERIES 1.76



BASIC MODEL SPRING VITON SEALS DPP-10M-06

NON-SYNCHRONOUS



SENSOR ACCESSORIES	ORDER #	QTY/UNIT
Inductive Sensor Mounting Kit (Mounts 2 sensors)	OSMK-119	1 or 2
NPN Inductive Sensor (with Qk. Disc.)*	OISN-014	1, 2, 3 or 4
PNP Inductive Sensor (with Qk. Disc.)*	0ISP-014	1, 2, 3 or 4
NPN Magneto Resistive Sensor (with Qk. Disc.)**	OHSN-017	1, 2, 3 or 4
PNP Magneto Resistive Sensor (with Qk. Disc.)**	OHSP-017	1, 2, 3 or 4
NPN Magneto Resistive Sensor 90° (with Qk. Disc.)* [†]	OHSN-011	1, 2, 3 or 4
PNP Magneto Resistive Sensor 90° (with Qk. Disc.)**	OHSP-011	1, 2, 3 or 4
Quick Disconnect Cable (2 meters long)*	CABL-010	1, 2, 3 or 4
Quick Disconnect Cable (5 meters long)*	CABL-013	1, 2, 3 or 4
PNEUMATIC ACCESSURIES	ORDER #	QTY/UNIT
Seal Repair Kit (Standard Buna-N)	SLKT-343	1
Seal Repair Kit (Viton)	SLKT-343V	1
Manifold Seal Kit (Viton [®] only)	SLKT-241V	1
Adjustable Flow Control-M3 Elbow-3MM OD Tube Push-in Style	VLVF-018	1 or 2
Adjustable Flow Control-M5 Elbow-6MM OD Tube Push-in Style	VLVF-008	1 or 2
Fail Safe Valve- M5	OFSV-004	1
*Sensor and cable sold separately. *Piston Magnet standard		

SAMPLE ORDER: DPP-10M-06-C-NS-V Ex: DPP-10 Metric Gripper, 6mm Stroke, Spring Closed, Non Synchronous, Viton Seals



Specifications	DPP-10	M-06
Total Rated Grip Force F @ 100 psi, 7 bar*	27 lbs.	120 N
Stroke	0.25 in.	6.4 mm
Weight	0.35 lbs.	0.16 Kg
Pressure Range (Without Springs)	5-100 psi	0.3-7 bar
Pressure Range (With Springs)	20-100 psi	1.4-7 bar
Cylinder Bore (2X)	0.406 in.	10.3 mm
Displacement	0.032 in ³ .	0.5 cm ³
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~150° C
Actuation (Without Spring/With Spring)	0.10/0.11 sec.	0.10/0.11 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate single acting	3-way, 2-p	position
Valve required to actuate double acting *With Springs	4-way, 2-p	position

PARALLEL GRIPPERS DPP-10M-06 DIRECTCONNECT PRECISION SERIES



Static

60 lbs. [267 N]

60 lbs. [267 N]

35 in.-1bs. [4.0 Nm]

50 in.-1bs. [5.6 Nm]

35 in.-1bs. [4.0 Nm]

Loading Capacity

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

Note: Capacities are per set of jaws and are not simultaneous.

Maximum Tensile T

$\left[\right]$

-My

Dynamic

20 lbs. [89 N]

20 lbs. [89 N]

12 in.-Ibs. [1.4 Nm]

17 in.-Ibs. [1.9 Nm]

12 in.-Ibs. [1.4 Nm]

Accessory Mounting Technical Data



DIRECTCONNEC

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PARALLEL GRIPPERS DPP-10M-12 DIRECTCONNECT PRECISION SERIES





SAMPLE ORDER: DPP-10M-12-C-NS-V Ex: DPP-10 Metric Gripper, 12mm Stroke, Spring Closed, Non Synchronous, Viton Seals

DPP SERIES



Specifications	DPP-10	M-12
Total Rated Grip Force F @ 100 psi, 7 bar*	27 lbs.	120 N
Stroke	0.50 in.	12.7 mm
Weight	0.45 lbs.	0.20 Kg
Pressure Range (Without Springs)	5-100 psi	0.3-7 bar
Pressure Range (With Springs)	20-100 psi	1.4-7 bar
Cylinder Bore (2X)	0.406 in.	10.3 mm
Displacement	0.065 in ³ .	1.1 cm ³
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~250° F	-30°~120° C
Actuation (Without Spring/With Spring)	0.11/0.12 sec.	0.11/0.12 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate single acting	3-way, 2-p	position
Valve required to actuate double acting	4-way, 2-p	position
*With Springs		

PARALLEL GRIPPERS DPP-10M-12 DIRECTCONNECT PRECISION SERIES



Static

70 lbs. [311 N]

70 lbs. [311 N]

50 in.-1bs. [5.6 Nm]

65 in.-1bs. [7.3 Nm]

50 in.-1bs. [5.6 Nm]

Dynamic

23 lbs. [102 N]

23 lbs. [102 N]

17 in.-Ibs. [1.9 Nm]

22 in.-Ibs. [2.5 Nm]

17 in.-Ibs. [1.9 Nm]

Loading Capacity

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

Note: Capacities are per set of jaws and are not simultaneous.

Maximum Tensile T

$\left[\right]$

Accessory Mounting Technical Data



DIRECTCONNECT

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PARALLEL GRIPPERS DPP-14M-15 DIRECTCONNECT PRECISION SERIES





NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE



SAMPLE ORDER: DPP-14M-15-C-NS-V Ex: DPP-14 Metric Gripper, 15mm Stroke, Spring Closed, Non Synchronous, Viton Seals



Specifications	DPP-14	M-15
Total Rated Grip Force F @ 100 psi, 7 bar*	51 lbs.	227 N
Stroke	0.63 in.	15.9 mm
Weight	1.05 lbs.	0.48 Kg
Pressure Range (Without Springs)	5-100 psi	0.3-7 bar
Pressure Range (With Springs)	50-100 psi	3.4-7 bar
Cylinder Bore (2X)	0.563 in.	14.3 mm
Displacement	0.156 in ³ .	2.5 cm ³
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation (Without Spring/With Spring)	0.15/0.16 sec.	0.15/0.16 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate single acting	3-way, 2-p	oosition
Valve required to actuate double acting	4-way, 2-p	position
*With Springs		

PARALLEL GRIPPERS DPP-14M-15 DIRECTCONNECT PRECISION SERIES



Loading Capacity

Maximum Tensile T	125 lbs. [556 N]	42 lbs. [187 N]
Maximum Compressive C	125 lbs. [556 N]	42 lbs. [187 N]
Maximum Moment Mx	80 in1bs. [9.0 Nm]	27 in1bs. [3.1 Nm]
Maximum Moment My	105 inIbs. [12 Nm]	35 in1bs. [4.0 Nm]
Maximum Moment Mz	80 in1bs. [9.0 Nm]	27 inIbs. [3.1 Nm]
Note: Capacities are per set of jaws and are	not simultaneous.	

Static

Dynamic

Accessory Mounting Technical Data



1.81

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PARALLEL GRIPPERS DPP-14M-25 DIRECTCONNECT PRECISION SERIES

DPP SERIES 1.82



NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

How to Order: (Order Accessories separately from Basic Model)

BASIC MODEL DPP-14M-2 Spring JAW Synchronization	SPRING VITON SEALS 5 - C - NS - V NON-SYNCHRONOUS C Spring Closed Leave Blank. No Spring Option (standard) NS Non-Synchronous Operation	SENSOR ACCESSORIES Inductive Sensor Mounting Kit (Mounts 2 sensors) NPN Inductive Sensor (with Qk. Disc.)* PNP Inductive Sensor (with Qk. Disc.)* NPN Magneto Resistive Sensor (with Qk. Disc.)*† PNP Magneto Resistive Sensor 90° (with Qk. Disc.)*† NPN Magneto Resistive Sensor 90° (with Qk. Disc.)*† PNP Magneto Resistive Sensor 90° (with Qk. Disc.)*† Quick Disconnect Cable (2 meters long)* Quick Disconnect Cable (5 meters long)*	ORDER # OSMK-119 OISN-014 OISP-014 OHSP-017 OHSP-017 OHSN-011 OHSP-011 CABL-010 CABL-013	QTY/UNIT 1 or 2 1, 2, 3 or 4 1, 2, 3 or 4
VITON® SEALS	 Leave Blank for Synchronous (standard) V High Temperature Viton Seals 	PNEUMATIC ACCESSORIES Seal Repair Kit (Standard Buna-N) Seal Repair Kit (Viton) Manifold Seal Kit (Viton® only) Adjustable Flow Control-M3 Elbow-3MM OD Tube Push-in Style Adjustable Flow Control-M5 Elbow-6MM OD Tube Push-in Style Fail Safe Valve- M5 *Sensor and cable sold separately. 'Piston Magnet standard	ORDER # SLKT-344 SLKT-344V SLKT-344V SLKT-241V VLVF-018 VLVF-008 OFSV-004	qту/илт 1 1 1 or 2 1 or 2 1

SAMPLE ORDER: DPP-14M-25-C-NS-V Ex: DPP-14 Metric Gripper, 25mm Stroke, Spring Closed, Non Synchronous, Viton Seals



Metric [mm]

Imperial in. $\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$

Metric Threads

Course Pitch



Specifications	DPP-14	M-25
Total Rated Grip Force F @ 100 psi, 7 bar*	48 lbs.	214 N
Stroke	1.00 in.	25.4 mm
Weight	1.25 lbs.	0.57 Kg
Pressure Range (Without Springs)	5-100 psi	0.3-7 bar
Pressure Range (With Springs)	50-100 psi	3.4-7 bar
Cylinder Bore (2X)	0.563 in.	14.3 mm
Displacement	0.249 in ³ .	4.1 cm ³
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation (Without Spring/With Spring)	0.19/0.20 sec.	0.19/0.20 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate single acting	3-way, 2-p	oosition
Valve required to actuate double acting *With Springs	4-way, 2-r	position

PARALLEL GRIPPERS DPP-14M-25 DIRECTCONNECT PRECISION SERIES



Loading Capacity

Maximum Tensile T	165 lbs. [734 N]	55 lbs. [245 N]		
Maximum Compressive C	165 lbs. [734 N]	55 lbs. [245 N]		
Maximum Moment Mx	100 inIbs. [11 Nm]	33 inIbs. [3.7 Nm]		
Maximum Moment My	125 inIbs. [14 Nm]	42 inIbs. [4.7 Nm]		
Maximum Moment Mz	100 inIbs. [11 Nm]	33 in1bs. [3.7 Nm]		
Note: Capacities are per set of jaws and are not simultaneous.				

Static

Dynamic

Accessory Mounting Technical Data



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PARALLEL GRIPPERS DPP-20M-25 DIRECTCONNECT PRECISION SERIES

DPP SERIES 1.84



BASIC MODEL SPRING VITON SEALS Inductive Sensor Mounting Kit (Mounts 2 sensors) **OSMK-120** 1 or 2 **OISN-014** NPN Inductive Sensor (with Qk. Disc.)* 2. 3 or 4 **DPP-20M-25** PNP Inductive Sensor (with Qk. Disc.)* **OISP-014** 2.3 or 4 NPN Magneto Resistive Sensor (with Qk. Disc.)*1 OHSN-017 3 or 4 2. OHSP-017 PNP Magneto Resistive Sensor (with Qk. Disc.)*+ 2, 3 or 4 1 **NON-SYNCHRONOUS** NPN Magneto Resistive Sensor 90° (with Qk. Disc.)* OHSN-011 1, 2, 3 or 4 OHSP-011 PNP Magneto Resistive Sensor 90° (with Qk. Disc.)*+ 1, 2, 3 or 4 **SPRING** C Spring Closed Quick Disconnect Cable (2 meters long)* CABL-010 1, 2, 3 or 4 Leave Blank. No Spring Option (standard) CABL-013 Quick Disconnect Cable (5 meters long)* 1, 2, 3 or 4 **JAW SYNCHRONIZATION** NS Non-Synchronous Operation **PNEUMATIC ACCESSORIES ORDER** # QTY/UNIT Leave Blank for Synchronous (standard) SLKT-345 Seal Repair Kit (Standard Buna-N) 1 VITON[®] SEALS V High Temperature Viton Seals Seal Repair Kit (Viton) SLKT-345V 1 Manifold Seal Kit (Viton® only) SLKT-242V 1 Adjustable Flow Control-M5 Elbow-6MM OD Tube Push-in Style VLVF-008 1 or 2 OFSV-004 Fail Safe Valve- M5 1 *Sensor and cable sold separately. *Piston Magnet standard

SENSOR ACCESSORIES

ORDER #

OTY/UNIT

SAMPLE ORDER: DPP-20M-25-C-NS-V Ex: DPP-20 Metric Gripper, 25mm Stroke, Spring Closed, Non Synchronous, Viton Seals

How to Order: (Order Accessories separately from Basic Model)



Specifications	DPP-201	M-25
Total Rated Grip Force F @ 100 psi, 7 bar*	103 lbs.	458 N
Stroke	1.00 in.	25.4 mm
Weight	2.25 lbs.	1.02 Kg
Pressure Range (Without Springs)	5-100 psi	0.3-7 bar
Pressure Range (With Springs)	40-100 psi	2.8-7 bar
Cylinder Bore (2X)	0.813 in.	20.7 mm
Displacement	0.519 in ³ .	8.5 cm ³
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation (Without Spring/With Spring)	0.20/0.22 sec.	0.20/0.22 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate single acting 3-way, 2-position		position
Valve required to actuate double acting	4-way, 2-p	oosition
*With Springs		

PARALLEL GRIPPERS DPP-20M-25 DIRECTCONNECT PRECISION SERIES



Loading Capacity

Maximum Tensile T	150 lbs. [667 N]	50 lbs. [222 N]
Maximum Compressive C	150 lbs. [667 N]	50 lbs. [222 N]
Maximum Moment Mx	300 in1bs. [34 Nm]	100 in1bs. [11 Nm]
Maximum Moment My	350 in1bs. [40 Nm]	117 inIbs. [13 Nm]
Maximum Moment Mz	300 in1bs. [34 Nm]	100 inIbs. [11 Nm]
Note: Capacities are per set of jaws and are not simultaneous.		

Static

Dynamic

Accessory Mounting Technical Data



DIRECTCONNI

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

PARALLEL GRIPPERS DPP-20M-38 DIRECTCONNECT PRECISION SERIES



ORDER #

OSMK-120

OISN-014

OISP-014

OHSN-017

OHSP-017

OHSN-011

OHSP-011

CABL-010

CABL-013

ORDER #

SLKT-345

SLKT-345V

SLKT-242V

VLVF-008

OFSV-004

OTY/UNIT

1 or 2

1 2.3 or 4

2. 3 or 4

3 or 4 1.2.

2, 3 or 4 1.

1, 2, 3 or 4

QTY/UNIT

1

1

1

1 or 2

1



NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE



SERIES

PP

1.86

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Specifications	DPP-20N	1-38
Total Rated Grip Force F @ 100 psi, 7 bar*	101 lbs.	449 N
Stroke	1.50 in.	38.1 mm
Weight	3.10 lbs.	1.41 Kg
Pressure Range (Without Springs)	5-100 psi	0.3-7 bar
Pressure Range (With Springs)	30-100 psi	2.1-7 bar
Cylinder Bore (2X)	0.813 in.	20.7 mm
Displacement	0.779 in ³ .	12.8 cm ³
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation (Without Spring/With Spring)	0.24/0.29 sec.	0.24/0.29 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate single acting 3-way, 2-position		osition
Valve required to actuate double acting	4-way, 2-p	osition
*With Springs		

PARALLEL GRIPPERS DPP-20M-38 DIRECTCONNECT PRECISION SERIES



Static

200 lbs. [890 N]

200 lbs. [890 N]

400 in.-1bs. [45 Nm]

450 in.-Ibs. [51 Nm]

400 in.-1bs. [45 Nm]

Loading Capacity

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

Note: Capacities are per set of jaws and are not simultaneous.

Maximum Tensile T

My

Dynamic

67 lbs. [298 N]

67 lbs. [298 N]

133 in.-1bs. [15 Nm]

150 in.-Ibs. [17 Nm]

133 in.-1bs. [15 Nm]

Accessory Mounting Technical Data



DIRECTCONNEC

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DPP SERIES EXPLODED VIEW

Serres

1.88



Assembly Procedure:

- 1) Lubricate #1 body (jaw cavity & bore).
- 2) Plug cross ports in body with #13 set screws.
- 3) Press #14 pivot pin into body.
- Insert #22 magnet(s) into each #4 piston making sure magnets repel each other between pistons.
- 5) Lubricate and install #18 seals onto pistons.
- 6) Insert pistons into body with magnet sides facing in toward pivot pin.
- 7) Press #7 equalizer pins into #5 equalizer.
- Assemble equalizer with #6 links and place onto pivot pin in body making sure holes in links line up with holes in pistons.
- 9) Place #8 linkage cover over equalizer and link assembly and seat in body pocket.
- 10) Press #12 drive pin into each #2 jaw.
- 11) Lubricate jaw bearing surfaces and install #9 wiper on each jaw end with #21 mounting screws.
- 12) Place #23 cage and roller bearing assemblies on jaw bearing grooves.
- 13) Place jaws into body aligning the drive pins with the holes in the linkage cover, links, and pistons. If jaws have off center key slot in them, jaws should be installed with this slot farther away from the gripper's center.

- 14) Slide #10 ways into body trapping them between body and jaws.
- 15) Install #16 way locating pins at each end of body to secure ways.
- 16) For –C spring closed option, insert #20 springs into pistons.
- 17) Place # 17 seals onto #3 caps and install onto body with #19 retaining rings.
- 18) Install #15 preload screws and torque per preload adjustment procedure.

Preload Adjustment Procedure:

- 1) Tighten center preload screw first and then outer ones to the torque specification in step 2.
- 2) Use the following torque specification per gripper.
 - DPP-10M 6 in-lbs [0.68 Nm]
 - DPP-10M = 6 in-lbs [0.68 Nm]DPP-14M = 8 in-lb [0.90 Nm]
 - DPP-20M 13 in-lb [1.47 Nm]

Note: Torque specifications provided are factory settings. Fine adjustment may be needed based on intent & application.

ltem	Qty	Name
01	1	Body
02	2	Jaw
03	2	Сар
04	2	Piston
05	1	Equalizer
06	2	Link
07	2	Equalizer Pin
08	1	Linkage Cover
09	4	Wiper
10	2	Way
12	2	Drive Pin
13	10	Set Screw – Air & Purge Plug
14	1	Pivot Pin
15	3	Preload Screw
16	4	Way Locating Pin
17	2	0-Ring – Cap Seal
18	4	U-Cup – Piston Seal
19	2	Retaining Ring
20	2	Spring for -C Spring Closed Option
21*	-	BHCS – Wiper Mounting Screw
22*	-	Magnet
23*	-	S'assy, Cage & Roller Bearings

Notes:

- Contact the Robohand Sales Department for a complete spare parts list with order number and prices.
- 2)* Item #21 quantity varies per gripper size. Size -10M has 4 per unit. Sizes -14M, -20M have 8 per unit.
- 3)* Item #22 quantity varies per gripper size. Size -10M has 4 per unit. Sizes -14M, -20M have 2 per unit.
- 4)* Item #23 quantity and number of different sub-assemblies varies per gripper model. Contact Sales to determine the correct quantity and part numbers needed.
 - SK Seal Repair Kit Order #'s See Product Data Sheets

Non-Synchronous Procedure:

- 1) Remove preload screws, press out way locating pins, and slide out ways.
- 2) Pull out jaws and roller bearing assemblies. (If **-C** spring closed option, remove retaining rings, caps, and springs first.)
- 3) Remove linkage cover from body.
- 4) Remove equalizer and links from body.
- 5) Re-install linkage cover into body.
- 6) Re-install jaws and roller bearing assemblies into body aligning the drive pins with the hole in the linkage cover and each piston.
- 7) Re-install ways, press in way locating pins, and re-install preload screws. (If **-C** spring closed option, re-install springs, caps and retaining rings.)



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DPP SERIES ASSEMBLED VIEW



ltem	Qty	Name	
01	1	Body	
02	2	Jaw	-
03	2	Сар	
04	2	Piston	
05	1	Equalizer	_
06	2	Link	
08	1	Linkage Cover	
12	2	Drive Pin	_
14	1	Pivot Pin	_
23*	-	S'assy, Cage & Roller Bearings	_

Notes:

- 1) Contact the Robohand Sales Department for a complete spare parts list with order number and prices.
- 2)* Item #23 quantity and number of different sub-assemblies varies per gripper model. Contact Sales to determine the correct quantity and part numbers needed.

Accessory Installation & Adjustment Instructions



Magneto-Resistive Sensors:

- 1) Install sensors in profile slots of gripper body as shown.
- 2) Set sensors with integrated screw.

Inductive Sensors:

- 1) Insert sensor bracket (#30) into slot of body.
- 2) Insert dowel pin (#33) and target (#11)
- ínto jaw slot.
- 3) Insert sensor into bracket and adjust sensor depth so that sensor light indicates on target.
- 4) Tighten sensor locking screw (#31) to hold sensor depth.
- 5) Position sensor bracket for desired stroke detection.
- 6) Tighten sensor bracket with set screw (#32) to lock stroke detection position.



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Parallel Grippers w Profile Series



- Precision applications: Preloaded "Dual-V" roller bearings eliminate side play for excellent part position repeatability.
- Repeatable grip force: Low friction mechanism allows for consistent, repeatable gripping forces. To grip delicate parts, grip force can be easily altered by adjusting air pressure.
- Longer finger applications: Rigid design allows for longer gripper finger lengths to be used when compared to other grippers of equal weight & size.

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• Non-synchronous motion: The unit can be made non-synchronous providing independent jaw motion allowing the gripper to pick or place at a point other than it's center.

Mounting Information:

Grippers can be mounted & operated in any orientation





Body mounts with screws and locates with slip fit dowel pins for accuracy



Warning! Protect drive and bearing mechanism from falling debris when mounted upside down





Fingers attach to jaws with screws and locate by keying

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate

Imperial Metric 5-100 psi .3-7 bar **Dual Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Yes Yes (dry)

Air Quality Requirements Air

Air Filtration	40 Micron or Better
Air Lubrication	Not Necessary*
Air Humidity	Low Moisture Content (dr

Temperature Operating Range

-30°~180° F Buna-N Seals (standard) -35°~80° C Viton[®] Seals (optional) -20°~250° F -30°~120° C

Maintenance Specifications

Expected Life	
Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycles*
Field Repairable	Yes
Seal Repair Kits Available	Yes

Application Restrictions

- Dirty or gritty environments
- Machining operations generating chips
- · Environments with loose particulate Applications where mechanism lubricant could
- cause contamination

*Addition of lubrication will greatly increase service life *See Maintenance Section

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PARALLEL GRIPPER RPL-1M PRECISION DUAL "V" LOW PROFILE SERIES





Specifications	RPL-1	RPL-1M
Total Rated Grip Force F @ 100 psi, 7 bar	26 lbs.	116 N
Stroke	0.25 in.	6.4 mm
Weight	0.16 lbs.	0.07 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.438 in.	11.1 mm
Displacement	0.038 in ³ .	0.6 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation	0.10 sec.	0.10 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition



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PARALLEL GRIPPER RPL-2M **PRECISION DUAL "V" LOW PROFILE SERIES**



Specifications	RPL-2	RPL-2M
Total Rated Grip Force F @ 100 psi, 7 bar2	6 lbs.	116 N
Stroke	0.50 in.	12.7 mm
Weight	0.20 lbs.	0.09 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.438 in.	11.1 mm
Displacement	0.075 in ³ .	1.2 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-position	



[6.4]





Course Pitch

 $0.000 = \pm .005$ $0.0000 = \pm .0005$

[22.2]

JAW MOUNTING PATTERN

Loading Information

How to Order: (Order Accessories separately from Basic Model)

Projection



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

PARALLEL GRIPPER RPL-3M PRECISION DUAL "V" LOW PROFILE SERIES





Specifications	RPL-3	RPL-3M
Total Rated Grip Force F @ 100 psi, 7 bar	36 lbs.	160 N
Stroke	0.75 in.	19.1 mm
Weight	0.32 lbs.	0.15 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.500 in.	12.7 mm
Displacement	0.147 in ³ .	2.4 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation	0.14 sec.	0.14 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-position	



Loading Information

How to Order: (Order Accessories separately from Basic Model)



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PARALLEL GRIPPER RPL-4M PRECISION DUAL "V" LOW PROFILE SERIES



Specifications	RPL-4	RPL-4M
Total Rated Grip Force F @ 100 psi, 7 bar	36 lbs.	160 N
Stroke	1.00 in.	25.4 mm
Weight	0.38 lbs.	0.17 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.500 in.	12.7 mm
Displacement	0.196 in ³ .	3.2 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation	0.19 sec.	0.19 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition



[6.4]



Metric [mm]



Loading Information

[33.3]

How to Order: (Order Accessories separately from Basic Model)



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RPL Series Exploded View





ltem	Otv	Name
		1 1 1 1 1 1 1 1 1

01	1	Body
02	1	Piston
03	2	Сар
04	1	Equalizer
05	2	Link
06	4	Way
08	2	Jaw
13	2	Pin
20	1	Piston W/Magnet Slot
21	4	S'assy,Cage & Rollers
30	3	SHCS
31	1	Dowel Pin
32	2	Dowel Pin
40	2	Magnet

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install seals.
 2) Press dowel pin into center of body.
- Place links and equalizers into body.
 Press dowel pins into jaws.
- 5) Place jaws through links and into pistons.
- 6) İnstall cages on jaws.
- Place ways behind cages with flat facing out and install screws.
- 8) Adjust preload.

Preload Adjustment Procedure

- 1) Tighten center screw (#30) so that fingers bind slightly.
- 2) Tighten outer screws in the same fashion.
- 3) Cycle the gripper.
- 4) Re-adjust screws so that when you push the cage, the finger moves freely. (the finger movement should not feel gritty.)

Non-Synchronous Procedure

- 1) Remove preload screws (#30) and ways.
- 2) Remove cages, jaws and dowel pins.
- 3) Remove equalizer, links, and roller bearings.
- 4) Re-assemble jaws and dowel pins into pistons.
- 5) Re-install cages on jaws.
- 6) Place ways behind cages with flat facing out and install preload screws.
- 7) Adjust preload.



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RPL Se	ries <i>l</i>	Assem	bled	View
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Item	Qty	Name	
			_
01	1	Body	
02	1	Piston	-
03	2	Сар	_ `
04	1	Equalizer	-
05	2	Link	-
06	4	Way	-
08	2	Jaw	-
13	2	Bearing,Roller	-
20	1	Piston W/Magnet Slot	-
21	4	S'assy,Cage & Rollers	-
30	3	SHCS	-

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Dowel Pin

Dowel Pin

Magnet

Accessory Installation & Adjustment Instructions



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Parallel Grippers

Clean Room / Harsh Environments Series

• Precision applications:

Preloaded "Dual-V" roller bearings eliminate side play for excellent part position repeatability.

• Clean Room rated:

A corrosion resistant shield protects the drive and bearing mechanism. All internal components are lubricated with clean room grade lubricant. The scavenge port can be used with vacuum pressure to prevent escape

of particulate generated by the internal mechanism.

Mounting Information:

• Harsh environments:

All moving components are located within the stainless steel shield. The body has a purge port which can expel contaminates from the mechanism using low air pressure.

Repeatable grip force: Low friction mechanism allows for

consistent, repeatable gripping forces. To grip delicate parts, grip force can be easily altered by adjusting air pressure.

Longer finger applications:

Rigid design allows for longer gripper finger lengths to be used when compared to other grippers of equal weight.

• **Non-synchronous motion:** The unit can made non-synchronous providing independent jaw motion allowing the gripper to pick or place at a point other than it's center.

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate Imperial Metric 5-100 psi .3-7 bar Dual Double Acting Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements

Air Filtration	40 Micron or Better
Air Lubrication	Not Necessary*
Air Humidity	Low Moisture Content (dry)

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F -35°~80° C Viton® Seals (optional) -20°~250° F -30°~120° C

Maintenance Specifications

expected Life	
Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycles*
Field Repairable	Yes
Seal Repair Kits Available	Yes
Addition of lubrication will greatly increase service life	9

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Grippers can be mounted & operated in any orientation





Body mounts with screws and locates with slip fit dowel pins for accuracy



Shields provide protection from falling debris when mounted upside down







Fingers attach to jaws with screws and locate by keying

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RPLC SERIES

1.99

See **1.103**

• The synchronizing elements can be removed for non-synchronous operation.

U.S. Patent # 5,529,359 Designed and manufactured in the USA

PARALLEL GRIPPER RPLC-1M **PRECISION DUAL "V" CLEAN ROOM SERIES**



RPLC-1M





116 N 0.25 in. 6.4 mm 0.16 lb 0.07 Kg 5-100 psi 0.3-7 bar 0.438 in. 11.1 mm 0.038 in³. 0.6 cm3 -35°~80° C -30°~120° C -30°~180° F -20°~250° F 0.10 sec. 0.10 sec. ±0.05 mm ±0.002 in. ±0.001 in. ±0.03 mm 4-way, 2-position



N Ibs.	GRIP F	ORCE PER FIN	GER				
62 14 -	100 PSI [7	bar]				RASIC MODEL NON-SYNCHRONOL	21
53 12 -	80 PSI (5 F	barl	DO NOT E	ng! (Ceed		DASIO MODEL NOR-STROMOROO	0
🖁 44 10 -	00101[0.0		MAXIMUM EF	FECTIVE			
່ມ 35 8 -	60 PSI [4.1	bar]		Numb		KPLG-1 MENSEV	
101 26 6 -	40 PSI [2.7	barl					
			<u> </u>			METRIC VITON® SE	ALS
≧ 10 4 - L	20 PSI [1.4	bar]	`	2		INETINO VITOR OF	MLU
92-				7			
00-				÷		SENSOR ACCESSORIES** ORD	R # QTY/UNIT
	U I 0 25	2	, 7	3 m. 5mm		Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors) OSMK	-008 1
	EFFECTIV	e finger leng	TH - L			NPN Magneto Resistive Sensor with Quick Disconnect* OHSN	-017 1 or 2
		7		7		PNP Magneto Resistive Sensor with Quick Disconnect [*] UHSP Quick Disconnect 2 Motor Cable Longth*	-017 1 0r 2
			Mz <			Quick Disconnect 5 Meter Cable Length*	-010 1012
		<i>⊢</i> ⊐				PNEUMATIC ACCESSORIES	
i i i i i i i i i i i i i i i i i i i	T T	X		6 0		Fail Safe Valve (Imperial) OFSV	-001 1
			Y		х	Fail Safe Valve (Metric) OFSV	-004 1
li			F/2	F/2		Standard Seal Repair Kit SLKT	-010 1
t i i i i i i i i i i i i i i i i i i i		\sim				Viton [®] Seal Repair Kit SLKI-	U1UV 1
'		1	VIX	· IVIY		*Sensor and cable sold separately 'Piston magnet standard	
Loading	J Capacity [†]	Stat Imperial	ic Metric	Dyna Imperial	mic Metric		
Maximum Te	ensile T	50 lbs.	222 N	15 lbs.	67 N		
Maximum C	ompressive C	50 lbs.	222 N	15 lbs.	67 N		
Maximum N	loment M x	30 inIbs.	3.4 Nm	10 inIbs.	1.1 Nm		
Maximum N	loment My	40 inIbs.	4.5 Nm	12 inIbs.	1.4 Nm		30 [8]
Maximum N	loment Mz	30 inIbs.	3.4 Nm	10 inIbs.	1.1 Nm	╙╓┰ᢍ ╡╤╴2.30 [58] MIN.	MAX
[†] Capacities are	e per set of jaws and a	re not simultane	eous				

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PARALLEL GRIPPER RPLC-2M PRECISION DUAL "V" CLEAN ROOM SERIES

Specifications	RPLC-2	RPLC-2M
Total Rated Grip Force F @ 100 psi, 7 bar2	6 lb	116 N
Stroke	0.50 in.	12.7 mm
Weight	0.20 lb	0.09 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.438 in.	11.1 mm
Displacement	0.075 in ³ .	1.2 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-po	osition



GRIP FORCE PER FINGER N lbs 62 14 100 PSI [7 bar] **BASIC MODEL NON-SYNCHRONOUS** WARNING! 53 12 DO NOT EXCEED MAXIMUM EFFECTIVE 80 PSI [5.5 har] F/2 44 10 FINGER LENGTHS **RPLC-2** 60 PSI [4,1 bar FINGER FORCE 35 8 26 6 0 PSI **VITON® SEALS** METRIC 18 1 20 PSI [1.4 bar 92 SENSOR ACCESSORIES** ORDER # OTY/UNIT **OSMK-008** 0 0 Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors) 1 3 in. 2 NPN Magneto Resistive Sensor with Quick Disconnect* OHSN-017 1 or 2 Ô 25 50 75mm PNP Magneto Resistive Sensor with Quick Disconnect* OHSP-017 1 or 2 EFFECTIVE FINGER LENGTH - L Quick Disconnect 2 Meter Cable Length* CABL-010 1 or 2 CABL-013 Quick Disconnect 5 Meter Cable Length* 1 or 2 z Ζ **PNEUMATIC ACCESSORIES** Mz Fail Safe Valve (Imperial) **OFSV-001** 1 Fail Safe Valve (Metric) **OFSV-004** 1 Standard Seal Repair Kit **SLKT-010** 1 Viton® Seal Repair Kit SLKT-010V 1 С Т F/2 F/2 *Sensor and cable sold separately [†]Piston magnet standard . Mx M Static Dynamic rial Metric Loading Capacity FAIL SAFE MAGNETO RESITIVE Imperial Metric Imperial .36 [9] VALVE OPTION SENSOR OPTION -.63 [16] 89 N Maximum Tensile T 289 N 20 lb 65 lbs. Maximum Compressive C 65 lbs. 289 N 20 lb 89 N Фc \oplus Maximum Moment Mx 45 in.-Ibs. 5.1 Nm 15 in.-Ibs. 1.7 Nm \oplus Maximum Moment My 60 in.-lbs. 6.8 Nm 20 in.-lbs. 2.3 Nm ₩__ ¢ 0 .12 [3] MAX Maximum Moment Mz - 2.30 [58] MIN 45 in.-lbs. 5.1 Nm 15 in.-Ibs. 1.7 Nm *Capacities are per set of jaws and are not simultaneous

PARALLEL GRIPPER RPLC-3M PRECISION DUAL "V" CLEAN ROOM SERIES





Specifications	RPLC-3	RPLC-3M
Total Rated Grip Force F @ 100 psi, 7 bar	36 lb	160 N
Stroke	0.75 in.	19.1 mm
Weight	0.32 lb	0.15 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.500 in.	12.7 mm
Displacement	0.147 in ³ .	2.4 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation	0.14 sec.	0.14 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition
Valve required to actuate	4-way, 2-p	osition



IAW MOUNTING PATTERN

Loading Information

(SHOWN IN OPEN POSITION)



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

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Imperial in.

 $\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$

Metric [mm]

q ₽� $\mathbf{\Theta}$ Dimensions are Third Angle Projection All Dowel Holes are SF (Slip Fit). Metric Threads Course Pitch symmetrical about Locational Tolerance centerline ±.0005" or [±.013mm

How to Order: (Order Accessories separately from Basic Model)



Please see back cover for DE-STA-CO Global Locations. www.destaco.com



PARALLEL GRIPPER RPLC-4M PRECISION DUAL "V" CLEAN ROOM SERIES



Specifications	RPLC-4	RPLC-4M
Total Rated Grip Force F @ 100 psi, 7 bar	36 lb	160 N
Stroke	1.00 in.	25.4 mm
Weight	0.38 lb	0.17 Kg
Pressure Range	5-100 psi	0.3-7 bar
Cylinder Bore Ø	0.500 in.	12.7 mm
Displacement	0.196 in ³ .	3.2 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation	0.19 sec.	0.19 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-wav. 2-p	osition



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4X #5-40 X .15 DP [M3 X 4 DP]

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Loading Information

.224 .001 [5.69 0.03]

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How to Order: (Order Accessories separately from Basic Model)



RPLC SERIES 1.103

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

RPLC Series Exploded View





ltem	Qty	Name	

01	1	Body
02	1	Piston
03	2	Сар
04	1	Equalizer
05	2	Link
06	4	Way
08	2	Jaw
10	1	Cover, Bottom
11	2	Cover, Bottom, Corners
12	2	Cover, End
13	2	Bearing, Roller
20	1	Piston W/Magnet Slot
21	4	S'assy, Cage & Rollers
30	3	SHCS
31	1	Dowel Pin
32	2	Dowel Pin
40	0	Magnet

Note: contact the robohand sales department for a complete spare parts list with order numbers and prices.

Assembly procedure

- 1) Lubricate and install seals.
- 2) Glue magnets into one piston, install pistons, caps and retaining rings.
- 3) Press dowel pin into center of body.
- 4) Place links and equalizers into body.
- 5) Press dowel pins into jaws. 6) Place jaws through links and into pistons.
- 7) Install cages on jaws.8) Place ways behind cages with flat facing
- out and install screws.
- 9) Adjust preload.
- 10) Install bottom cover, bottom cover corners and end covers.

Preload adjustment procedure

- 1) Tighten center screw (#30) so that fingers 2) Tighten outer screws in the same fashion.
- Bind slightly.
- 3) Cycle the gripper.
- 4) Re-adjust screws so that when you push the cage, the finger moves freely. (the finger movement should not feel gritty.)

Non-synchronous procedure

- 1) Remove end covers, bottom cover corners, and bottom cover.
- 2) Remove preload screws (#30) and ways.
- 3) Remove cages, jaws and dowel pins.
- 4) Remove equalizer, links, and roller

bearings.

- 5) Re-assemble jaws and dowel pins into pistons.
- 6) Re-install cages on jaws.
- 7) Place ways behind cages with flat facing out and
- 8) Adjust preload. Install preload screws.
- 9) Re-attach bottom cover, bottom cover corners and end covers. Gripper is now non-synchronous.





Please see back cover for DE-STA-CO Global Locations. www.destaco.com



RPLC Series Assembled View

Name

Item Qty





01	1	Body
02	1	Piston
03	2	Сар
04	1	Equalizer
05	2	Link
06	4	Way
08	2	Jaw
10	1	Cover, Bottom
11	2	Cover, Bottom, Corners
12	2	Cover, End
13	2	Bearing, Roller
20	1	Piston W/Magnet Slot
21	4	S'assy, Cage & Rollers
30	3	SHCS
31	1	Dowel Pin
32	2	Dowel Pin
40	2	Magnet

Note: contact the robohand sales department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Parallel Grippers -Miniature Series 1.106



- Precision applications: Preloaded dual-"V" roller bearings eliminate side play for excellent part position repeatability.
- Miniature size: Compact design allows for gripping small parts in small spaces.
- Top manifold: Grippers can be manifolded through the top mounting surface. This eliminates the need for air fittings and allows grippers to be mounted in close array.
- Repeatable grip force: Low friction mechanism allows for consistent, repeatable gripping forces. To grip delicate parts, grip force can be easily altered by adjusting air pressure.

Unit has top

manifold ports



Mounting Information:

Grippers can be mounted & operated in any orientation



Fingers attach to jaws with screws and locate with dowel pins or by keying

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate

Imperial Metric 40-100 psi 1.3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

40 Micron or Better Not Necessary* Low Moisture Content (dry)

5 million cycles

Yes

Yes

10+ million cycles*

Temperature Operating Range

-30°~180° F Buna-N Seals (standard) Viton[®] Seals (optional) -20°~250° F

-35°~80° C -30°~120° C

Maintenance Specifications[†]

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available

Application restrictions

Dirty or gritty environments Machining operations generating chips Environments with loose particulate Applications where mechanism lubricant could cause contamination *Addition of lubrication will greatly increase service life

*See Maintenance Section



RPM SERIES

1.107

- motion of the wedge into horizontal synchronous motion of the jaws.
- This gripper is suitable for internal or external gripping.

U.S. Patent #5,529,359 & #5,125,708 Designed and manufactured in the USA

PARALLEL GRIPPER RPM-1M MINIATURE SERIES





Loading Information



RPM-1M Specifications Total Rated Grip Force F @ 100 psi, 7 bar8 lbs. 36 N 3.2 mm Stroke..... .13 in. Weight 0.052 lbs. 0.024 Kg Pressure Range..... 40-100 psi 3-7 bar Cylinder Bore Ø 0.394 in. 10.0 mm Displacement 0.008 in³. 0.13 cm3 Temperature Range -35°~80° C Standard Seals -30°~180° F -30°~120° C Viton® Seals -20°~250° F Actuation 0.10 sec. 0.10 sec. ±0.05 mm Accuracy..... +0.002 in Repeatability..... ±0.001 in. ±0.03 mm Valve required to actuate 4-way, 2-position



Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]
Metric Threads Course Pitch	Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .000$	Metric [mm] [0.] = [±.25] [0.0] = [±.13] 5 [0.00] = [+.013]





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2X M2 AUX. AIR PORTS-

SUPPLIED PLUGGED

(CLOSE)

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2X M2 X .18 [4.5] DP

[12.00] [16.0]

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OPEN

.630

2X Ø .0787 SF X .13 DP

[Ø 2 H7 X 3.3 DP]

2X M3 AIR PORTS

.98

[25]

(OPEN)

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Specifications RPM-2M Total Rated Grip Force F @ 100 psi, 7 bar8 lbs. 36 N Stroke..... 4.8 mm .19 in. 0.058 lbs. 0.026 Kg Weight Pressure Range 40-100 psi 3-7 bar Cylinder Bore Ø 0.394 in. 10.0 mm Displacement 0.012 in³. 0.20 cm3 Temperature Range -35°~80° C -30°~180° F Standard Seals -30°~120° C -20°~250° F Viton® Seals Actuation .. 0.10 sec. 0.10 sec. ±0.05 mm Accuracy..... ±0.002 in. Repeatability..... ±0.001 in. ±0.03 mm

Valve required to actuate

4-way, 2-position



TOLERAN	CES ARE AS	SHOWN BELOW
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]
Metric Threads Course Pitch	$\begin{array}{l} \text{Imperial in.}\\ 0.00 = \pm .01\\ 0.000 = \pm .005\\ 0.0000 = \pm .000 \end{array}$	Metric [mm] [0.] = [±.25] [0.0] = [±.13] 5 [0.00] = [±.013]

Loading Information

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How to Order: (Order Separately) **GRIP FORCE PER FINGER** N lbs 20 4.5 WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE 100 PSI [7 har] 18 **4.0** 16 3.5 **BASIC MODEL** 80 PSI [5.5 bar] FINGER LENGTHS 13 **3.0** FINGER FORCE 60 PSI [4.1 bar] **RPM-2M -** V 11 2.5 9 2.0 . 40 PSI [2.7 bar] 7 1.5 20 PSI [1.4 bar] **VITON® SEALS** 4 1.0 2 0.5 PNEUMATIC ACCESSORIES QTY/UNIT 0 0 Order # .25 6 1.25 32 1.5 in 0 .5 .75 19 1 M3 Plumbing Fitting Push-in for 3mm 0.D. Tube PLFT-021 2 Õ 13 25 EFFECTIVE FINGER LENGTH - L M3 Plumbing Fitting Barb for 2mm I.D. Tube PLFT-022 2 Standard Seal Repair Kit SLKT-121 1 z Viton® Seal Repair Kit SLKT-121V 1 M₂ Top Air Ports Manifold Seal Kit (available in Viton® only) SLKT-142V 1 0 0 0 R X Т c F/2 F/2 M× M PLFT-021 **PLFT-022** Static Dynamic AIR FITTING Loading Capacity[†] AIR FITTING SLKT-142V Imperial Metric Imperial Metric O-RINGS FOR Maximum Tensile T 20 lbs. 89 N 7 lbs. 31 N MANIFOLD OPTION 0 Q Maximum Compressive C 89 N 31 N (C'BORE Ø.125 X .022.001 DP) 20 lbs. 7 lbs. M3 PLUGS FOR Maximum Moment Mx 12 in.- lbs. 1 Nm 4 in.-lbs. 0.5 Nm 4 MANIFOLD OPTION Maximum Moment My 15 in.-Ibs. 2 Nm 5 in.-lbs. 0.6 Nm ൘ Maximum Moment Mz 12 in.-lbs. 1 Nm 4 in.-lbs. 0.5 Nm [16] .68 [17] *Capacities are per set of jaws and are not simultaneous

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

PARALLEL GRIPPER RPM-3M MINIATURE SERIES





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RPM-3M **Specifications** Total Rated Grip Force F @ 100 psi, 7 bar8 lbs. 36 N Stroke..... 6.3 mm .25 in. Weight 0.074 lbs. 0.034 Kg Pressure Range..... 40-100 psi 3-7 bar Cylinder Bore Ø 10.0 mm 0.394 in. Displacement 0.015 in³. 0.25 cm3 Temperature Range -30°~180° F -35°~80° C Standard Seals -30°~120° C Viton® Seals -20°~250° F Actuation ... 0.10 sec. 0.10 sec. ±0.05 mm Accuracy..... ±0.002 in. Repeatability..... ±0.001 in. ±0.03 mm Valve required to actuate 4-way, 2-position





Loading Information

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Loading Capacity ⁺	Statio Imperial	: Metric	Dyna Imperial	mic Metric
Maximum Tensile T	20 lbs.	89 N	7 lbs.	31 N
Maximum Compressive C	20 lbs.	89 N	7 lbs.	31 N
Maximum Moment M _X	12 inIbs.	1 Nm	4 inIbs.	0.5 Nm
Maximum Moment My	15 inIbs.	2 Nm	5 inIbs.	0.6 Nm
Maximum Moment Mz	12 inIbs.	1 Nm	4 inIbs.	0.5 Nm
[†] Capacities are per set of jaws and are	not simultaneous			

How to Order: (Order Separately)

BASIC MODEL RPM-3M - V VITON® SEALS

PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
M3 Plumbing Fitting Push-in for 3mm 0.D. Tube	PLFT-021	2
M3 Plumbing Fitting Barb for 2mm I.D. Tube	PLFT-022	2
Standard Seal Repair Kit	SLKT-121	1
Viton [®] Seal Repair Kit	SLKT-121V	1
Top Air Ports Manifold Seal Kit (available in Viton® only)	SLKT-142V	1









RPM Series Exploded View

Item Qty Name

01	1	Body
02	2	Jaw
03	1	Wedge
04	1	Piston
05	1	Сар
06	2	Way
07	4	Kit, Roller Bearings And Cage
08	1	Preload
12	2	Dowel Pin
15	4	Stop Screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install seals
- 2) Install pins (12) and wedge (3) into body
- 3) Install piston (4), screw, cap (5), & retaining ring
- 4) Install set screws for airport plugs
- 5) Install jaws (2) over pins
- 6) Install ways (6), cages (7), & screws (15)

Preload Adjustment

- 1) Install preload screw (8) w/Loctite on 1st 6-8 threads
- 2) Tighten until there is no side-pay in the jaws
- 3) Cycle gripper (w/fingers preferably)
- 4) Recheck for play in jaws & tighten or loosen as needed





RPM Series Assembled View



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Item Qty Name

01	1	Body
02	2	Jaw
03	1	Wedge
04	1	Piston
05	1	Сар
06	2	Way
07	4	Kit, Roller Bearings And Cage
08	1	Preload
12	2	Dowel Pin
15	4	Stop Screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Non-Repairable Items List NONE



RECIDESIGN NOTES RPM SERIES 1.113

Parallel Grippers Miniature Clea Room Se P



1.114

• Precision applications:

Preloaded dual-"V" roller bearings eliminate side play for excellent part position repeatability.

• Miniature size: Compact design allows for gripping small parts in small spaces.

 Top manifold: Grippers can be manifolded through the top mounting surface. This eliminates the need for air fittings and allows grippers to be mounted in close array.

Clean room rated:

A corrosion resistant shield protects the drive and bearing mechanism. All internal components are lubricated with clean room grade grease. The scavenge port can be used with vacuum pressure to prevent escape of particulate generated by the internal mechanism.

Harsh environments:

All moving components are located within the corrosion resistant cover. The body has a purge port which can expel contaminates from the mechanism using low pressure compressed air.

Mounting Information:

Grippers can be mounted & operated in any orientation



Body mounts with screws and locates with slip fit dowel pins for accuracy



Unit has top manifold ports



Fingers attach to jaws with screws and locate with dowel pins or by keying

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements Air Fil

Air Filtration	40 Micron or Better
Air Lubrication	Not Necessary*
Air Humidity	Low Moisture Content (dry)

Temperature Operating Range

-30°~180° F Buna-N Seals (standard) -35°~80° C Viton[®] Seals (optional) -20°~250° F -30°~120° C

Maintenance Specifications[†]

Expected Life Normal Application 5 million cycles w/ Preventative Maintenance 10+ million cycles* Field Repairable Yes Seal Repair Kits Available Yes *Addition of lubrication will greatly increase service life See Maintenance Section





RPMC SERIES

1.115

- The pin wedge slides in a hole located in each of the jaws converting vertical motion of the wedge into horizontal synchronous motion of the jaws.
- This gripper is suitable for internal or external gripping.

U.S. Patent #5,529,359 & #5,125,708 Designed and manufactured in the USA

PARALLEL GRIPPER RPMC-1M MINIATURE CLEAN ROOM SERIES



-2 X M2 X 0 4 X 09 DP



Specifications	RPMC-1	IM
Total Rated Grip Force F @ 100 psi, 7 bar8	3 lb	36 N
Stroke	.13 in.	3.2 mm
Weight	0.052 lb	0.024 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.394 in.	10.0 mm
Displacement	0.008 in ³ .	0.13 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation Time	0.10 sec.	0.10 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition



Loading Information



How to Order: (Order Separately)

BASIC MODEL		
RPMC-1M -		
VIIUN	JEAL3	
TIC ACCESSORIES	ORDER #	QTY/UNIT
ing Fitting Push-in for 3mm 0.D. Tube	PLFT-021	2

M3 Plumbing Fitting Push-in for 3mm 0.D. Tube	PLFT-021	2	
M3 Plumbing Fitting Barb for 2mm I.D. Tube	PLFT-022	2	
Standard Seal Repair Kit	SLKT-121	1	
Viton [®] Seal Repair Kit	SLKT-121V	1	
Top Air Ports Manifold Seal Kit (available in Viton® only)	SLKT-143V	1	

For Detailed Accessory Mounting Technical Data Refer to Accessories Section



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

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PARALLEL GRIPPER RPMC-2M MINIATURE CLEAN ROOM SERIES

Specifications	RPMC-2	M
Total Rated Grip Force F @ 100 psi, 7 bar8	lb	36 N
Stroke	.19 in.	4.8 mm
Weight	0.058 lb	0.026 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.394 in.	10.0 mm
Displacement	0.012 in ³ .	0.20 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation Time	0.10 sec.	0.10 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-po	osition



UNLESS OTHERWISE NOTED ALL				
TOLERAN	CES ARE AS	SHOWN BELOW		
Ģ	\Rightarrow	\bullet		
Dimensions are symmetrical about centerline	Third Angle A Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]		
\oplus	Imperial in.	Metric [mm]		
Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$		

Loading Information

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*Capacities are per set of jaws and are not simultaneous

How to Order: (Order Separately)

BASIC MODEL RPMC-2M-V

VITON® SEALS

PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
M3 Plumbing Fitting Push-in for 3mm 0.D. Tube	PLFT-021	2
M3 Plumbing Fitting Barb for 2mm I.D. Tube	PLFT-022	2
Standard Seal Repair Kit	SLKT-121	1
Viton [®] Seal Repair Kit	SLKT-121V	1
Top Air Ports Manifold Seal Kit (available in Viton® only)	SLKT-143V	1

For Detailed Accessory Mounting Technical Data Refer to Accessories Section



PARALLEL GRIPPER RPMC-3M MINIATURE CLEAN ROOM SERIES





Specifications	RPMC-	3M
Total Rated Grip Force F @ 100 psi, 7 bar8	lb	36 N
Stroke	.25 in.	6.3 mm
Weight	0.074 lb	0.034 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.394 in.	10.0 mm
Displacement	0.015 in ³ .	0.25 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~250° F	-30°~120° C
Actuation Time	0.10 sec.	0.10 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm

Valve required to actuate



VIEW A-A

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are $\triangleright \odot$ € All Dowel Holes are SF (Slip Fit). Third Angle symmetrical about Projection Locational Tolerance centerline ±.0005" or [±.013mm] ٩ Imperial in. Metric [mm] $\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$ Metric Threads Course Pitch

4-way, 2-position

Loading Information



How to Order: (Order Separately)

BASIC MODEL		
RPMC-3M	I-V	
VITO	N [®] SEALS	
C ACCESSORIES	ORDER #	QTY/UNIT
a Fitting Duch in for 2mm 0 D. Tuha		•

M3 Plumbing Fitting Push-in for 3mm 0.D. Tube	PLFT-021	2	
M3 Plumbing Fitting Barb for 2mm I.D. Tube	PLFT-022	2	
Standard Seal Repair Kit	SLKT-121	1	
Viton® Seal Repair Kit	SLKT-121V	1	
Top Air Ports Manifold Seal Kit (available in Viton® only)	SLKT-143V	1	

For Detailed Accessory Mounting Technical Data Refer to Accessories Section



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

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RPMC Series Exploded View

Item Qty Name



01	1	Body
02	2	Jaw
03	1	Wedge
04	1	Piston
05	1	Сар
06	2	Way
07	4	Kit, Roller Bearings And Cage
08	1	Screw, Preload
10	2	Shield,Side
11	1	Shield,Top
12	2	Dowel Pin
15	4	Stop Screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedures

- 1) Lubricate and install seals.
 2) Install pins (12) and wedge (3) into body.
- 3) Install piston (4), screw, cap (5), & Retaining Ring.
- 4) Install set screws for air port plugs.
 5) Install jaws (2) over pins.
- 6) Install ways (6), cages (7), & screws (15).

- Preload Adjustment 1) Install preload screw (8) with Loctite on first 6 -8 threads. 2) Tighten until there is no side play in
- the jaws.
- 3) Cycle gripper(w/finger assembly)4) Recheck for play in jaws & tighten or loosen as needed.



Seal Repair Kit Order #'s **See Product Data Sheets**



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

RPMC Series Assembled View

Item Qty Name

01	1	Body
02	2	Jaw
03	1	Wedge
04	1	Piston
05	1	Сар
06	2	Way
07	4	Kit, Roller Bearings And Cage
08	1	Screw, Preload
10	2	Shield,Side
11	1	Shield,Top
12	2	Dowel Pin
15	4	Ston Screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.





Parallel Grippers -DPG DIRECTCONNECT™ Modular Series



- Multiple mounting locations: DIRECTCONNECT[™] mounting on top and back of body. Fingers mount to sides or bottom of jaws.
- Multiple air port positions: Tapped air ports on front and both sides are standard. Top air ports with counterbores for o-ring manifolded operation and threads for screw-in type fittings are available.

C(0)

• Sensing options: Magneto resistive (Hall Effect) or inductive proximity sensors available.

DREC

- Sense up to four positions: Up to four jaw positions can be sensed to allow open, closed, part present, or variable part size sensing.
- **Shielded to repel contaminate:** Design repels chips and particulate. Closed jaw position spacing eliminates "chip compactor" effect.
- Longer finger applications: Rigid design and full body support of jaw allows for longer finger lengths.
- Spring assist, spring return: Cylinders can be double acting, double acting spring assist, failsafe, or single acting in either open or closed direction.

10

- Non-synchronous motion: Non-synchronous motion option provides independent jaw motion allowing the gripper to pick or place at a point other than it's center.
- Single jaw motion with fixed jaw: This option locks one jaw in a fixed position while the other jaw is free to move.

Mounting Information:

Grippers can be mounted & operated in any orientation



Body mounts with screws and locates with slip fit dowel pins for accuracy



Fingers attach with screws and locate on jaws by keying or dowel pin holes

Technical Specifications: **Pneumatic Specifications** Imperial Metric Pressure Operating Range 40-100 psi 3-7 bar Cylinder Type **Double Acting** or Single Acting Spring Return or Double Acting Spring Assist **Dynamic Seals** Internally Lubricated Buna-N Valve Required 4-way, 2-position for Double Acting to Operate or 3-way, 2-position for Single Acting **Air Quality Requirements** Air Filtration 40 Micron or Better Not Necessary* Air Lubrication Low Moisture Content (dry) Air Humidity **Temperature Operating Range** Buna-N Seals (standard) -30°~180° F -35°~80° C Viton[®] Seals (optional) -20°~300° F -30°~150° C

Maintenance Specifications[†]

5 million cycles
10+ million cycles*
Yes
Yes

Application Restrictions

Applications where mechanism lubricant could cause contamination

*Addition of lubrication will greatly increase service life *See Maintenance Section

DPG SERIES

1.122





PARALLEL GRIPPER DPG-10M-1 DIRECTCONNECT[™] MODULAR SERIES





Ex: DPG-10M Gripper, Metric, Size 1, Spring Close, Viton® Seals

SERIES DPG











Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open	6 lbs.	26 N	9 lbs.	40 N
@ Full Close	11 lbs.	49 N	6 lbs.	26 N

Specifications	DPG-10N	1-1
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	0.25 in.	6.4 mm
Weight	0.39 lbs.	0.17 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.688 in.	17.5 mm
Displacement	0.076 in ³ .	1.2 cm ³

Accessory Mounting Technical Data







<i>N</i> aximum Tensile T	175 lbs. [778 N]	20 lbs. [89 N]
Aaximum Compressive C	400 lbs. [1779 N]	20 lbs. [89 N]
/laximum Moment Mx	150 in1bs. [17 Nm]	20 in1bs. [2 Nm]
/laximum Moment My	175 in1bs. [20 Nm]	30 in1bs. [3 Nm]
Naximum Moment Mz	150 in1bs. [17 Nm]	20 in1bs. [2 Nm]
Canacities are per set of jaws and are	not simultaneous	

is are per set of jaws and are not simulta

Specifications (cont.)	DPG-	10M-1
Temperature Range: Standard Seals Viton® Seals	-30°~180° F -20°~300° F	-35°~80° C -30°~150° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	± 0.002 in.	±0.05 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate	4-way, 2-p	osition



- · Choose from magneto resistive and inductive prox
- · Capable of sensing 4 positions open and closed on both jaws PNP and NPN available
- · Magneto resistive sensors are slot mounted, no mounting
- kits required
- Threaded quick disconnect with built-in led output
- · Sensors mount on either side of gripper



· Available for 5mm OD tubing

Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com

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PARALLEL GRIPPER DPG-10M-2 DIRECTCONNECT™ MODULAR SERIES





Ex: DPG-10M Gripper, Metric, Size 2, Spring Close, Left Jaw Fixed, Viton® Seals

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

www.comoso.com

DPG SERIES

1.126







Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open	6 lbs.	26 N	14 lbs.	62 N
@ Full Close	15 lbs.	66 N	6 lbs.	26 N

Specifications	DPG-10	1-2
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	0.50 in.	12.7 mm
Weight	0.53 lbs.	0.24 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.688 in.	17.5 mm
Displacement	0.153 in ³ .	2.5 cm ³

Accessory Mounting Technical Data





Maximum Tensile T 200 lbs. [890 N] 25 lbs. [111 N] Maximum Compressive C 425 lbs. [1890 N] 25 lbs. [111 N] Maximum Moment Mx 175 in.-1bs. [20 Nm] 25 in.-1bs. [3 Nm] Maximum Moment My 200 in.-1bs. [23 Nm] 35 in.-1bs. [4 Nm] Maximum Moment Mz 175 in.-Ibs. [20 Nm] 25 in.-Ibs. [3 Nm]

*Capacities are per set of jaws and are not simultaneous

Specifications (cont.)	DPG-	10M-2
Temperature Range: Standard Seals	-30°~180° F -20°~300° F	-35°~80° C -30°~150° C
Actuation	0.19 sec.	0.19 sec.
Accuracy Reneatability	±0.002 in. +0.002 in	±0.05 mm ±0.05 mm
Valve required to actuate	4-way, 2-p	osition



Flow Controls · Thumb screw adjust with locking nut



· Available for 5mm OD tubing



PARALLEL GRIPPER DPG-10M-3 DIRECTCONNECT[™] MODULAR SERIES





SAMPLE ORDER: DPG-10M-3-C-RF-V Ex: DPG-10M Gripper, Metric, Size 3, Spring Close, Right Jaw Fixed, Viton* Seals

SERIES

DPG

1.128



PARALLEL GRIPPER DPG-10M-3 DIRECTCONNECT **MODULAR SERIES**







Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open	6 lbs.	26 N	15 lbs.	66 N
@ Full Close	23 lbs.	102 N	6 lbs.	26 N

Specifications	DPG-10	DM-3
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	0.75 in.	19.1 mm
Weight	0.68 lbs.	0.30 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.688 in.	17.5 mm
Displacement	0.230 in ³ .	3.8 cm ³

Accessory Mounting Technical Data



Maximum Tensile T	225 lbs. [1001 N]	30 lbs. [133 N]
Maximum Compressive C	450 lbs. [2002 N]	30 lbs. [133 N]
Maximum Moment Mx	200 in1bs. [23 Nm]	30 in1bs. [3 Nm]
Maximum Moment My	225 in1bs. [25 Nm]	40 in1bs. [5 Nm]
Maximum Moment Mz	200 in1bs. [23 Nm]	30 in1bs. [3 Nm]
Capacities are per set of jaws and are not	simultaneous	

Specifications (cont.)	DPG-10M-3	
Temperature Range: Standard Seals Viton® Seals Actuation Accuracy Repeatability Valve required to actuate	-30°~180° F -20°~300° F 0.29 sec. ±0.002 in. ±0.002 in. 4-way. 2-p	-35°~80° C -30°~150° C 0.29 sec. ±0.05 mm ±0.05 mm
•	27 1	



PARALLEL GRIPPER DPG-10M-4 DIRECTCONNECT[™] MODULAR SERIES



NPN Magneto Resistive Sensor w/Qk. Disconnect*

PNP Magneto Resistive Sensor w/Qk. Disconnect*

Quick Disconnect Cable (2 meters long)*

Quick Disconnect Cable (5 meters long)*

PNEUMATIC ACCESSORIES

Standard Seal Repair Kit

Viton[®] Seal Repair Kit

NPN Magneto Resistive Sensor (90°) w/Qk. Disconnect*

PNP Magneto Resistive Sensor (90°) w/Qk. Disconnect*

Quick Disconnect Cable Extension Cord (1 meter long)*

Quick Disconnect Cable Extension Cord (2 meters long)*

-T Option Plumbing Fitting - M3 male to 3mm OD Tube Push-in Style

-T Option Plumbing Fitting - M3 male to 2mm ID Tube Barb Style

OHSN-017

OHSP-017

OHSN-011

OHSP-011

CABL-010

CABL-013

CABL-015

CABL-016

ORDER #

SLKT-183

SLKT-183V

PLFT-021

PLFT-022

OFSV-004

VLVF-008

SLKT-184V

1,2,3, or 4

QTY/UNIT

1

1

1 or 2

1 or 2

1

1 or 2

1

SPRING DIRECTION

CONFIGURATION

JAW SYNCHRONIZATION

SERIES

DPG

1.130

Fail Safe Valve - M5 (Metric) Adjustable Flow Control (Metric) Top Port Manifold Seal Kit *Sensor and cable sold separately SAMPLE ORDER: DPG-10M-4-0-NS-V Ex: DPG-10M Gripper, Metric, Size 4, Spring Open, Non-Synchronous Jaws, Viton® Seals

VITON® SEALS

Spring Open Spring Closed Leave Blank. No Spring Option (standard)

Non-Synchronous Jaws Leave Blank for Synchronous (standard)

JAW SYNC

Left Jaw Fixed

Right Jaw Fixed

0

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LF

RF

NS

(See Below)

Please see back cover for DE-STA-CO Global Locations. www.destaco.com



PARALLEL GRIPPER DPG-10M-4 DIRECTCONNECT[™] MODULAR SERIES

Ζ

Mz







Total Additional Grip Force	Spring	Open	Spring	Close
@ Full Open	6 lbs.	26 N	15 lbs.	66 N
@ Full Close	22 lbs.	97 N	6 lbs.	26 N

Specifications DPG-10M-4		M-4
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	1.00 in.	25.4 mm
Weight	0.81 lbs.	0.36 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.688 in.	17.5 mm
Displacement	0.306 in ³ .	5.0 cm ³

Accessory Mounting Technical Data





[†]Capacities are per set of jaws and are not simultaneous

Specifications	DPG-10M-4	
Temperature Range: Standard Seals	-30°~180° F -20°~300° F	-35°~80° C -30°~150° C
Actuation	0.40 sec.	0.40 sec.
Repeatability	± 0.002 m. ± 0.002 in.	$\pm 0.05 \text{ mm}$ $\pm 0.05 \text{ mm}$
Valve required to actuate	4-way, 2-position	



- Sensors
- Choose from magneto resistive and inductive prox
 Conclusion of accepting 4 positions area and closed on both interview.
- Capable of sensing 4 positions open and closed on both jaws
 DND and NDN available
- PNP and NPN available
- Magneto resistive sensors are slot mounted, no mounting
- kits required
- Threaded quick disconnect with built-in led output
- Sensors mount on either side of gripper



Flow Controls
 Thumb screw adjust with locking nut for adjusting actuation time

Available for 5mm 0D tubing

DPG SERIES EXPLODED VIEW



ltem	Qty	Name
01	1	Body
02	2	Jaw
03	2	Сар
04	2	Piston
05	2	Drive Pin
06	2	Synchronizing Bar
07	1	Equalizer
08	2	Retaining Ring
09	1	Pivot Pin
10	4	Magnet
11	4	Targets for Inductive
		Sensors
12	2	Set Screw - Drive Pin
		Access Plug
13	2	Equalizer/Synchronizing
		Bar pivot pin
14	4	Set Screw - End Port
		Plugs
15	2	O-ring - Top Porting
		Manifold Seals (-T option)
<u>16</u>	2	O-ring - Cap Seals
<u>17</u>	4	U-cup - Piston Seals
18	2	Springs for "-0"
		Spring-Open Option
19	2	Springs for "-C"
		Spring-Closed Option
21	3	Set Screw - Internal
		Porting Plugs
23	2	Set Screw - Side Porting
		Plugs (-T option)
39	1	Set Screw - Plug (-LF
		and -RF options only)

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



Assembly Procedure

- 1) Lubricate body.
- 2) Plug cross ports in body.
- 3) Press pivot pin into body.
- Insert magnets into pistons making sure magnets attract to each other.
- 5) Lubricate and install seals onto pistons.
- Insert pistons into body aligning drive pin hole in pistons with the drive pin hole in the body.
- 7) Press pins into equalizer.
- 8) Assemble equalizer with synchronizing bars and place onto pivot pin in body

making sure holes in synchronizing bars line up with holes in pistons.9) From top body mounting surface insert

- From top body mounting surface insert drive pins through the pistons and into the synchronizing bars making sure not to go through the synchronizing bars.
- 10) Place jaws into body aligning the drive pins with the hole in the jaws.
- 11) Press drive pins into jaws.
- 12) Install drive pin plugs into body.
- 13) Place seals onto caps and install with retaining rings.

Non-Synchronous Procedure

- Remove drive pin plugs.
 Press drive pins out of body from
- jaw side.
- 3) Remove jaws from body.
- Remove equalizer and synchronizing bars from body.
- 5) Re-install jaws into body aligning the drive pin with the hole in the jaws
- 6) Press drive pins into jaws.
- 7) Re-install drive pin plugs into body.



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DPG	SERIES	ASSEMBLED	VIEW
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Item Qty Name

01	1	Body
02	2	Jaw
03	2	Сар
04	2	Piston
05	2	Drive Pin
06	2	Synchronizing Bar
07	1	Equalizer
09	1	Pivot Pin
12	2	Set Screw - Drive Pin
		Access Plug
39	1	Set Screw - Plug (-LF and
		-RF options only)

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation:

Magneto Resistive Sensors

- 1) Install sensors in profile slots of gripper body as shown.
- 2) Set sensors with integrated screw.

Inductive Sensors

- Insert sensor bracket into slot of body.
 Insert sensor into bracket and adjust
- Insert sensor into bracket and adjust sensor depth so that sensor light indicates on target.
- 3) Tighten sensor locking screw (#31) to hold sensor depth.
- 4) Position sensor bracket for desired stroke detection.
- 5) Tighten sensor bracket with setscrew (#32) to lock stroke detection position.



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

Parallel Grippers -DPDS DIRECTCONNECT[™] Modular Series



- Multiple mounting locations: DIRECTCONNECT[™] tapped and dowel mounting on top and back of body.
- **Thru-body mounting:** Front-to-back thru-body mounting.
- **Multiple air port positions:** Tapped air ports on front, top, and back sides are standard.
- Front purge/scavenge port: Negative pressure used as a scavenge port for clean room applications. Positive pressure used as a purge port to repel contaminants in harsh environments. Port can also be used for lubrication.
- Manifold air porting: Top and back air ports can be manifold o-ring sealed.
- **Sensing:** Full range adjustable magneto resistive sensors.
- Different strokes: All gripper sizes are available in 3 different strokes.
- **Multiple jaw styles:** All sizes available with end mounts jaws as standard or bottom mount jaws as an option.
- Long finger applications: Rigid design and full body support of jaws allows for longer finger lengths.

Mounting Information:

Grippers can be mounted & operated in any orientation

Body mounts with screws and locates with slip fit dowel pins for accuracy



BOTTOM JAW MOUNTING

Fingers attach with screws and locate on jaws by keying and/or dowel pins. Fingers can be mounted in any orientation with respect to the jaw.

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate	Imperial 20-100 psi Double Internally Lubr 4-way, 2	Metric 1.5-7 bar Acting ricated Buna-N -position
Air Ouality Requirements		
Air Filtration Air Lubrication Air Humidity	40 Micro Not Nece Low Moisture	n or Better essary* Content (dry)
Comporatura Aparating Bar		
Buna-N Seals (standard) /iton® Seals (optional)	-30°~180° F -20°~300° F	-35°~80° C -30°~150° C
Maintenance Specification	S [†]	
Expected Life Normal Application	5 million	cycles
w/ Preventative Maintenanc	e 10+ milli	on cycles*
Field Repairable	Yes	S
Seal nepali nils Avallable	te	5

Application Restrictions

Applications where mechanism lubricant could cause contamination (use DPDL gripper with **-E** sealed jaw option) *Addition of lubrication will greatly increase service life 'See Maintenance Section

Please see back cover for DE-STA-CO Global Locations. www.destaco.com



U.S. Patent # 5,125,708 **Designed and manufactured in the USA**

PARALLEL GRIPPER DPDS-047M DIRECTCONNECT™ MODULAR SERIES





SERIES

DPDS

1.136


PARALLEL GRIPPER DPDS-047M DIRECTCONNECT[™] MODULAR SERIES

-B Option Shown

ТС_⊮Мх

Static

F/2

-My

Loading Information



Specifications	DPDS-04	17M
Total Rated Grip Force F @ 100 psi, 7 bar	14 lbs	-62 N
Maximum Stroke	0.13 in.	–3.2 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Maximum Pressure for Purge Port	20 psi	1.4 bar
Cylinder Bore Ø	0.469 in.	11.9 mm
Displacement	0.013 in ³ .	0.2 cm ³

Accessory Mounting Technical Data

[18.2]

OHSP-01

OHSN-011 OHSP-017

Sensors

.16 [4]

OHSN-017



Loading Capacity[†]

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

DPDS-047M

Maximum Tensile T

- **Manifold O-Ring Seals**
- · Can be used to seal front, top, or back
- air ports and front purge/scavenge port Seals in Manifold kit are Viton[®]
- O-Ring C'bores in customer's mounting plate must be:
- Ø.215 [Ø5.5] X .060±.002 [1.52±.05] deep

· Kit is supplied with all seals, plugs, & wrenches needed

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Multiple Air Port Locations

BACK SURFACE

• 3 standard M3 air port locations (front, top, and back surface)

· Top and Back air ports are plugged as standard

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

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Dynamic 30 lbs. [134 N] 6 lbs. [27 N] 50 lbs. [223 N] 10 lbs. [45 N] 20 in.-1bs. [2 Nm] 5 in.-1bs. [0.6 Nm] 5 in.-1bs. [0.6 Nm] 20 in.-Ibs. [2 Nm] 20 in.-1bs. [2 Nm] 5 in.-1bs. [0.6 Nm]

F/2

DPDS-047M-B (Bottom Jaw Mounting Option)			
Maximum Tensile T	24 lbs. [107 N]	5 lbs. [22 N]	
Maximum Compressive C	40 lbs. [178 N]	8 lbs. [36 N]	
Maximum Moment Mx	16 in1bs. [2 Nm]	4 in1bs. [0.5 Nm]	
Maximum Moment My	16 in1bs. [2 Nm]	4 in1bs. [0.5 Nm]	
Maximum Moment Mz	16 in1bs. [2 Nm]	4 in1bs. [0.5 Nm]	
*Capacities are per set of jaws and are not simultaneous			

Specifications (cont.)	DPDS-047M	
Weight Temperature Bange: Standard Seals	0.086 lbs. -30°~180° F	0.04 Kg -35°~80° C
Viton [®] Seals	-20°~300° F 0.13 sec.	-30°~150° C 0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve Required to Actuate	4-way, 2-position	

PARALLEL GRIPPER DPDS-056M DIRECTCONNECT™ MODULAR SERIES







PARALLEL GRIPPER DPDS-056M DIRECTCONNECT™ MODULAR SERIES

-B Option Shown

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Specifications	DPDS-05	56M
Total Rated Grip Force F @ 100 psi, 7 bar	22 lbs	-98 N
Maximum Stroke	0.19 in.	-4.8 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Maximum Pressure for Purge Port	20 psi	1.4 bar
Cylinder Bore Ø	0.563 in.	14.3 mm
Displacement	0.028 in ³ .	0.5 cm ³

Accessory Mounting Technical Data

	T C Mx	F/2
Loading Capacity ⁺ DPDS-056M	Static	Dynamic
Maximum Tensile T	60 lbs. [267 N]	10 lbs. [45 N]
Maximum Compressive C	90 lbs. [401 N]	15 lbs. [67 N]
Maximum Moment M_X	40 in1bs. [5 Nm]	7 in1bs. [0.8 Nm]
Maximum Moment My	40 in1bs. [5 Nm]	7 in1bs. [0.8 Nm]
Maximum Moment Mz	40 in1bs. [5 Nm]	7 in1bs. [0.8 Nm]
DPDS-056M-B (Bottom Jaw Mou	Inting Option)	
Maximum Tensile T	48 lbs. [214 N]	8 lbs. [36 N]
Maximum Compressive C	72 lbs. [320 N]	12 lbs. [53 N]
Maximum Moment M x	32 in1bs. [4 Nm]	6 inIbs. [1 Nm]
Maximum Moment My	32 in1bs. [4 Nm]	6 inIbs. [1 Nm]
Maximum Moment Mz	32 in1bs. [4 Nm]	6 in1bs. [1 Nm]
*Capacities are per set of jaws and are not sir	nultaneous	

Specifications (cont.)	cifications (cont.) DPDS-056M	
Weight	0.155 lbs.	0.07 Kg
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.16 sec.	0.16 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability ± 0.001 in. ± 0.001		±0.03 mm
Valve Required to Actuate	. 4-way, 2-position	



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PARALLEL GRIPPER DPDS-088M DIRECTCONNECT™ MODULAR SERIES





SERIES

DPDS

1.140





PARALLEL GRIPPER DPDS-088M DIRECTCONNECT[™] MODULAR SERIES

M7

Dynamic

F/2

-B Option Shown

0

TC

Static





F/2



Specifications	DPDS-088M	
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	-222 N
Maximum Stroke	0.25 in.	-6.4 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Maximum Pressure for Purge Port	20 psi	1.4 bar
Cylinder Bore Ø	0.875 in.	22.2 mm
Displacement	0.090 in ³ .	1.5 cm ³

Accessory Mounting Technical Data





Loading Capacity[†]

Specifications (cont.)	DPDS-088M	
Weight	0.51 lbs.	0.23 Kg
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.20 sec.	0.20 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve Required to Actuate	4-way, 2-position	



Plumbing Fittings

- · Adjustable flow controls: Have thumb screw adjust with locking nut for adjusting actuation time:
 Available for 6mm 0.D. tubing
- Failsafe valve for applications: - Where it is critical that the part being gripped not be dropped
- if air pressure is lost Can mount directly to gripper or in-line with plumbing to gripper
- M5 air port



RECTCONNI

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

www.comoso.com



Multiple Air Port Locations

• 3 standard M5 air port locations (front, top, and back surface)

. Top and Back air ports are plugged as standard

PARALLEL GRIPPER DPDS-125M DIRECTCONNECT[™] MODULAR SERIES





SERIES

DPDS



PARALLEL GRIPPER DPDS-125M DIRECTCONNECT™ MODULAR SERIES







Specifications	DPDS-125M	
Total Rated Grip Force F @ 100 psi, 7 bar	100 lbs	-445 N
Maximum Stroke	0.38 in.	-9.5 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Maximum Pressure for Purge Port	20 psi	1.4 bar
Cylinder Bore Ø	1.250 in.	31.8 mm
Displacement	0.274 in ³ .	4.5 cm ³

Accessory Mounting Technical Data



• Top and Back air ports are plugged as standard





Mz

Loading Capacity [†] DPDS-125M	Static	Dynamic
Maximum Tensile T	500 lbs. [2225 N]	65 lbs. [289 N]
Maximum Compressive C	950 lbs. [4228 N]	65 lbs. [289 N]
Maximum Moment Mx	425 in1bs. [48 Nm]	70 in1bs. [8 Nm]
Maximum Moment My	425 in1bs. [48 Nm]	70 in1bs. [8 Nm]
Maximum Moment Mz	425 in1bs. [48 Nm]	70 in1bs. [8 Nm]
DPDS-125M-B (Bottom Jaw M	lounting Option)	
Maximum Tensile T	400 lbs. [1780 N]	52 lbs. [231 N]
Maximum Compressive C	760 lbs. [3382 N]	52 lbs. [231 N]
Maximum Moment Mx	340 in1bs. [38 Nm]	56 in1bs. [6 Nm]
Maximum Moment My	340 in1bs. [38 Nm]	56 in1bs. [6 Nm]
Maximum Moment Mz	340 in1bs. [38 Nm]	56 in1bs. [6 Nm]
⁺ Capacities are per set of jaws and are not	simultaneous	

Specifications (cont.)	DPDS-125M	
Weight Temperature Bange: Standard Seals	1.03 lbs. -30°~180° F	0.46 Kg -35°∼80° C
Viton® Seals	-20°~300° F	-30°~150° C 0.30 sec
Accuracy	±0.003 in.	$\pm 0.08 \text{ mm}$
Valve Required to Actuate	± 0.001 in. ± 0.03 mm 4-way, 2-position	
	<i>37</i>	





- Adjustable flow controls:
- Hays table how controls.
 Have thumb screw adjust with locking nut for adjusting actuation time
 Available for 6mm 0.D. tubing
- Failsafe valve for applications:
 Where it is critical that the part being gripped not be dropped
 - if air pressure is lost - Can mount directly to gripper or in-line with plumbing to gripper
- M5 air port
 Consult factory for additional plumbing fittings



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

DPDS SERIES EXPLODED VIEW

89

DPDS SERII Maintenan

1.144





Assembly Procedure:

- 1) Install #23 airport plugs with thread-locker. 2) Press pins #20 & #27 Into Plate #4.

- 3) Install threaded inserts #30, #31, & #32.
 4) Install #22 vent or plug with thread-locker.
 5) Mount magnet #25 to piston #8 with
- retainer Ring #24. 6) Install #28 metric plumbing fitting adapters.
- 7) Lubricate body #1 (jaw cavity & bores).
- 8) Lubricate & install all seals into body,
- piston, & cap. 9) Sub-assemble the #2 jaws on either side of

- the #6 shaft wedge with lubrication.
- 10) Insert the jaws and shaft wedge sub-assembly into body.
- 11) Insert piston #8 into the body bore and fasten it to the shaft wedge with Mounting screw # 26 using thread locker. 12) Install cap #7 into body with retaining
- ring #44.
- 13) Insert #4 bottom plate with pressed-in pins onto the body and fasten with #21 screws with thread-locker.

ltem	Qty	Name
01	1	Body
02	2	Jaw
04	1	Bottom Plate
06	1	Shaft Wedge
07	1	Сар
08	1	Piston
20	2	Bottom Plate
		Locating Dowels
21	6	Bottom Plate Screws
22*	1	Breather Vent Plug
		(Purge)
23	4	Manifold Port Plugs
24	1	Piston Mag. Ret. Ring
25	1	Piston Magnet
26	1	Piston Mounting Screw
27	1	Shaft guide dowel pin
28*	2	Plumbing Fitting -
		Adapter - 1/8NPT male
		to 1/8BSPP female
30*	8	Threaded Inserts (Body)
31*	8	Threaded Inserts (Jaw -
		End Mount)
32*	4	Threaded Inserts
		(Jaw - Bottom Mount
		"-B" option only)
40	1	Cap O-ring
41	1	Piston O-ring
42	1	U-cup
43*	2	Piston Teflon Ring
44	1	Cap Ret. Ring

NOTES:*

- 1) Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Item #30 is for size -175 and -250 only.
- 3) Item #31 and #32 are for size -250 only.
- 4) Item #22 Breather vent plug is a set screw plug for sizes -047 & -056.
- 5) Item #43 is for size -175 and -250 only.
- 6) Item #28 is for metric size -175M and -250M only.

SK Seal Repair Kit Order #'s See Product Data Sheets



Please see back cover for DE-STA-CO Global Locations. www.destaco.com





NOTES:*

- 1) Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Item #30 is for size -175 and -250 only.

3) Item #31 and #32 are for size -250 only.

- 4) Item #22 breather vent plug is a set screw plug for sizes -047 & -056.
- 5) Item #43 is for size -175 and -250 only.
- 6) Item #28 is for metric size -175M and -250M only.



lte	em Qty	Name
50	1 or 2	Magneto Resistive Sensor (short barrel) w/Qk. Disconnect
51	1 or 2	Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect
52	1 or 2	Magneto Resistive Sensor (12mm Dovetail) w/Qk. Disconnect
53	1,2 or 3	Plumbing Fitting - M3 male to 3mm OD Push-in Style
54	1,2 or 3	Plumbing Fitting - M3 male to 2mm ID Barb Style
59	1 or 2	Adjustable Flow Control (Metric) M5 elbow - 6mm OD Push-in Style
61	1 or 2	Adjustable Flow Control (Metric) G1/8 elbow - 6mm OD Push-in Style
63	1	Fail Safe Valve (Metric) M5
65	1	Fail Safe Valve (Metric) G1/8 (1/8 BSPP)

NOTE: Other Plumbing Fittings are available for each size - Consult Factory

DPDS SERIES ASSEMBLED VIEW

Item	Qty	Name
01	1	Body
02	2	Jaw
04	1	Bottom Plate
06	1	Shaft Wedge
07	1	Сар
08	1	Piston
20	2	Bottom Plate
		Locating Dowels
21	6	Bottom Plate Screws
22*	1	Breather Vent Plug
		(Purge)
23	4	Manifold Port Plugs
24	1	Piston Mag. Ret. Ring
25	1	Piston Magnet
26	1	Piston Mounting Screw
27	1	Shaft guide dowel pin
28*	2	Plumbing Fitting -
		Adapter - 1/8NPT male
		to 1/8BSPP female
30*	8	Threaded Inserts (Body)
31*	8	Threaded Inserts (Jaw -
		End Mount)
32*	4	Threaded Inserts
		(Jaw - Bottom Mount
		"-B" option only)
40	1	Cap O-ring
41	1	Piston 0-ring
42	1	U-cup
43*	2	Piston Teflon Ring
44	1	Cap Retainer Ring

Accessory Installation & Adjustment Instructions



Magneto-Resistive Sensors:

- Insert sensors #50 or #51 from either end of the profile slots and set the sensor with the integrated screw.
- 2) Insert sensor #52 into the dovetail slot at any point and set the sensor with the integrated screw & locking shoe.

Plumbing Fittings:

- 1) M3 plumbing fittings #53 & #54 can be used in any airport or purge/scavenge port.
- 2) Flow controls can be inserted and used in any open or closed airport to help control the stroke actuation.
- Fail-safe valve can be used in either the open or closed airport to help limit the possibility of dropping the part if air pressure is lost.

Parallel Grippers -DPDL DIRECTCONNECT Modular Series

- Multiple mounting locations: DIRECTCONNECT[™] tapped and dowel mounting on top and back of body.
- Thru body mounting: Front-toback thru-body mounting.
- Multiple air port positions: Tapped air ports on front, top, and back sides are standard.
- Manifold air porting: Top and back air ports can be manifold o-ring sealed.
- Front purge/scavenge port: Negative pressure used as a scavenge port used for cleanroom applications. Positive pressure used as a purge port to repel contaminants in harsh environment. Port can also be used for lubrication.
- **Sensing:** Full range adjustable magneto resistive sensors.

- **Different strokes:** All gripper sizes are available in 3 different strokes.
- **Multiple jaw styles:** All sizes available with end mounts jaws as standard or bottom mount jaws as an option.
- True sealed jaw option: Rugged integral rubber boot seals the unit against harsh environments. Designed to be used in machine coolant and metal chip environment applications.
- Long finger applications: Rigid design and full body support of jaws allows for longer finger lengths.

Mounting Information:

Grippers can be mounted & operated in any orientation



Body mounts with screws and locates with slip fit dowel pins for accuracy



Fingers attach with screws and locate on jaws by keying and/or dowel pins. Fingers can be mounted in any orientation with respect to the jaw.



Technical Specifications:

Pneumatic Specifications
Pressure Operating Range
Cylinder Type
Dynamic SealsIn
20Unamic Seals
Valve Required to OperateInt

Imperial Metric 20-100 psi 1.5-7 bar Double Acting Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements

Air Flitration	40 IVIICTO	n or better	
Air Lubrication	Not Nec	essary*	
Air Humidity	Low Moisture Content (dry)		
Temperature Operating I	Range		
Buna-N Seals (standard)	-30°~180° F	-35°~80° C	

 Buna-N Seals (standard)
 -30°~180° F
 -35°~80° C

 Viton® Seals (optional)
 -20°~300° F
 -30°~150° C

Maintenance Specifications[†] Expected Life

Normal Application w/ Preventative Maintenance Field Repairable	5 million cycles 10+ million cycles' Yes
Seal Repair Kits Available	Yes
F Antion Seals Jaw Rubber B	ant Specifications

Boot Material Temperature Rating (boot only)

bber Boot Specifications 60 Durometer Buna-N (Nitrile) v) -20°~250° F -30°~120° C

Compatible Chemicals:

-20°~250° F -30°~120° C
 Water, Coolant, Petroleum Oils,
 Silicone Lubricants, Dilute Acids

& Alkalis, Hydraulic Fluid, Transmission Fluid

Ozone, Ketones, Strong Acids, Brake Fluid

Non-Compatible Chemicals:

Example Applications:

Grinding Dust, Machine Chip & Coolant, Painting, Paper Dust, Washdown Applications

Application Restrictions

Applications where mechanism lubricant could cause contamination (use **-E** sealed jaw option) *Addition of lubrication will greatly increase service life 'See Maintenance Section

DPDL SERIES

1.146



U.S. Patent # 5,125,708 **Designed and manufactured in the USA**

DIRECTCO

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PARALLEL GRIPPER DPDL-047M DIRECTCONNECT[™] MODULAR SERIES







Loading Information



Specifications	DPDL-04	7M
Total Bated Grip Force F @ 100 psi, 7 bar	14 lbs.	-62 N
Maximum Stroke	0.38 in.	-9.5 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Max Pressure for Purge Port: (Standard)	20 psi	1.4 bar
with -E Jaw Boot	4 psi	0.25 bar
Cylinder Bore Ø	0.469 in.	11.9 mm
Displacement	0.038 in ³ .	0.6 cm ³

Accessory Mounting Technical Data







Loading Capacity [†] DPDL-047M	Static	Dynamic
Maximum Tensile T	100 lbs. [445 N]	15 lbs. [67 N]
Maximum Compressive C	150 lbs. [668 N]	25 lbs. [111 N]
Maximum Moment M_X	90 in1bs. [10 Nm]	15 inIbs. [2 Nm]
Maximum Moment My	90 in1bs. [10 Nm]	15 inIbs. [2 Nm]
Maximum Moment Mz	90 in1bs. [10 Nm]	15 inIbs. [2 Nm]
DPDL-047M-B (Bottom Jaw Mo	ounting Option)	
Maximum Tensile T	80 lbs. [356 N]	12 lbs. [53 N]
Maximum Compressive C	120 lbs. [534 N]	20 lbs. [89 N]
Maximum Moment M_X	72 in1bs. [8 Nm]	12 inIbs. [1 Nm]
Maximum Moment My	72 in1bs. [8 Nm]	12 inIbs. [1 Nm]
Maximum Moment M_z	72 in1bs. [8 Nm]	12 inIbs. [1 Nm]
Capacities are per set of jaws and are not	simultaneous	

Specifications (cont.)	DPDL-04	47M
Weight Temperature Range: Standard Seals	0.186 lbs. -30°~180° F	0.08 Kg -35°~80° C
Viton® Seals	-20°~300° F 0.20 sec.	-30°~150° C 0.20 sec.
Accuracy Repeatability.	±0.002 in. ±0.001 in.	±0.05 mm ±0.03 mm
Valve Required to Actuate	4-way, 2-p	osition



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PARALLEL GRIPPER DPDL-056M DIRECTCONNECT[™] MODULAR SERIES





DPDL SERIES





PARALLEL GRIPPER DPDL-056M DIRECTCONNECT[™] MODULAR SERIES

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Loading Information



Specifications	DPDL-05	6M
Total Rated Grip Force F @ 100 psi, 7 bar	22 lbs	—98 N
Maximum Stroke	0.50 in.	–12.7 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Max Pressure for Purge Port: (Standard)	20 psi	1.4 bar
with -E Jaw Boot	4 psi	0.25 bar
Cylinder Bore Ø	0.563 in.	14.3 mm
Displacement	0.074 in ³ .	1.2 cm ³

Accessory Mounting Technical Data





\$

Mz

Loading Capacity [†]	Static	Dynamic	
DPDL-056M			
Maximum Tensile T	125 lbs. [556 N]	25 lbs. [111 N]	
Maximum Compressive C	250 lbs. [1113 N]	25 lbs. [111 N]	
Maximum Moment Mx	115 inIbs. [13 Nm]	20 in1bs. [2 Nm]	
Maximum Moment My	115 inIbs. [13 Nm]	20 in1bs. [2 Nm]	
Maximum Moment Mz	115 inIbs. [13 Nm]	20 in1bs. [2 Nm]	
DPDL-056M-B (Bottom Jaw Me	ounting Option)		
Maximum Tensile T	100 lbs. [445 N]	20 lbs. [89 N]	
Maximum Compressive C	200 lbs. [890 N]	20 lbs. [89 N]	
Maximum Moment Mx	92 in1bs. [10 Nm]	16 inIbs. [2 Nm]	
Maximum Moment My	92 in1bs. [10 Nm]	16 inIbs. [2 Nm]	
Maximum Moment Mz	92 in1bs. [10 Nm]	16 inIbs. [2 Nm]	
*Capacities are per set of jaws and are not simultaneous			

Specifications (cont.)	DPDL-05	6M
Weight Temperature Range: Standard Seals Viton® Seals Actuation Accuracy Repeatability	0.315 lbs. -30°~180° F -20°~300° F 0.25 sec. ±0.002 in. ±0.001 in.	0.14 Kg -35°~80° C -30°~150° C 0.25 sec. ±0.05 mm ±0.03 mm
Valve Required to Actuate 4-way, 2-posit		osition



PARALLEL GRIPPER DPDL-088M DIRECTCONNECT™ MODULAR SERIES



DPDL SERIES

1.152



PARALLEL GRIPPER DPDL-088M DIRECTCONNECT[™] MODULAR SERIES



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Loading Information



Specifications	DPDL-08	8M
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs	<u> 222 N</u>
Maximum Stroke	0.75 in.	—19.1 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Max Pressure for Purge Port: (Standard)	20 psi	1.4 bar
with -E Jaw Boot	4 psi	0.25 bar
Cylinder Bore Ø	0.875 in.	22.2 mm
Displacement	0.269 in ³ .	4.4 cm ³

Accessory Mounting Technical Data



Loading Capacity[†]



¢

DPDL-088M				
Maximum Tensile T	350 lbs. [1558 N]	40 lbs. [178 N]		
Maximum Compressive C	650 lbs. [2893 N]	40 lbs. [178 N]		
Maximum Moment M_X	250 in1bs. [28 Nm]	40 in1bs. [5 Nm]		
Maximum Moment My	250 in1bs. [28 Nm]	40 in1bs. [5 Nm]		
Maximum Moment Mz	250 in1bs. [28 Nm]	40 in1bs. [5 Nm]		
DPDL-088M-B (Bottom Jaw Mounting Option)				
Maximum Tensile T	280 lbs. [1246 N]	32 lbs. [142 N]		
Maximum Compressive C	520 lbs. [2314 N]	32 lbs. [142 N]		
Maximum Moment M_X	200 in1bs. [23 Nm]	32 in1bs. [4 Nm]		
Maximum Moment My	200 in1bs. [23 Nm]	32 in1bs. [4 Nm]		
Maximum Moment Mz	200 in1bs. [23 Nm]	32 in1bs. [4 Nm]		
Capacities are per set of jaws and are not s	simultaneous			

Static

Specifications (cont.)	DPDL-08	BM
Weight	0.95 lbs.	0.43 Kg
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Actuation	-20 ~300 P 0.30 sec. ±0.002 in.	-30 ~ 150 ° C 0.30 sec. ±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve Required to Actuate	4-way, 2-p	osition



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

PARALLEL GRIPPER DPDL-125M DIRECTCONNECT[™] MODULAR SERIES

DPDL SERIES



Corrosion Resistant Hardware with Clean Room Grade Grease. Viton® Seals



PARALLEL GRIPPER DPDL-125M DIRECTCONNECT **MODULAR SERIES**

F/2

Мz

-B Option Shown

тс

Static

675 lbs. [3004 N]

1300 lbs. [5785 N]

650 in.-Ibs. [73 Nm]

650 in.-Ibs. [73 Nm]

650 in.-1bs. [73 Nm]

540 lbs. [2403 N]

1040 lbs. [4628 N]

520 in.-1bs. [59 Nm]

520 in.-1bs. [59 Nm]

520 in.-1bs. [59 Nm]



F/2

Dynamic

90 lbs. [401 N]

90 lbs. [401 N]

110 in.-Ibs. [12 Nm]

110 in.-Ibs. [12 Nm]

110 in.-Ibs. [12 Nm]

72 lbs. [320 N]

72 lbs. [320 N]

88 in.-1bs. [10 Nm]

88 in.-Ibs. [10 Nm]

88 in.-1bs. [10 Nm]

DPDL-125M

· Can be used to seal jaws in harsh environments

· Boot replacement available as an accessory

· Boot material is Buna-N (Nitrile) only

Loading Information



Specifications	DPDL-12	25M
Total Rated Grip Force F @ 100 psi, 7 bar	100 lbs	-445 N
Maximum Stroke	1.00 in.	-25.4 mm
Maximum Operating Pressure Range	20-100 psi	1.5-7 bar
Maximum Vacuum for Scavenge Port	8 in. Hg	200 mm Hg
Max Pressure for Purge Port: (Standard)	20 psi	1.4 bar
with -E Jaw Boot	4 psi	0.25 bar
Cylinder Bore Ø	1.250 in.	31.8 mm
Displacement	0.730 in ³ .	12.0 cm ³

Accessorv Mounti

I Rated Grip Force F @ 100 psi, 7 bar dimum Stroke dimum Operating Pressure Range dimum Vacuum for Scavenge Port. (Pressure for Purge Port: (Standard) with -E Jaw Boot hder Bore Ø placement	100 lbs. 20 1.00 in. 20 20-100 psi 1 8 in. Hg 2 20 psi 1 4 psi 0 0.730 in.3 3	445 N 25.4 mm 1.5-7 bar 200 mm Hg 1.4 bar 0.25 bar 31.8 mm 12.0 cm ³	Weight Temperature Range: Stand Viton Actuation Repeatability Valve Required to Actuate	lard Seals [®] Seals	1.99 lbs. -30°~180° F -20°~300° F 0.50 sec. ±0.003 in. ±0.001 in. 4-way, 2-p	0.90 Kg -35°~80° C -30°~150° C 0.50 sec. ±0.08 mm ±0.03 mm osition
ccessorv Mounting Techn	ical Data					
HSP-017 HSP	FRONT 27 SURFACE 8.5]	 Plumbing Fittir Adjustable flow cont Have thumb screw for adjusting actua Available for 6mm Failsafe valve: For applications wi the part being grip pressure is lost Can mount directly with plumbing to g M5 air port Consult factory for a 	VLVF-008 - rols: adjust with locking nut tion time: 0.D. tubing here it is critical that bed not be dropped if air to gripper or in-line ripper dditional plumbing fittings	2.18 [55] OFSV-0		-B JAW OPTION SHOWN
 Simple adjustment with slotted screw driver 				.07	6 [1.9]	
 Built in LED for ease of positioning and troubleshooti Low profile underflush sensor version or 90° wire ex 	ing kit					
sensor version	abla		5.44 [138] (CL		1 181+ 003	
Available with 2M or 5M Quick Disconnect mating cl (order separately)	able		-E SÉALÉĎ J	AW BOOT OPTION	1.181±.003 [30.0±.08] .625±.003 [15.88±.08]	- 003
DAUK SUHPACE		(O-RING	SLKT-199V MANIFOLD SEAL KIT) SLKT-194 (BOOT REPLACEMENT)		(30.1 (30.1 (30.1) (30.	(17.7 DP. DP.]
	RFAGE	Can be used to	o seal front, top. or back			
		air ports and t • Seals in Mani	ront purge/scavenge port fold kit are Viton®	Sealed .	Jaw Boot Opti	ion

Loading Capacity[†]

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

Maximum Tensile T

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

Specifications (cont.)

DPDL-125M-B (Bottom Jaw Mounting Option)

*Capacities are per set of jaws and are not simultaneous

DPDL-125M

Maximum Tensile T

Multiple Air Port Locations • 3 standard M5 air port locations (front, top, and back surface)

• Top and Back air ports are plugged as standard

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

www.comoso.com

O-Ring C'bores in customer's mounting plate must be: Ø.290 [Ø7.4] X .060±.002 [1.52±.05] deep

· Kit is supplied with all seals, plugs, & wrenches needed

DIRECTCONNE

DPDL SERIES EXPLODED VIEW



nem	ŲĮ	y Name
01	1	Body
02	2	Jaw
04	1	Bottom Plate
06*	1	Shaft Wedge
07	1	Сар
08	1	Piston
<u>11</u>	2	Boot
12	2	Boot Flange
13	2	Boot Spacer Cap
14	2	Boot Spacer
20	2	Bottom Plate Locating Dowels
21	6	Bottom Plate Screws
22*	1	Breather Vent Plug (Purge)
23	4	Manifold Port Plugs
24	1	Piston Mag. Ret. Ring
25	1	Piston Magnet
26	1	Piston Mounting Screw
27	1	Shaft guide dowel pin
29	8	Boot Flange Mounting Screws
34	4	Boot Spacer Dowel Pins
<u>35*</u>	2	Boot Spacer Mtg Screws
40	1	Cap O-ring
41	1	Piston O-ring
42	1	U-cup
44	1	Can Ret Ring

NOTES:*

- 1) Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 4) Item #22 Breather vent plug is a set screw plug for sizes -047 & -056.
- 7) Item #35 is for sizes -088 thru -125 only.
- 8) End-of-jaw mounting holes on -B option are supplied plugged to prevent debris from entering the gripper. These set screws can be removed for customer finger mounting. It is recommend that all unused holes be plugged for the same reason.

Seal Repair Kit Order #'s See Product Data Sheets

Assembly Procedure:

- Install #23 airport plugs with thread-locker.
 Press pins #20 & #27 into plate #4.
- 3) Install #22 vent or plug with thread-locker.
- 4) Mount magnet #25 to piston #8 with retaining ring #24.
- 5) Lubricate body #1 (jaw cavity & bores).
- 6) Lubricate & install all seals into body, piston, & cap.
- 7) Sub-assemble the #2 jaws on either side of the #6 shaft wedge with lubrication. 8) Insert the jaws and shaft wedge
- sub-assembly into body.

- 9) Insert piston #8 into the body bore and fasten it to the shaft wedge with Mounting screw # 26 using thread locker.
- 10) Install cap #7 into body with retaining ring #44.
- 11) Insert #4 bottom plate with pressed-in pins onto the body and fasten with #21 screws with thread-locker.

-E Option Assembly Procedure:

- 1) Insert pins #34 into the jaw dowel pin holes.
- 2) Place #14 boot spacer over pins
- 3) Fasten boot #11 and flange #12 to body #1 with #29 screws.
- 4) Fasten the spacer cap #13 to the spacer #14 with #35 screw.







DPDI	. SE	RIES ASSEMBLED VIEW
Item	Qty	Name
01	1	Body
02	2	Jaw
04	1	Bottom Plate
00*	1	Oh off Wedge

01	1	Body
02	2	Jaw
04	1	Bottom Plate
06*	1	Shaft Wedge
07	1	Сар
08	1	Piston
11	2	Boot
12	2	Boot Flange
13	2	Boot Spacer Cap
14	2	Boot Spacer
20	2	Bottom Plate Locating Dowels
21	6	Bottom Plate Screws
22*	1	Breather Vent Plug (Purge)
23	4	Manifold Port Plugs
24	1	Piston Mag. Ret. Ring
25	1	Piston Magnet
26	1	Piston Mounting Screw
27	1	Shaft guide dowel pin
29	8	Boot Flange Mounting Screws
34	4	Boot Spacer Dowel Pins
35*	2	Boot Spacer Mtg Screws
40	1	Cap O-ring
41	1	Piston 0-ring
42	1	U-cup
44	1	Cap Ret. Ring

NOTES:*

- 1) Contact the Destaco-Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Item #22 breather vent plug is a set screw plug for sizes -047 & -056.

Accessory Installation & Adjustment Instructions



1) Insert sensors #50 or #51 from either end of the profile slots and set the sensor with the integrated screw.

Plumbing Fittings:

- 1) M3 plumbing fittings #53 & #54 can be used in any airport or purge/scavenge port.
- 2) Flow controls can be inserted and used in any open or closed airport to help control the stroke actuation.
- 3) Fail-safe valve can be used in either the open or closed airport to help limit the possibility of dropping the part if air pressure is lost.

Ite	em Qty	Name
50	1 or 2	Magneto Resistive Sensor (short barrel) w/Qk. Disconnect
51	1 or 2	Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect
53	1,2, or 3	Plumbing Fitting - M3 male to 3mm OD Push-in Style
54	1,2, or 3	Plumbing Fitting - M3 male to 2mm ID Barb Style
59	1 or 2	Adj. Flow Control (Metric) M5 elbow - 6mm 0D Push-in Style
63	1	Fail Safe Valve (Metric) M5

NOTE: Other Plumbing Fittings are available for each size - Consult Factory



Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com

50

5

(58)(59

0

DPDL-088 & DPDL-125

(62)(63)

Sans 1.158

Parallel Grippers -Long Stroke Series

DIRECTOONN

- **Compact and robust design** This gripper is designed for use in confined spaces, combining long strokes with the high gripping force provided by two simultaneously acting pistons.
- For long finger applications: Jaws are supported throughout the length of the body, enabling long fingers.
- Multipurpose gripper:

A wide range of options and accessories (safety springs, in-line jaws, magneto resistive or inductive sensors) allow these grippers to be used in a number of applications.

• Harsh environments: Enclosed, shielded design repels chips

and other particulate from internal drive mechanism.

• Spring assist, spring return: Can be used as failsafe, single acting spring return, or double acting spring assist.



Mounting Information:

Grippers can be mounted & operated in any orientation



The gripper is protected from falling debris when it is mounted and operated upside down.



Gripper locates from the top with 2 dowel pins and can be assembled with 4 screws from the top or bottom.



Gripper can be operated with rear inlets (manifold).



Fingers are located on jaws with 2 dowel pins and assembled with 2 screws.

Technical Specifications:

Pneumatic Specifications	Imperial	Metric
Pressure Operating Range: Standard	30-100 nei	2-7 har
with -R Spring Option	60-100 psi	1-7 bar
Cylinder Type	Double	Acting
Dynamic Seals	Internally Lubri	icated Runa-N
Valve Required 4-way	2-position for	Double Acting
to Operate or 3-w	ay, 2-position for	or Single Acting
Air Quality Requirements		
Air Filtration	40 Micro	n or Better
Air Lubrication	Not Nec	essary*
Air Humidity	Low Moisture	Content (dry)
Temperature Operating Rai	nge	
Buna-N Seals (Standard)	-4°~180° F	-20°~80° C
Maintenance Specification	S [†]	
Expected Life		
Normal Application	5 million	cycles
w/ Preventative Maintenanc	e 10+ milli	ion cycles*
Field Repairable	Ye	S
Seal Repair Kits Available	Ye	S
*Addition of lubrication will greatly increase s *See Maintenance Section	service life	

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PARALLEL GRIPPER DPL-2520 TWO JAW LONG STROKE

정비원 보장





*Capacities are per set of jaws and are not simultaneous

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PARALLEL GRIPPER DPL-2535 TWO JAW LONG STROKE



NRECTONN

OISP-011

OISN-011

CABL-010

CABL-013

SLKT-233

SLKT-316

PLFT-037

PLFT-041

ODPL-002

1 to 3

1 to 3

1 to 3

1 to 3

1

1

1 to 2

1 to 2

1

SERIES

1.161

Maximum Compressive C	411 lbs.	1380 N	34 lbs.	150 N	Can detailed ontion and economy information at the and of this contion
Maximum Moment Mx	513 inIbs.	58 Nm	35 inIbs.	4 Nm	See detailed option and accessory mormation at the end of this section.
Maximum Moment My	1947 inIbs.	220 Nm	142 inIbs.	16 Nm	
Maximum Moment Mz	1151 inIbs.	130 Nm	142 inIbs.	16 Nm	
*Capacities are per set of jaws and	are not simultaneou	JS			

12 in.

Mz

F/2

Dynamic

Metric

150 N

M٧

Imperial

34 lbs.

2 **4** 100 6 8 10

50

150 200

EFFECTIVE FINGER LENGTH - L

Static

Imperial

324 lbs.

F/2

Metric

1440 N

0

Loading Capacity[†]

Maximum Tensile T

Maximum Compressiv

M8 PNP Inductive Sensor with Quick Disconnect*

M8 NPN Inductive Sensor with Quick Disconnect*

Quick Disconnect 2 Meter Cable Length*

Quick Disconnect 5 Meter Cable Length*

Fitting Push-in Straight M5 - 6mm 0.D. Tube

Fitting Push-in 90° Elbow M5 - 6mm O.D. Tube

PNEUMATIC ACCESSORIES Standard Seal Repair Kit

Rear Inlet Seal Repair Kit

MOUNTING ACCESSORIES

In-Line Jaw Mounting Kit

*Sensor and cable sold separately.

PARALLEL GRIPPER DPL-3230 TWO JAW LONG STROKE





Maximum Moment Mz

*Capacities are per set of jaws and are not simultaneous

1062 in.-Ibs.

120 Nm

195 in.-Ibs.

22 Nm

정비원 보장

1.162

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*Capacities are per set of jaws and are not simultaneous

PARALLEL GRIPPER DPL-3250 TWO JAW LONG STROKE



. SERIES

1.163

PARALLEL GRIPPER DPL-4040 TWO JAW LONG STROKE

SHRIES

1.164





1947 in.-Ibs. 220 Nm

381 in.-Ibs.

43 Nm

Maximum Moment Mz



*Capacities are per set of jaws and are not simultaneous

PARALLEL GRIPPER DPL-4070 TWO JAW LONG STROKE





Optional Spring Assist (-R): The safety spring allows the gripper to retain the part should the air supply fail or allows the gripper to be used in single acting mode. The **-R** option is ideal for internal (ID) or external gripping (OD). The ID or OD will depend on the finger design. The fingers will face towards center of gripper for OD gripping or will face outward for ID gripping.



In-Line Jaw Adapter:

The In-Line Jaw Adapter allows for the simplification of the finger design. It provides for "in-line" alignment of the finger mounting holes. The kit includes 2 interfaces, screws, and dowel kit.



Fingers can be mounted on the acc essory

from the top (using SHC screws) or from the bottom (using low head SHC screws)



Second direction for mounting the accessory When used with the -R option, it allows to secure for internal or external clamping



Order #	Use With	A	B	C	D	E	F	G	H	J	K	L	М	N	P	Q	R
ODPL-001	DPL-2520	0.51[13]	M6	0.20 [5]	0.14[3.5]	0.28[7]	M5	0.20 [5]	1.46[37]	0.79[20]	1.65[42]	1.57 [40]	0.30[7.5]	1.18[30]	0.24[6]	1.65[42]	3.15 [80]
0DPL-002	DPL-2535	0.51 [13]	M6	0.20 [5]	0.14[3.5]	0.28[7]	M5	0.20[5]	2.05 [52]	0.79[20]	2.83[72]	2.76[70]	0.30[7.5]	1.18[30]	0.24[6]	1.65[42]	3.44[87.5]
ODPL-003	DPL-3230	0.59 [15]	M8	0.27 [6.8]	0.12[3]	0.39[10]	M6	0.24[6]	1.97 [50]	0.87[22]	2.44[62]	2.36[60]	0.39[10]	1.54[39]	0.31 [8]	1.93 [49]	3.70 [94]
ODPL-004	DPL-3250	0.59 [15]	M8	0.27 [6.8]	0.12[3]	0.39[10]	M6	0.24[6]	2.76 [70]	0.87[22]	4.02[102]	3.94[100]	0.39[10]	1.54[39]	0.31 [8]	1.93 [49]	4.09[104]
ODPL-005	DPL-4040	0.83 [21]	M10	0.33 [8.5]	0.20[5]	0.47 [12]	M8	0.31 [8]	2.48[63]	1.02[26]	3.23[82]	3.15[80]	0.47 [12]	1.87 [47.5]	0.35[9]	2.24[57]	4.45[113]
ODPL-006	DPL-4070	0.83 [21]	M10	0.33 [8.5]	0.20[5]	0.47[12]	M8	0.31 [8]	3.66 [93]	1.02[26]	5.59[142]	5.51 [140]	0.47 [12]	1.87 [47.5]	0.35[9]	2.24[57]	5.04[128]

Inductive Sensors Holder:

Sense up to 3 jaw positions; open jaws, closed jaws, and part present. The kit includes 3 sensor holders and 2 flags. Sensors are not included.

Order #	Use With	U	V	W	X	Y
OSMK-099	DPL-2520	0.31 [8]	1.18 [30]	0.95 [24]	2.28 [58]	1.83 [46.5]
	DPL-2535	0.31 [8]	1.18 [30]	0.95 [24]	2.28 [58]	1.83 [46.5]
OSMK-100	DPL-3230	0.31 [8]	0.87 [22]	0.95 [24]	2.64 [67]	1.97 [50]
	DPL-3250	0.31 [8]	0.87 [22]	0.95 [24]	2.64 [67]	1.97 [50]
OSMK-101	DPL-4040	0.47 [12]	0.87 [22]	1.06 [27]	3.23 [82]	2.26 [57.5]
	DPL-4070	0.47 [12]	0.87 [22]	1.06 [27]	3.23 [82]	2.26 [57.5]



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www.comoso.com





DPL Series Exploded View

ltem	Qty	Name
01	1	Body
02	2	Piston
04	4	Сар
05	1	Gear Cover
06	2	Jaw
08	1	Shielded Case
50	4	Seal, Cap
<u>51</u>	1	Synchronization Pinion
<u>52</u>	2	Set Screw-Manifold Port Plugs
53	4	Retainer Ring, Cap
54	4	Piston Ring Guidance
<u>55</u>	4	Piston U-Cup
56	4	Magnet
57	2	Drive Pin Retainer Ring
<u>58</u>	2	Manifold Port Plugs
59	2	Drive Pin
60	2	Center Retaining Ring
<u>63</u>	4	Jaw Dowel Pin
64	6	Shielded Case Screws
79	2	Spring Cap
80	2	Spring

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Glue magnets #56 into the piston slots #2.
- 2) If top air ports are not used, plug the body #1 with screws #52 using glue.
- Lubricate and install the U-Cup seals #55 and the guidance ring #54 onto the piston #2.
- Lubricate and assemble the piston #2 into the body #1 using the adequate tooling
- 5) Press dowel pins #63 into the jaws #6.
- 6) Lubricate and install the jaws #6 into the slots #1.
- 7) Press the drive pin #59 and the retaining ring #57 through the jaws #6 and the piston #2.
- 8) Lubricate and install the axis #5, the pinion #51, the retaining ring #60 into the body. Beware of the correctly place the jaws to get a synchronous motion.
- 9) Lubricate and install the seal #50 onto the cap #4.
- 10) Install the cap #4 and the retaining ring #53 into the cap #1.
- 11) Install the shielded case #8.
- 12) Screw the plugs #58 into the body #1.

Assembly - Spring option

- 1) Lubricate and install the seal (#50) onto the cap.
- Install the spring into the piston bore and into the cap bore.
- Compress the spring till the cap reach its correct position on the body.
- 4) Install the retaining ring.

SK Seal Repair Kit Order #'s See Product Data Sheets



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DPL Series Assembled View



ltem	Qty	Name
01	1	Body
02	2	Piston
04	4	Сар
05	1	Axis
06	2	Jaw
08	1	Shielded Case
50	4	Seal, Cap
51	1	Synchronization Pinion
52	2	Set Screw-Manifold Port Plugs
53	4	Retainer Ring, Cap
54	4	Piston Ring Guidance
55	4	Piston U-Cup
56	4	Magnet
57	2	Drive Pin Retainer Ring
58	2	Stopper-Manifold Port Plugs
59	2	Drive Pin
60	2	Center Retaining Ring
63	4	Jaw Dowel Pin
64	6	Shielded Case Screws

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions







Installation - Inductive Sensors Holder Kit

- 1) Place the flags (#2) on the jaws as shown.
- 2) Install the sensor holder (#72) on the adapter (#73) using the screws (#75)
- 3) Tighten the sensor (not shown) into the sensor holder(#73).
- 4) Install the nut (#71) into the slot of the body and the adapter (#72) on the slot. Install the screw (#74) to fix the adapter on the nut.
- 5) Loosen the screw (#74) and slide the assembly until the light indicates.
- 6) Tighten the screw (#74).

Installation - In-Line Jaws

- Install the interface (#77) onto the jaws. When combined with the -R option and according to the mounting direction, the interface can be used for internal or external clamping.
- 2) Tighten the screw (#78) between the interface (#77) and the jaw.

RECIDESIGN NOTES (DESAGO **DPL SERIES** 1.169

Parallel Grippers-Miniature Series Double Wedge

• General purpose: This style gripper is the most widely used in the industry. It is a rugged design and supplies very high grip force.

1.170

- Small parts handling: Compact size, high gripping force, and extended jaw design facilitates finger attachment for smaller parts.
- Robotic applications: High grip force to weight ratio make these grippers very popular on small robots.
- **Miniature Size:** Allows banks of grippers to be mounted in close proximity for multiple part picking and placing.

Mounting Information:

Grippers can be mounted & operated in any orientation





Body mounts with screws and locates with slip fit dowel pins for accuracy

Warning! Protect jaw mechanism from falling debris when mounted upside down





Fingers attach to jaws with screws and locate by keying

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate Imperial Metric 40-100 psi 3-7 bar Double Acting Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements Air Filtration

Air Lubrication Air Humidity 40 Micron or Better Not Necessary* Low Moisture Content (dry)

5 million cycles

Yes

Yes

10+ million cycles*

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F Viton® Seals (optional) -20°~300° F

)° F -35°~80° C)° F -30°~150° C

Maintenance Specifications[†]

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available

Application Restrictions

- Dirty or gritty environments
- Machining operations generating chips
- Environments with loose particulate
 Applications where mechanism lubricant could cause contamination

*Addition of lubrication will greatly increase service life *See Maintenance Section

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- The wedge slides in a slot located in each of the jaws converting vertical motion
- of the wedge into horizontal synchronous motion of the jaws.
- The large surface area of the wedge minimizes frictional wear.
- This gripper is suitable for internal or external gripping.

U.S. Patent # 5,125,708 **Designed and manufactured in the USA**



Serres

PARALLEL GRIPPER RP-5M-FS MINIATURE DOUBLE WEDGE SERIES





Specifications	RP-5	RP-5M
Total Rated Grip Force F @ 100 psi, 7 bar3	5 lb	156 N
Stroke	.16 in.	4.1 mm
Weight	0.18 lb	0.08 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.750 in.	19.1 mm
Displacement	0.042 in ³ .	0.7 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.14 sec.	0.14 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate	4-way, 2-p	osition





Ψt	≠⊕		Ŷ	imperial in.	Metric [mm]
Dimensions are Th symmetrical about Pr centerline	rojection All Dow ±.0	el Holes are SF (Slip Fit). ocational Tolerance 1005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	

Loading Information

How to Order: (Order Accessories separately from Basic Model)






2X #6-32 X .25 DP [M4 X 6 DP]

PARALLEL GRIPPER RP-10M MINIATURE DOUBLE WEDGE SERIES

Specifications	RP-10	RP-10M
Total Rated Grip Force F @ 100 psi, 7 bar4	0 lb	178 N
Stroke	0.25 in.	6.4 mm
Weight	0.28 lb	0.13 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.00 in.	25.4 mm
Displacement	0.098 in ³ .	1.6 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.001 in.	±0.03 mm
Repeatability	±0.0005 in.	±0.01 mm
Valve required to actuate	4-way, 2-p	osition





— UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW —

Ģ	₽⊕	\bullet	\oplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{l} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	

Loading Information

How to Order: (Order Accessories separately from Basic Model)



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RP-5 &10 Series Exploded View



Item Qty Name

01	1	Body	
02	2	Jaw	
03	1	Cap	
04	1	Piston	
05	1	Plate,Bottom	
06	1	Shaft/Wedge	
07*	1	Gib	
30*	4	SSS,Cup Point	
* RP-10 Only			

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedures

- 1) Lubricate and install seals.
- 2) Install piston into body.
 3) Place wedge, jaws, and gib plate into body.
- 4) Attach bottom plate to body.5) Install cap and retaining ring.

Gib Adjustment Procedure

- 1) Tighten set screws (#30) so that they just just touch the gib plate.
- 2) Cycle the gripper.3) Adjust screws so that there is no play in jaws.





RP-5 & 10 Series Assembled View



Item	Otv	Nam

01	1	Body	
02	2	Jaw	
03	1	Cap	
04	1	Piston	
05	1	Plate, Bottom	
06	1	Shaft/Wedge	
07*	1	Gib	
30*	4	SSS,Cup Point	
* RP-10 Only			

NOTE: Contact the Robohand Sales

Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Parallel Grippers -Double Wedge Series 1.176

- **Machining applications:** Sealed design repels chips and other particulate from internal drive mechanism.
- **General purpose:** This style gripper is the most widely used in the industry. It is a rugged design and supplies very high grip forces for its size.
- Part pressing: Hardened steel bottom plate provides a solid surface for part pressing.

Mounting Information:

RP SERIES

Grippers can be mounted & operated in any orientation



Fingers attach to jaws with screws and locate by keying or dowel pins

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

40 Micron or Better Not Necessary* Low Moisture Content (dry)

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F -20°~300° F Viton[®] Seals (optional)

-35°~80° C -30°~150° C

Maintenance Specifications⁺ otod Life

Expected Life Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycles*
Field Repairable	Yes
Seal Repair Kits Available	Yes
Addition of lubrication will greatly increase service life	•

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• This gripper is suitable for internal or external gripping.

U.S. Patent # 5,125,708 Designed and manufactured in the USA

Style-RP Parallel Gripper Size-11M RP-11M Style: **RP-11** 6.4 mm 178 N Stroke 0 25 in Grip Force: 40 lbs. .25 lbs. Weight: .11 Kg See 1.178 Page Style-RP Parallel Gripper Size-12M Style: Stroke: RP-12M **RP-12** 0.38 in. 9.5 mm Grip Force: Weight: 40 lbs 178 N .56 lbs. .25 Kg See **1.179** Style-RP Parallel Gripper Size-15M Style: Stroke: **RP-15 RP-15M** 12.7 mm 0.50 in. 310 N Grip Force: Weight: 70 lbs. 1.25 lbs .57 Kg See **1.180 Style-RP Parallel Gripper** Size-17M Style: **RP-17 RP-17M** 19.1 mm 979 N Stroke: 0.75 in. Grip Force: Weight: 220 lbs 2.2 lbs. 1.0 Kg See **1.181** Page **Style-RP Parallel Gripper** Size-18M Style: Stroke: **RP-18 RP-18M** 1.25 in. 31.8 mm Grip Force: 400 lbs 1779 N Weight: 77 lbs 3.5 Ka See **1.182 Style-RP Parallel Gripper** Size-19M Style: Stroke: Grip Force: **RP-19** RP-19M 2.00 in. 50.8 mm 600 lbs. 2669 N 9.5 Kg Neight: 21 lbs. See **1.183** Note: Please refer to our new DPDS/DPDL Series grippers found on pages 1.134-1.157. The RP Series is still available for sale and the related information remains available on our website but we encourage you to consider the new DPDS/DPDL Series grippers found on pages

1.134-1.157 for new projects.

Serres

2

1.177

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

PARALLEL GRIPPER RP-11M DOUBLE WEDGE SERIES





Specifications	RP-11	RP-11M
Total Rated Grip Force F @ 100 psi, 7 bar4	0 lbs.	178 N
Stroke	.25 in.	6.4 mm
Weight	0.26 lbs.	0.12 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.000 in.	25.4 mm
Displacement	0.098 in ³ .	1.6 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-p	osition



 UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

 C
 Imperial in.
 Metric [mm]

 Dimensions are symmetrical about centerline
 Third Angle Projection
 All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]
 Metric Threads Course Pitch
 0.00 = ±.01 0.000 = ±.005 0.0000 = ±.0015
 [0.1] = [±.25] [0.0] = [±.13] [0.0] = [±.13]

Loading Information

How to Order: (Order Accessories separately from Basic Model)



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PARALLEL GRIPPER RP-12M DOUBLE WEDGE SERIES

Specifications	RP-12	RP-12M
Total Rated Grip Force F @ 100 psi, 7 bar4	10 lbs.	178 N
Stroke	.38 in.	9.5 mm
Weight	0.56 lbs.	0.25 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.000 in.	25.4 mm
Displacement	0.150 in ³ .	2.5 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.13 sec.	0.13 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-p	osition



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW All Dowel Holes are SF (Slip Fit). \odot Ç ightarrowImperial in. Metric [mm] $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Dimensions are symmetrical about Third Angle Metric Threads Projection Course Pitch centerline ±.0005" or [±.013mm]

Loading Information

How to Order: (Order Accessories separately from Basic Model)



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PARALLEL GRIPPER RP-15M DOUBLE WEDGE SERIES





Specifications	RP-15	RP-15M
Total Rated Grip Force F @ 100 psi, 7 bar	70 lbs.	311 N
Stroke	.50 in.	12.7 mm
Weight	1.25 lbs.	0.57 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.25 in.	31.8 mm
Displacement	0.300 in ³ .	4.9 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.20 sec.	0.20 sec.
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-p	osition





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	LESS VINEN	NISE NUIED ALL IULE	INANUES AF	IE AJ JHUWN E	DELUW
Ç	$\Rightarrow \odot$	\bigcirc	\odot	Imperial in.	Metric [mm]
Dimensions are symmetrical abo centerline	Third Angle ut Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	$\begin{array}{l} [0.] = [\pm .25] \\ [0.0] = [\pm .13] \\ [0.00] = [\pm .013] \end{array}$

Loading Information

How to Order: (Order Accessories separately from Basic Model)



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Maximum Moment Mz

*Capacities are per set of jaws and are not simultaneous

750 in.-Ibs.

85 Nm 125 in.-Ibs. 14 Nm



SERIES

2

1.181



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ADJUSTABILITY

www.comoso.com

[41.1]

PARALLEL GRIPPER RP-18M DOUBLE WEDGE SERIES





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PARALLEL GRIPPER RP-19M DOUBLE WEDGE SERIES



	CC ATHEDV	VICE NATER ALL TALE	рамсес аб	DE AC CUAWN D	
UNLE	33 UIRERV	VIJE NUTED ALL TULE	NAIVUEJ AI	ne Aj Jhuwii D	
Ģ	\Rightarrow	\bullet	\oplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{l} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	$\begin{array}{l} [0.] = [\pm .25] \\ [0.0] = [\pm .13] \\ [0.00] = [\pm .013] \end{array}$

Loading Information

How to Order: (Order Accessories separately from Basic Model)



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

RP Double Wedge Series Exploded View





ltem Qty Name

01	1	Body
03	1	Shaft/Wedge
05	1	Сар
06	1	Plate, Bottom
07	1	Target
08	2	Plate,Seal
09	1	Piston
20	2	Jaw, Target Ready
30	2	Dowel Pin
31	1	Dowel Pin
32	2	Boll Pin

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install seals.
- Install target on one jaw.
 Place wedge, shaft and jaws into body.

- a) Install piston into body.
 b) Install cap and retaining ring.
 b) Attach bottom plate to body.







RP Double Wedge Series Assembled View



Item Otv Nar			
	Item	Otv	Nar

01	1	Body
03	1	Shaft/Wedge
05	1	Сар
06	1	Plate, Bottom
07	1	Target
08	2	Plate,Seal
09	1	Piston
20	2	Jaw,Target Ready
30	2	Dowel Pin
31	1	Dowel Pin
32	2	Boll Pin

ne

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation

- 1) Install sensors as shown.
- 2) Adjust for desired end of stroke detection.

GC SERIES

```
1.186
```



Parallel Grippers -Two Jaw Precision Spring Series

- **Compact and shielded gripper:** This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Standard safety springs retain the components should the air supply fail, or during gripping, the spring provides additional gripforce.
- **Multipurpose gripper:** The safety springs allow this gripper to be used to clamp on arbor or in bore without the need for any modifications. All the user has to do is to change the jaw position in the jaw holders.

• Harsh environments: Shielded design repels chips and other particulate from internal drive mechanism.

Mounting Information:

Grippers can be mounted & operated in any orientation

The gripper is protected from falling debris when it is mounted and operated upside down.



Gripper is located from the top with 2 dowel pins and assembled with 2 screws (by pulling).



Fingers are located on jaws with 2 dowel pins and assembled with 2 screws.



Gripper is located on the side with 2 dowel pins and assembled with 2 through body screws.

Gripper can be operated utilizing top manifold air ports.

Technical Specifications:

Pneumatic Specifica	tions Imperial Metric
Pressure Operating Rat	nge 45-100 psi 3-7 bar
Cylinder Type	Double Acting Spring Assist
Dynamic Seals Valve Required to Operate	or Single Acting Spring Return Internally Lubricated Buna-N 4-way, 2-position for Double Acting or 3-way, 2-position for Single Acting
Air Quality Requirem	ents 40 Micron or Better
Air Lubrication	Not Necessary*
Air Humidity	Low Moisture Content (dry)
Temperature Operati	ng Range
Buna-N Seals (Standard	d) -30°~180° F -35°~80° C

Buna-N Seals (Standard) -30°~180° F -35°~80° C Viton® Seals (Optional) -20°~300° F -30°~150° C

Maintenance Specifications[†]

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available *Addition of lubrication will greatly increase service life 'see Maintenance Section

DIRECTCONNECT

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- It converts vertical motion of the piston into horizontal opposite synchronous motion of the 2 jaws.
- In order to benefit from spring power and from pneumatic control power, the pneumatic inlet must be applied to "S" for gripping and with "D" for release. An arrow etched onto each jaw holder indicates the gripping direction.
- Springs can be used to increase the grip force or to hold part in the event of air loss. It also allows the gripper to be used in single acting mode.

DIRECTCONN

PARALLEL GRIPPER DGC-25 TWO JAW PRECISION SPRING ASSIST

GC SERIES

1.188

IRECTCONNE





Dimensions are symmetrical about \oplus Imperial in. Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $0.00 = \pm .01$ Metric Threads $0.000 = \pm .005$ Course Pitch $[0.00] = [\pm .013]$ $0.0000 = \pm .0005$

Drawing hereafter shows gripper gripping at the end of stroke (inlet through "**S**")



Loading Information



How to Order: (Order Separately)

BASIC MODEL DGC - 25 -V SIZE VITON[®] SEALS

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
4mm PNP Inductive Sensor with Qk Disconnect*	OISP-014	1 or 2
4mm NPN Inductive Sensor with Qk Disconnect*	OISN-014	1 or 2
Quick Disconnect 2 Meter Cable*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SLKT-319	1
Viton [®] Seal Repair Kit *Sensor and cable sold separately.	SLKT-319V	1



Specifications

Stroke.

Total Rated Grip Force **F** @ 100 psi, 7 bar* 108 lbs.

..... 1.181 in

PARALLEL GRIPPER DGC-45 TWO JAW PRECISION SPRING ASSIST

F +0.032

Top air port M5 x 0.22 [5.5] DP For GRIPPING

(supplied plugged)

[14.5] 0.571

[⁵ 0 +0.0005 2 x Ø0.1969 0.0000 x 0.39 [10] DP

[17 ±0.02] 0.6693 ±0.0008

1 [5^{+0.012}]

Weight Pressure Range Cylinder Bore Ø Displacement	1.32 lbs. 45-100 psi 1.46 in. 1.77 in ³ .	0.60 kg 3-7 bar 37 mm 29 cm ³		[11 -0.005] [11 -0.015] -0.002 0.4331 -0.0006	$\begin{array}{c} 0.2 \\ 0.2 \\ 0.008 \\ 0.0008 \\ 0.0008 \\ 0.0008 \\ 0.0008 \\ 0.0008 \\ 0.0008 \\ 0.0013 \\ 0.0008 \\ 0.013 \\ 0.0008 \\ 0.013 \\ 0.0008 \\ 0.013 \\ 0.0008 \\ 0.013 \\ 0.0008 \\ 0.013 \\ 0.0013 \\$
Temperature Range Standard Seals Viton® Seals Actuation Accuracy Repeatability Valve required to actuate single acting Valve required to actuate double acting With springs.	-30°~180° F -20°~300° F 0.25 sec. ±0.0009 in. ±0.0004 in. 3-way 2-pc 4-way, 2-pc	-35°~80° C -30°~150° C 0.25 sec. ±0.02 mm ±0.01 mm. sition psition		[15.5] 0.610 1 [13] 0.51 [13 ±0.01] 0.5118 ±0.0004	1 0.001 1 0.012 1 0.013 1 0.012 0.4331-0.006 1 0.51 1 0.51 1 0.51 1 0.51 1 0.51 1 0.002 0.4331-0.006 1 0.518 ± 0.0004 1 0.518 ± 0.0004 1 0.335 1 1.870
Our grippers are supplied with open side air ports and top air ports plugged. When operating top air ports, produce mainfold sealing as shown. Gripper's top air port top air	2x (Ø5H7 x8DP)	Sensors Ø0. not included	Sensors hol 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0.8268 ±0.0008 0	ders Purge / Scavenge port M5 x.24 [6]DP [6.5] 2 x 00.26 through 0.032 (11) x.0.27 [7] DP C Bore [45] [34.5] 1.77 1.358 1.38 [35] 1.77 1.358 1.38 [36] 1.77 1.358 1.38 [36] 1.77 1.358 1.38 [36] 1.77 1.558 1.38 [36] 1.77 1.558 1.38 [36] 1.77 1.558 1.38 [36] 1.77 1.558 1.38 [36] 1.77 1.558 1.38 [36] [37] [10] 0.39 [10] 0.39 [10] 0.39 [10] 0.39 [10] 0.78 [10]	[95] 3.74 (5 ±0.012) 2 × 00.1968 0.0000 × 0.39 [10] DP (at the rear) (at the rear) (17 ±0.02] 0.6693 ±0.0008 (15.5 ±0.02] 1.280 1.280 ±0.0008 (5 ±0.02] 2.1280 ±0.0008 (5 ±0.02] 5.1280 ±0.0008 (5 ±0.02] (5 ±0.02] (5 ±0.02] (5 ±0.02] (5 ±0.02] (5 ±0.02] (5 ±0.02] (5 ±0.002) (5 ±0.02] (5 ±0.02] (5 ±0.02] (5 ±0.02] (5 ±0.02] (5 ±0.02] (5 ±0.02] (5 ±0.008 (5 ±0.008) (5 ±0.008) (5 ±0.008) (5 ±0.02] (5 ±0.02] (5 ±0.008) (5 ±0.02) (5 ±0.008) (5 ±0.00



[14.5] 0.571 Top air port M5 x 0.22 [5.5] DP For RELEASE [54 ±0.02] 2.1260 ±0.0008 **UNLESS OTHERWISE NOTED ALL** [8] [37] 1.46 ດ້ 3 (supplied plugged **TOLERANCES ARE AS SHOWN BELOW** NOTE: To benefit from safety springs $\triangleright \oplus$ Ç € gripper must always be operated with "S" for GRIPPING and with "D" for RELEASE. Dimensions are symmetrical about centerline All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] Third Angle [20] 0.79 Projection t [13] 0.51 [10] 0.39 Drawing hereafter shows gripper gripping at the end of stroke (inlet through **"S**") ¢ [81] Imperial in. Metric [mm] 2 x M6 x 0.51 [13] DP 3.19 [94 3.7($0.00 = \pm .01$ $0.000 = \pm .005$ Metric Threads Course Pitch $0.0000 = \pm .0005$

DGC-45

481 N

30 mm

Loading Information



How to Order: (Order Separately)

BASIC MODEL DGC - 45 -V SIZE VITON[®] SEALS

Quick Disconnect 5 Meter Cable* CABL-013 1 or 2 PNEUMATIC ACCESSORIES Standard Seal Repair Kit SLKT-321 1 Viton® Seal Repair Kit SLKT-321V 1	SENSOR ACCESSORIES 4mm PNP Inductive Sensor with Qk Disconnect* 4mm NPN Inductive Sensor with Qk Disconnect* Quick Disconnect 2 Meter Cable*	ORDER # OISP-014 OISN-014 CABL-010	QTY/UNIT 1 or 2 1 or 2 1 or 2
Standard Seal Repair Kit SLKT-321 1 Viton [®] Seal Repair Kit SLKT-321V 1	Quick Disconnect 5 Meter Cable*	CABL-013	1 or 2
Standard Seal Repair Kit SLKT-321 1 Viton [®] Seal Repair Kit SLKT-321V 1	PNEUMATIC ACCESSORIES		
	Standard Seal Repair Kit Viton® Seal Repair Kit	SLKT-321 SLKT-321V	1

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PARALLEL GRIPPER DGC-65 TWO JAW PRECISION SPRING ASSIST



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8 x M6 x 0.47 [12] DP



Specifications

RECTCONNE

Total Rated Grip Force F @ 100 psi, 7 bar*	179 lbs.	796 N
Stroke	1.575 in	40 mm
Weight	2.87 lbs.	1.30 kg
Pressure Range	45-100 psi	3-7 bar
Cylinder Bore Ø	1.85 in.	47 mm
Displacement	3.78 in ³ .	62 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.35 sec.	0.35 sec.
Accuracy	±0.0009 in.	±0.02 mm
Repeatability	±0.0004 in.	±0.01 mm.
Valve required to actuate single acting	3-way 2-pc	osition
Valve required to actuate double acting	4-way, 2-p	osition
Valve required to actuate double acting	4-way, 2-p	osition

* With springs

	45-100 psi 1.85 in. 3.78 in ³ .
	-30°~180° F -20°~300° F 0.35 sec. ±0.0009 in.
	±0.0004 in.
gle acting	3-way 2-po
ible acting	4-way, 2-pc

DGC-65









NOTE: To benefit from safety springs power, on open or on close, gripper must always be operated with "S" for GRIPPING and with "D" for RELEASE.

Drawing hereafter shows gripper gripping at the end of stroke (inlet through "**S**")



Loading Information



How to Order: (Order Separately)

BASIC MODEL DGC - 65 -V SIZE VITON[®] SEALS SENSOR ACCESSORIES

SENSON AGGESSONIES		Q11/Onit
8mm PNP Inductive Sensor with Qk Disconnect*	OISP-011	1 or 2
8mm NPN Inductive Sensor with Qk Disconnect*	OISN-011	1 or 2
Quick Disconnect 2 Meter Cable*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SLKT-323	1
Viton [®] Seal Repair Kit *Sensor and cable sold separately.	SLKT-323V	1



PARALLEL GRIPPER GC-85 TWO JAW PRECISION SPRING ASSIST



Loading Information



How to Order: (Order Separately)

BASIC MODEL GC - 85 - V SIZE VITON® SEALS

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
8mm PNP Inductive Sensor with Qk Disconnect*	OISP-011	1 or 2
8mm NPN Inductive Sensor with Qk Disconnect*	OISN-011	1 or 2
Quick Disconnect 2 Meter Cable*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SLKT-325	1
Viton [®] Seal Repair Kit *Sensor and cable sold separately.	SLKT-325V	1

PARALLEL GRIPPER GC-105 TWO JAW PRECISION SPRING ASSIST

27

+0.040 8 +0.018 +0.0016

8 x M10 x 0.71 [18] DP

2 x

QTY/UNIT

8600

Ø0.3150 +0.0007 x 0.31 [8] DP



Specifications	GC-105		
Total Rated Grip Force F @ 100 psi, 7 bar*	521 lbs.	2318 N	
Stroke	2.362 in	60 mm	
Weight	9.50 lbs.	4.31 kg	
Pressure Range	45-100 psi	3-7 bar	
Cylinder Bore Ø	2.99 in.	76 mm	
Displacement	15.93 in ³ .	261 cm ³	
Temperature Range			
Standard Seals	-30°~180° F	-35°~80° C	
Viton [®] Seals	-20°~300° F	-30°~150° C	
Actuation	0.7 sec.	0.7 sec.	
Accuracy	±0.0009 in.	±0.02 mm	
Repeatability	±0.0004 in.	±0.01 mm.	
Valve required to actuate single acting	3-way 2-pc	osition	
Valve required to actuate double acting	4-way, 2-p	osition	

* With springs.









[10.5 ±0.02] 0.4134 ±0.001

8

0.005 21 -0.015 -0.0002 0.8268 -0.0006

Loading Information



How to Order: (Order Separately),

2 x M12 x 0.79 [20] DP

BASIC MODEL GC - 105 -SIZE VITON[®] SEALS ORDER # **SENSOR ACCESSORIES**

[176] 6.93

12mm PNP Inductive Sensor with Qk Disconnect*	OISP-017	1 or 2
12mm NPN Inductive Sensor with Qk Disconnect*	OISN-017	1 or 2
Quick Disconnect 2 Meter Cable*	CABL-014	1 or 2
Quick Disconnect 5 Meter Cable*	CABL-018	1 or 2
PNEUMATIC ACCESSORIES		
Standard Seal Repair Kit	SLKT-327	1
Viton® Seal Repair Kit *Sensor and cable sold separately.	SLKT-327V	1







DGC/GC Series Exploded View

ltem	Qty	Name
01	1	Body
02	1	Piston
03	1	Piston Shaft
04	1	Double Wedge
05	1	Сар
06	2	Jaw Holder
07	1	Cover
08	2	Spacer
09	1	Piston Guidance Tape
62	1	Outer Spring
63	1	Inner Spring

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install the seals into cap (x1) and body (x1)
- 2) If rear inlets are used, clear them and plug the side inlets on the body (#1)
- Lubricate the slot of jaws (#6), the double wedge (#4), and the slot of the body (#1).
- Place the double wedge between the two jaws and then introduce the jaws in the slots of the body.
- 5) Assemble the piston: **DGC-25 & DGC-65 (not shown):** lubricate and install the seal onto the one piece piston (#3) Insert the piston into the body, locate it on the double wedge, place the seal ring under the screw cap and screw all the pieces together..

GC-85 (not shown): Insert the shaft (#3) into the body and center it in the double wedge. Lubricate and insert the seals on the piston (#2). Insert the piston into the body while centering on the shaft. Place the seal ring under the screw cap and screw all the pieces together.

GC-105: Insert the shaft (#3) into the body and center it in the double wedge. Lubricate and insert the seals and the guidance ring (#9) on the piston (#2). Insert the piston into the body while centering on the shaft. Place the seal ring under the screw cap and screw all the pieces together.

- 6) Make by hand the piston move into the body
- 7) Insert the two springs (#62 & 63) into the counterbore of the piston
 8) Install the cos (#5) and finite it.
- 8) Install the cap (#5) and fix it with the retaining ring.
- 9) Place and fix the wiper (#7) in the body.
- 10) Mount the sensor holder (#64) and the spacer (#8) on the body sides





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DGC/GC Series Assembled View





ltem	Qty	Name
01	1	Body
02	1	Piston
03	1	Piston Shaft
04	1	Double Wedge
05	1	Сар
06	2	Jaw Holder
07	1	Cover
08	2	Spacer
09	1	Piston Guidance Tape
62	1	Outer Spring
<u>63</u>	1	Inner Spring

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



		Y	PRE		DES	IGN	NOTES	RIES
EC	IS	10		UR	ABI		QUALI	ਲ ਤ 1.195
RA	B			<u>ou</u>		Y PR	ECISIO	
			PRE	CIS	SION	DUF		
EC	IS	10		UR	ABI		QUALI	
RA	BI			QU		YPR	ECISIO	
					SION	DUF		
EC	S	10		UR	ABI		QUALI	
RA	B		TY	QU		Y PR	ECISIO	
			PR		SIGN	DUF		
EC				UR	ABI			
RA				QU		YPR	ECISIO	
			Please see back	cover for DE-STA-0	CO Global Locations. wv	vw.destaco.com		

An Series 1.196

Parallel Grippers -DPW DIRECTCONNECT Wide Body Series

- DIRECTCONNECT[™] Connectivity: DIRECTCONNECT[™] Tapped and Dowel mounting on body.
- Large or Wide Parts: Wide body design provides secure gripping of large & wide parts.
- Multiple air port positions: Tapped air ports on top and front are standard.
- Manifold Air Porting: Top air ports can be manifold o-ring sealed.
- Inductive Sensor Flexibility: Mount either 3mm or 4mm Inductive sensors with the same bracket (3mm only on DPW-250).
- Magnetoresistive Sensing: Full range adjustable Magnetoresistive Sensors. Magnet supplied standard.
- Long Finger Applications: Jaw support thru the length of the body allows for long fingers to be attached to jaws.
- Thru Jaw Mounting: Offers a wider variety of mounting applications for jaws.
- Shaft Wiper Option: Rugged urethane shaft wipers seal the unit against harsh environments. Designed to be used in machine coolant and metal chip environment applications.

DIRECTEONNE

- **Multiple Strokes:** All gripper sizes are available in 2 different strokes.
- **Non-synchronous motion:** The unit can be made non-synchronous providing independent jaw motion allowing the gripper to pick or place at a point other than its center.

Mounting Information:

Grippers can be mounted & operated in any direction

Fingers attach with screws and locate on jaws with dowel pins





DIRECTCONNE

Body mounts on top with screws and locates with slip fit dowel pin holes for accuracy



Thru mounting on inside of jaws to allow for alternate finger mounting

Jaw design allows for simplified mounting of fingers



Symmetrical mounting pattern on jaws allows for multiple finger orientation

Technical Specifications:

Pneumatic Specifications	Imperial	Metric
Pressure Operating Range	40-100 psi	3-7 bar
Cylinder Type	Double	e Acting
Dynamic Seals	Internally Lub	ricated Buna-N
Valve Required to Operate	4-way, 2	-position
Air Quality Requirements		
Air Filtration	40 Micror	n or Better
Air Lubrication	Not Ne	ecessary*
Air Humidity	Low Moisture	e Content (dry)
Temperature Operating Range)	
Buna-N Seals (standard)	-30°~180° F	-35°~80° C
Viton [®] Seals (optional)	-20°~300° F	-30°~150° C
Maintenance Specifications		
Expected Life		
Normal Application	5 million	cycles
w/ Preventative Maintenance	10+ millio	on cycles*
Field Repairable	Ye	S
Seal Repair Kits Available	Ye	s
-W Option Shaft Wiper Specifi	ications	
Wiper Material	90 Duromete	er Urethane
Temperature Rating (Wiper Only)	-65°~275° F	-54°~135° C
Compatible Chemicals v	water, coolant, pet	roleum oils,
sili	icone, lubricants,	dilute acids &
alkalis	s, hydraulic fluid, t	ransmission fluid
Non-Compatible Chemicals	Ozone, ketones,	strong acids,
Formula Annihesticae	brake f	luid abiaa abiaa 0
Example Applications	Grinding dust, ma	chine chips &
Annlication Restrictions	coolant, paper du	si, washu0Wh
Applications where mechanism lu	ubricant could caus	e contamination

*Addition of lubrication will greatly increase service life

Please see back cover for DE-STA-CO Global Locations. www.destaco.com



 This gripper is suitable for internal or external gripping and can be mounted in any orientation.

U.S Patent #5,163,729 Designed, manufactured and assembled in the USA

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

See **1.208**

PARALLEL GRIPPERS DPW-250M-1 DIRECTCONNECT WIDE BODY SERIES





SERIES

NAO

1.198



Specifications	DPW-2 50	M-1
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	0.75 in.	19.1 mm
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.625 in.	15.9 mm
Displacement	0.023 in ³ .	3.8 cm ³
Weight	0.662 lbs.	0.30 Kg
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.12 sec.	0.12 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition

PARALLEL GRIPPERS DPW-250M-1 DIRECT CONNECT WIDE BODY SERIES





$\left[\right]$

DIRECTCONNEC

F/2

-M

Loading Capacity[†] Static Dynamic Maximum Tensile T 60 lbs. [267 N] 12 lbs. [53 N] Maximum Compressive C 60 lbs. [267 N] 12 lbs. [53 N] Maximum Moment Mx 120 in.-1bs. [14 Nm] 24 in.-1bs. [3 Nm] Maximum Moment My 180 in.-Ibs. [20 Nm] 36 in.-Ibs. [4 Nm] 24 in.-Ibs. [3 Nm] Maximum Moment $\mathbf{M}_{\mathbf{Z}}$ 120 in.-1bs. [14 Nm] *Capacities are per set of jaws and are not simultaneous

Mx F/2

Accessory Mounting Technical Data



Please see back cover for DE-STA-CO Global Locations. www.destaco.com WWW.COMOSO.COM

PARALLEL GRIPPERS DPW-250M-2 DIRECTCONNECT WIDE BODY SERIES





SERIES

Mad

1.200



Ex: DPW-250M Gripper, 31.8mm Stroke, Shaft Wipers, Viton Seals



Specifications	DPW-250N	I-2
Total Rated Grip Force F @ 100 psi, 7 bar	50 lbs.	222 N
Stroke	1.25 in.	31.8 mm
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.625 in.	15.9 mm
Displacement	0.383 in ³ .	6.3 cm ³
Weight	0.856 lbs.	0.39 Kg
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.14 sec.	0.14 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition

PARALLEL GRIPPERS DPW-250M-2 DIRECT CONNECT WIDE BODY SERIES



M E/2

Static

60 lbs. [267 N]

60 lbs. [267 N]

120 in.-1bs. [14 Nm]

180 in.-Ibs. [20 Nm]

120 in.-1bs. [14 Nm]

Loading Capacity[†]

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment $\mathbf{M}_{\mathbf{Z}}$

*Capacities are per set of jaws and are not simultaneous

Maximum Tensile T



F/2

Dynamic

12 lbs. [53 N]

12 lbs. [53 N]

24 in.-1bs. [3 Nm]

36 in.-Ibs. [4 Nm] 24 in.-Ibs. [3 Nm]

-M

Accessory Mounting Technical Data



DIRECTCONNE

Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com

PARALLEL GRIPPERS DPW-375M-1 DIRECTCONNECT WIDE BODY SERIES





SERIES

1.202

Please see back cover for DE-STA-CO Global Locations. www.destaco.com



Specifications	DPW-375M-1		
Total Rated Grip Force F @ 100 psi, 7 bar	100 lbs.	445 N	
Stroke	1.00 in.	25.4 mm	
Pressure Range	40-100 psi	3-7 bar	
Cylinder Bore Ø	0.938 in.	23.8 mm	
Displacement	0.690 in ³ .	11.3 cm ³	
Weight	1.80 lbs.	0.81 Kg	
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C	
Viton [®] Seals	-20°~300° F	-30°~150° C	
Actuation	0.16 sec.	0.16 sec.	
Accuracy	±0.003 in.	±0.08 mm	
Repeatability	±0.001 in.	±0.03 mm	
Valve required to actuate	4-way, 2-p	osition	

PARALLEL GRIPPERS DPW-375M-1 DIRECT CONNECT WIDE BODY SERIES



Mx F/2

Static

120 lbs. [534 N]

120 lbs. [534 N]

210 in.-Ibs. [24 Nm]

300 in.-1bs. [34 Nm]

210 in.-1bs. [24 Nm]

Loading Capacity[†]

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment $\mathbf{M}_{\mathbf{Z}}$

*Capacities are per set of jaws and are not simultaneous

Maximum Tensile T



F/2

Dynamic

24 lbs. [107 N]

24 lbs. [107 N]

42 in.-Ibs. [5 Nm] 60 in.-Ibs. [7 Nm]

42 in.-Ibs. [5 Nm]

-M

Accessory Mounting Technical Data



Please see back cover for DE-STA-CO Global Locations. www.destaco.com WWW.COMOSO.COM

PARALLEL GRIPPERS DPW-375M-2 DIRECTCONNECT WIDE BODY SERIES





Specifications	DPW-375	M-2
Total Rated Grip Force F @ 100 psi, 7 bar	100 lbs.	445 N
Stroke	2.00 in.	50.8mm
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	0.938 in.	23.8 mm
Displacement	1.382 in ³ .	22.6 cm ³
Weight	2.66 lbs.	1.20 Kg
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.20 sec.	0.20 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition

PARALLEL GRIPPERS DPW-375M-2 DIRECT CONNECT WIDE BODY SERIES





		My	
Loading Capacity ^{\dagger}	Static	Dynamic	
Maximum Tensile T	120 lbs. [534 N]	24 lbs. [107 N]	
Maximum Compressive C	120 lbs. [534 N]	24 lbs. [107 N]	
Maximum Moment Mx	210 in1bs. [24 Nm]	42 inIbs. [5 Nm]	
Maximum Moment My	300 inIbs. [34 Nm]	60 inIbs. [7 Nm]	

210 in.-Ibs. [24 Nm]

Maximum Moment Mz

*Capacities are per set of jaws and are not simultaneous

42 in.-Ibs. [5 Nm]

Accessory Mounting Technical Data



DIRECTCONNE

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

PARALLEL GRIPPERS DPW-500M-1 DIRECTCONNECT WIDE BODY SERIES

SERIES





SAMPLE ORDER: DPW-500M-1-W-V Ex: DPW-500M Gripper, 38.1mm Stroke, Shaft Wipers, Viton Seals

*Sensor and cable sold separately



Specifications	DPW- 500)M-1
Total Rated Grip Force F @ 100 psi, 7 bar	180 lbs.	800 N
Stroke	1.50 in.	38.1 mm
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.250 in.	31.8 mm
Displacement	1.841 in ³ .	30.2 cm ³
Weight	3.27 lbs.	1.48 Kg
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.20 sec.	0.20 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition

PARALLEL GRIPPERS DPW-500M-1 DIRECT CONNECT WIDE BODY SERIES





Static

Dynamic

Loading Capacity[†]

Maximum Tensile T	600 lbs. [2668 N]	60 lbs. [267 N]		
Maximum Compressive C	600 lbs. [2668 N]	60 lbs. [267 N]		
Maximum Moment M x	600 in1bs. [68 Nm]	60 inIbs. [7 Nm]		
Maximum Moment My	900 in1bs. [102 Nm]	90 inIbs. [10 Nm]		
Maximum Moment Mz	600 in1bs. [68 Nm]	60 in1bs. [7 Nm]		
*Capacities are per set of jaws and are not simultaneous				

Accessory Mounting Technical Data



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Please see back cover for DE-STA-CO Global Locations. www.destaco.com

PARALLEL GRIPPERS DPW-500M-2 DIRECTCONNECT WIDE BODY SERIES



DIRECTCONNE


Specifications	DPW-500	M-2
Total Rated Grip Force F @ 100 psi, 7 bar	180 lbs.	800 N
Stroke	2.50 in.	63.5 mm
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.250 in.	31.8 mm
Displacement	3.068 in ³ .	50.3 cm ³
Weight	4.39 lbs.	2.0 Kg
Temperature Range: Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.28 sec.	0.28 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-p	osition

PARALLEL GRIPPERS DPW-500M-2 DIRECT CONNECT WIDE BODY SERIES





Static

Dynamic

Loading Capacity[†]

Maximum Tensile T	600 lbs. [2668 N]	60 lbs. [267 N]
Maximum Compressive C	600 lbs. [2668 N]	60 lbs. [267 N]
Maximum Moment M _X	600 in1bs. [68 Nm]	60 inIbs. [7 Nm]
Maximum Moment My	900 inIbs. [102 Nm]	90 inIbs. [10 Nm]
Maximum Moment Mz	600 in1bs. [68 Nm]	60 inIbs. [7 Nm]
⁺ Capacities are per set of jaws and are	not simultaneous	

Accessory Mounting Technical Data



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Please see back cover for DE-STA-CO Global Locations. www.destaco.com

DPW SERIES EXPLODED VIEW



Assembly Procedure:

- 1) Lubricate and install seals on piston.
- 2) Install pistons and shafts.
- 3) Mount end caps to enclose piston assembly.
- 4) Install tooling plates and shafts.
- 5) Place bearing, shaft, and gear into body and install cap and retaining ring for sync version.
- a) For disassembly, use magnet to pull gear out of body.
- b) Install 2 gear shafts with teeth facing syncing gear. Use dowel to align gear shafts in correct position.

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01	1	Body
02	8	Bushing, Oil Impregnated Bronze
03	2	End Cap
04	2	Jaw
05*	2	Guide Shaft, Rack
06*	2	Guide Shaft (Qty 4 for -NS)
07	2	Piston Rod
08	2	Piston
09	1	Cap, Gear
10*	1	Gear
<u>11*</u>	1	Bearing, Radial
12*	2	Piston Rod Wiper (Shaft Wiper
		"-W" option only)
13*	8	Shaft Wiper (Shaft Wiper "-W" option only)
14	2	Piston Bumper
15	2	Piston O-ring
16	2	Teflon Ring
17*	2	Body O-ring
18	2	U-cup
19	2	Jaw Bumper
20	1	Gear Cap O-ring
21	1	Retaining Ring
22	1	Magnet
23	8	End Cap Mntg Screw
24	4	Guide Shaft Mntg Screw
25	4	Piston Shaft Mntg Screw
26*	2	Guide Shaft Alignment Dowel
27	2	Manifold Port Plug
28	8	Retainer Ring (Shaft Wiper "-W" Option only)
29	2	Retainer Ring (Shaft Wiper "-W" Option only)
30*	4	End Cap Mntg Screw
31	4	End Cap Dowel Pins

*Notes:

(X

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- 1) Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Quantity of #6 is 4 when ordering a Non-synchronous aripper.
- 3) Items #5, #10, #11, and #26 are for synchronous grippers only.
- 4) Items #12 and #13 are for -W option only.
- 5) Item #17 (Body O-ring) shown in body groove.
- 6) Item #23 Quantity is 6 for 375-1 and 375-2 only.
- 7) Item #30 is only used in 375-1 and 375-2.

Non-Synchronous Procedure:

- 1) Take DPW synchronous gripper and remove the retaining ring and gear cap.
- Remove gear from gripper. 2)
- 3) Replace gear cap and retaining ring. The gripper is now non-synchronous

-W Option Assembly Procedure:

- Take out guide shaft and piston rod mounting screws.
 Remove jaws from guide shafts and piston rods.
- 3ĺ Take out end cap mounting screws and pull off end caps. Take out piston.
- 4) Slide out shafts and press wipers in pockets thru front side. Install retaining rings.
- 5) Replace shafts, pistons, and end caps.
- 6) Be sure to apply thread locker to mounting screws. The gripper now has shaft wipers.



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DPW SERIES ASSEMBLED VIEW





*Notes:

- 1) Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Quantity of #6 is 4 when ordering a Non-synchronous gripper.
- 3) Items #5, #10, #11, and #26 are for synchronous grippers only.
- 4) Items #12 and #13 are for –W option only.
- 5) Item #17 (Body O-ring) shown in body groove.
- 6) Item #23 Quantity is 6 for 375-1 and 375-2 only.
- 7) Item #30 is only used in 375-1 and 375-2.

item	Qty	Name
01	1	Body
02	8	Bushing, Oil Impregnated Bronze
03	2	End Cap
04	2	Jaw
05*	2	Guide Shaft, Rack
06*	2	Guide Shaft (Qty 4 for NS)
07	2	Piston Rod
08	2	Piston
09	1	Cap, Gear
10*	1	Gear
11*	1	Bearing, Radial
12*	2	Piston Rod Wiper (Shaft Wiper
		"-W" option only)
13*	8	Shaft Wiper (Shaft Wiper "-W" option only)
14	2	Piston Bumper
15	2	Piston O-Ring
16	2	Teflon Ring
17*	2	Body O-Ring
18	2	U-cup
19	2	Jaw Bumper
20	1	Gear Cap O-ring
21	1	Retaining ring
22	1	Magnet
23	8	End Cap Mntg Screw
24	4	Guide Shaft Mntg Screw
25	4	Piston Shaft Mntg Screw
26*	2	Guide Shaft Alignment Dowel
27	2	Manifold Port Plug
28	8	Retainer Ring (Shaft Wiper "-W" Option only)
29	2	Retainer Ring (Shaft Wiper "-W" Option only)
30*	4	End Cap Mntg Screw
31	4	End Cap Dowel Pins

Accessory Installation & Adjustment Instructions



Plumbing Fittings:

- 1) Flow Controls #39 or #40 can be inserted and used in any open or closed airport to help control the stroke actuation.
- 2) Fail-Safe Valve #37 or #38 can be used in either the open or closed airport to help limit the possibility of dropping the part if air pressure is lost.

Magneto-Resistive Sensors:

Insert sensors #28 or #29 into the opening at the end of the profile slot and lock the sensor into position with the integrated screw.

Inductive Sensors:

- Mount inductive sensor target (#32) to jaw using mounting screw (#36).
 Insert sensor bracket (#33) into slot of body.
 Insert sensor (#30 or #31) into appropriate 3mm or 4mm opening in
- bracket and adjust sensor depth so that sensor light indicates target (#32).
- 4) Tighten sensor locking screw (#34).
- 5) Position sensor bracket for desired stroke detection.
- 6) Tighten sensor bracket with set screw (#35) to lock stroke detection position.



Other Plumbing Fittings are available for each size - Consult Factory

item	Qty	Name
28	1,2	Magneto Resistive Sensor (short barrel) w/Qk. Disconnect
29	1,2	Magneto Resistive Sensor (90° barrel) w/Qk. Disconnect
30	1,2	Inductive Sensor (3mm) w/Qk. Disconnect
31	1,2	Inductive Sensor (4mm) w/Qk. Disconnect
		(DPW-375 & 500 only)
39	1,2	Adjustable Flow Control (Imperial) #10-32 elbow - 1/4" OD
		Push-in Style
40	1,2	Adjustable Flow Control (Metric) M5 elbow - 6mm 0D
		Push-in Style
37	1	Fail Safe Valve (Imperial) #10-32
38	1	Fail Safe Valve (Metric) M5

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DPW SERIES SPECIALS



Smaller or Larger Bores Metallic Rod Scrapers Extended Strokes Alternate Materials and more...

Drawings are for concept only. Contact Robohand Tech Support with project requirements.

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DPW SERIES SPECIALS

DPW SERIES SPECIALS 1.213

Please describe your application. Include a sketch or attach additional sheets if necessary.



RPW SERIES 1.214

Parallel Grippers -Wide Body Series





- Machining applications: Sealed design repels chips and other particulate from the internal drive mechanism.
- Long gripper fingers: Jaw support thru the length of the body allows for long fingers to be attached to the jaws.

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• Large or wide parts: Wide body design provides secure gripping of large & wide parts.

• Non synchronous motion: The unit can be made non-synchronous providing independent jaw motion allowing the gripper to pick or place at a point other than it's center.

Mounting Information:





Fingers attach with screws

and locate on jaws with

dowel pins

Mandalak



Jaw design allows for simplified mounting of fingers



Body mounts on top or on side with screws and locates with slip fit dowel pin holes for accuracy

Technical Specifications:

Pressure Operating Range Cylinder Type Dynamic Seals Valve Required	Imperial 40-100 psi Dual Doub Internally Lubri 4-way, 2	Metric 3-7 bar le Acting icated Buna-N 2-position
Air Quality Requirements Air Filtration Air Lubrication Air Humidity	40 Micro Not Ne Low Moisture	n or Better cessary* Content (dry)
Temperature Operating Ra Buna-N Seals (standard) Viton [®] Seals (optional)	nge -30°~180° F -20°~300° F	-35°~80° C -30°~150° C
Maintenance Specification Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available *Addition of lubrication will greatly increase 'See Maintenance Section	is [†] 5 milli Ce 10+ mill Ye Ye service life	on cycles ion cycles* s s

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- and are supported through the length of the body.
- Two double acting opposed pistons provide power to the jaws.
- The rack shafts of each jaw slide in opposite directions of one another and are synchronized by a pinion gear.
- This gripper is suitable for internal or external gripping.

U.S. Patent # 5,163,729 **Designed and manufactured in the USA**



541145

1.215

SERIES

MAX

1.216





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PARALLEL GRIPPER RPW-625M-2 WIDE BODY SERIES

Specifications	RPW-625-2	RPW-625M-2
Total Rated Grip Force F @ 100 psi, 7 bar2	40 lb	1068 N
Stroke	3.50 in.	88.9 mm
Weight	7.8 lb	3.6 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.625 in.	41.3 mm
Displacement	2.310 in ³ .	37.9 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.69 sec.	0.69 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-p	osition





2X Ø .1875 SF X .26 DP [Ø 5 H7 X 6 DP] 6X 1/4-20 X .42 DP [M6 X 10 DP] - 1.125 [28.6] 2X 3.240 [82.3] (JAW) 2.5000 [63.50] 3.250 [82.6] (BODY) - 5.375 [136.5]-





Loading Information

How to Order: (Order Accessories separately from Basic Model)



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PARALLEL GRIPPER RPW-750M WIDE BODY SERIES





Specifications	RPW-750	RPW-750M
Total Rated Grip Force F @ 100 psi, 7 bar4	70 lb	2091 N
Stroke	4.50 in.	114.3 mm
Weight	14 lb	6.4 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	2.000 in.	50.8 mm
Displacement	14.200 in ³ .	232.7 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	1.00 sec.	1.00 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate double acting	4-way, 2-p	osition



- 1.500 [38.1]

2X 3.928

[99.8] (JAW)

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6X 5/16-18 X .50 DP [M8 X 12 DP]

-		
.38 [10]	1.19 (30) 1.62 (41) (41) -3.00 [76] -2X #10-32 X .25 DP [M5 X 2X 1/8 NPT [G1/8"] AIR I 1.25 [32] 	6 DP] (SENSOR MNTG HOLES) PORTS (OPEN)
, · · · · · · · · · · · · · · · ·	- 16.14 [410] (OPEN)	

UNLES	S UTRENWI	JE NUIED ALL
TOLERAN	CES ARE AS	S SHOWN BELOW
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]
Metric Threads Course Pitch	$\begin{array}{l} \text{Imperial in} \\ 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .000 \end{array}$. Metric [mm] [0.] = [±.25] 5 [0.0] = [±.13] 95 [0.00] = [±.013]

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Loading Information

How to Order: (Order Accessories separately from Basic Model) **GRIP FORCE PER FINGER** N lbs. 1113 250 **BASIC MODEL NON-SYNCHRONOUS** 음^{890 200} WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE 100 **RPW-750** 80 PSI FINGER FORCE 668 **150** FINGER LENGTHS 60 PSI 445 100 METRIC **VITON® SEALS** 223 50 **SENSOR ACCESSORIES** ORDER # QTY/UNIT Sensor Mounting Kit for Imperial & Metric Units (mounts 2 sensors) **OSMK-014** 1 0 NPN Inductive Sensor with Quick Disconnect* OISN-011 1 or 2 Ò 8 12 16 20 in. PNP Inductive Sensor with Quick Disconnect* OISP-011 1 or 2 EFFECTIVE FINGER LENGTH - L Quick Disconnect 2 Meter Cable Length* CABL-010 1 or 2 Quick Disconnect 5 Meter Cable Length* CABL-013 1 or 2 Ζ **PNEUMATIC ACCESSORIES** М Fail Safe Valve (Imperial) **OFSV-002** 1 0:0 **OFSV-005** Fail Safe Valve (Metric) 1 **SLKT-060** Standard Seal Repair Kit х 1 L SLKT-060V 1 Viton[®] Seal Repair Kit Т C F/2 F/2 *Sensor and cable sold separately. Mx M INDUCTIVE SENSORS AND FAILSAFE Static Dynamic MOUNTING KIT VALVE Loading Capacity[†] Metric Imperial Metric Imperial -.88 [22] 0:0 0:0 Maximum Tensile T 2500 lb 1112 N 11121 N 250 lb 0 0 0 0 Maximum Compressive C 2500 lb 11121 N 250 lb 1112 N 0 t **a a** Maximum Moment Mx 2000 in.- lb 226 Nm 200 in.-Ib 22 Nm 0\$0 ()\$⊚ Maximum Moment My 3000 in.-Ib 339 Nm 250 in.-Ib 28 Nm 4.04 [103] .36 [9] BRACKET -2.20 [56] Maximum Moment Mz ADJUSTABILITY MIN. 2000 in.-Ib 226 Nm 200 in.-Ib 22 Nm [†]Capacities are per set of jaws and are not simultaneous

Please see back cover for DE-STA-CO Global Locations. www.destaco.com



Item Qty Name

Body

Piston

Сар

<u>Shaft</u> Gear Cover

Gear

Shaft, Piston

Block, End W/ Target Holes

Shaft,Gear

Dowel Pin

Ball

01

03 2

04 2

05 2

06 1

07 1

<u>09</u>

10 2

20 2

21

22

23

1



NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Bearing, Needle

Assembly Procedure

- 1) Lubricate and install seals.
- 2) Install pistons and shafts.*
- 3) Place piston caps and retaining rings into body
- 4) Install tooling plates and shafts
- Final team of the second - a) For disassembly, use magnet to pull gear out of body.
- b) Install 2 rack shafts with teeth facing syncing gear.

Non-Synchronous Procedure

- 1) Take RPW synchronous gripper and remove the retainer ring and gear cover.
- 2) Slide out dowel pin and bearing.
- Remove gear from gripper. (a magnet is often very helpful in removing the gear.)
- Replace the dowel pin, gear cover, and retainer ring. The gripper is now non-synchronous.

SK Seal Repair Kit Order #'s See Product Data Sheets







Item Qty Name

01	1	Body
03	2	Piston
04	2	Сар
05	2	Shaft
06	1	Gear Cover
07	1	Gear
09	2	Shaft, Piston
10	2	Shaft,Gear
20	2	Block, End W/ Target Holes
21	1	Bearing, Needle
22	1	Dowel Pin
23	1	Ball

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions

Install target as shown, install sensors as shown, adjust for proper end of stroke sensing.





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SERIES RPR SERIES 1.222

Parallel Grippers -RPR Gladiator Series

Long Finger Applications:

Non-synchronous motion:

than it's center.

allows for longer finger lengths.

Rigid design and full body support of jaws

The unit can be made non-synchronous

providing independent jaw motion allowing

the gripper to pick and place at a point other

- Large, heavy or wide parts: Wide body & long stroke design provide secure gripping of large heavy parts.
- Machining & foundry applications: Rod wipers repel chips and other particulate.
- Gripper Interchangeability: Bolt in replacement for PHD's GRR series gripper
- Multiple Sensing Options: Choose between inductive proximity sensors or a linear encoder.
- **Maximum rigidity:** Jaws are supported by 3 shafts, shafts are supported at 3 points.

Mounting Information:

Grippers can be mounted & operated in any orientation



Fingers mount on the bottom of the jaws with screws and dowel pins.



Body mounts with screws from behind and slip fit dowel pin holes for accuracy.

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type **Dynamic Seals** Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements

Air Filtration	40 Micron or Better
Air Lubrication	Not Necessary*
Air Humidity	Low Moisture Content (dry)

Temperature Operating Range

-30°~180° F Buna-N Seals (standard) -35°~80° C Viton[®] Seals (optional) -20°~300° F -30°~150° C

Maintenance Specifications

Expected Life	
Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycles*
Field Repairable	Yes
Seal Repair Kits Available	Yes
Addition of lubrication will greatly increase service lin	fe

Product Features

Rack & Pinion Synchronizer Rack and Pinion Synchronizer built inside the back plate for protection against contaminants and harsh environment. Optional non-synchronized gripper available.

Rigid, Jaw bearing support Four, Flouropolymer composite bushings provide enhanced support to the jaws, protect against contaminants and corrosive environment

Gripper Actuation Ports Easy access to gripper open and close ports



Low Friction Seals and Wipers Pressure energized seals inside jaws offer minimum breakaway friction and enhanced cycle time. Other optional seals available for higher temperature and specific chemical compatibility

ed onal gher cific liv v and precision guides provide higher stiffness and precision guide to the Jaws

Enhanced Piston Tube

Ground, stainless steel piston tube for

superior wear and corrosion resistsance

Bearing and Shaft Protection Four shaft wipers provide continuous protection to the bearings inside the jaws Optional - Gripper Open and Gripper Close Inductive Sensors Optional Inductive sensors available to detect gripper open and close positions

Stroke Available with 200mm stroke. Consult factory for different strokes



Optional - Rod Lock Optional Rod Lock valves available to lock jaws in position in case or air loss **Pented** Rod lock design integral inside the jaw provide provide protection against contaminants.

Optional - Jaw Position Analog sensors Optional Analog sensors available to continuously detect jaw positions along the stroke

Simplified Finger Mounting Large jaw configuration to accept heavy loads and equipped with dowel holes for precision assembly with fingers. The jaws are supplied with coated steel inserts for superior clamping force and corrosion resistance.



- The jaws are mechanically synchronized with two racks and a pinion located in the back plate.
- The gripper is also available without rack and pinion in non-synchronous configurtion.
- This gripper is available with inductive sensors to detect jaw open and jaw closed positions.
- This gripper is also available with anolog sensor to detect jaw positions any where along the gripper stroke.
- This gripper is suitable for internal or external gripping and can be mounted in any orientation.

Style -RPR-63M Parallel Gripper

Size -63M-200 Stroke: 7.87 in. 200 mm Grip Force: 800 lbs. 3520 N Weight: 35 lbs. 15.8 Kg





Note: Additional strokes available upon request. Contact DE-STA-CO for more information.

PARALLEL GRIPPER RPR GLADIATOR SERIES

SERIES

1.224





Ex: RPR-63M, Metric Gripper, 150 Stroke, Non Synchronized, Viton® Seals, Stainless Steel, 2 Rod Locks



PARALLEL GRIPPER RPR **GLADIATOR SERIES**

Mz

7500 in.-lbs. [825 Nm] Maximum Moment My 9000 lbs. [990 N] Maximum Moment Mz 7500 in.-lbs. [825 Nm] ΤŤ C Maximum Effective Finger Length L 20 in. [500mm] Mx WARNING! **GRIP FORCE PER FINGER** Ν N lbs. DO NOT EXCEED MAXIMUM EFFECTIVE 100 PSI [7 bar 1540 **350** FINGER LENGTHS 87 PSI 음 1320 300 H 1100 250 H 1100 250 H 660 200 H 660 150 H 440 100 60 _. PSI 220 50 My 0 ٥. **8 10 12** 203 254 305 14 356 16 406 18 457 n 20 in. 508mm 51 102 152 **EFFECTIVE FINGER LENGTH - L ROD LOCK-RHS** TARGET (Air Port - G 1/8) SLOPPED SUBFACE GRIPER OPEN PORT FACING SENSOR. **GRIPER CLOSE PORT-**SENSORS MTG BRACKET ROD LOCK-LHS (Air Port-G 1/8) OP SURFACE ADJUST GAP AT THICK EN (GRIPPER CLOSED): 0.25M R.H.S OPEN GRIPPER AND VALIE SENSOR OUT PUT FROM 0 0 0 6 L.H.S. 6 a 0 Rod Lock (Fail Safe Valve) • Used in applications where the part being gripped not be dropped if the air pressure is lost · Mounts directly to the jaw. (Must use Jaw with Rod lock option) Available options: LHS Rod Lock RHS Rod Lock Two Rod locks. (As shown) · Holding force: 1400 N (318 Lbf) max per rod lok. Note: If holding forces are exceeded, slippage may occur. MOVING TARGETS LOCATE ON THE JAW AND TIGHTEN TO SECURE • Rod lock 'clamp time' when air loss: 250 ms..... ref SENSOR MTG BRACKET valve, mufflers ... , and as apply) ADJUST GAP: 0.5 MM. (SENSOR FACE TO Air port: G 1/8 TARGET) MOVE THE JAW AND ADJUST Air specifications: AS REQUIRE Air Supply pressure: 10 bar (147 psig) max. Minimum release pressure: 3 bars (44.1 psig) • Air quality: Filteration: 40 micron, min. Non Lubricated, dry air. . The two inductive sensors are stationary and mounted with a bracket directly to the back plate • The target is mounted on the moving jaw The sensor cable has quick disconect connector at the sensor end and open pig tail wires at the otherend. Cable available in two lengths - 2M & 5M

Mz

- Adjustments required after assembly: • Air gap between sensor face and moving target to 0.5 mm and fine adjust as required. Tighten the lock nuts on the sensors to avoid loosensing under application.
- · Location of the moving target on the jaw to suit stroke

Accessory Mounting Technical Data

Loading Capacity:

Maximum Compressive C

Maximum Moment Mx

3500 lbs. [15570 N]

3500 lbs. [15570 N]

Maximum Tensile T



RPR SERIES EXPLODED VIEW





A. Standard - Synchronous Gripper

- 1) Lubricate and install O-rings in the two end blocks and in the middle block. Install set screws (air plug, Item 21) into the two end blocks and the middle block.
- 2) Assemble RHS and LHS Jaws E-Z locks, bushings, o-rings and piston assembly
- 3) Assemble RHS jaw assembly to the three guide shafts. Assemble RHS end block to the guide shafts.
- 4) Assemble the mid block and assemble RHS piston tubes and RHS cross tubes.
- 5) Assemble the LHS jaw to the three guide shafts.Install the piston tubes and the Cross tubes as described earlier. Install LHS end block and install it's fasteners, `snug tight' to the three guide rods. Verify that the two jaws can traverse along the guide bars without any binding
- 6) Install the cover to the middle block by locating it with the dowel pins above. Install the racks to the jaws by first locating with the dowel pins and then with fasteners. Lubricate the needle bearing, install it into the pinion and install this assembly to the middle dowel pin.
- 7) Lubricate the racks, the pinion and inside of the grooves of the back plate. Locate the back plate between the two end blocks and carefully engage it to the three dowel pin, protruding out of the middle block. Install the fasteners and snug tight to secure the back plate to the middle plate and to the end blocks. Install fastensers for the cover and tighten them.

Item	Qty	Name
01	1	Base Plate
21	2	End Block
03	1	Mid Block
04	4	Piston Tube
05	3	Guide Shaft
06	2	Piston
07	4	Сар
08	2	Cross Tube
09*	2	Rack
10	1	Cover
11*	2	Jaw
12	12	EZ-Lock Insert- Back Plate
13	2	Base Plate MTG Screws
14	8	Cover MTG Screws
15	12	Composite BushingS
16*	1	Needle Bearing
17*	1	Needle Bearing MTG Dowel
18	4	Rack MTG Screw
19*	4	Rack MTG Dowel
20	2	Cover MTG DoweL
21	3	Air Passage Plug - Set Screw
22	4	Cross Tube O-Ring
23	4	Piston Tube O-Ring
24	4	U-Cup Piston
25	2	Wear Band
26	12	Shaft Wiper
27	4	Cap O-Ring
28*	1	Pinion
29	4	Piston Tube O-Ring- Inner
30	8	EZ-Lock Insert- Jaws
31*	4	Cap Retaining Ring
32	12	End Block MTG Screw

*Notes:

- 1) Contact De-Sta-Co Sales Department for complete spare parts list with order number and process.
- 2) Item # 31 will be different between Imperial and Metric grippers. All other features will remain same.
- 3) Item numbers #9, #16, #17, # 19, and #28, are for Synchronous gripper only.
- 4) Item # 11 will be different for gripper with Rod lock options.
- 5) For High Temperature option, all O-rings will be of viton material.
- 6) For Corrosion resistant option, all fasteners will be stainless steel.

Note: Customer to plumb the rod lock valves to his safety circuit.

8) Assembly validation and torgue the fastener

- A) Torque all the fasteners to their specification. Bĺ
- Connect 40 psig air to the gripper ports. Cycle the gripper open/close and verify that the jaw motions are smooth, free of binding, noise and without air leak.
- C) Increase air pressure to 100 psig. Cycle the gripper open/close and verify that the jaw motions are smooth, free of binding, noise and wituout air leak.

B. Standard - Non Synchronous Gripper

For Non-Synchronous gripper, DO NOT install items #9, #16, #17, #19 and #28.

C. Gripper with ROD LOCK option

Note: Gripper with Rod Lock option will use different item #11 and will use Rod lock valve.

A) Assemble the jaws to the guide shafts with Rod Lock. B) All other steps, as above.



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RPR SERIES ASSEMBLED VIEW

Item	Qty	Name
01	1	Base Plate
21	2	End Block
03	1	Mid Block
04	4	Piston Tube
05	3	Guide Shaft
06	2	Piston
07	4	Сар
08	2	Cross Tube
09*	2	Rack
10	1	Cover
11*	2	Jaw
12	12	EZ-Lock Insert- Back Plate
13	2	Base Plate MTG Screws
14	8	Cover MTG Screws
15	12	Composite BushingS
16*	1	Needle Bearing
17*	1	Needle Bearing MTG Dowel
18	4	Rack MTG Screw
19*	4	Rack MTG Dowel
20	2	Cover MTG DoweL
21	3	Air Passage Plug - Set Screw
22	4	Cross Tube O-Ring
23	4	Piston Tube O-Ring
24	4	U-Cup Piston
25	2	Wear Band
26	12	Shaft Wiper
27	4	Cap O-Ring
28*	1	Pinion
29	4	Piston Tube O-Ring- Inner
30*	8	EZ-Lock Insert- Jaws
31	4	Cap Retaining Ring
32	12	End Block MTG Screw

*Notes:

- 1) Contact De-Sta-Co Sales Department for complete spare parts list with order number and prices.
- 2) For Synchronous gripper Items #9, #16, #17, #19 & #28 are installed in back plate.
- 3) For Metric gripper, item# 30 will be with metric threads. Other features remain same as in Imperial version.
- 4) For High Temperature option all O-rings will be of Viton material.
- 5) For Corrosion environment, all fasteners will be of stainless steel material.
- 6) For Rod-lock option item # 11 will be intrgrated with Rod-lock unit.

Note: Customer to provide and plumb their pneumatic safety circuitry to vent Rod-lock unit in case of air loss.

"B-Series" Industrial Parallel





BPW - WIDE BODY SERIES

The BPW Parallel Gripper feature a wide body design ideal for handling large and wide parts using long fingers. The jaws are supported through the full length of the body for high moment carrying capacity and are sealed against chips or particles, which makes it ideal for use in machining or foundry applications.

- For Large and Wide Parts
- High Grip Forces and Moment Loads
- Support for Long Fingers
- Non-synchronous Option
- Optional Spring Close (BPW-1600 only)

BRP - HEAVY DUTY SERIES

The BRP Parallel Gripper are heavy duty and rugged for reliable operation in real life industrial operations. Sealed jaws protect the internal mechanism from chips and coolant in machining applications. Hardened tool steel jaws and supports allow for long tooling fingers and high moments and forces.

- Rugged Design
- High Grip Forces and Moment Loads
- Support for Long Fingers
- Optional Spring Open or Close



BPG - LONG STROKE SERIES

The BPG Parallel Gripper feature a long stroke and low profile and they are often used to handle different size parts with the same fingers. The jaws and supports are made of hardened tool steel and the body is made of lightweight, hard anodized aluminum.

- Accommodate Multiple Part Sizes with same Fingers
- Long Strokes
- Optional Spring Open or Close
- Low Profile Design

Grippers



Model #	Stroke	Grip Force	Weight	X	Y	Z
BPW-1600	6.3 in [160 mm]	970 lbs [3868 N]	88 lbs [40 kg]	17.9 in [454 mm]	7.1 in [180 mm]	5.9 in [150 mm]
BPW-2000	7.8 in [200 mm]	1920 lbs [8536 N]	154 lbs [70 kg]	27 in [694 mm]	8.0 in [203 mm]	6.9 in [174 mm]



	SHUKE	Grip Force	weigin	^		2
BRP-20	1.5 in [38 mm]	1618 lbs [7200 N]	40.3 lbs [18.3 kg]	8.19 in [208 mm]	7.87 in [200 mm]	6.16 in [157 mm]
BRP-21	1.5 in [38 mm]	3462 lbs [15400 N]	81.6 lbs [37 kg]	12.13 in [308 mm]	10.63 in [270 mm]	6.69 in [170 mm]
BRP-21-D	2.5 in [64 mm]	2001 lbs [8900 N]	81.6 lbs [37 kg]	12.13 in [308 mm]	10.63 in [270 mm]	6.69 in [170 mm]



BPG-160 4.06 in [160 mm] 1787lbs [7950 N] 126 lbs [57 kg] 23.78 in [604 mm] 10.63 in [270 mm] 5.51 in [140 mm]

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Parallel Grippers -3-Jaw Centering Series

- Machining applications: The 3 concentric jaws and excellent repeatability make it easier to accurately load and unload round parts.
- Harsh environments: Shielded design repels chips and other particulate from internal drive mechanism. Viton[®] seals are standard.
- Compact, robust and powerful gripper This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

• **Different strokes:** All gripper sizes are available in 2 stroke sizes.

- For long fingers applications: The large surface area of the jaws coupled with the encapsulated bottom case design allows for long finger designs.
- Multipurpose gripper: A wide range of options & accessories (extended stroke, safety springs for internal or external gripping, magneto resistive or inductive sensors, stripper plate) allow these grippers to be used in a wide number of applications.



Mounting Information:

Grippers can be mounted & operated in any orientation

Gripper is located using two dowel pins and assembled from the top with 3 screws.



Body mounts with 4 screws

and locates with 2 slip fit

dowel pins for accuracy

The gripper can also be assembled from the bottom with 3 through body screws.



Gripper is protected from debris when operated upside down. Gripper can be operated utilizing top manifold air ports.



Fingers are located on jaws with 2 dowel sleeves (provided) and assembled with 2 screws.

Technical Specifications:

Pneumatic Specifications	Imperial	Metric
Pressure Operating Range without Springs	30-100 psi	2-7 bar
Cylinder Type	Double A or Double Acting or Single Acting	Acting Spring Assist Spring Return
Dynamic Seals Valve Required to Operate:	Internally Lubr	icated Viton®
Double Acting Single Acting (-C or -O Op	4-way, 2 - otion) 3-way, 2 -	position position
Air Quality Requirements Air Filtration Air Lubrication Air Humidity	40 Micro Not Nece Low Moisture (n or Better ssary* Content (dry)
Temnerature Onerating Ra	ange	
Buna-N Seals (Standard) Viton® Seals (Optional)	-30°~180° F -20°~300° F	-35°~80° C -30°~150° C
Maintenance Specificatio	ns [†]	
Expected Life	F	
w/ Preventative Maintenan	ce 10+ milli	cycles on cycles*
Field Repairable	Yes	5
Seal Repair Kits Available	Yes	6
*Addition of lubrication will greatly increase	e service life	

*Addition of lubrication will greatly increase service li *See Maintenance Section

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PARALLEL GRIPPER RTH/DTH-1M 3-JAW CENTERING SERIES



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RTH/DTH

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RTH/DTH-1M Loading Information



Loading Capacity ⁺	Static	Dynamic
Maximum Tensile T	182 lbs. [810 N]	20 lbs. [89 N]
Maximum Compressive C	238 lbs. [1060 N]	20 lbs. [89 N]
Maximum Moment M _X	195 inIbs. [22 Nm]	18 inIbs. [2 Nm]
Maximum Moment My	248 in lbs. [28 Nm]	27 inlbs. [3 Nm]
Maximum Moment Mz	159 inIbs. [18 Nm]	27 inlbs. [3 Nm]
*Capacities are per set of jaws and are not simulta	ineous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	153 lbs.	682 N
Without Spring Assist -L	100 lbs.	443 N
With Spring Assist	200 lbs.	889 N
With Spring Assist -L	130 lbs.	579 N
Total Stroke:		
Standard	0.16 in.	4 mm
Extended -L	0.32 in.	8 mm
Weight	0.6 lbs.	0.25 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	60-100 psi	4-7 Bar

Accessory Mounting Technical Data



RTH/DTH-1M-L Loading Information



	→ Mx F/3 →	F/3
Loading Capacity ⁺	Static	My Dynamic
Maximum Tensile T	164 lbs. [730 N]	13 lbs. [57 N]
Maximum Compressive C	216 lbs. [960 N]	13 lbs. [57 N]
Maximum Moment M _X	177 inIbs. [20 Nm]	9 inIbs. [1 Nm]
Maximum Moment My	204 in lbs. [23 Nm]	9 in lbs. [1 Nm]
Maximum Moment Mz	133 inlbs. [15 Nm]	9 inlbs. [1 Nm]

*Capacities are per set of jaws and are not simultaneous

Specifications (cont.)

Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Bore Ø	1.62 in.	32 mm
Displacement	0.40 in ³ .	6.5 cm ³
Temperature Range	-20°~300° F	-30°~150° C
Actuation (open/close)	0.06 sec./0.06 sec.	
Accuracy	±0.002 in.	±0.04 mm
Repeatability	±0.001 in.	±0.02 mm
Valve required to actuate single acting	3-way, 2-position	
Valve required to actuate double acting	4-way, 2-position	

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PARALLEL GRIPPER RTH/DTH-2M 3-JAW CENTERING SERIES

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SAMPLE ORDER: DTH-2M-L-C-SP-V Ex: DTH-2M DIRECTCONNECT Gripper, Metric, 12mm Extended Stroke, Spring Closed, Stripper Plate, Viton* Seals

High Temperature Viton® Seals

VITON[®] SEALS V



RTH/DTH-2M Loading Information



Loading Capacity ⁺	Static	Dynamic
Maximum Tensile T	270 lbs. [1200 N]	29 lbs. [129 N]
Maximum Compressive C	351 lbs. [1560 N]	29 lbs. [129 N]
Maximum Moment Mx	398 inIbs. [45 Nm]	35 inIbs. [4 Nm]
Maximum Moment My	566 inlbs. [64 Nm]	53 in lbs. [6 Nm]
Maximum Moment Mz	363 inIbs. [41 Nm]	53 in lbs. [6 Nm]
[†] Canacities are per set of jaws and are not	simultaneous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	278 lbs.	1238 N
Without Spring Assist -L	183 lbs.	812 N
With Spring Assist	335 lbs.	1490 N
With Spring Assist -L	220 lbs.	979 N
Total Stroke:		
Standard	0.24 in.	6 mm
Extended -L	0.47 in.	12 mm
Weight	1.2 lbs.	0.53 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	60-100 psi	4-7 Bar

Accessory Mounting Technical Data



PARALLEL GRIPPER RTH/DTH-2M 3-JAW CENTERING SERIES

F/3

F/3

Dynamic

19 lbs. [84 N]

19 lbs. [84 N] 27 in.- lbs. [3 Nm]

35 in.-Ibs. [4 Nm]

35 in.- lbs. [4 Nm]

8 in. Ha

30 psi

20 mm Hg

2.1 Bar

43 mm

17 cm³

±0.04 mm

±0.02 mm

0.07 sec./0.07 sec.

3-way, 2-position

4-way, 2-position

My

RTH/DTH-2M-L Loading Information

Loading Capacity[†]

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

Specifications (cont.)

Displacement.....

*Capacities are per set of jaws and are not simultaneous

Max. Vacuum for Scavenge Port

Max. Pressure for Purge Port.....

Actuation (open/close)

Valve required to actuate single acting

Valve required to actuate double acting

Cylinder Bore Ø..... 1.70 in.

Accuracy...... ±0.002 in. Repeatability ±0.001 in.

Maximum Tensile T



С

🖌 Mx

Static

243 lbs. [1080 N]

315 lbs. [1400 N]

354 in.-lbs. [40 Nm]

460 in.- lbs. [52 Nm]

292 in.- lbs. [33 Nm]

..... 1.05 in³.

Temperature Range -20°~300° F -30°~150° C

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PARALLEL GRIPPER RTH/DTH-3M 3-JAW CENTERING SERIES

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SAMPLE ORDER: DTH-3M-L-C-SP-V Ex: DTH-3M DIRECTCONNECT Gripper, Metric, 16mm Extended Stroke, Spring Closed, Stripper Plate, Viton* Seals

Spring Open

Leave Blank. No Spring Option (standard)

High Temperature Viton® Seals

0

STRIPPER PLATE SP VITON[®] SEALS V



RTH/DTH-3M Loading Information



Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	378 lbs. [1680 N]	68 lbs. [302 N]
Maximum Compressive C	490 lbs. [2180 N]	68 lbs. [302 N]
Maximum Moment Mx	637 inlbs. [72 Nm]	97 inIbs. [11 Nm]
Maximum Moment My	903 in lbs. [102 Nm]	142 inIbs. [16 Nm]
Maximum Moment Mz	584 inlbs. [66 Nm]	142 inlbs. [16 Nm]
*Capacities are per set of jaws and are not s	simultaneous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	467 lbs.	2078 N
Without Spring Assist -L	303 lbs.	1349 N
With Spring Assist	591 lbs.	2627 N
With Spring Assist -L	384 lbs.	1708 N
Total Stroke:		
Standard	0.31 in.	8 mm
Extended -L	0.63 in.	16 mm
Weight	2.4 lbs.	1.08 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

Accessory Mounting Technical Data



PARALLEL GRIPPER RTH/DTH-3M 3-JAW CENTERING SERIES

RTH/DTH-3M-L Loading Information

Loading Capacity[†]

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

Specifications (cont.)

Valve required to actuate single acting.....

Valve required to actuate double acting

Maximum Tensile T



T

🖌 Mx

Static

337 lbs. [1500 N]

436 lbs. [1940 N]

566 in.-lbs. [64 Nm]

717 in.- lbs. [81 Nm]

469 in.-lbs. [53 Nm]

F/3

F/3

Dvnamic

44 lbs. [197 N]

44 lbs. [197 N]

62 in.- lbs. [7 Nm]

80 in.-Ibs. [9 Nm]

3-way, 2-position

4-way, 2-position

My

С



80 in.-Ibs. [9 Nm] *Capacities are per set of jaws and are not simultaneous Max. Vacuum for Scavenge Port..... 8 in. Ha 20 mm Hg Max. Pressure for Purge Port..... 30 psi 2.1 Bar Cylinder Bore Ø..... 55 mm 2.17 in. Displacement..... 2.30 in³. 37 cm³ Temperature Range -20°~300° F -30°~150° C Actuation (open/close) 0.08 sec./0.08 sec. ±0.04 mm Accuracy ±0.002 in. Repeatability ±0.001 in. ±0.02 mm

DIRECTCONNI

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PARALLEL GRIPPER RTH/DTH-4M 3-JAW CENTERING SERIES



How to Order: (Order Accessories separately from Basic Model)

SENSOR ACCESSORIES

BASIC MODE	I SĽ	7F MFTRIC SPRING ASSIST	SENSOR ACCESSORIES			
			8mm NPN Inductive Sensor w/Quick Disconnect*	OISN-011	1, 2 or 3	
	- 4		8mm PNP Inductive Sensor w/Quick Disconnect*	0ISP-011	1, 2 or 3	
			PNP Magneto Resistive Sensor Short Barrel w/Qk Disc*	OHSP-017	1, 2 or 3	
	EXTE	NDED STROKE STRIPPER PLATE	NPN Magneto Resistive Sensor Short Barrel w/Qk Disc*	OHSN-017	1, 2 or 3	
			PNP Magneto Resistive Sensor (90° barrel) w/Qk. Disc*	OHSP-011	1, 2 or 3	
BASIC MODEL	RTH	Without DIRECTCONNECT Mounting Pattern	NPN Magneto Resistive Sensor (90° barrel) w/Qk. Disc*	OHSN-011	1, 2 or 3	
	DIH	With DIRECTCONNECT Mounting Pattern	Quick Disconnect 2 Meter Cable Length*	CABL-010	1, 2 or 3	
SIZE	4		Quick Disconnect 5 Meter Cable Length*	CABL-013	1, 2 or 3	
METRIC	м		PNEUMATIC ACCESSORIES			
			Buna-N Seal Repair Kit	SLKT-350	1	
EXTENDED STROKE	-	0.39" [10mm] Leave Blank (standard)	Buna-N Rear Inlet Seal Repair Kit	SLKT-365	1	
	L	0.79" [20mm]	Viton [®] Seal Repair Kit	SLKT-350V	1	
SPRING	Ç	Spring Closed	Viton [®] Rear Inlet Seal Repair Kit	SLKT-365V	1	
	0	Spring Upen	G 1/8" Adjustable Flow Control	VLVF-005	1 or 2	
		Leave blank. No Spring Option (Standard)	Adapter G 1/8 Male to 1/8 NPT Female	PLFT-025	1 or 2	
STRIPPER PLATE	SP		*Sensor and cable sold separately.			
VITON® SEALS	V	High Temperature Viton [®] Seals				
SAMF		RDER: DTH-4M-L-C-SP-V				

DIRECTCONNE

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RTH/DTH-4M Loading Information



Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	474 lbs. [2110 N]	96 lbs. [425 N]
Maximum Compressive C	627 lbs. [2790 N]	96 lbs. [425 N]
Maximum Moment Mx	814 inIbs. [92 Nm]	142 inIbs. [16 Nm]
Maximum Moment My	1133 inlbs. [182 Nm]	195 in lbs. [22 Nm]
Maximum Moment Mz	734 inlbs. [84 Nm]	195 in lbs. [22 Nm]
Canacities are ner set of jaws and are not	simultaneous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	819 lbs.	3644 N
Without Spring Assist -L	532 lbs.	2366 N
With Spring Assist	1026 lbs.	4562 N
With Spring Assist -L	667 lbs.	2967 N
Total Stroke:		
Standard	0.39 in.	10 mm
Extended -L	0.79 in.	20 mm
Weight	4.3 lbs.	1.95 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	45-100 psi	3-7 Bar

Accessory Mounting Technical Data



PARALLEL GRIPPER RTH/DTH-4M 3-JAW CENTERING SERIES

RTH/DTH-4M-L Loading Information



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M١ Loading Capacity[†] Static Dynamic Maximum Tensile T 423 lbs. [1880 N] 62 lbs. [275 N] Maximum Compressive C 560 lbs. [2490 N] 62 lbs. [275 N] Maximum Moment Mx 726 in.-lbs. [82 Nm] 89 in.- lbs. [10 Nm] Maximum Moment My 903 in.- lbs. [102 Nm] 115 in.-lbs. [13 Nm] 593 in.-lbs. [67 Nm] Maximum Moment Mz 115 in.- lbs. [13 Nm] *Capacities are per set of jaws and are not simultaneous

Specifications (cont.)

Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Bore Ø	2.85 in.	72 mm
Displacement	4.90 in ³ .	80 cm ³
Temperature Range	-20°~300° F	-30°~150° C
Actuation (open/close)	0.1 sec./0).1 sec.
Accuracy	±0.0024 in.	±0.06 mm
Repeatability	±0.0012 in.	±0.03 mm
Valve required to actuate single acting	3-way, 2	2-position
Valve required to actuate double acting	4-way, 2	2-position

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PARALLEL GRIPPER RTH/DTH-5M 3-JAW CENTERING SERIES



SIZE 5

Μ

SPRING C

0

Spring Closed

SAMPLE ORDER: DTH-5M-L-C-SP-V

Spring Open

METRIC

STRIPPER PLATE SP

VITON[®] SEALS V

EXTENDED STROKE

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RTH/DTH

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Ex: DTH-5M DIRECTCONNECT Gripper, Metric, 26mm Extended Stroke, Spring Closed, Stripper Plate, Viton® Seals
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0.51" [13mm] Leave Blank (standard) 1.02" [26mm]

Leave Blank. No Spring Option (standard)

High Temperature Viton® Seals

www.comoso.com

Quick Disconnect 5 Meter Cable Length*

PNEUMATIC ACCESSORIES

Buna-N Rear Inlet Seal Repair Kit

Viton® Rear Inlet Seal Repair Kit

G 1/8" Adjustable Flow Control

Adapter G 1/8 Male to 1/8 NPT Female

Buna-N Seal Repair Kit

Viton® Seal Repair Kit

*Sensor and cable sold separately

CABL-013

SLKT-351

SLKT-365

SLKT-351V

SLKT-365V

VIVE-005

PLFT-025

1, 2 or 3

1

1

1

1

1 or 2

1 or 2



RTH/DTH-5M Loading Information



Loading Capacity [†]	Static	Dynamic
Maximum Tensile T	672 lbs. [2990 N]	152 lbs. [674 N]
Maximum Compressive C	895 lbs. [3980 N]	152 lbs. [674 N]
Maximum Moment M x	1124 inIbs. [127 Nm]	221 inlbs. [25 Nm]
Maximum Moment My	1584 inIbs. [179 Nm]	310 inlbs. [35 Nm]
Maximum Moment Mz	1036 in lbs. [117 Nm]	310 inlbs. [35 Nm]
[†] Capacities are per set of jaws and are not	simultaneous	

My

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	1428 lbs.	6353 N
Without Spring Assist -L	927 lbs.	4125 N
With Spring Assist	1771 lbs.	7877 N
With Spring Assist -L	1152 lbs.	5124 N
Total Stroke:		
Standard	0.51 in.	13 mm
Extended -L	1.02 in.	26 mm
Weight	8.6 lbs.	3.9 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	45-100 psi	3-7 Bar

Accessory Mounting Technical Data



PARALLEL GRIPPER RTH/DTH-5M 3-JAW CENTERING SERIES

RTH/DTH-5M-L Loading Information



Y	X
	F/3 → 🗖 🗖 🖛 F/3
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Loading Capacity[†]

Maximum Tensile T	602 lbs. [2680 N]	97 lbs. [432 N]
Maximum Compressive C	803 lbs. [3570 N]	97 lbs. [432 N]
Maximum Moment M x	1009 inIbs. [114 Nm]	142 inIbs. [16 Nm]
Maximum Moment My	1275 inIbs. [144 Nm]	177 inIbs. [20 Nm]
Maximum Moment Mz	832 inlbs. [94 Nm]	177 inIbs. [20 Nm]
*O	- Here e e	

Static

[†]Capacities are per set of jaws and are not simultaneous

Specifications (cont.)

	<u></u>	
Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Bore Ø	3.75 in.	95 mm
Displacement	11.0 in ³ .	180 cm ³
Temperature Range	-20°~300° F	-30°~150° (
Actuation (open/close)	0.19 sec./	0.19 sec.
Accuracy	±0.0024 in.	±0.06 mm
Repeatability	±0.0012 in.	±0.03 mm
Valve required to actuate single acting	3-way, 2	2-position
Valve required to actuate double acting	4-way, 2	2-position

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PARALLEL GRIPPER RTH-6M 3-JAW CENTERING SERIES

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SPRING

STRIPPER PLATE SP

VITON[®] SEALS V

Spring Closed

Leave Blank. No Spring Option (standard)

High Temperature Viton® Seals

SAMPLE ORDER: RTH-6M-L-C-SP-V Ex: RTH-6M Parallel Gripper, Metric, 32mm Extended Stroke, Spring Closed, Stripper Plate, Viton® Seals

Spring Open

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RTH/DTH SER

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Buna-N Rear Inlet Seal Repair Kit

Viton® Rear Inlet Seal Repair Kit

G 1/8" Adjustable Flow Control

Adapter G 1/8 Male to 1/8 NPT Female

Viton® Seal Repair Kit

*Sensor and cable sold separately

SLKT-365

SLKT-352V

SLKT-365V

VIVE-005

PLFT-025

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1

1

1 or 2

1 or 2



RTH/DTH-6M Loading Information



Loading Capacity ⁺	Static	Dynamic
Maximum Tensile T	971 lbs. [4320 N]	296 lbs. [1315 N]
Maximum Compressive C	1306 lbs. [5810 N]	296 lbs. [1315 N]
Maximum Moment Mx	1522 inlbs. [172 Nm]	398 in lbs. [45 Nm]
Maximum Moment My	2213 inlbs. [250 Nm]	575 in lbs. [65 Nm]
Maximum Moment Mz	1452 inlbs. [164 Nm]	575 in lbs. [65 Nm]
*Canacities are ner set of jaws and are not sim	ultaneous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	2294 lbs.	10202 N
Without Spring Assist -L	1490 lbs.	6629 N
With Spring Assist	3099 lbs.	13786 N
With Spring Assist -L	2017 lbs.	8971 N
Total Stroke:		
Standard	0.63 in.	16 mm
Extended -L	1.26 in.	32 mm
Weight	17.4 lbs.	7.89 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	55-100 psi	4-7 Bar

Accessory Mounting Technical Data



PARALLEL GRIPPER RTH-6M 3-JAW CENTERING SERIES

RTH/DTH-6M-L Loading Information



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	Static	Dynamic		
Maximum Tensile T	868 lbs. [3860 N]	192 lbs. [852 N]		
Maximum Compressive C	1165 lbs. [5180 N]	192 lbs. [852 N]		
Maximum Moment Mx	1363 inlbs. [154 Nm]	257 inlbs. [29 Nm]		
Maximum Moment My	1761 inIbs. [199 Nm]	327 inlbs. [37 Nm]		
Maximum Moment Mz	1159 inIbs. [131 Nm]	327 inlbs. [37 Nm]		
Canacities are not set of jaws and are not simultaneous				

🗶 Mx

F/3

F/3

🗶 My

Capacities are per set of jaws and are not s

Specifications (cont.)

Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg	
Max. Pressure for Purge Port	30 psi	2.1 Bar	
Cylinder Bore Ø	4.72 in.	120 mm	
Displacement	22 in ³ .	355 cm ³	
Temperature Range	-20°~300° F	-30°~150° C	
Actuation (open/close)	0.36 sec./0.36 sec.		
Accuracy	±0.0032 in.	±0.08 mm	
Repeatability	±0.002 in.	±0.04 mm	
Valve required to actuate single acting	3-way, 2-position		
Valve required to actuate double acting	4-way, 2-position		

PARALLEL GRIPPER RTH-7M 3-JAW CENTERING SERIES



SAMPLE ORDER: RTH-7M-L-C-SP-V Ex: RTH-7M Parallel Gripper, Metric, 50mm Extended Stroke, Spring Closed, Stripper Plate, Viton® Seals

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PARALLEL GRIPPER RTH-7M 3-JAW CENTERING SERIES

RTH/DTH-7M Loading Information



Loading Capacity ⁺	Static	Dynamic
Maximum Tensile T	1214 lbs. [5400 N]	396 lbs. [1763 N]
Maximum Compressive C	1601 lbs. [7120 N]	396 lbs. [1763 N]
Maximum Moment Mx	1903 inlbs. [215 Nm]	531 inlbs. [60 Nm]
Maximum Moment My	2699 inlbs. [305 Nm]	761 inIbs. [86 Nm]
Maximum Moment Mz	1841 inlbs. [208 Nm]	761 inlbs. [86 Nm]
[†] Canacities are ner set of jaws and are not simul	taneous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	3859 lbs.	17165 N
Without Spring Assist -L	2496 lbs.	11102 N
With Spring Assist	4967 lbs.	22093 N
With Spring Assist -L	3222 lbs.	14322 N
Total Stroke:		
Standard	0.98 in.	25 mm
Extended -L	1.97 in.	50 mm
Weight	34.6 lbs.	15.7 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	55-100 psi	4-7 Bar

Accessory Mounting Technical Data



RTH/DTH-7M-L Loading Information GRIP FORCE PER FINGER (with Spring Assist Option) WARNING DO NOT EXCEED MAXIMUM EFFECTIVE FINGER | FNGTHS 4.00 6.00 8.00 10.00 102 152 203 250 EFFECTIVE FINGER LENGTH - L 12.00 14.00 in Мz F1



Loading Capacity[†] Static Dynamic Maximum Tensile T 1054 lbs. [4690 N] 257 lbs. [1141 N] Maximum Compressive C 1389 lbs. [6180 N] 257 lbs. [1141 N] Maximum Moment Mx 1646 in.-lbs. [186 Nm] 345 in.- lbs. [39 Nm] Maximum Moment My 2036 in.- lbs. [230 Nm] 425 in.- lbs. [48 Nm] Maximum Moment Mz 1381 in.-lbs. [156 Nm] 425 in.- lbs. [48 Nm]

*Capacities are per set of jaws and are not simultaneous

Sp	ecifica	ations	(cont.)	

N Ibs

4450 1000

F2 3560 800

FINGER FORCE 3670 600

1780 400

890 200

> 0 0

> > 2.00

n 51

Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Bore Ø	6.15 in.	156 mm
Displacement	37 in ³ .	940 cm ³
Temperature Range	-20°~300° F	-30°~150° C
Actuation (open/close)	0.85 sec.	/0.85 sec.
Accuracy	±0.004 in.	±0.1 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate single acting	3-way, 2-position	
Valve required to actuate double acting	4-way, 2	2-position

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PARALLEL GRIPPER RTH-8M 3-JAW CENTERING SERIES

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STRIPPER PLATE SP

VITON[®] SEALS V

Spring Open

Leave Blank. No Spring Option (standard)

High Temperature Viton® Seals

SAMPLE ORDER: RTH-8M-L-C-SP-V Ex: RTH-8M Parallel Gripper, Metric, 70mm Extended Stroke, Spring Closed, Stripper Plate, Viton® Seals



Buna-N Rear Inlet Seal Repair Kit

Viton® Rear Inlet Seal Repair Kit

G 1/4" Adjustable Flow Control

Adapter G 1/4 Male to 1/4 NPT Female

Viton® Seal Repair Kit

*Sensor and cable sold separately.

SLKT-366

SLKT-354V

SLKT-366V

VLVF-010

PLFT-024

1

1

1

1 or 2

1 or 2



RTH/DTH-8M Loading Information



Loading Capacity ⁺	Static	Dynamic
Maximum Tensile T	1850 lbs. [8230 N]	614 lbs. [2733 N]
Maximum Compressive C	2405 lbs. [10700 N]	614 lbs. [2733 N]
Maximum Moment Mx	4027 inlbs. [455 Nm]	1159 inIbs. [131 Nm]
Maximum Moment My	5116 inlbs. [578 Nm]	1478 inIbs. [167 Nm]
Maximum Moment Mz	3204 in lbs. [362 Nm]	1478 inIbs. [167 Nm]
[†] Capacities are per set of jaws and are not sir	nultaneous	

Specifications

Total Rated Grip Force, F @ 100 psi [7 bar]:		
Without Spring Assist	7933 lbs.	35288 N
Without Spring Assist -L	5122 lbs.	22784 N
With Spring Assist	9971 lbs.	44354 N
With Spring Assist -L	6450 lbs.	28690 N
Total Stroke:		
Standard	1.38 in.	35 mm
Extended -L	2.76 in.	70 mm
Weight	96.8 lbs.	43.9 Kg
Pressure Range without Spring	30-100 psi	2-7 Bar
Pressure Range with Spring	50-100 psi	3.5-7 Bar

Accessory Mounting Technical Data



PARALLEL GRIPPER RTH-8M 3-JAW CENTERING SERIES

RTH/DTH-8M-L Loading Information



F/3 F/3 Mx

Μy

Dynamic

Loading Capacity[†]

• • •		•
Maximum Tensile T	1592 lbs. [7080 N]	398 lbs. [1772 N]
Maximum Compressive C	2070 lbs. [9210 N]	398 lbs. [1772 N]
Maximum Moment Mx	3461 inlbs. [391 Nm]	752 inIbs. [85 Nm]
Maximum Moment My	3788 in lbs. [428 Nm]	823 inIbs. [93 Nm]
Maximum Moment Mz	2372 inlbs. [268 Nm]	823 inIbs. [93 Nm]
10 W 1 K 1 K 1	-	

Static

*Capacities are per set of jaws and are not simultaneous

Specifications (cont.)

Max. Vacuum for Scavenge Port	8 in. Hg	20 mm Hg
Max. Pressure for Purge Port	30 psi	2.1 Bar
Cylinder Bore Ø	8.86 in.	225 mm
Displacement	166 in ³ .	2720 cm ³
Temperature Range	-20°~300° F	-30°~150° C
Actuation (open/close)	1.7 sec./	1.7 sec.
Accuracy	±0.004 in.	±0.01 mm
Repeatability	±0.002 in.	±0.05 mm
Valve required to actuate single acting	3-way, 2	2-position
Valve required to actuate double acting	4-way, 2	2-position

RTH/DTH Series Exploded View



Assembly Procedure

- 1) Lubricate and install seals #55 into the body #1
- 2) Install #59 SS screws with thread locker into the body #1
- 3) Sub assemble the sensing nuts #9 into the jaws #6
- 4) Sub assemble the jaws #6 on either side of the triple wedge #3 with lubrication
- 5) Insert the jaws and triple wedge sub assembly into the body. To ensure a good positioning of the magnet, the dowel hole of the triple wedge (on tapped hole side) has to be positioned on the opposite side of the air ports (except size 1). For size 1, it has to be positioned between the sensor slots of the body.
- 6) Install seals #58 into the plugs #7
- 7) Insert the plugs #7 into the bottom case #5
- 8) Install bottom case #5 with pressed-in pins

- #63 onto the body and fasten with #64 screws with thread locker
- 9) Lubricate and install seals #54 into the piston #2
- 10) Mount magnet #56 to piston #2 with thread locker
- 11) For **-C** option, insert the spring #65 into the body counterbore holes
- 12) Insert the piston #2 with pressed-in pin #57 onto the triple wedge#3 and fasten with screw #61 and washer #62. Face mount the piston counterbore holes to the body counterbore holes for -C option. Opposite mount for -O option. For -O option, insert the spring #65 into the piston counterbore holes
- 14) Install #52 air ports plugs with thread locker onto the cap #4
- 15) Install seals #50 and #51 into the cap #4
- 16) Insert the cap into the body and locate it using cap dowel pin holes.

Item Qty Name

01	1	Body
02	1	Piston
03	1	Triple wedge
04	1	Сар
05	1	Bottom Case
06	3	Jaws
07	3	Plug
08	6	Locating sleeve
09	3	Sensing nut
50	1	Cap, O-ring
51	2	Cap, O-ring
52	3	Cap, SS screw
53	3	Cap, SHC screw
54	1	Piston, O-ring
55	1	Body, O-ring
56	1	Piston, Magnet
57	1	Piston, Pin
58	3	Plug, O-Ring
59	2	Body, SS screw
<u>61</u>	1	Triple wedge, HH screw
62	1	Triple wedge, Seal
63	2	Slide, Pin
64	6	Slide, SHC Screw
65	6	Spring
71	3	Sensor holder
72	6	Sensor holder, SHC screw
73	3	Sensing nut, SHC screw
80	3	Stud
<u>81</u>	1	Pressure plate
82	3	Springs
83	3	Stud. screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

SK Seal Repair Kit Order #'s See Product Data Sheets

- 17) Fasten the cap with #53 screws with thread locker
- 18) Install the sensor holder #71 onto the body and fasten with screw #72
- 19) Insert screw #73 into the sensing nuts #9 from the body holes
- 20) Insert locating sleeves #8 into the jaws

-SP Assembly Procedure

- 1) Disassemble bottom case #5 unfastening #64 screws
- 2) Sub assemble springs #82 into the stud #70
- 3) Insert the spring and stud sub assembly into the bottom case
- 4) Install bottom case #5 onto the body and fasten with #64 screws with thread locker
- 5) Install pressure plate #8 onto the studs and fasten with #83 screws



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RTH/DTH Series Assembled View

Item Qty Name



02 1 Piston 03 1 Triple wedge 04 1 Cap 05 1 Bottom Case 06 3 Jaws 07 3 Plug 08 6 Locating sleeve 09 3 Sensing nut 50 1 Cap, O-ring 51 2 Cap, O-ring 52 3 Cap, SS screw 53 3 Cap, SHC screw 54 1 Piston, O-ring 55 1 Body, O-ring 56 1 Piston, Magnet 57 1 Piston, Pin 58 3 Plug, O-Ring 59 2 Body, SS screw 61 1 Triple wedge, HH screw 62 1 Triple wedge, Seal 63 2 Slide, Pin 64 6 Slide, SHC Screw 65 6 Spring 71	01	1	Body
03 1 Triple wedge 04 1 Cap 05 1 Bottom Case 06 3 Jaws 07 3 Plug 08 6 Locating sleeve 09 3 Sensing nut 50 1 Cap, O-ring 51 2 Cap, O-ring 52 3 Cap, SS screw 53 3 Cap, SS screw 54 1 Piston, O-ring 55 1 Body, O-ring 56 1 Piston, Magnet 57 1 Piston, Pin 58 3 Plug, O-Ring 59 2 Body, SS screw 61 1 Triple wedge, HH screw 62 1 Triple wedge, Seal 63 2 Slide, Pin 64 6 Slide, SHC Screw 65 6 Spring 71 3 Sensor holder 72 <td>02</td> <td>1</td> <td>Piston</td>	02	1	Piston
04 1 Cap 05 1 Bottom Case 06 3 Jaws 07 3 Plug 08 6 Locating sleeve 09 3 Sensing nut 50 1 Cap, O-ring 51 2 Cap, O-ring 52 3 Cap, SS screw 53 3 Cap, SS screw 54 1 Piston, O-ring 55 1 Body, O-ring 56 1 Piston, Magnet 57 1 Piston, Pin 58 3 Plug, O-Ring 59 2 Body, SS screw 61 1 Triple wedge, HH screw 62 1 Triple wedge, Seal 63 2 Slide, Pin 64 6 Slide, SHC Screw 65 6 Spring 71 3 Sensor holder 72 6 Sensor holder 72 </td <td>03</td> <td>1</td> <td>Triple wedge</td>	03	1	Triple wedge
051Bottom Case063Jaws073Plug086Locating sleeve093Sensing nut501Cap, O-ring512Cap, O-ring523Cap, SS screw533Cap, SHC screw541Piston, O-ring551Body, O-ring561Piston, Magnet571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	04	1	Сар
06 3 Jaws 07 3 Plug 08 6 Locating sleeve 09 3 Sensing nut 50 1 Cap, 0-ring 51 2 Cap, 0-ring 52 3 Cap, SS screw 53 3 Cap, SHC screw 54 1 Piston, 0-ring 55 1 Body, 0-ring 56 1 Piston, Magnet 57 1 Piston, Pin 58 3 Plug, 0-Ring 59 2 Body, SS screw 61 1 Triple wedge, HH screw 62 1 Triple wedge, Seal 63 2 Slide, Pin 64 6 Slide, SHC Screw 65 6 Spring 71 3 Sensor holder 72 6 Sensor holder, SHC screw 73 3 Sensing nut, SHC screw	05	1	Bottom Case
07 3 Plug 08 6 Locating sleeve 09 3 Sensing nut 50 1 Cap, 0-ring 51 2 Cap, 0-ring 52 3 Cap, SS screw 53 3 Cap, SHC screw 54 1 Piston, 0-ring 55 1 Body, 0-ring 56 1 Piston, Magnet 57 1 Piston, Pin 58 3 Plug, 0-Ring 59 2 Body, SS screw 61 1 Triple wedge, HH screw 62 1 Triple wedge, Seal 63 2 Slide, Pin 64 6 Slide, SHC Screw 65 6 Spring 71 3 Sensor holder 72 6 Sensor holder, SHC screw 73 3 Sensing nut, SHC screw	06	3	Jaws
086Locating sleeve093Sensing nut501Cap, O-ring512Cap, O-ring523Cap, SS screw533Cap, SHC screw541Piston, O-ring551Body, O-ring561Piston, Magnet571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	07	3	Plug
093Sensing nut501Cap, O-ring512Cap, O-ring523Cap, SS screw533Cap, SHC screw541Piston, O-ring551Body, O-ring561Piston, Magnet571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	08	6	Locating sleeve
501Cap, O-ring512Cap, O-ring523Cap, SS screw533Cap, SHC screw541Piston, O-ring551Body, O-ring561Piston, Magnet571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	09	3	Sensing nut
512Cap, O-ring523Cap, SS screw533Cap, SHC screw541Piston, O-ring551Body, O-ring561Piston, Magnet571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	50	1	Cap, O-ring
523Cap, SS screw533Cap, SHC screw541Piston, O-ring551Body, O-ring561Piston, Magnet571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	51	2	Cap, O-ring
533Cap, SHC screw541Piston, O-ring551Body, O-ring561Piston, Magnet571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	52	3	Cap, SS screw
541Piston, O-ring551Body, O-ring561Piston, Magnet571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	53	3	Cap, SHC screw
551Body, O-ring561Piston, Magnet571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	54	1	Piston, O-ring
561Piston, Magnet571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	55	1	Body, O-ring
571Piston, Pin583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	56	1	Piston, Magnet
583Plug, O-Ring592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	57	1	Piston, Pin
592Body, SS screw611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	58	3	Plug, O-Ring
611Triple wedge, HH screw621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	59	2	Body, SS screw
621Triple wedge, Seal632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	61	1	Triple wedge, HH screw
632Slide, Pin646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	62	1	Triple wedge, Seal
646Slide, SHC Screw656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	63	2	Slide, Pin
656Spring713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	64	6	Slide, SHC Screw
713Sensor holder726Sensor holder, SHC screw733Sensing nut, SHC screw	65	6	Spring
726Sensor holder, SHC screw733Sensing nut, SHC screw	71	3	Sensor holder
73 3 Sensing nut, SHC screw	72	6	Sensor holder, SHC screw
	73	3	Sensing nut, SHC screw

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions

Magneto Resistive Sensor

- 1) Insert sensors #90 from either end of the profile slots
- 2) Set the sensor with the integrated screw

Inductive Sensor

- 1) Insert sensors #91 into the sensor holder #72
- 2) Tighten the sensor using the SHC screw onto the sensor holder #72
- 3) Insert the SHC screw #73 into the sensing nuts #9. The SHC screws are the targets to be adjusted in front of the sensor. Depending on the position to sense, use different length for the SHC screw #73 (shortest screw for open position, longest screw for close position). The sensing nut #9 has a thread insert that prevents the target from loosening. This may make the target harder to tighten into the nut.



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

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Fixed Jaws, Food-Grade Grease, Stroke Limiters, Custom Fingers and Jaws, Stainless Steel Components and more...

Drawings are for concept only. Contact Robohand Tech Support with project requirements.



Fixed Jaws



Custom Fingers and Jaws





Stroke Limiter



Built-in Sensor with 2 Sensing Faces 2 or 3 Wire Technology



Custom Stripper Plate

Please see back cover for DE-STA-C0 Global Locations. www.destaco.com



Please describe your application. Include a sketch or attach additional sheets if necessary. Z X Υ

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

3P Parallel Gripper-3-Jaw Precision Series

Precision Gripper

The 3 concentric jaws and very good repeatability [0.02mm] allows loading and unloading accurate cylindrical parts.

Harsh Environments

Shielded design (-E) repels chips and other particulate from internal drive mechanism depending on the chosen material of the shield.

Compact and Powerful

This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Multipurpose Gripper

A wide range of options and accessories (extended stroke, hydraulic power, safety springs for internal or external gripping, inductive sensors, tandem cylinder, Viton[®] seals, and protective boot) allow these grippers to be used in a number of applications.

Mounting Information:



Technical Specifications:

Pneumatic Specifications Pressure Operating Range	Imperial 30-100 psi	Metric 2-7 bar
Cylinder Type	Double or do spring-assist acting wit	uble acting ed or single th spring
Dynamic Seals	Buna	a-N
Valve Required to Operate:		
Double Acting	4-way, 2-	position
Single acting (Option RE or RI)	3-way, 2-	position
Air Quality Requirements		
Filtration	40 Micron	or Better
Lubrification	Not Nec	essary*
Temperature Operating Range		
Buna-N Seals (standard)	-30°~180° F	-35°~80° C
Viton [®] Seals (optional)	-20°~300° F	-30°~150° C
Application Restrictions		
Expected Life		
Normal Application	5 million	cycles
w/ Preventative Maintenance	10+ millio	n cycles*
Field Repairable	Ye	S
Seal Repair Kits Available	Ye	S

*Addition of lubrication will greatly increase service life

PRECISION 3P 1.253

6003P-C

16 mm

422 N

107 N

0.60 kg

8003P-C

20 mm

1219 N

398 N

0.97 kg

11003P-C

30 mm

1979 N

628 N

2.35 kg

14003P-C

40 mm

3930 N

1453 N

4.70 kg

16503P-C

50 mm

6707 N

2235 N

9.04 kg



- The rotation of the levers converts the vertical movement of the piston in a horizontal motion and synchronized two-bit gates, which are guided in grooves in «T» fitting body.
- This gripper is suitable for internal or external gripping and can be mounted in any orientation
- Optional failsafe spring can be used to maintain gripping force if gripper looses air pressure or as a single acting return gripper.

PARALLEL GRIPPER 6003P PRECISION 3P GRIPPER SERIES

PRECISION 3P

1.254





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PARALLEL GRIPPER 6003P-C PRECISION 3P GRIPPER SERIES



PARALLEL GRIPPER 8003P PRECISION 3P GRIPPER SERIES





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PARALLEL GRIPPER 8003P-C PRECISION 3P GRIPPER SERIES



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PARALLEL GRIPPER 11003P **PRECISION 3P GRIPPER SERIES**



Pressure Range with Springs Ø Cylinder Bore Displacement Actuation (open / close)

1. Force with spring and air at 6bar 2. Force with spring without air

Repeatability

	11003P						E A C CHUMN B	
ngs Mid-Way, L=0	2967 N			WIJE NU		nangej an		
ngs Mid-Way, L=0	941 N	<u>L</u>	₽♥		\bullet	\oplus	Imperial in.	Metric [mm]
	20 mm	Dimensions are symmetrical about	Third Angle Projection	All Dowel F	loles are SF (Slip Fit). ional Tolerance	Metric Threads	$0.00 = \pm .01$ $0.000 = \pm .005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$
	2.35 kg	centerline	riojection	±.0005	5" or [±.013mm]	COULSE FILCH	$0.0000 = \pm .0005$	$[0.00] = [\pm .013]$
	2 -7 bar							
	4 -7 bar				Grippore are cupr	liod with		ear inlet operation
	76 mm				onen side air nort	s and ton		<u>+</u>
	87 cm3				manifold air ports	pluaaed.	[4] [] [] [] [] [] [] [] [] [] [] [] [] []	<u>v</u> .8
	0.10 s / 0.10 s				Top manifold seal	ing _4		<u> </u>
	+ 0.02 mm				dimensions show	n. d)-Ring [Ø1.5 x Ø5]
	± 0.02 mm							
		3 Air Port G188 DP OPEN 16 010 010 010 010			aws Open 15 2381 4025 Jaws Open 15 4025 Jaws Open 10 5 48 381 4025 381 4005 381 4000	2 ØS -0.01 x MB ngs ti inici a a a a a a a a a a a a a		

86

13

Air Port G1/8 8 DP CLOSE

Loading Information:



Port M5 5 DP OPENING

(seals included)



Ø8H9

15° _

Port M5 5 DP CLOSING eals include





Ø95.25

Capacités de chargement [*]	Statique	Dynamique
Traction maximale T	1560 N	695 N
Compression maximale C	2652 N	695 N
Moment maximum Mx	60 Nm	31 Nm
Moment maximum My	80 Nm	41 Nm
Moment maximum Mz	90 Nm	41 Nm
* The Canacities are ner set of jaws and are not simu	Itaneous	

cl

3 x Ø9 M8

How To Order:





PARALLEL GRIPPER 11003P-C PRECISION 3P GRIPPER SERIES

S110H

1





Options and Accessories: See Page 1.264

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

Hydraulic Seal Repair Kit

PARALLEL GRIPPER 14003P PRECISION 3P GRIPPER SERIES







PARALLEL GRIPPER 14003P-C PRECISION 3P GRIPPER SERIES



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

PARALLEL GRIPPER 16503P PRECISION 3P GRIPPER SERIES







PARALLEL GRIPPER 16503P-C PRECISION 3P GRIPPER SERIES



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OPTIONS AND ACCESSORIES PRECISION 3P GRIPPER SERIES



SUPPLY: (P) Pneumatic (H) (H80) Hydraulic

As standard, the clamp is supplied with air to a pressure of 7 bar. The clamp is fitted with Viton O-ring seals for high temperatures.

On request (contact us) the gripper can be supplied with hydraulic fluid. The clamp is fitted with seals Viton Quad-Ring.

- Choice (H) allows a hydraulic power to a pressure of 20 bar max. In this case the overall dimensions do not change. For better security the gripper must be fixed on their support before being fired. CAUTION: Hydraulic cycle times are longer.
- Choice (H80) allows a hydraulic power to a pressure of 80 bar max. In this case the total height of the gripper is increased (contact us).

The hydraulic power is incompatible with the option tandem (M).

Option (RE) or (RI): Spring Assist

The internal springs of the gripper ensures failsafe operation by retaining the component during pressure loss, to increase the gripporce, or allows the usage of the gripper in single acting operation.

Option (RE) for external gripping. Option (RI) for internal gripping.

The (RE) is incompatible with the option (RI).

Option (T): Sensor Rod

Option (**T**) is a steel rod which comes out on the rear side of the gripper. The rod is fixed with the piston and has the same stroke movement. The open end of the rod allows for mounting a cam which allows to control the position of the jaws by using inductive sensors, micro switches,etc

WARNING: when screwing on cam rod, make sure the sensor rod does not rotate to prevent twisting of the springs of options (RE) or (RI).

Option (T) is incompatible with option (K).



Model	A	В	C	D	E	F
6003P & 6003P-C	35	5	30	15	M6	10
8003P & 8003P-C	35	6.5	28.5	15	M6	10
11003P & 11003P-C	35	10	25	15	M6	15
14003P & 14003P-C	55	13	42	20	M8	15
16503P & 16503P-C	53	23	30	20	M8	15

Option (M): Tandem Cylinder

The (**M**) is a cylinder light-alloy that fits behind the bottom plate. This actuator's integral action allows to double the gripforce by using the same pressure.

The combination of tandem option tandem (M) and Option (RE) or (RI) can double the clamping forces of the spring assist option. For cycle times of the tandem option, apply a factor of 3 to the actuation time.

The (M) is incompatible with the option (H).

Model	Ay	ØC	ØD	W	Weight (kg)
6003P & 6003P-C	28.5	38.1	60	3	0.200
8003P & 8003P-C	27	50.8	80	3	0.300
11003P & 11003P-C	34	76.2	110	3	0.750
14003P & 14003P-C	49	107.95	140	5	2.100
16503P & 16503P-C	65	127	165	6	3.600



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Option (KT1), (KX1), (KT2), (KX2): Sensor Unit

The (K) is a lightweight alloy housing that fits on the back of the gripper. An integrated shaft follows the movement of the piston to provide information to the sensor attached to the side of the unit. It can control two positions of the grippers jaws. 2 types of inductive sensors (KT, KX) and 2 detection zones (1, 2) are possible to allow for the combination of 2 to 4 possible positions (KT1, KX1, KT2, KX2). For KT, KX sensor specifications.





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Model #	Ax	Bx	ØC	ØD	w	Weight (kg)	No. of Sensing Postions (please specify when ordering)	Information area from the open grip position (green LED) X (mm)	Area information relative to the closed grip position (yellow LED) $\chi \ (mm)$
6003D	23	30°	38.1	60	3	0 180	1	0 - 1 +0,5	4 ⁺⁰ _{-0,5} to 5
00001	20	50	50.1	00	5	0.100	2	0 - 2 + 0.5 - 0	3 ⁺⁰ _{-0,5} to 5
6003P-C	23	30°	38.1	60	3	0 180	1	0 - 1.6 ^{+0,8} -0	7 ⁺⁰ _{-0,8} to 8
00001-0	20	50	50.1	00	5	0.100	2	$0 - 3.2 + 0.8 - 0^{+0.8}$	4.8 ⁺⁰ _{-0,8} to 8
8003D	28	3Uo	50.8	80	3	0.400	1	$0 - 1 \stackrel{+0,5}{-0}$	5.5 $^{+0}_{-0,5}$ to 6,5
00031	20	50	50.0	00	5	0.400	2	0 - 2 + 0.5 - 0	4.5 $^{+0}_{-0,5}$ to 6,5
9003D-C	28	3Uo	50.8	80	3	0.400	1	0 - 1.5 ^{+0,8} -0	8.5 ⁺⁰ _{-0,8} to 10
0003F~0	20	50	50.0	00	5	0.400	2	0 - 3.1 ^{+0,8} -0	6.9 ⁺⁰ _{-0,8} to 10
110020	26	20°	76.2	110	2	0.000	1	0 - 1 + 0.5 - 0	9 ⁺⁰ _{-0,5} to 10
110031	50	50	70.2	110	5	0.500	2	$0 - 3 \stackrel{+0,5}{-0}$	7 ⁺⁰ _{-0,5} to 10
100020-0	36	3Uo	76.2	110	3	0 000	1	0 - 1.5 ^{+0,8} -0	13.5 ⁺⁰ _{-0,8} to 15
100037-0	50	50	70.2	110	5	0.500	2	$0 - 4.5 \stackrel{+0,8}{-0}$	10.5 ⁺⁰ _{-0,8} to 15
140020	45.5	1650	107.05	140	5	1 670	1	0 - 2 + 0.5 - 0	11 ⁺⁰ _{-0,5} to 13
140036	43.3	105	107.95	140	J	1.070	2	$0 - 4 \stackrel{+0,5}{-0}$	9 ⁺⁰ _{-0,5} to 13
140020 0	15 F	1650	107.05	140	5	1 670	1	0 - 3 ^{+0,8} -0	17 ⁺⁰ _{-0,8} to 20
140037-0	43.3	105	107.95	140	5	1.070	2	0 - 6.2 ^{+0,8} -0	13.8 ⁺⁰ _{-0,8} to 20
165020	65 5	1650	107	165	6	2 670	1	0 - 2 ^{+0,5} -0	13 ⁺⁰ _{-0,5} to 15
103035	05.5	105	127	105	0	2.070	2	$0 - 4 \stackrel{+0,5}{-0}$	11 ⁺⁰ _{-0,5} to 15
165020 0	65 F	1650	107	165	6	2,670	1	0 - 3.3 + 0.8 - 0	21.7 $^{+0}_{-0,8}$ to 25
100038-0	00.0	105	127	100	0	2.070	2	0 - 7 ^{+0,8} -0	18 ⁺⁰ _{-0,8} to 25

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OPTIONS AND ACCESSORIES PRECISION 3P GRIPPER SERIES



Option (V): Viton® Seals

6 Gripper with Viton[®] seals allows for use in high temperature environments [-30 ° C or 150 ° C].

Accessory (E): Protective Boot

The accessory (\mathbf{E}) is a protective boot that fits over the gripper. It protects the mechanism and thus improves the life of the gripper in hostile environments. The accessory (\mathbf{E}) causes a different location of the fingers on the jaws as compared to the standard installation. Before attaching the boot, perform the following steps:

- 1. Mount gripper to machine.
- 2. Slip boot over gripper and secure in place.
- 3. Attached fingers to jaws using finger adapter.

Depending on the environment 2 types of envelopes are available:

- (E) Envelope of black or brown PVC for environmental grinding with emery presence.
- (E3) red envelope containing KEVLAR fireproof silicone environment for hot chips and weld spatter.

The accessory (E) is incompatible with the accessory (SD)

Model Code	Order #	Model	A	В	C	D	E	F	G	H	J	K	S	т	тх	v	Y
E F3	ER62P E3B62P	6003P & 6003P-C	88	98	35	13.5	8	29	29	17.5	13	_	3	M4	9	13	6
E	ER82P	8003P &	89	110	34	13.5	10	33	30	22.3	16	_	3	M5	10	16	6
E3	E3K82P ER112P	11003P &		See drawing													
E3 E	E3R112P KP-311	11003P-C 14003P &											_				_
E3	KP-313	14003P-C	143	185	50	18	12	55	34	19.5	24	18	5	M8	14	-	8
E E3	KP-314 KP-316	16503P & 16503P-C	172	220	70	16	14	67	37	24 19	28	23	6	M10	19	_	8







OPTIONS AND ACCESSORIES PRECSION 3P GRIPPER SERIES



Accessory (SD): Inductive Sensor Mounting Kit

Allows for sensing of two positions: open and closed jaw. The accessory kit (SD) includes: 1 sensor bracket, 1 flag and screws. Sensors are not provided.

NOTES:

To be usable, the cylindrical inductive sensors selected by the customer must have tapped their bodies to a minimum depth H (see table below).

Depending on their length, the cylindrical inductive sensors can extend below the clamp, requiring provision of suitable housing in the surrounding parts. It is possible to control more than 2 positions using a second attachment (**SD**).



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Through Hole Parallel Gripper PPC Series

Through Hole Gripper:

Designed for unique applications where a component ejector is needed after un-gripping the part or to blow air for cleaning the part center. The through hole design allows for the mounting of sensors to detect part presence, and for feeding parts to machining centers.

Machining applications:

The 3 concentric jaws and the excellent repeatability make it easier to accurately load and unload round parts.

Compact, robust and powerful gripper: This gripper is designed for use in confined spaces, combining long strokes with a high grip force. Optional safety springs retain the components, should the air supply fail or to increase grip force.

Harsh environments:

Shielded design repels chips and other particulate from internal drive mechanism.

Multipurpose gripper:

A wide range of options and accessories (extended stroke, safety springs for internal or external gripping, inductive sensors, Viton[®] seals) allow these grippers to be used in a number of applications.

Mounting Information:

Grippers can be mounted and operated in any direction



Technical Specifications:

Seal Repair Kits Available

*Addition of lubrication will greatly increase service life *See Maintenance Section

Pneumatic Specifications	Imperial	Metric
Pressure Operating Range without springs	30-100 psi	2-7 bar
Pressure Operating Range	45-100 psi	3-7 bar
Cylinder Type	Double <i>or</i> Double Actin	Acting g Spring Assist
Dynamic Seals Valve Bequired to Operate	or Single Acting Internally Lubri	y Spring Return cated Buna-N
Double Acting	4-way, 2-	position
Single Acting	3-way, 2-	position
Air Quality Requirements		
Air Filtration	40 Micro	n or Better
Air Lubrication	Not Ne	ecessary*
All Humany		e content (ury)
Temperature Operating Ra	nge	
Buna-N Seals (standard)	-30°~180° F	-35°~80° C
Viton [®] Seals (optional)	-20°~300° F	-30°~150° C
Maintenance Specification	1S [†]	
Expected Life		
Normal Application	5 million	cycles
W/ Preventative Maintenan	ce 10+ millio	on cycles*
Field Repairable	Yes	5

Yes



PPC SERIES

This gripper is suitable for internal or external gripping.



*Capacities are per set of jaws and are not simultaneous

PPC SERIES

1.270







*Capacities are per set of jaws and are not simultaneous

PARALLEL GRIPPERS PPC-12-C THROUGH HOLE SERIES





Maximum Moment Mz

*Capacities are per set of jaws and are not simultaneous

575 in.-lbs. [65 Nm]

PPC SERIES

1.272





221 in.-lbs. [25 Nm]



*Capacities are per set of jaws and are not simultaneous

PARALLEL GRIPPERS PPC-25-C THROUGH HOLE SERIES

PPC SERIES

1.273





Maximum Moment My

Maximum Moment Mz

*Capacities are per set of jaws and are not simultaneous

575 in.-lbs. [65 Nm]

885 in.-lbs. [100 Nm]





283 in.-lbs. [32 Nm]

487 in.-lbs. [55 Nm]



*Capacities are per set of jaws and are not simultaneous

PARALLEL GRIPPERS PPC-34-C THROUGH HOLE SERIES



SENSOR ACCESSORIES



Accessory (OSMK): Inductive Sensor Holders

Each kit allows sensing up to 2 jaw positions: open jaws, closed jaws. or part present. Two kits can be used on each gripper allowing sensing up to 4 positions. The accessory (OSMK) comes with 1 sensor holder, 1 flag, 2 spacers and screws for mounting. The sensors are not included.



	Α	В	C	D	Е	F	G
PPC-12	3.13 [79.5]	1.26 [32]	0.95 [24]	0.1 [2.5]	1.72 [43.75]	M8	2.56 [65]
PPC-12-C	3.13 [79.5]	1.26 [32]	0.95 [24]	0.1 [2.5]	1.72 [43.75]	M8	2.72 [69]
PPC-25	3.72 [94.5]	1.26 [32]	0.95 [24]	0.1 [2.5]	2.12 [53.75]	M8	3.03 [77]
PPC-25-C	3.72 [94.5]	1.26 [32]	0.95 [24]	0.1 [2.5]	2.12 [53.75]	M8	3.23 [82]
PPC-34	4.69 [119]	1.26 [32]	0.95 [24]	0.1 [2.5]	2.84 [72.05]	M8	3.86 [98]
PPC-34-C	4.69 [119]	1.26 [32]	0.95 [24]	0.1 [2.5]	2.84 [72.05]	M8	4.06 [103]





PPC Series Exploded View

Item	Otv	Name

1

1

1

3

3

3

1

3

6

01

02

04

05

06

07

08

09

65

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Springs

Assembly Procedure

- Lubricate and install the seals onto the cam driver piston
 Lubricate and install the seals into
- 2) Lubricate and install the seals into the cap
- Plug rear ports in the cap if rear inlets are not used. If rear inlets are used, plug body ports.
- 4) Insert the piston into body. Place springs into counterbore holes between the body and the piston for -RE option or between the piston and the cap for -RI option
- 5) Assemble the cap

7

- 6) Insert together the jaw and the cam lever into the body
- Insert the pivot pin aligning cam lever hole. Screw SS Screw into the body for preventing pivot pin from moving
- 8) Assemble the cover
- 9) Assemble the shielded case





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PPC SERIES ASSEMBLED VIEW



ltem	Otv	Name

01	1	Body	
02	1	Cam Driver Piston	
04	1	Сар	
05	3	Cam Lever	
06	3	Jaw	
07	3	Cover	
08	1	Shielded Case	
09	3	Pivot Pin	
65	6	Springs	

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation-Inductive Sensor

- Assemble the sensor holder (#50) onto the gripper
 Place the flag (#52) on one of the jaws above the sensor holder
- 3) Place the spacer (#53) on the other jaws
- 4) Position sensor for desired stroke position
- 5) Tighten sensor locking nuts (#56) to hold sensor depth
- 6) Repeat these operations in case of the use of two sensors holders

Angular Grippers

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Angular Motion Gripper Product Overview

2.2

RUA Series Angular Gripper

- 2-Jaw Angular Gripper Spring Assist
- · Pneumatic or Hydraulic Operation

Preferred Market:
Global



NEW

Vulcan Series Hi-Temp Angular Gripper

• Air Top or Lateral Blowing Port · Optional Kelvar® Boot, metal seals, or stainless

- heat shield · Optional stainless steel jaws and hardware

Preferred Market: A NA

RA Series **Cam Driven Gripper**

RA-5 & 6 DESIGN ADVANTAGES

- Inexpensive
- Adjustable stroke Rugged design

RA-10 DESIGN ADVANTAGES

- Extremely small (1in.) and lightweight (1 oz.)
- Inexpensive

Preferred Market:
Global



See **2.22** Page

See **2.16**

DCT/CT Series

DIRECTONNIECT **180° Angular Gripper**

- 180° of travel (Optional Adjustable Stop) • Features DIRECTCONNECT mounting (sizes 12-25)
- Sealed design protects internal components
- from chips and other particulate
- · Optional Resistive or Inductive Sensors



See 2.32

See **2.44**

Preferred Market:
Global

DCT-RE/CT-RE Series

DIRECTCONNECT **180° Failsafe Angular Gripper**

- 180° of travel (Optional Adjustable Stop)
- Spring Assist
- Features DIRECTCONNECT mounting (sizes 12-25) Sealed design protects internal components
- from chips and other particulate
- Optional Magneto Resistive or Inductive Sensors

Preferred Market:
 Global

FUA Series Food Gripper

- Designed for direct product contact in the food zone. according to the food industry standard (EN 1672-2)
- All parts are corrosion resistant, non-toxic, non-contaminating, non-porous, non-absorbent and non-reactive
- · Stainless steel design resists chemical cleaning procedures

Preferred Market:
 Global



See 2.56
Destaco-Robohand Angular Gripper Product Selector

6

	Two Jaws	12 Degrees 30 Degrees 70 Degrees 180 Degrees	1 - 10 lbs. [0.45 - 45Kg] 10 - 25 lbs. [45 - 111Kg] 25 - 50 lbs. [111 - 223Kg] 50 - 100 lbs. [223 - 445Kg] 100 - 500 lbs. [223 - 445Kg] 500 - 3000 lbs. [2225 - 13350]	0- 2 in. [0- 50.8mm] 2- 4 in. [50.8 - 102mm] 4- 6 in. [102 - 152mm] 8- 8 in. [152 - 203mm] 8- 10 in. [203 - 254mm] 10 - 12 in. [205 - 305mm] 12 - 14 in. [305 - 305mm] 14 - 16 in. [305 - 406mm] 16 - 18 in. [406 - 457mm] 18 - 20 in. [508mm+] 20 in+ [508mm+]	0.05 - 0.1 sec. 0.1 - 0.5 sec. 0.5 - 0.75 sec. 0.75 - 1 sec.	5 - 100 psi [0.3 - 7 bar] 20 - 100 psi [1.5 - 7 bar] 40 - 100 psi [3 - 7 bar] 50 - 100 psi [3.5 - 7 bar] 70 - 150 psi [5 - 7 bar]	Clean Room Environment Normal Environment Harsh/Dirty Environment	Failsafe Operation	Inductive Sensors Magneto Resistive Sensors	Double Acting Cylinder Single Acting/Spring Return Double Acting/Spring Assist Non-Synchronous Option
Model #	Stroke Range		Total Grip Force Range	Maximum Finger Length @ 60 PSI [4 bar]	Actuation Time	Operating Pressure	Environ- ment			
CYLINDRICAL I	DESIGN									
RUA-62	•	•		_	-	•	••	•	• •	• • •
RUA-82	•	•				•	••	•	• •	• • •
RUA-112	•	•			-	•	• •	•	• •	• • •
RUA-142	•	•			_	•	• •	•	•	• • •
RUA-162	•	•				•	• •	•	•	• • •
HI-TEMP DESIG	3N	_				_			-	
VULCAN-112	•	•			-	•	• •	•		• • •
VULCAN-142	•	•				•	• •	•		• • •
VULCAN-162	•	•				•	••	•		• • •
CAM DRIVEN D	DESIGN									
RA-5	•	•				•	•		•	•
RA-6	•	•				•	•		•	•
RA-10	•	•	-			•	•		•	•
180° DESIGN										
DCT-12	•	•	-		1	•	••			•
DCT-16	•	•				•	••		• •	•
DGT-20	•••••••••••	•				•	••		••	•
DC1-25	•	•	_			•	••		•••	•
GT-32										
CT-50										
100° FAIL SAF										
DCT-12-RF	•					•				
DCT-16-RF	•	•	_			•	••	•		• • •
DCT-20-RE		•				•	• •	•	• •	
DCT-25-RE	•	•				•	• •	•	• •	
CT-32-RE	•	•				•	• •	•	• •	• • •
CT-40-RE	•	•			_	•	• •	•	• •	• • •
CT-50-RE	•	•				•	• •	•	• •	• • •
FOOD GRIPPER	DISSIGN									
FUA-63	•	•				•	•			• •

Angular Grippers -High Power Series

2.4

• Cost effective:

The simplified drive mechanism makes these grippers an excellent value

• Compact, robust & powerful gripper:

This gripper is designed for use in confined spaces, combining large opening angle with a high torque. Optional safety springs retain the components, should the air supply fail or to increase grip force.

• Multipurpose gripper:

A wide range of options and accessories (hydraulic or pneumatic operation, safety springs for internal or external clamping, Viton[®] seals, and magneto resistive or inductive sensing) allow these grippers to be used in a number of applications.

• Harsh environment:

Shielded design repels chips and other particulate from internal drive mechanism

• High Temperature Design (Vulcan Series):

Designed for heavy-duty, extreme high temperature applications, the Vulcan Series Gripper can be ordered with optional metal seals and fireproof kevlar boot or stainless steel heat shield for added protection.

Mounting Information:

Grippers can be mounted & operated in any orientation

Gripper is located using pilot boss and a dowel pin and assembled with 4 through body screws. Gripper can be operated utilizing top manifold air ports.





Fingers are located on jaws with 2 dowel pins and assembled with 1 screw.

Technical Specifications:

Specifications Pneumatic Pressure Operating	Imperial Range:	Metric
Standard	30-100 psi	2-7 bar
with -RE, -RI Spring Option	45-100 psi	3-7 bar
Hydraulic Pressure Operating	Range:**	0.00 hav
Hydraulic with DE DI Spring Option	30-290 psi	2-20 Dar 2-20 bor
Cylinder Type	AD-290 USI	3-20 Dar ting
	Actina Sinalo	uny oring Roturn
0	Double Acting S	oring Assist
Dynamic Seals	Internally Lubric	ated Buna-N
Valve Required 4-way	, 2-position for D	ouble Acting
to Operate or 3-w	ay, 2-position for	Single Acting
Air Quality Requirements		
Air Filtration	40 Micron	or Better
Air Lubrication	Not Neces	sary*
Air Humidity	Low Moisture Co	ontent (dry)
Temperature Operating Ran	ae	
Viton [®] Seals (RUA Series)	-20°~300° F	-30°~150° C
Vulcan Series	-20°~842° F	-30°~450° C
Maintenance Specification	St	
Expected Life		
Normal Application	5 million o	cycles
w/ Preventative Maintenanc	e 10+ millio	n cycles*
Field Repairable	Yes	
Seal Repair Kits Available	Yes	

*Addition of lubrication will greatly increase service life

* See Maintenance Section ** The gripper can be operated at 290psi (20 bars) MAXIMUM hydraulic pressure. Cycle times are longer and may depend on the hydraulic system. Grippers must be mounted before being operated under hydraulic pressure. Please contact factory for more information.



- cams levers. - The piston's translatory motion makes the cams levers rotate in a
- synchronous motion.
- Optional springs can be used to increase the grip force, to hold part in the event of loss of air, or to use the gripper in single acting mode.
- This gripper is suitable for internal or external gripping.

00PSI [7 bar], L=2" [50.8], with spring, jaws at 0° $$					
VULCAN	Angula	r Gripp	er		
162M	Style: Stroke: Grip Force:* Weight:	VULCAN 34.0 2015 lbs 14.77 lbs See Page 2	-162M 5° 8964 N 6.7 Kg		

*Grip force @ 100PSI [7 bar], L=2" [50.8], with spring, jaws at 0°

Size

384 N

0.39 Ka

1228 N

0.70 Kg

2150 N 1.70 Kg

5775 N

4.1 Kg

3983 N

1.7 Ka

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

ANGULAR GRIPPER RUA-62M SPRING ASSISTED SERIES



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Metric [mm]

Imperial in.

ę	₽⊕
Dimensions are symmetrical about centerline	Third Angle Projection

$\sim \phi$		1 A
+		*
$- \psi$	$\mathbf{\Psi}$	42

Dimensions are
symmetrical about
centerline

	$\Rightarrow \oplus$	\bullet	\odot	Imperial in.
re out	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$

Dimonolono aro	
symmetrical about	Pro
centerline	

ow to	Order	(Order Concretely)



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Specifications	RUA-6	i2M	
Total Rated Grip Force L=1 in [25.4mm] @ 0°			
100 psi, 7 bar, w/spring	86 lbs.	384 N	
100 psi, 7 bar, w/o spring	70 lbs.	313 N	
Stroke	16.8° of stroke fo	or each finger	
Weight	0.86 lbs.	0.39 kg	
Pressure Range (without springs)	30-100 psi	2-7 bar	
Pressure Range (with springs)	45-100 psi	3-7 bar	
Cylinder Bore Ø	1.57 in.	40 mm	
Displacement	0.73 in ³ .	12 cm ³	
Temperature Range			
Viton [®] Seals Standard	-20°~300° F	-30~150° C	
Actuation (open/close)	0.18 sec./0.18 sec.		
Accuracy	±0.002 in.	±0.05 mm	
Repeatability	±0.0008 mm.	±0.02 mm	
Valve required to actuate single acting	3-way, 2-position		
Valve required to actuate double acting	4-way, 2-	-position	

ANGULAR GRIPPER RUA-62M SPRING ASSISTED SERIES



Loading Capacity[†] Static Dynamic Maximum Tensile T 53 lbs. [236 N] 11 lbs. [47.2 N] Maximum Compressive C 53 lbs. [236 N] 11 lbs. [47.2 N] Maximum Moment Mx 111 in.-Ibs. [12.5 Nm] 27 in.-Ibs. [3.1 Nm] 305 in.-1bs. [34.5 Nm] 31 in.-Ibs. [3.5 Nm] Maximum Moment My Maximum Moment Mz 111 in.-Ibs. [12.5 Nm] 27 in.-Ibs. [3.1 Nm]

*Capacities are per set of jaws and are not simultaneous

Accessory Mounting Technical Data



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

ANGULAR GRIPPER RUA-82M SPRING ASSISTED SERIES





	Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	- Metric Threads Course Pitch	Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	$\begin{array}{l} \textbf{Metric [mm]} \\ [0.] = [\pm .25] \\ [0.0] = [\pm .13] \\ [0.00] = [\pm .013] \end{array}$
How to Order: (Order Separately)						
BASIC MODEL SPRING ASSIST (See Below) RUA-822M -	SE PN PP PN PN PN PV Qu Qu Qu Qu Qu Qu Qu Qu Qu Vit *Ser Yit	NSOR ACCES IP Magneto Re N Magneto Re IP Magneto	SSORIES esistive Sensor w/Qk Disco esistive Sensor w/Qk Disco esistive Sensor (90° Barrel) esistive Sensor (90° Barrel IP Double Inductive Sensor ct 2 Meter Cable* ct 5 Meter Cable* ct 2 Meter Cable (for KT15 KITS / Boot Kit (includes 2 interfa aw Boot Kit (includes 2 interfa)) (includes 2 interfa))	onnect* ** ti onnect* ** ti) w/Qk Disc* **) w/Qk Disc* **) w/Qk Disc* **) multiple) multiple () m	ORDER # OHSP-01 OHSN-01 TOHSN-01 TOHSN-01 KT15 CABL-01	qTy/UNIT 7 1 or 2 7 1 or 2 1 1 or 2 1 1 or 2 3 1 or 2 3 1 or 2 3 1 or 2 1 1 or 2 1 1 or 2 2 1
SAMPLE ORDER: RUA-82M-H-RE-KT2 Ex: RUA-82M Gripper, Hydraulic, Spring Closed, Sensing Range KT2	***	Requires K11 or F	12 Inductive Case Option			

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UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

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Specifications	RUA-8	2M
Total Rated Grip Force L=1 in [25.4mm] @ 0°		
100 psi, 7 bar, w/spring	276 lbs	1228 N
100 psi, 7 bar, w/o spring	207 lbs.	922 N
Stroke	15.9° of stroke fo	r each finger
Weight	1.55 lbs.	0.70 kg
Pressure Range (without springs)	30-100 psi	2-7 bar
Pressure Range (with springs)	45-100 psi	3-7 bar
Cylinder Bore Ø	2.36 in.	60 mm
Displacement	2.14 in ³ .	35 cm ³
Temperature Range		
Viton [®] Seals Standard	-20°~300° F	-30~150° C
Actuation (open/close)	0.10 sec./0.10 sec.	
Accuracy	±0.002 in.	±0.05 mm
Repeatability	±0.0008 mm.	±0.02 mm
Valve required to actuate single acting	3-way, 2-	-position
Valve required to actuate double acting	4-way, 2-	-position

ANGULAR GRIPPER RUA-82M SPRING ASSISTED SERIES





Louding Capacity	ouno	Dynamio			
Maximum Tensile T	65 lbs. [290 N]	13 lbs. [58 N]			
Maximum Compressive C	65 lbs. [290 N]	13 lbs. [58 N]			
Maximum Moment M _X	168 in1bs. [19 Nm]	42 inIbs. [4.8 Nm]			
Maximum Moment My	1071 in1bs. [121 Nm]	106 inIbs. [12 Nm]			
Maximum Moment Mz	168 in1bs. [19 Nm]	42 in1bs. [4.8 Nm]			
Capacities are per set of jaws and are not simultaneous					

Accessory Mounting Technical Data



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

ANGULAR GRIPPER RUA-112M SPRING ASSISTED SERIES

75.0 2.953 [32.0] 1.260 [95.3] Ø 3.750 [5 h7] Ø 0.1969 SF [16.0] 0.630 [21.5] 0.846 [38.4] 1.512 [8.5] - 4 x Ø 0.335 2 [G1/8 x 8 DP] [M8 x 13 DP] 0-Ø φ Close \oplus 4 5 [40.0] 1.575 ¢ \odot [22.1] 0.870 E 6 OF 5 [110.0] Ø 4.331 1 15° 200 Æ 0 ĝ F [9.0] 0.354 Ć Ø Ð φ \cap Open Purge port 6 ¢ 80 [8 H9 x 13 DP] [25.40] 1.0000 E N° Purge / Scavenge port [M5 x 6] Ø 0.3150 SF x 0.512 ¢ [76.2 h7] 40 Open [45.0] 1.772 Close Ø3.0000 SF [19 f8] 0.7480 [3.0] 0.118 [3.1] 0.122 Manifold air port [48.0] 1.890 Supplied plugged [66.0] 2.598 -KT: Inductive sensor [111.0] 4.370 Sensing range Opened: 13° (From close position) Yellow LED Green LED a 0 KT1 17.2° to 19.1° 0° to 1.9° П 0 KT2 0° to 5.7° 13.4° to 19.1° 0 0 Inductive sensor 0 0 -0-Closed: 6.2° Same attachment [102.0] 4.016 as gripper

	Ģ	₽⊕	•	\oplus	Imperial in. N	letric [mm]
s	Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{l} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array} [0.0000 = \pm .0005] \end{array}$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$
How to Order: (Order Separately)						
	SE	NSOR ACCES	SORIES		ORDER #	QTY/UNIT
	PN	IP Magneto Re	esistive Sensor w/Qk Disco	nnect* ** ⁺⁺	OHSP-017	1 or 2
RUA-112M	NF	PN Magneto R	esistive Sensor w/Qk Disco	onnect* ** 👖	OHSN-017	1 or 2
	PN	IP Magneto Re	esistive Sensor (90° Barrel)) w/Qk Disc* **	** OHSP-011	1 or 2
POWER INTEGRATED SENSOR	NF	N Magneto R	esistive Sensor (90° Barrel) w/Qk Disc* **	" OHSN-011	1 or 2
P-Pneumatic	Re	eplacement PN	IP Double Inductive Sensol	r^ ^^^	KI15	1
H-Hydraulic	QL QL	lick Disconned	t 5 Meter Cable*		CARL-UIU	1 or 2
POWER P Pneumatic Hydraulic (20 bar max.)	QL	uick Disconned	t 2 Meter Cable (for KT15	Inductive Sense	or)* CABL-013	1 or 2
SPRING RE Closed	SE	ALED BOOT	KITS			
RI Open	PV	/C Sealed Jaw	Boot Kit (includes 2 interfa	aces, 1 collar, 1	boot) SLKT-373	1
Leave Blank. No Spring Option (standard)	Ke Fir	evlar Sealed Ja reProof Kevlar	aw Boot Kit (includes 2 inte Sealed Jaw Boot Kit	erfaces, 1 collar	; 1 boot) SLKT-374	1
INDUCTIVE CASE* KT1 Sensing Range KT1		(includes 2 int	erfaces, 1 collar, 1 boot)		SLKT-375	1
Leave Blank No Inductive Ontion						
* Inductive Case not available with DUA model	SE	al repair kit		PNEUMATIC	HYDRAULIC	
	Vit	ton® Seal Repa	air Kit	SLKT-158V	SLKT-332V	1
	*Sei ††N ***	nsor and cable so lot compatible wit Requires KT1 or k	ld separately †Requires Mounti h Hydraulic (- H) option and requir T2 Inductive Case Option	ng Kit **Piston ma res -RE or -ORI optio	ignet standard on	

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SAMPLE ORDER: RUA-112M-P-RI-KT2 Ex: RUA-112M Gripper, Pneumatic, Spring Open, Sensing Range KT2

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

RUA SERIES 2.10

Please see back cover for DE-STA-CO Global Locations. www.destaco.com



Specifications	RUA-1	12M
Total Rated Grip Force L=1 in [25.4mm] @ 0°		
100 psi, 7 bar, w/spring	483 lbs.	2150 N
100 psi, 7 bar, w/o spring	360 lbs.	1600 N
Stroke	19.1° of stroke fo	or each finger
Weight	3.75 lbs.	1.70 kg
Pressure Range (without springs)	30-100 psi	2-7 bar
Pressure Range (with springs)	45-100 psi	3-7 bar
Cylinder Bore Ø	2.99 in.	76 mm
Displacement	5.19 in ³ .	85 cm ³
Temperature Range		
Viton [®] Seals Standard	-20°~300° F	-30~150° (
Actuation (open/close)	0.35 sec./0).35 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.0008 mm.	±0.03 mm
Valve required to actuate single acting	3-way, 2-	-position
Valve required to actuate double acting	4-way, 2-	-position

ANGULAR GRIPPER RUA-112M SPRING ASSISTED SERIES



Loading Capacity[†] Static Dynamic Maximum Tensile T 65 lbs. [290 N] 13 lbs. [58 N] Maximum Compressive C 65 lbs. [290 N] 13 lbs. [58 N] 42 in.-Ibs. [4.8 Nm] Maximum Moment Mx 168 in.-Ibs. [19 Nm] Maximum Moment My 1071 in.-Ibs. [121 Nm] 106 in.-Ibs. [12 Nm] Maximum Moment Mz 168 in.-1bs. [19 Nm] 42 in.-1bs. [4.8 Nm] *Capacities are per set of jaws and are not simultaneous

Accessory Mounting Technical Data



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Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com

ANGULAR GRIPPER RUA-142M SPRING ASSISTED SERIES

[6 m6]

[2 x M8 x 18 DP]

26.0

1.024

24.0 0.945

24.0 0.945



—— UNLESS	OTHERWISE NOTED ALL	TOLERANCES ARE	AS SHOWN BELOW -	

[140.5] 5.531

Inductive sensor

٤	Ð
Dimensions are symmetrical about centerline	Third Proje

15°

	$\Rightarrow \oplus$	\bullet	\odot	Imperial in.	Metric [mm]
ut	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{l} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	$\begin{array}{l} [0.] = [\pm .25] \\ [0.0] = [\pm .13] \\ [0.00] = [\pm .013] \end{array}$

Inductive sensor

How to Order: (Order Separately)

Closed: 4.6°



SENSOR ACCESSORIES		ORDER #	QTY/UNIT
Replacement PNP Double Inductive Sensor* 3	***	KT15	1
Quick Disconnect 2 Meter Cable (for KT15 In	ductive Sensor)*	CABL-014	1 or 2
SEALED BOOT KITS			
PVC Sealed Jaw Boot Kit (includes 2 interface	es, 1 collar, 1 boot)	SLKT-376	1
Kevlar Sealed Jaw Boot Kit (includes 2 interfa	aces, 1 collar, 1 boot)	SLKT-377	1
FireProof Kevlar Sealed Jaw Boot Kit			
(includes 2 interfaces, 1 collar, 1 boot)		SLKT-378	1
SEAL REPAIR KIT	PNEUMATIC	HYDRAULIC	
Viton [®] Seal Repair Kit	SLKT-333V	SLKT-334V	1

*Sensor and cable sold separately ***Requires KT1 or KT2 Inductive Case Option

2.12

Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com



Specifications	RUA-1	42M
Total Rated Grip Force L=1 in [25.4mm] @ 0°		
100 psi, 7 bar, w/spring	1298 lbs.	5775 N
100 psi, 7 bar, w/o spring	886 lbs.	3941 N
Stroke	17.6° of stroke fo	or each finger
Weight	9.05 lbs.	4.1 kg
Pressure Range (without springs)	30-100 psi	2-7 bar
Pressure Range (with springs)	60-100 psi	4-7 bar
Cylinder Bore Ø	4.13 in.	105 mm
Displacement	13.2 in ³ .	215 cm ³
Temperature Range		
Viton [®] Seals Standard	-20°~300° F	-30~150° C
Actuation (open/close)	0.60 sec./0.60 sec.	
Accuracy	±0.003 in.	±0.8 mm
Repeatability	±0.0008 mm.	±0.03 mm
Valve required to actuate single acting	3-way, 2	-position
Valve required to actuate double acting	4-way. 2	-position

ANGULAR GRIPPER RUA-142M SPRING ASSISTED SERIES

GRIP FORCE PER FINGER N Ibs. (at 0° with Spring Assist) 7500 1686 6250 1405 FINGER FORCE - F/2 5000 1124 290 PSI [20 bar] WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE FINGER LENGTHS 3750 843 100 PSI [7 bar] 2500 562 -80 PSI [5.5 bar] 1250 281 0 2 3 5 6 8 9 in. 25 51 76 102 127 152 178 203 228 nm EFFECTIVE FINGER LENGTH FROM ROTATION AXIS - L



Loading Capacity ⁺	Static	Dynamic
Maximum Tensile T	142 lbs. [630 N]	28 lbs. [126 N]
Maximum Compressive C	142 lbs. [630 N]	28 lbs. [126 N]
Maximum Moment Mx	460 in1bs. [52 Nm]	115 inIbs. [13 Nm]
Maximum Moment My	6160 in1bs. [696 Nm]	611 inIbs. [69 Nm]
Maximum Moment Mz	460 in1bs. [52 Nm]	115 inIbs. [13 Nm]
⁺ Capacities are per set of jaws and are no	t simultaneous	

Accessory Mounting Technical Data



RUA SERIES 5.13

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

ANGULAR GRIPPER RUA-162M SPRING ASSISTED SERIES





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Ģ	\Rightarrow	\bullet	\oplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	$\begin{array}{l} [0.] = [\pm .25] \\ [0.0] = [\pm .13] \\ [0.00] = [\pm .013] \end{array}$

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Dimensions are	Thir
ymmetrical about	Pro
centerline	

	$\Rightarrow \oplus$	\bullet	\oplus	Imperial in.
t	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

How to Order: (Order Separately)



SENSOR ACCESSORIES	ORDER #	QTY/UNIT
Replacement PNP Double Inductive Sensor* ***	KT15	1
Quick Disconnect 2 Meter Cable (for KT15 Inductive Sensor)*	CABL-014	1 or 2
SEALED BOOT KITS		
PVC Sealed Jaw Boot Kit (includes 2 interfaces, 1 collar, 1 boot)	SLKT-379	1
Kevlar Sealed Jaw Boot Kit (includes 2 interfaces, 1 collar, 1 boot)	SLKT-380	1
FireProof Kevlar Sealed Jaw Boot Kit		
(includes 2 interfaces, 1 collar, 1 boot)	SLKT-381	1
SEAL REPAIR KIT PNEUMATIC	HYDRAULIC	
Viton® Seal Repair Kit SLKT-335V	SLKT-336V	1

*Sensor and cable sold separately ***Requires KT1 or KT2 Inductive Case Option

Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com



Specifications	RUA-16	62M
Total Rated Grip Force L=2 in [50.8mm] @ 0°		
100 psi, 7 bar, w/spring	1234 lbs.	5490 N
100 psi, 7 bar, w/o spring	853 lbs.	3790 N
Stroke	17.2° of stroke fo	r each finger
Weight	14.8 lbs.	6.7 kg
Pressure Range (without springs)	30-100 psi	2-7 bar
Pressure Range (with springs)	60-100 psi	4-7 bar
Cylinder Bore Ø	4.72 in.	120 mm
Displacement	19.7 in ³ .	322 cm ³
Temperature Range		
Viton [®] Seals Standard	-20°~300° F	-30~150° C
Actuation (open/close)	0.80 sec./0	.80 sec.
Accuracy	±0.003 in.	±0.8 mm
Repeatability	±0.0008 mm.	±0.03 mm
Valve required to actuate single acting	3-way, 2-position	
Valve required to actuate double acting	4-way, 2-	position

ANGULAR GRIPPER RUA-162M SPRING ASSISTED SERIES

GRIP FORCE PER FINGER N lbs. 7500 1686 (at 0° with Spring Assist) 6250 1405 FINGER FORCE - F/2 5000 1124 290 PSI [20 bar] WARNING! DO NOT EXCEED 3750 843 MAXIMUM EFFECTIVE FINGER LENGTHS 100 PSI [7 bar] 2500 562 -80 PSI [5.5 ba 1250 281 0 **4 5** 102 127 9 10 11 in. 2 3 76 6 7 8 152 178 203 229 51 254 280mm EFFECTIVE FINGER LENGTH FROM ROTATION AXIS - L



Loading Capacity ^{†1}	Static	Dynamic
Maximum Tensile T	189 lbs. [840 N]	38 lbs. [168 N]
Maximum Compressive C	189 lbs. [840 N]	38 lbs. [168 N]
Maximum Moment Mx	664 in1bs. [75 Nm]	166 inIbs. [18.8 Nm]
Maximum Moment My	9293 in1bs. [1050 Nm]	885 inIbs. [100 Nm]
Maximum Moment Mz	664 in1bs. [75 Nm]	166 inIbs. [18.8 Nm]
[†] Canacities are per set of jaws and are pr	nt simultaneous	

Accessory Mounting Technical Data 1.15 29.2 1.067[27.1] Plumbing Fittings • Adjustable flow controls: – Have thumb screw adjust with locking 0.49[12.4] nut for adjusting actuation time ADJUSTABLE FLOW - Available for 6mm 0D tubing CONTROL G1/4 PLUMBING FITTING • Plumbing fittings: VLVF-010 PLFT-039 For side air port location • Top airport are plugged as standard 1.339 34 Adapter plate 050 7.48 190 Boot for cover set up · Protects the gripper mechanism Provides better performance and longer life time in harsh environment 0 Θ ۲ Three materials available depending on 4.783 121.5 He application: – PVC for grinding applications (up to 176°F / 80°C) ۲ \bigcirc Kevlar for machine applications (up to 480°F / 250°C) Fireproof Kevlar for welding applications (up to 525°F / 275°C) \bigcirc Clamping · A provided spacer has to be added to the jaws Crown

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

ANGULAR GRIPPER VULCAN-112M HIGH TEMPERATURE SERIES



SAMPLE ORDER: VULCAN-112M-HT-RI-E5 Ex: Vulcan-112M Gripper, Dynamic Steel Ring, Spring Open, Fire-proof Kevlar Sealed Jaw Boot up to 450° C

*HT and T Options are not compatible.

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

Fire-proof Kevlar Sealed Jaw Boot (up to 275°C)

Fire-proof Kevlar Sealed Jaw Boot (up to 450°C)

Leave Blank. No Protection Option (Standard)

Stainless Steel Heat Shield

PROTECTION

E3

E5

ET



ANGULAR GRIPPER VULCAN-142M HIGH TEMPERATURE SERIES



SAMPLE ORDER: VULCAN-142M-T-ET Ex: Vulcan-142M Gripper, Rear Output Shaft for Sensing, Stainless Steel Heat Shield

*HT and T Options are not compatible

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

Fire-proof Kevlar Sealed Jaw Boot (up to 275°C)

Fire-proof Kevlar Sealed Jaw Boot (up to 450°C)

Leave Blank. No Protection Option (Standard)

Stainless Steel Heat Shield

PROTECTION

E3

E5

ET

ANGULAR GRIPPER VULCAN-162M HIGH TEMPERATURE SERIES

SELLES

ULCAN

2.18



SAMPLE ORDER: VULCAN-162M-RE-T-E3 Ex: Vulcan-162M Gripper, Spring Closed, Rear Output Shaft for Sensing, Fireproof Kevlar Sealed Jaw Boot up to 275°

*HT and T Options are not compatible.

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

www.comoso.com

Rear Output Shaft for Sensing

Stainless Steel Heat Shield

Leave Blank. No Sensing Option (Standard)

Fire-proof Kevlar Sealed Jaw Boot (up to 275°C)

Fire-proof Kevlar Sealed Jaw Boot (up to 450°C)

Leave Blank. No Protection Option (Standard)

SENSING T*

E3

E5

ET

PROTECTION







RUA/VULCAN Series Exploded View

ltem	Qty	Name
01	1	Body
02	1	Piston
03	1	Cam Driver
04	1	Сар
06	2	Jaw
08	1	Shielded case
09	2	Pivot Pin
52	2	SS Screw, Cap
53	4	SHC Screw, Cap
56	1	Magnet
57	2	SS Screw, Body
<u>61</u>	1	SHC Screw, Piston
62	1	Nut, Piston
63	4	Pin, Jaw
64	2	Screw, Shielded case
65	1	Springs
90	1	KT Body
<u>91</u>	1	KT Body, O-Ring
92	1	KT Sensor
93	1	KT Body, Screw
94	1	Target
95	1	Target, Screw
96	2	KT Body, O-Ring
97	1	KT Body, Screw
98	1	Wire Holder
99	3	KT Body, Screw
<u>100</u>	1	Cap for KT Shaft
101	1	Shaft
102	1	KT Body, Pin

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install the seals onto the cap (x3), the piston (x2) and the body (x1).
- 2) If top airports are used, remove the plug screws from the cap (#4) and insert into side airports of the body (#1).
- 3) Assemble the piston (#2) and the cam driver (#3) with the washer and the screw.
 - RE option : Place the counterbore holes of the piston on the cam driver side.
 - RI option : Place the counterbore holes of the piston on the screw side.
- Insert the piston into the body. Orientate the piston so that the magnets are placed in front of the body slots.
 - RE option : insert the springs (#65) between the body and the piston in the counterbore holes.
- 5) Place and screw the cap onto the body. The dowel holes of the cap and of the body have to be aligned.
 - RI option : insert the springs (#65) between the cap and the piston in the counterbore holes.
- 6) Lubricate the slots and the jaws (#6) and the groove of the cam driver.
- 7) Place the jaws into the body slot and insert the pivot pin aligning with the jaw hole. The flat of the pivot pin has put in front of the rear side of the body. Screw SS screw into the body to prevent the pivot pin from moving.
 8) Attach the children case.
- 8) Attach the shielded case.

SK Seal Repair Kit Order #'s See Product Data Sheets

SK		KRYTOX	0	G	GLUE	$\Box \oplus$
Seal Kit	Thread	Krytox [™]	Lightweight	Teflon [®] Based	Super	Third Angle
Items	Locker	Lubricant	Machine Oil	Grease	Bonder	Projection

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

RUA/VULCAN Series Assembled View





A

81

82

90

80

83



ltem	Qty	Name
01	1	Body
02	1	Piston
03	1	Cam Driver
04	1	Сар
06	2	Jaw
08	1	Shielded case
09	2	Pivot Pin
52	2	SS Screw, Cap
53	4	SHC Screw, Cap
56	1	Magnet
57	2	SS Screw, Body
61	1	SHC Screw, Piston
62	1	Nut, Piston
63	4	Pin, Jaw
64	2	Screw, Shielded case
65	1	Springs

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions

Installation - MR Sensors

- 1) Insert sensors (#90) for either end of the profile slots
- 2) Set the sensors with the integrated screw

Installation - Boot

- 1) Mount the gripper onto the customer mounting plate
- 2) Insert the spacer (#81) into the pins of the jaws
- 3) Insert sensor slot plugs (#82) into sensor mounting groove. Install the boot (#80) on the gripper. The jaw opening of the boot has to fit with the spacer. Insert lip of boot seal into the groove of the gripper
- 4) Use the clamping ring (#83) to fasten the boot on the gripper
- 5) Attach fingers to the jaws (ensure that boot is sealed between the jaws and the finger)

Installation - Stainless Steel Shield

- 1) Mount the gripper onto the customer mounting plate
- 2) Insert the spacer plate (#88) using (2) fasteners (#87) to the center of the gripper
- 3) Install the stainless steel shield (#84) using the (2) fasteners (#86) on top of the stainless steel shield and the (4) fasteners (#85) on the side of the stainless steel shield
- 4) Install fingers to gripper as required



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PRECISESIGN NOTESTY

(DESAGO



Angular Grippers -Cam Driven Series



SERIES

2.22

• General Purpose: This style gripper is widely used in the industry and is a rugged design that supplies very high grip force for its size.

 Cost Effective: The simplified drive mechanism makes these grippers an excellent value.

Mounting Information:

Grippers can be mounted & operated in any orientation





Body mounts with screws and locates with slip fit dowel pins for accuracy

Warning! Protect jaw mechanism from falling debris when mounted upside down







Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements Air Filtration

Air Lubrication Air Humidity

40 Micron or Better Not Necessary* Low Moisture Content (dry)

Temperature Operating Range

-30°~180° F Buna-N Seals (standard) -35°~80° C Viton[®] Seals (optional) -20°~300° F -30°~150° C

Maintenance Specifications[†]

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available *Addition of lubrication will greatly increase service life See Maintenance Section

5 million cycles 10+ million cycles* Yes Yes

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the wedge into angular synchronous motion of the jaws.
This gripper is suitable for internal or external gripping.

Designed and manufactured in the USA

2.23

Please see back cover for DE-STA-CO Global Locations. www.destaco.com WWW.COMOSO.COM

ANGULAR GRIPPER RA-5M CAM DRIVEN SERIES









Specifications RA-5 RA-5M Total Rated Grip Force **F** @ 100 psi, 7 bar20 lbs. 89 N Stroke 15° of stroke for each finger Open Stroke Adjustment 15° of stroke for each finger Weight 0.25 lbs. 0.11 Kg Pressure Range..... 40-100 psi 3-7 bar Cylinder Bore Ø813 in. 20.6 mm Displacement 2.1 cm³ 0.130 in³. Temperature Range -35°~80° C Standard Seals -30°~180° F Viton® Seals -20°~300° F -30°~150° C 0.10 sec. 0.10 sec. Actuation Accuracy..... ±0.005 in. ±0.13 mm Repeatability..... ±0.003 in. ±0.08 mm Valve required to actuate 4-way, 2-position





Loading Information



How to Order: (Order Separately)

BASIC MODEL N RA-5 M VITON	IETRIC - V I° SEALS	
SENSOR ACCESSORIES	ORDER #	QTY/UNIT
4mm NPN Magneto Resistive Sensor*	OHSN-017	1 or 2
4mm PNP Magneto Resistive Sensor*	OHSP-017	1 or 2
4mm NPN 90° Magneto Resistive Sensor*	OHSN-011	1 or 2
4mm PNP 90° Magneto Resistive Sensor*	OHSP-011	1 or 2
Quick Disconnect 2 Meter Cable Length*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable Length*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Fail Safe Valve (Imperial)	OFSV-001	1
Fail Safe Valve (Metric)	OFSV-004	1
Standard Seal Repair Kit	SLKT-022	1
Viton [®] Seal Repair Kit	SLKT-022V	1
*Sensor and cable sold separately.		
	FAILSAFE VALVE	[16]

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Loading Information

Maximum Moment Mz

*Capacities are per set of jaws and are not simultaneous



20 in.-Ibs.

2.3 Nm

20 in.-lbs.

2.3 Nm

ANGULAR GRIPPER RA-6M CAM DRIVEN SERIES

Specifications	RA-6	RA-6M
Total Rated Grip Force F @ 100 psi, 7 bar4	14 lbs.	196 N
Stroke	15° of stroke for	r each finger
Open Stroke Adjustment	15° of stroke for	r each finger
Weight	0.69 lbs.	0.31 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	1.250 in.	31.8 mm
Displacement	0.300 in ³ .	4.9 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation	0.11 sec.	0.11 sec.
Accuracy	±0.005 in.	±0.13 mm
Repeatability	±0.003 in.	±0.08 mm
Valve required to actuate	4-way, 2-p	osition





How to Order: (Order Separately)

BASIC MODEL ME		
KA-O	Щ	
VITON®	SEALS	
SENSOR ACCESSORIES	ORDER #	QTY/UNIT
4mm NPN Magneto Resistive Sensor*	OHSN-017	1 or 2
4mm PNP Magneto Resistive Sensor*	OHSP-017	1 or 2
4mm NPN 90° Magneto Resistive Sensor*	OHSN-011	1 or 2
4mm PNP 90° Magneto Resistive Sensor*	OHSP-011	1 or 2
Quick Disconnect 2 Meter Cable Length*	CABL-010	1 or 2
Quick Disconnect 5 Meter Cable Length*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES		
Fail Safe Valve (Imperial)	OFSV-001	1
Fail Safe Valve (Metric)	OFSV-004	1
Standard Seal Repair Kit	SLKT-023	1
Viton [®] Seal Repair Kit	SLKT-023V	1
*Sensor and cable sold separately.		
HALL EFFECT SENSOR	FAILSAFE VALVE	.63 [16]
	4-2.67 [68] MIN.——

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

Seal Kit Items Thread Locker Krytox™ Lubricant





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Teflon® Based Grease Super Bonder Third Angle Projection

www.comoso.com

Lightweight Machine Oil



RA-5 & 6 Series Assembled View





Item Qty Name

01	1	Body
02	2	Jaw
03	1	Wedge
04	1	Piston
05	1	Сар
06	1	Plate, Adjustment
30	1	SSS, Nylon Patch, Cup Point
31	2	Dowel Pin
40	2	Magnet

2.27

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation

1) Install sensors in profile slots as shown.

2) Set with integrated set screw.

Δ GLUE SK 0 G THREAD > KRYTOX Seal Kit Items Thread Locker Krytox™ Lubricant Lightweight Machine Oil Teflon® Based Grease Super Bonder Third Angle Projection

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

ANGULAR GRIPPER RA-10M CAM DRIVEN SERIES





RA SERIES

2.28

Specifications	RA-10	RA-10M
Total Rated Grip Force F @ 100 psi, 7 bar1	6 lbs.	71 N
Stroke	15° of stroke for	r each finger
Weight	0.063 lbs.	0.03 Kg
Pressure Range	40-100 psi	3-7 bar
Cylinder Bore Ø	.813 in.	20.6 mm
Displacement	0.026 in ³ .	.4 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton [®] Seals	-20°~300° F	-30°~150° C
Actuation Time	0.08 sec.	0.08 sec.
Accuracy	±0.003 in.	±0.08 mm
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-po	osition



— UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW —

Ç	\Rightarrow	\bullet	\oplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	

Loading Information

GRIP FORCE PER FINGER N lbs 36 8 WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE 31 7 10n - F/2 27 6 FINGER LENGTHS 22 5 FINGER FORCE 60 PSI 18 4 40 PSI 13 **3** 92 51 0 0 Ó 5 1.5 38 mm **EFFECTIVE FINGER LENGTH - L** 7 Ζ Mz t ·Χ Т c F/2 F/2 M× MY Static Dynamic Loading Capacity[†] Metric Imperial Imperial Metric Maximum Tensile T 5 lbs. 22 N 5 lbs. 22 N Maximum Compressive C 5 lbs. 22 N 5 lbs. 22 N Maximum Moment Mx 5 in.-lbs. 0.6 Nm 5 in.-Ibs. 0.6 Nm Maximum Moment My 5 in.-lbs. 0.6 Nm 5 in.-Ibs. 0.6 Nm Maximum Moment Mz 0.6 Nm 5 in.-lbs. 0.6 Nm 5 in.-lbs. *Capacities are per set of jaws and are not simultaneous

BASIC MODEL METRIC RA-10 - V VITON® SEALS

How to Order: (Order Separately)

PNEUMATIC ACCESSORIES	Order #	QTY/UNIT
Standard Seal Repair Kit	SLKT-018	1
Viton [®] Seal Repair Kit	SLKT-018V	1

Please see back cover for DE-STA-CO Global Locations. www.destaco.com



ew

Seal Repair Kit Order #'s See Product Data Sheet

SK

Item	Qty	Name
01	1	Body
02	1	Сар
03	2	Jaw
04	1	Piston
05	1	Shaft
06	1	Pin
31	2	Dowel Pin
NOTE: Depar list wit	: Conta tment th orde	ict the Robohand Sales for a complete spare parts er numbers and prices.





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www.comoso.com

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Item	ŲLY	Name

01	1	Body
02	1	Сар
03	2	Jaw
04	1	Piston
05	1	Shaft
06	1	Pin
31	2	Dowel Pin

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



PRECISESIGN NOTESTY

(DESAGO



Angular Grippers -Series

- 180° angular gripper: The full jaw opening (180°) means that the part can be direct fed, avoiding any release movement by the robot or by the actuator.
- Multiple mounting locations: DIRECTCONNECT[™] mounting on back of body (sizes 12-25). Standard mounting on top.
- Compact gripper: This gripper is designed for use in confined spaces.
- Multipurpose gripper: Several accessories (adjustable stop, magneto resistive or inductive sensors*) allow this gripper to be used in a number of applications.
- **Harsh environments:** Shielded design repels chips and other particulate from internal drive mechanism. * Inductive sensors not available on CT-12

Technical Specifications:

Presumatic Specifications	Imperial	Metric
Pressure Operating Range	40-100 psi	3-7 bar
Cylinder Type	Double A	cting
Dynamic Seals	Internally Lubric:	ated Buna-N
Valve Required to Operate	4-way, 2-p	oosition

Air Quality Requirements

ŀ 1

Air Filtration	40 Micron or Better
Air Lubrication	Not Necessary*
Air Humidity	Low Moisture Content (dry)

Temperature Operating Range -30°~180° F Buna-N Seals (Standard) -35°~80° C Viton[®] Seals (Optional) -20°~300° F -30°~150° C

Maintenance Specifications

Expected Life	
Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycles*
Field Repairable	Yes
Seal Repair Kits Available	Yes
*Addition of lubrication will greatly increase service life	•

Mounting Information:

Grippers can be mounted & operated in any orientation

Gripper is located from the top with 2 dowel pins and assembled with 2 screws.

DIRECTCONNECT mounting pattern: Gripper is located with 2 dowel pins and assembled with 4 screws. Alternative pattern: Gripper is located with 2 dowel pins and assembled with 2 screws.



Fingers are centered over the jaws, located with 1 dowel pin and assembled with 2 screws.

Gripper can be operated utilizing top manifold air ports.

2.32



The gripper

is protected from falling

debris when it is mounted and operated upside down.



- is connected to a fork driver on which 2 drive pins are fixed.
- · Jaw rotation is synchronized with the drive pin-jaw assembly.
- · Sliding in these slots, drive pins convert vertical motion of the piston into rotating opposite synchronous motion of both jaws.
- Each jaw has a useful rotation stroke of 90°, between the 90° open position and the 0° gripping position, plus a gripping over-stroke of approximately 1.5° before reaching the fully gripped position. Jaws have to be designed for a 0° gripping position (parallel jaws)

Style-DCT /	Angular	Gripper
Size -12M	Style: Stroke: Grip Force: Weight:	DCT-12M 90° each finger 7.2 lbs 32 N 0.20 lbs 0.09 Kg
	IJ	See 2.34
Style-DCT /	Angular	Gripper
Size -16M	Style: Stroke: Grip Force: Weight:	DCT-16M 90° each finger 16 lbs 70 N 0.35 lbs 0.16 Kg
		See 2.35 Page
Style-DCT /	Angular	Gripper
Size -20M	Style: Stroke: Grip Force: Weight:	DCT-20M 90° each finger 25 lbs 112 N 0.62 lbs 0.28 Kg
	J	See 2.36 Page
Style-DCT /	Angular	Gripper
Size -25M	Style: Stroke: Grip Force: Weight:	DCT-25M 90° each finger 35 lbs 157 N 1.08 lbs 0.49 Kg
		See 2.37
Style-CT Ar	ngular (aripper
Size -32M	Style: Stroke: Grip Force: Weight:	CT-32M 90° each finger 61 lbs 272 N 1.59 lbs 0.72 Kg
		See 2.38 Page
Style-CT Ar	ngular (ripper
Size -40M	Style: Stroke: Grip Force: Weight:	CT-40M 90° each finger 100 lbs 446 N 2.60 lbs 1.18 Kg
		See 2.39
Style-CT Ar	ngular (aripper
Size -50M	Style: Stroke: Grip Force: Weight:	CT-50M 90° each finger 146 lbs 651 m 4.00 lbs 1.82 Kg
		See 2.40 Page

DCT/CT SERIES

2.33

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ANGULAR GRIPPER DCT-12M **180° SERIES**





Please see back cover for DE-STA-CO Global Locations. www.destaco.com

0.59 [15]

ADJUSTABLE

STOP KIT (BR

2 lbs.

3 in.-Ibs.

3 in.-lbs.

3 in.-lbs.

0.3 Nm

0.3 Nm

0.3 Nm

1.1 Nm

1.1 Nm

1.1 Nm

10 in.-Ibs.

10 in.-Ibs.

10 in.-Ibs.

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mx

*Capacities are per set of jaws and are not simultaneous



ANGULAR GRIPPER DCT-16M 180° SERIES



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

DCT SERIES

ANGULAR GRIPPER DCT-20M **180° SERIES**

SERIES

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Please see back cover for DE-STA-CO Global Locations. www.destaco.com



Maximum Moment Mz

*Capacities are per set of jaws and are not simultaneous

89 in.-Ibs.

10 Nm

22 in.-Ibs.

2.5 Nm

ANGULAR GRIPPER DCT-25M 180° SERIES



DIRECTCONNECT

SERIES

50

2.37

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ANGULAR GRIPPER CT-32M 180° SERIES

SERIES

5

2.38









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Please see back cover for DE-STA-CO Global Locations. www.destaco.com


ANGULAR GRIPPER CT-40M 180° SERIES



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

*Capacities are per set of jaws and are not simultaneous

ANGULAR GRIPPER CT-50M 180° SERIES

Maximum Moment My

Maximum Moment Mz

*Capacities are per set of jaws and are not simultaneous

266 in.- lbs.

266 in.- lbs.

30 Nm

30 Nm

66 in.-lbs.

66 in.-Ibs.

7.5 Nm

7.5 Nm

SEI HES

5

2.40





Please see back cover for DE-STA-CO Global Locations. www.destaco.com

2.38 [60.5] 0.87 [22] 0.7

Sensors Ø 0.47 [12

0.30

0.83 [2





Item Qty Name 01 Body 02 Driver 03 1 Piston 2 04 Jaw 05 Washer 1 06 Cap 1 07 Shielded Plate 08 2 Wiper Cover Drive Pin 09 2 2 **Pivot Pin** 10 54 1 Magnet

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install the seals into cap (x1), piston (x2) and body (x1)
- 2) If top air ports are used, clear them and plug the side air ports on the body (#1)
- 3) Lubricate the sloping rack of jaws (#4)
- 4) Install both drive pins (#9) into driver (#2) through sloping racks of jaws. Check that the pin flat surface is correctly aligned before continuing with their installation.
- 5) Lock drive pins in the driver with screws, tightening down on to the flat surface of the pins.
- 6) Position driver and jaws assembly into body.
- 7) Install both pivot pins (#10) into body, through the bore of jaws. Check that the pin flat surface is correctly aligned before continuing with their installation.
- 8) Pivot pin locking:
 - DCT-12 (not shown): lock pivot pins into body with screws, tightening down on to the flat surface of the pins (pins are fixed into body and rotating into jaws)
 - DCT-16 to CT-50: lock pivot pins into jaws with screws, tightening down on to the flat surface of the pins (pins are fixed into jaws and rotating into body)
- 9) Magnet mounting: DCT-12 to DCT-20: install the magnet (#54) on the washer (#5)
 - DCT-25 to CT-50 (not shown): install magnet (#54) onto piston (#3) and lock it by means of its retaining ring.
- 10) Piston mounting:
 - DCT-12 to DCT-20: insert the piston and the washer with magnet into body. Fix the assembly at the end of the driver with screw.
 - DCT-25 to CT-50 (not shown): insert the piston with magnet into body. Fix the assembly at the end of the drivers with screw.
- 11) Check unit operation unladen.
- 12) Install the cap (#6) into body and lock it by means of its retaining ring.
- 13) Place both wiper covers (#8) into body and lock them with their screws.
- 14) Fix the shielded plate (#7) onto body with both screws.

Seal Repair Kit Order #'s SK **See Product Data Sheets**



Please see back cover for DE-STA-CO Global Locations. www.destaco.com



Item Qty Name

01	1	Body
02	1	Driver
03	1	Piston
04	2	Jaw
05	1	Washer
06	1	Сар
07	1	Shielded Plate
08	2	Wiper Cover
09	2	Drive Pin
10	2	Pivot Pin
54	1	Magnet

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation - Adjustment Stop

- 1) Unscrew both screws for mounting of the shielded plate and remove it.
- 2) Fix the new shielded plate (#1) and the stop (#2) onto body with both screws (#3)
- 3) Install the locknut system (#4) and (#5) on the stop.
- 4) Tighten screw for maximum target jaw opening and lock with locknut.



Installation - Inductive Sensor Holders

- 1) Fix the flags (#1) at the end of pivot pins with their screws (#2)
- 2) Holder mounting: - DCT-16M to DCT-32
 - DCT-16M to DCT-32M: fix holder (#3) and spacer (#5) onto body with both screws (#6)
 DCT-40M to DCT-50M: fix holder (#3) onto body with both screws (#6)
- 3) Sensor mounting:
 - DCT-16M to DCT-20M: unscrew lightly both screws for mounting (#6) of holder and insert sensor (#8, not included) into it. Position sensor so that it senses up on flag. Lock the sensor by tightening both screws.
 - DCT-25M to DCT-32M: unscrew lightly screw (#7) on holder and insert sensor (#8, not included) into it. Position sensor so that it senses up the flag. Lock the sensor by tightening screw.
 - CT-40M to CT-50M: insert sensor (#8, not included) in stop into holder. Lock the sensor by tightening the collar holder with both screws (not shown).

4) Adjust flag position by unscrewing their screws for desired sensing positions.



Please see back cover for DE-STA-CO Global Locations. www.destaco.com



PRECISIESIGN NOTESTY

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		A									U								P				C		60	CT/CT SERIES DCT/CT SERIES
						P				C		5		Ū				D	U		R			B		TY
		6	5																							
	R	A	5																P				G		6	
				Y		P		R		C		5						D	U		R			B		
		B	5							U																
	R		8																P				G		5	
										C		5						D						B		
		B	5							U										/						
	R		B																P				G		S	
				Y		PI	ease s	see ba	ack co	ver fo	r DE-S	STA-CO) Glob	al Loc	ations	s. ww	w.des	taco.c	com		2	Ā		B		

Angular Grippers -180° Spring Assist Series

- **180° angular gripper:** The full jaw opening (180°) means that the part can be direct fed, avoiding any release movement by the robot or by the actuator.
- Multiple mounting locations: DIRECTCONNECT[™] mounting on back of body (sizes 12-25). Standard mounting on top.
- Fail safe operation: The force supplied from the internal spring can be used to maintain gripping force if the gripper looses air pressure.
- Compact gripper: This gripper is designed for use in confined spaces.

- **Multipurpose gripper:** Several accessories (adjustable stop, magneto resistive or inductive sensors) allow this gripper to be used in a number of applications.
- Harsh environments: Shielded design repels chips and other particulate from internal drive mechanism.

Mounting Information:

Grippers can be mounted & operated in any orientation

Gripper is located from the top with 2 dowel pins and assembled with 2 screws. DIRECTCONNECT mounting pattern: Gripper is located with 2 dowel pins and assembled with 4 screws. Alternative pattern: Gripper is located with 2 dowel pins and assembled with 2 screws.



Fingers are centered over the jaws, located with 1 dowel pin and assembled with 2 screws.

Gripper can be operated utilizing top manifold air ports.



Imperial Metric 60-100 psi 4-7 bar Double Acting Spring Assist or Single Acting Spring Return
4-way, 2-position
40 Micron or Better Not Necessary* Low Moisture Content (dry)
nge -30°~180° F -35°~80° C -20°~300° F -30°~150° C
IS [†]
5 million cycles ce 10+ million cycles* Yes Yos

Seal Repair Kits Available *Addition of lubrication will greatly increase service life *See Maintenance Section

DIRECTCONNECT

dct-re/ct-re Series

2.44



90° each finger 40 N 9 lbs 0.26 lbs 0.12 Kg E/CT-RE RIES See **2.46** DCT-16M-RE Stroke: Grip Force: 90° each finger 19 lbs 87 N 2.45 0.44 lbs 0.20 Kg See **2.47** DCT-20M-RE 90° each finger 32 lbs 141 N Grip Force: 0.73 lbs 0.33 Kg See 2.48 DCT-25M-RE Stroke: Grip Force: 90° each finger 45 lbs 199 Nm 1.26 lbs 0.57 Kg See **2.49** CT-32M-RE 90° each finger 79 lbs 353 N Stroke: Grip Force: 1.83 lbs 0.83 Kg See **2.50** CT-40M-RE 90° each finger 133 lbs 592 N Grip Force: 1.39 Kg 3 06 lbs See **2.51** CT-50M-RE 90° each finger Grip Force: Weight: 201 in-lbs 893 N 4.87 lbs 2.21 Kg See **2.52**

DCT-12M-RE

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rotating opposite synchronous motion of both jaws.

for a 0° gripping position (parallel jaws)

 Each jaw has a useful rotation stroke of 90°, between the 90° open position and the 0° gripping position, plus a gripping over-stroke of approximately 1.5° before reaching the fully gripped position. Jaws have to be designed

• The fail safe spring allow the gripper to retain the component should the air

supply fail or for the gripper to be used in single acting mode.

ANGULAR GRIPPER DCT-12M-RE **180° SERIES**

DCT-RE SERIES





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1.1 Nm

*Capacities are per set of jaws and are not simultaneous

3 in.-lbs.

1.1 Nm



ANGULAR GRIPPER DCT-16M-RE 180° SERIES

DCT-RE SERIES

2.47



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ANGULAR GRIPPER DCT-20M-RE **180° SERIES**

DCT-RE SERIES





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ANGULAR GRIPPER DCT-25M-RE 180° SERIES

DCT-RE SERIES

2.49



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ANGULAR GRIPPER CT-32M-RE 180° SERIES

RE SERIES

5

2.50

Maximum Moment Mz

*Capacities are per set of jaws and are not simultaneous

142 in.-lbs.

16 Nm

35 in.-Ibs.

4 Nm





Please see back cover for DE-STA-CO Global Locations. www.destaco.com

2.68 [68.2] 0.79 [20] 0.47

Ø 0.31 [8]



ANGULAR GRIPPER CT-40M-RE 180° SERIES



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ANGULAR GRIPPER CT-50M-RE 180° SERIES





Please see back cover for DE-STA-CO Global Locations. www.destaco.com



item	Qty	Name
01	1	Body
02	1	Driver
03	1	Piston
04	2	Jaw
05	1	Washer
06	1	Сар
07	1	Shielded Plate
08	2	Wiper Cover
09	2	Drive Pin
10	2	Pivot Pin
54	1	Magnet
64	1	Spring

2.53

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install the seals into cap (x1), piston (x2) and body (x1)
- 2) If top air ports are used, clear them and plug the side air ports on the body (#1)
- 3) Lubricate the sloping rack of jaws (#4)
- 4) Install both drive pins (#9) into driver (#2) through sloping racks of jaws. Check that the pin flat surface is correctly aligned before continuing with their installation.
- 5) Lock drive pins in the driver with screws, tightening down on to the flat surface of the pins.
- 6) Position driver and jaws assembly into body.
- 7) Install both pivot pins (#10) into body, through the bore of jaws. Check that the pin flat surface is correctly aligned before continuing with their installation.
- 8) Pivot pin locking:
 - DCT-12 (not shown): lock pivot pins into body with screws, tightening down on to the flat surface of the pins (pins are fixed into body and rotating into jaws)
 DCT-16 to CT-50: lock pivot pins into jaws with screws,
 - tightening down on to the flat surface of the pins (pins are fixed into jaws and rotating into body)
- 9) Magnet mounting:
 - DCT-12 to DCT-20: install the magnet (#54) on the washer (#5)
 - DCT-25 to CT-50 (not shown): install magnet (#54) onto piston (#3) and lock it by means of its retaining ring.
- 10) Piston mounting:
 - DCT-12 to DCT-20: insert the spring, then the piston and the washer with magnet into body. Fix the assembly at the end of the driver with screw.
 - DCT-25 to CT-50 (not shown): insert the spring, then the piston with magnet into body. Fix the assembly at the end of the drivers with screw.
- 11) Check unit operation unladen.
- 12) Install the cap (#6) into body and lock it by means of its retaining ring.
- 13) Place both wiper covers (#8) into body and lock them with their screws.
- 14) Fix the shielded plate (#7) onto body with both screws.

SK Seal Repair Kit Order #'s See Product Data Sheets



Please see back cover for DE-STA-CO Global Locations. www.destaco.com







Item Qty Name

01	1	Body
02	1	Driver
03	1	Piston
04	2	Jaw
05	1	Washer
06	1	Сар
07	1	Shielded Plate
08	2	Wiper Cover
09	2	Drive Pin
10	2	Pivot Pin
54	1	Magnet
64	1	Spring

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Installation - Adjustment Stop

(5

- 1) Unscrew both screws for mounting of the shielded plate and remove it.
- 2) Fix the new shielded plate (#1) and the stop (#2) onto body with both screws (#3)
- 3) Install the locknut system (#4) and (#5) on the stop.
- 4) Tighten screw for maximum target jaw opening and lock with locknut.



- 1) Fix the flags (#1) at the end of pivot pins with their screws (#2)
- 2) Holder mounting:
 - DCT-16M to DCT-32M: fix holder (#3) and spacer (#5) onto body with both screws (#6) - CT-40M to CT-50M: fix holder (#3) onto body with both screws (#6)
- 3) Sensor mounting:
 - DCT-16M to DCT-20M: unscrew lightly both screws for mounting (#6) of holder and insert sensor (#8, not included) into it. Position sensor so that it senses up on flag. Lock the sensor by tightening both screws.
 - DCT-25M to DCT-32M: unscrew lightly screw (#7) on holder and insert sensor (#8, not included) into it. Position sensor so that it senses up the flag. Lock the sensor by tightening screw.
 - CT-40M to CT-50M: insert sensor (#8, not included) in stop into holder. Lock the sensor by tightening the collar holder with both screws (not shown).
- 4) Adjust flag position by unscrewing their screws for desired sensing positions.



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

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Angular Grippers -Food Handling Gripper Series

FEATURES & BENEFITS:

- Designed for direct product contact in the food zone, according to the food industry standard (EN 1672-2)
- All parts are corrosion resistant, non-toxic, non-contaminating, non-porous, non-absorbent and non-reactive
- Stainless steel design resists chemical cleaning procedures
- Optional body made of High Performance Polymer, conform to FDA, for a significantly lighter weight
- Electro-polished exterior with no recessed or inaccessible zones prevents retention of contaminants and simplifies cleaning
- Sealed motion components (IP69K design) for high-pressure and high-temperature daily cleanings
- Any metal/metal contact protected by gasket to obtain a leakproof assembly against bacteria
- Angular gripper design for easier radial sealing of jaws
- Optional security springs for external gripping, in case of air supply failure, in single acting or spring assist mode
- No external fasteners to avoid any foreign matter in food
- Contains special lubricants suitable for food industry
- Long maintenance-free service life

APPLICATIONS:

- Food zone and splash zone handling of product
- Non-food zone applications
- Other applications requiring a sealed and corrosion resistant gripper



ANGULAR GRIPPER FUA-63M FOOD GRIPPER SERIES



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

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Rotary Actuators

DRG

DIRECTONNIECT Shaft Output

- For use in applications where low precision end stop positioning and backlash are acceptable
- · Great for inverter gates, escapements, ejection stations. Provides rotational torque for payloads positioned and decelerated by customers supplied shocks and stops.
- End stop positioning for built-in precision end stop positioning and zero backlash see our DRF Rotary Actuator Series.
- Multiple Body Mounting Locations: Tapped and thru flange on top and bottom mounting surfaces, DIRECTCONNECT tapped pattern on bottom surface.

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Preferred Market:
 Global



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Flange Output

- · For use in applications where precision end stop position and zero backlash are required.
- Multiple Mounting Locations: Tapped and thru flange on top and bottom mounting surfaces, DIRECTCONNECT tapped pattern on bottom flange.
- Turntable has DIRECTCONNECT mounting pattern.

Preferred Market:
 Global

RR-18/28 Light Duty Rack and Pinion



- Payload can be connected directly to the turn table. Eliminates the need for a bearing block.
- Zero backlash, preloaded ball bearings, and slip fit dowel pins make this a very precise and repeatable rotary actuator

Preferred Market:
Global

RR-36/46 Medium Duty Rack and Pinion

- · Low profile and bearing supported turn table provides an
- extremely compact package for tight space applications • Payload can be connected directly to the turn table.
- Eliminates the need for a bearing block. Zero backlash, preloaded ball bearings, and slip fit dowel pins make this a very precise and repeatable rotary actuator
- · Air manifold option available
- Midstop position available

Preferred Market:
 Global

Optional Mid Stop

Model	RR-36M
Model	RR-46M

	9	96
See Page	J.	JJ
	2	27
See Page	J.	J

Optional Rotary Manifold

Model	RR-36M
Model	RR-46M

See Page	3.	3	5
See Page	3.	3	7

RR-56/66/76 **Heavy Duty Rack and Pinion Rotary Actuator Series**

- · Designed for large or heavy-duty applications
- · Low profile and bearing supported turn table provides an extremely compact package for tight space applications • Payload can be connected directly to the turn table.
- Eliminates the need for a bearing block.
- · Zero backlash, preloaded ball bearings, and slip fit dowel pins make this a very precise and repeatable rotary actuator
- Air manifold option available
- · Midstop position available

Preferred Market:
 Global

Optional Mid Stop

-		-
Model	RR-56M	See Page 3.45
Model	RR-66M	See Page 3.47
Model	RR-76M	See Page 3.53

Optional Rotary Manifold

	-		-	
Model	RR-	56M		See Page 3.45
Model	RR-	66M		See Page 3.47
Model	RR-	76M		See Page 3.53



See 3.32 Page 3.32

See 2

See **3.14**

See 3.26

See **3.42**

Rotary Actuator DRG DIRECTCONNECT Shaft Output Rotaries

DIRECTCO

Application: Use in applications where low precision end stop positioning and backlash are acceptable

Application Examples: Diverter gates, escapements, ejection stations.

Torque Generation: Provides rotational torque for payloads positioned and decelerated by customers supplied shocks and stops.

End Stop Positioning: For built-in precision end stop positioning and zero backlash see our DRF Rotary Actuator Series.

Multiple Body Mounting Locations: Tapped and thru flange on top and bottom mounting surfaces, DirectConnect tapped pattern on bottom surface.

Mounting Information:

Rotaries can be mounted & operated in any orientation



Mounting thru top flange clearance holes into tapped holes in customer application



Mounting thru bottom flange clearance holes into tapped holes in customer application

Body mounts with screws and slip fit dowels from bottom side

Mounting from underside of table using tapped holes in body top flange

> Payload is attached to output shaft using standard

> > keys and set screws

Technical Specifications:

Pneumatic Specifications
Pressure Operating Range
Cylinder Type
Dynamic Seals
Valve Required
to Operate

Air Lubrication

Air Humidity

Imperial Metric 40-100 psi 3-7 bar Double Acting Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements Air Filtration

40 Micron or Better Not Necessary* Low Moisture Content (dry)

Temperature Operating Range Buna-N Seals (standard) -30°~180° F

-35°~80° C

Maintenance Specifications[†]

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available

5 million cycles 10+ million cycles* Yes Yes

Application Restrictions

Application requiring precise positioning and no backlash (See DRF product line)

*Addition of lubrication will greatly increase service life



DIRECTCONNECT Mounting



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

ROTARY ACTUATOR DRG-075M SHAFT OUTPUT SERIES



2.51

[64]



NOTE: DIRECTCONNECT[™] DIMENSIONS ARE SHOWN IN BLUE

How to Order: (Order Accessories separately from Basic Model)



DEGREES OF ROTATION: 45°, 90°, 135°,180° (for intermediate degrees of rotation use -R option)

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
Magneto Resistive Sensor (PNP)*	OHSP-017	1 or 2
Magneto Resistive Sensor (NPN)*	OHSN-017	1 or 2
Magneto Resistive Sensor 90° Barrel (PNP)*	OHSP-011	1 or 2
Magneto Resistive Sensor 90° Barrel (NPN)*	OHSN-011	1 or 2
Quick Disconnect Cable (2 meters long)*	CABL-010	1 or 2
Quick Disconnect Cable (5 meters long)*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
Seal Repair kit (Standard Buna-N)	SLKT-210	1
Rotational Adjustment Seal Kit (Standard Buna-N)	SLKT-212	1
Flow Control Push-in 90° Elbow M5-6mm 0.D. Tube**	VLVF-008	1 or 2
*Sensor and cable sold separately		

**Flow Controls recommended for most applications

SAMPLE ORDER: DRG-075M-180-R Ex: DRG Rotary, size 075, metric, 180° rotation with rotational adjustment option



Specifications	DRG-075M		
Maximum Payload	0.5 lbs.	0.23 kg	
Maximum Payload Inertia0.	0008 in-lbssec. ²	9.0 X10 ⁻⁵ N-m-sec. ²	
Maximum Torque @ 100psi/7 bar	8.3 lbsin.	0.9 N-m	
Maximum Rotation	180°	180°	
Pitch Diameter of Pinion	0.375 in.	9.5 mm	
Weight without rotational adjuster	0.52 lbs.	0.24 kg	
Weight without rotational adjuster (-R option)	0.72 lbs.	0.33 kg	
Pressure Range	40-100 psi	3-7 bar	
Bore	0.750 in.	19.1 mm	
Displacement (180°)	0.31 in ³ .	5.1 cm ³	
Actuation Time (180° @ 100psi/7 bar)	0.38 sec.	0.38 sec.	
Actuation Time (90° @ 100psi/7 bar)	0.29 sec.	0.29 sec.	
Temperature Range: Standard Seals	-30°~180° F	-35°~82° C	
End Stop Adjustability (-R option)	23°	23°	
Over Travel (each end)	1° to 3°	1° to 3°	
Valve required to actuate	4-way, 2	-position	

Accessory Mounting Technical Data



Flow Controls · Flow controls for adjusting rotational speed





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Loading Capacity	Static	Dynamic
Maximum Tensile T	10 lbs. [44 N]	2 lbs. [9 N]
Maximum Compressive C	20 lbs. [89 N]	4 lbs. [18 N]
Maximum Moment Mx	20 in-1bs. [2.3 Nm]	4 in-1bs. [0.5 Nm]
Maximum Moment My	20 in-1bs. [2.3 Nm]	4 in-1bs. [0.5 Nm]
Maximum Payload W		0.5 lbs. [.23 kg]
Maximum Inertia J		.0008 in-lbssec. ² [9.0 X 10 ⁻⁵ N-m-sec. ²]

Note: Higher payloads and inertia possible with external shocks and stops.



Sensors

- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting kits required
- · Simple adjustment with slotted screw driver
- Built-in LED for ease of positioning and troubleshooting
- Low profile underflush sensor version or 90° wire exit sensor version
- Available with 2M or 5M Quick Disconnect mating cable (order separately)
 Sensor Magnet standard

ROTARY ACTUATOR DRG-094M Shaft output series





How to Order: (Order Accessories separately from Basic Model)

BASIC MODEL ROTATION DRG-094M R	SENSOR ACCESSORIES Magneto Resistive Sensor (PNP)* Magneto Resistive Sensor (NPN)* Magneto Resistive Sensor 90° Barrel (PNP)*	ORDER # OHSP-017 OHSN-017 OHSP-011	QTY/UNIT 1 or 2 1 or 2 1 or 2
ROTATIONAL ADJUSTMENTS DEGREES OF ROTATION: 45°, 90°, 135°,180° (for intermediate degrees of rotation use -R option)	Magneto Resistive Sensor 90° Barrel (NPN)* Quick Disconnect Cable (2 meters long)* Quick Disconnect Cable (5 meters long)* PNEUMATIC ACCESSORIES	OHSN-011 CABL-010 CABL-013 ORDER #	1 or 2 1 or 2 1 or 2 qty/unit
	Seal Repair Ki (Staridard Buna-N) Rotational Adjustment Seal Kit (Standard Buna-N) Flow Control Push-in 90° Elbow M5-6mm 0.D. Tube** *Sensor and cable sold separately **Flow Controls recommended for most applications	SLKT-218 SLKT-218 VLVF-008	1 1 or 2

SAMPLE ORDER: DRG-094M-180-R Ex: DRG Rotary, size 094, metric, 180° rotation with rotational adjustment option

DRG SERIES

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Specifications	DRG-	094M
Maximum Payload	1.5 lbs.	0.68 kg
Maximum Payload Inertia0	.0056 in-lbssec. ²	6.3 X10 ⁻⁴ N-m-sec. ²
Maximum Torque @ 100psi/7 bar	17.3 lbsin.	1.9 N-m
Maximum Rotation	180°	180°
Pitch Diameter of Pinion	0.500 in.	12.7 mm
Weight without rotational adjuster	1.0 lbs.	0.45 kg
Weight without rotational adjuster (-R option)	1.2 lbs.	0.54 kg
Pressure Range	40-100 psi	3-7 bar
Bore	0.938 in.	23.8 mm
Displacement (180°)	0.55 in ³ .	9.0 cm ³
Actuation Time (180° @ 100psi/7 bar)	0.38 sec.	0.38 sec.
Actuation Time (90° @ 100psi/7 bar)	0.29 sec.	0.29 sec.
Temperature Range: Standard Seals	-30°~180° F	-35°~82° C
End Stop Adjustability (-R option)	23°	23°
Over Travel (each end)	1° to 3°	1° to 3°
Valve required to actuate	4-way, 2	2-position

Accessory Mounting Technical Data



Flow Controls · Flow controls for adjusting rotational speed

ROTARY ACTUATOR DRG-094M SHAFT OUTPUT SERIES

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Loading Capacity	Static	Dynamic
Maximum Tensile T	15 lbs. [67 N]	3 lbs. [13 N]
Maximum Compressive C	30 lbs. [133 N]	6 lbs. [27 N]
Maximum Moment Mx	50 in-Ibs. [5.6 Nm]	10 in-Ibs. [1.1 Nm]
Maximum Moment My	50 in-Ibs. [5.6 Nm]	10 in-Ibs. [1.1 Nm]
Maximum Payload W		1.5 lbs. [0.68 kg]
Maximum Inertia J		0.0056 in-lbssec. ² [6.3 X 10 ⁻⁴ N-m-sec. ²]

Note: Higher payloads and inertia possible with external shocks and stops.



- Sensors
 PNP and NPN Magneto Resistive available
 Sensors are slot mounted, no mounting kits required
 Simple adjustment with slotted screw driver
 Built-in LED for ease of positioning and troubleshooting
 Low profile underflush sensor version or 90° wire exit sensor version
 Available with DM or EM Oxide Discover and the sensor version
- Available with 2M or 5M Quick Disconnect mating cable (order separately)
- Sensor Magnet standard

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NOTE: DIRECTCONNECT[™] DIMENSIONS ARE SHOWN IN BLUE

How to Order: (Order Accessories separately from Basic Model)



DEGREES OF ROTATION: 45°, 90°, 135°,180° (for intermediate degrees of rotation use -R option)

SENSOR ACCESSORIES	ORDER #	QTY/UNIT
Magneto Resistive Sensor (PNP)*	OHSP-017	1 or 2
Magneto Resistive Sensor (NPN)*	OHSN-017	1 or 2
Magneto Resistive Sensor 90° Barrel (PNP)*	OHSP-011	1 or 2
Magneto Resistive Sensor 90° Barrel (NPN)*	OHSN-011	1 or 2
Quick Disconnect Cable (2 meters long)*	CABL-010	1 or 2
Quick Disconnect Cable (5 meters long)*	CABL-013	1 or 2
		OTV/UNIT
PNEUMAIIG AGGESSURIES	URDER #	UI 1/UNIT
Seal Repair kit (Standard Buna-N)	SLKT-222	1
Rotational Adjustment Seal Kit (Standard Buna-N)	SLKT-224	1
Flow Control Push-in 90° Elbow M5-6mm 0.D. Tube**	VLVF-008	1 or 2
*Sensor and cable sold separately		

**Flow Controls recommended for most applications

SAMPLE ORDER: DRG-106M-180-R Ex: DRG Rotary, size 106, metric, 180° rotation with rotational adjustment option



Specifications	DRG-1	06M
Maximum Payload	4 lbs.	1.8 kg
Maximum Payload Inertia	.0207 in-lbssec. ²	2.3 X10 ⁻³ N-m-sec. ²
Maximum Torque @ 100psi/7 bar	33.2 lbs in.	3.8 N-m
Maximum Rotation	180°	180°
Pitch Diameter of Pinion	0.750 in.	19.1 mm
Weight without rotational adjuster	2.5 lbs.	1.1 kg
Weight without rotational adjuster (-R option)	2.7 lbs.	1.2 kg
Pressure Range	40-100 psi	3-7 bar
Bore	1.063 in.	27.0 mm
Displacement (180°)	1.16 in ³ .	19.0 cm ³
Actuation Time (180° @ 100psi/7 bar)	0.60 sec.	0.60 sec.
Actuation Time (90° @ 100psi/7 bar)	0.45 sec.	0.45 sec.
Temperature Range: Standard Seals	-30°~180° F	-35°~82° C
End Stop Adjustability (-R option)	23°	23°
Over Travel (each end)	1° to 3°	1° to 3°
Valve required to actuate	4-way, 2	2-position

Accessory Mounting Technical Data



Flow Controls · Flow controls for adjusting rotational speed

ROTARY ACTUATOR DRG-106M SHAFT OUTPUT SERIES

Static

25 lbs. [111 N]

50 lbs. [222 N]

75 in-Ibs. [8.5 Nm]

75 in-Ibs. [8.5 Nm]

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Dynamic

5 lbs. [22 N]

10 lbs. [44 N]

15 in-Ibs. [1.7 Nm] 15 in-lbs. [1.7 Nm]

4 lbs. [1.8 kg]

0.0207 in-lbs.-sec.² [2.3 X 10⁻³N-m-sec.²]

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Loading Capacity

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Payload W

Maximum Inertia J

Maximum Tensile T

0 ||

-"X"

Note: Higher payloads and inertia possible with external shocks and stops.

Sensors

- PNP and NPN Magneto Resistive available
- Sensors are slot mounted, no mounting kits required
 Simple adjustment with slotted screw driver
- Built-in LED for ease of positioning and troubleshooting
- Low profile underflush sensor version or 90° wire exit sensor version
- Available with 2M or 5M Quick Disconnect mating cable (order separately)
- Sensor Magnet standard

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DRG SERIES

ROTARY ACTUATOR DRG-131M SHAFT OUTPUT SERIES





DEGREES OF ROTATION: 45°, 90°, 135°,180° (for intermediate degrees of rotation use -R option)

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Magneto Resistive Sensor (PNP)*	OHSP-017	1 or 2
Magneto Resistive Sensor (NPN)*	OHSN-017	1 or 2
Magneto Resistive Sensor 90° Barrel (PNP)*	OHSP-011	1 or 2
Magneto Resistive Sensor 90° Barrel (NPN)*	OHSN-011	1 or 2
Quick Disconnect Cable (2 meters long)*	CABL-010	1 or 2
Quick Disconnect Cable (5 meters long)*	CABL-013	1 or 2
PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
Seal Repair kit (Standard Buna-N)	SLKT-228	1
Rotational Adjustment Seal Kit (Standard Buna-N)	SLKT-230	1
Fitting Push-in 90° Elbow G1/8, 6mm 0.D. Tube	PLFT-042	1 or 2
Fitting Push-in 90° Elbow G1/8, 8mm 0.D. Tube	PLFT-048	1 or 2
Fitting Push-in Straight G1/8, 6mm 0.D. Tube	PLFT-038	1 or 2
Fitting Push-in Straight G1/8, 8mm O.D. Tube	PLFT-045	1 or 2
Flow Control Push-in 90° Elbow G1/8, 6mm 0.D. Tube**	VLVF-005	1 or 2
*Sensor and cable sold separately		
**Flow Controls recommended for most applications		

SAMPLE ORDER: DRG-131M-180-R

ROTATIONAL ADJUSTMENTS



Specifications	DRG-1	31M
Maximum Payload	7.5 lbs.	3.4 kg
Maximum Payload Inertia	0.0485 in-lbssec. ²	5.5 X10 ⁻³ N-m-sec. ²
Maximum Torque @ 100psi/7 bar	68 lbs-in.	7.6 N-m
Maximum Rotation	180°	180°
Pitch Diameter of Pinion	1.000 in.	25.4 mm
Weight without rotational adjuster	5.4 lbs.	2.4 kg
Weight without rotational adjuster (-R option) 5.6 lbs.	2.5 kg
Pressure Range	40-100 psi	3-7 bar
Bore	1.313 in.	33.4 mm
Displacement (180°)	2.11 in ³ .	34.6 cm ³
Actuation Time (180° @ 100psi/7 bar)	0.87 sec.	0.87 sec.
Actuation Time (90° @ 100psi/7 bar)	0.68 sec.	0.68 sec.
Temperature Range: Standard Seals	-30°~180° F	-35°~82° C
End Stop Adjustability (-R option)	23°	23°
Over Travel (each end)	1° to 3°	1° to 3°
Valve required to actuate	4-way, 2	-position

Accessory Mounting Technical Data



Flow Controls · Flow controls for adjusting rotational speed

ROTARY ACTUATOR DRG-131M SHAFT OUTPUT SERIES



Loading Capacity	Static	Dynamic
Maximum Tensile T	50 lbs. [222 N]	10 lbs. [44 N]
Maximum Compressive C	100 lbs. [445 N]	20 lbs. [89 N]
Maximum Moment Mx	100 in-Ibs. [11.3 Nm]	20 in-lbs. [2.5 Nm]
Maximum Moment My	100 in-Ibs. [11.3 Nm]	20 in-lbs. [2.5 Nm]
Maximum Payload W		7.5 lbs. [3.4 kg]
Maximum Inertia J		0.0485 in-lbssec. ² [5.5 X 10 ⁻³ N-m-sec. ²]

Note: Higher payloads and inertia possible with external shocks and stops.



Sensors

- Sensors
 PNP and NPN Magneto Resistive available
 Sensors are slot mounted, no mounting kits required
 Simple adjustment with slotted screw driver
 Built-in LED for ease of positioning and troubleshooting
 Low profile underflush sensor version or 90° wire exit sensor version
 Available with DM or EM Oxide Discover and the sensor version
- Available with 2M or 5M Quick Disconnect mating cable (order separately)
- Sensor Magnet standard

DIRECTCONNEC

DRG SERIES EXPLODED VIEW



ltem Qty

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and -131 respectively.

Name

Body

Rack

Piston

Hex Nut

Gasket

Bumper

Magnet

Roll Pin

Adjuster

Hex Nut

Fixed Orifice

Seal Washer

Department for a complete spare parts list with order numbers and prices.

Angle Adjuster

End Plate Rotational

End Plate Rotational Adj. Screw

U-cup

Pinion Shaft

Upper Bearing

Lower Bearing

Bearing Retainer

Retaining Ring

Bumper Washer

Bumper Screw

Retainer Screw

End Plate Screw

End Plate



Assembly Procedure

- 1) Press the Upper Bearing #4 onto the Pinion #2.
- Install the Retaining Ring#9 or Hex Nut #10 onto the Pinion #2. 2)
- 3) Assemble the Rack #6 to the Piston #7 with Roll Pins #19.
- Grease the U-Cups #13 and install them onto the Piston #7. 4)
- 5) Press the Magnet #14 into the Piston #7.
- Assemble the Bumper #12, Washers #15 and Bumper Screw #16 6) onto the Piston #7.
- Lubricate the Body #1 bore and install the Piston Assembly into 7) the body.
- Press the Lower Bearing #5 into the Body #1. 8)
- Locate the Piston assembly so it is aligned with an outer edge 9) of the body.
- 10) Lubricate the Pinion assembly and align the key with the same edge of the Body as the Piston and Press the Pinion into the Body.

- 11) Rotate the Pinion through the full travel and insure that the Piston is correctly located in the Body, adjust the travel of the Piston if necessary.
- 12) Grease the Gasket and install the End Plate #3 onto the Body #1.
- 13) Install the 2 Orifice #20 into the Body #1 screw them in until they bottom.
- 14) Install the Bearing Flange #8 with the 4 Flange Screws #17.

-R Option Assembly Procedure:

- 1) Screw the Angle Adjuster into the End Block Angle Adjuster.
- 2) Place the sealing washer over the threaded extension.
- 3) Screw on the Hex Nut over the Sealing Washer.
- Screw the End Block onto the Body with a Gasket.



Please see back cover for DE-STA-CO Global Locations. www.destaco.com



(4` (22 8 **9** 12 11 (21) ÌM Shown with -R Option Rotational Adjusters 0 (20

Warning: Removal of Orifices will void warranty.

SK

Seal Kit Items

Thread Locker

DRG SERIES ASSEMBLED VIEW

Item Qty Name	
---------------	--

01	1	Body
02	1	Pinion Shaft
04	1	Upper Bearing
06	1	Rack
07	1	Piston
08*	1	Bearing Retainer
09*	1	Retaining Ring
11	2	Gasket
12	2	Bumper
20	2	Fixed Orifice
21	2	Angle Adjuster
22	2	End Plate Rotational
		Adjuster

*NOTES:

1) Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices. 2) Item #09 is for size -075 only.

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Accessory Installation & Adjustment Instructions

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Super Bonder

Third Angle Projection

lte	m Qty	Name
50	1 or 2	Magneto Resistive Sensor with Quick Disconnect
51	1 or 2	Magneto Resistive Sensor (90° barrel)
		with Quick Disconnect
54	1 or 2	Fitting Push-in Straight 1/8 NPT, 1/4" O.D. Tube (-131 Only)
55	1 or 2	Fitting Push-in 90° Elbow 1/8 NPT, 1/4" O.D. Tube (-131 Only)

Magneto Resistive Sensors

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Teflon[™] Based Grease

1) Insert sensors #50 or #51 from either end of the profile slots and set the sensor with the integrated slotted screw set.



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O

Lightweight Machine Oil

KRYTOX

Krytox™ Lubricant

Rotary Actuator -**DRF DIRECTCONNECT Flange Output Rotaries**



Mounting Information:

Rotaries can be mounted & operated in any orientation



Mounting thru bottom flange clearance holes into tapped holes in customer application.





Mounting thru top flange clearance holes into tapped holes in customer application.



Body mounts with screws and slip fit dowels from bottom. Payload is attached with screw and slip fit dowels.

DIRECTCONNECT Mounting: Gripper is mounted from the under side of Turntable with Button Head screws and slip fit dowels. Turntable is then mounted to rotary with one screw thru the center of the pinion and two slip fit dowel pins.



Top mounting from underside of table using tapped holes in body top flange. Application: Use in applications where precision end stop position and zero backlash are required.

Multiple Mounting Locations: Tapped and thru flange on top and bottom mounting surfaces, DIRECTCONNECT tapped pattern on bottom flange.

Turntable: Has DIRECTCONNECT mounting pattern.

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate	Imperial 40-100 psi Double Ad Internally Lubric 4-way, 2-p	Metric 3-7 bar cting ated Buna-N position

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

40 Micron or Better Not Necessary' Low Moisture Content (dry)

> -35°~80° C 0°~66° C

Temperature Operating Range

Buna-N Seals (standard) with shocks

-30°~180° F 32°~150° F

Maintenance Specifications

Expected Life	
Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycles*
Field Repairable	Yes
Seal Repair Kits Available	Yes
*Addition of lubrication will greatly increase service life	











SAMPLE ORDER: DRF-075M-180-A Ex: DRF Rotary, size 075, metric, 180° rotation with Shock Absorbers

DIRECTCONNECT


ROTARY ACTUATOR DRF-075M FLANGED SERIES

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Low profile underflush sensor version

Available with 2M or 5M Quick

Loading Capacity Static Dynamic Maximum Tensile T 10 lbs. [44 N] 2 lbs. [9 N] Maximum Compressive C 4 lbs. [18 N] 20 lbs. [89 N] Maximum Moment Mx 20 in-lbs. [2.3 Nm] 4 in-lbs. [0.5 Nm] Maximum Moment My 20 in-lbs. [2.3 Nm] 4 in-lbs. [0.5 Nm] Maximum Payload W (with shocks) 1.0 lbs. [0.45 kg] Maximum Inertia J (with shocks) 0.0016 in-lbs.-sec.2 (1.8 X 10⁻⁴ N-m-sec.²)

Note: Higher payloads and inertia possible with external shocks and stops.

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Accessory Mounting Technical Data

SURFACE

"A'

DB' DC

[5.9]

DH

* DIMENSIONS ALSO APPLY TO BLANK TURNTABLE C'BORE F OR BUTTON HEAD SCREWS

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DRF-075M

1 lbs

0.5 lbs.

8.3 lbs.-in.

180°

0.375 in.

0.72 lbs.

0.54 lbs.

40-100 psi

0.750 in.

0.31 in³.

0.38 sec.

0.29 sec.

1° to 3°

-30°~180° F

32°~150° F

23°

 $\pm 0.02^{\circ}$

0.45 kg

0.23 kg

1.8 X10⁻⁴N-m-sec.²

9.0 X10⁻⁵N-m-sec.²

0.9 N-m

180°

9.5 mm

0.34 kg

0.24 kg

3-7 bar

19.1 mm

5.1 cm³

0.38 sec.

0.29 sec.

1° to 3°

35°~82° C

0°~66° C

23°

±0.02°

4-way, 2-position

STANDARD MOUNTING PATTERN FOR ALL SIZES Imperial (inches) Metric (mm) DA .375 9.5 DB 750 19.1 DC 38.1 DD 5 mm THRU C'bore for M5 Button head screws DF DH M5 THRU DQ 3 H7 THRU C'bored for M3 Button head screws DS DU M3 THRU

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Please see back cover for DE-STA-CO Global Locations. www.destaco.com

www.comoso.com

Specifications

Bore

Repeatability ...

Over Travel (each end) ...

Maximum Payload with shocks (-A).....

Maximum Payload without shocks

Maximum Torque @ 100psi/7 bar.....

Maximum Rotation

Pitch Diameter of Pinion

Weight with shocks (-A Option)

Weight without shocks

Pressure Range

Displacement (180°).....

Actuation Time (180° @ 100psi/7 bar)

Actuation Time (90° @ 100psi/7 bar)

Temperature Range without Shocks

Temperature Range with Shocks (-A)

End Stop Adjustability (each end)

Valve required to actuate.....

Maximum Payload Inertia with shocks (-A) 0.0016 in-lbs.-sec.²

Maximum Payload Inertia without shocks 0.0008 in-lbs.-sec.²

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DRF SERIES

3.18

ROTARY ACTUATOR DRF-094M FLANGED SERIES





SAMPLE ORDER: DRF-094M-180-A Ex: DRF Rotary, size 094, metric, 180° rotation with Shock Absorbers



Specifications

Maximum Payload with shocks (-A).....

Maximum Payload without shocks

Maximum Torque @ 100psi/7 bar.....

Maximum Rotation

Pitch Diameter of Pinion

Maximum Payload Inertia with shocks (-A)...... 0.0111 in-lbs.-sec.²

Maximum Payload Inertia without shocks 0.0056 in-lbs.-sec.²

ROTARY ACTUATOR DRF-094M FLANGED SERIES

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Please see back cover for DE-STA-CO Global Locations. www.destaco.com

TURNTABLE C'BORE FOR BUTTON HEAD SCREWS

DRF-094M

1.4 kg

0.68 kg 1.3 X10⁻³ N-m-sec.²

6.3 X10⁻⁴ N-m-sec.²

1.9 N-m

180°

12.7 mm

3 lbs.

1.5 lbs.

17.3 lbs.-in.

180°

0.500 in.



DRF SERIES

3.20

ROTARY ACTUATOR DRF-106M FLANGED SERIES





Flow Control Push-in 90° Elbow M5-6mm 0.D. Tube** *Sensor and cable sold separately

Seal Repair Kit (Standard Buna-N)

Shock Seal Repair Kit

SLKT-222

SLKT-225

VLVF-008

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1 or 2

**Flow Controls recommended for most applications

SAMPLE ORDER: DRF-106M-180-A Ex: DRF Rotary, size 106, metric, 180° rotation with Shock Absorbers



ROTARY ACTUATOR DRF-106M FLANGED SERIES

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TURNTABLE C'BORE'S FOR BUTTON HEAD SCREWS

www.comoso.com

Specifications

Maximum Payload with shocks (-A)	8 lbs.	3.6 kg
Maximum Payload without shocks	4 lbs.	1.8 kg
Maximum Payload Inertia with shocks (-A)	0.0414 in-lbssec. ²	4.7 X10-3 N-m-sec.
Maximum Payload Inertia without shocks	0.0207 in-lbssec.2	2.3 X10-3 N-m-sec.
Maximum Torque @ 100psi/7 bar	33.2 lbsin.	3.8 N-m
Maximum Rotation	180°	180°
Pitch Diameter of Pinion	0.750 in.	19.1 mm
Weight with shocks (-A Option)	3.1 lbs.	1.4 kg
Weight without shocks	2.5 lbs.	1.1 kg
Pressure Range	40-100 psi	3-7 bar
Bore	1.063 in.	27.0 mm
Displacement (180°)	1.16 in ³ .	19.0 cm ³
Actuation Time (180° @ 100psi/7 bar)	0.60 sec.	0.60 sec.
Actuation Time (90° @ 100psi/7 bar)	0.45 sec.	0.45 sec.
Over Travel (each end)	1° to 3°	1° to 3°
Temperature Range without Shocks	-30°~180° F	-35°~82° C
Temperature Range with Shocks (-A)	32°~150° F	0°~66° C
and Stop Adjustability (each end)	23°	23°
	±0.02°	±0.02°

DRF-106M

Accessory Mounting Technical Data



SAMPLE ORDER: DRF-131M-180-A Ex: DRF Rotary, size 131, metric, 180° rotation with Shock Absorbers

DIRECTCONNECT

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Specifications

Bore

Repeatability ...

Over Travel (each end) ...

Maximum Payload with shocks (-A)

Maximum Payload without shocks

Maximum Torque @ 100psi/7 bar.....

Maximum Rotation

Pitch Diameter of Pinion

Weight with shocks (-A Option)

Weight without shocks

Pressure Range

Displacement (180°).....

Actuation Time (180° @ 100psi/7 bar)

Actuation Time (90° @ 100psi/7 bar)

Temperature Range without Shocks

Temperature Range with Shocks (-A)

End Stop Adjustability (each end)

Valve required to actuate.....

VLVF-005

Flow Controls

Maximum Payload Inertia with shocks (-A) 0.0970 in-lbs.-sec.²

Maximum Payload Inertia without shocks 0.0485 in-lbs.-sec.²

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Accessory Mounting Technical Data

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ROTARY ACTUATOR DRF-131M FLANGED SERIES

Static

50 lbs. [222 N]

100 lbs. [445 N]

100 in-lbs. [11.3 Nm]

100 in-lbs. [11.3 Nm]

"M", y

Dynamic

10 lbs. [44 N]

20 lbs. [89 N]

20 in-lbs. [2.3 Nm]

20 in-lbs. [2.3 Nm]

15 lbs. [6.8 kg]

0.0970 in-lbs.-sec.2

(1.1 X 10⁻² N-m-sec.²)

0







- or 90° wire exit sensor version

Sensors PNP and NPN Magneto Resistive available Sensors are slot mounted, no mounting kits required

Note: Higher payloads and inertia possible with external shocks and stops.

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Maximum Payload W (with shocks)

Maximum Inertia J (with shocks)

ODRF-022

Loading Capacity

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Tensile T

 Simple adjustment with slotted screw driver

 Built-in LED for ease of positioning and troubleshooting Low profile underflush sensor version

 Available with 2M or 5M Quick Disconnect mating cable (order separately)

Sensor Magnet standard

· Flow controls for adjusting rotational speed



DRF-131M

6.8 kg

3.4 kg

1.1 X10⁻² N-m-sec.² 5.5 X10⁻³ N-m-sec.²

7.6 N-m

180°

25.4 mm

3.1kg

2.9 kg

3-7 bar

33.4 mm

34.6 cm3

0.87 sec.

0.68 sec.

1° to 3°

35°~82° C

0°~66° C

23°

±0.02°

0.727 [18.5]

.734

[18.6]

4-way, 2-position

OHSN-011 OHSP-011

15 lbs

7.5 lbs.

67.6 lbs-in.

180°

1.000 in.

6.8 lbs.

6.3 lbs.

40-100 psi

1.313 in.

2.11 in³.

0.87 sec.

0.68 sec.

1° to 3°

-30°~180° F

32°~150° F

23°

±0.02°

Flanged Output Options

- · Easily machinable by customer
- · Blank Turntable, easily removed, pin located
- High quality aircraft aluminum, Black anodize finish
- · Mounts through pinion with one screw & two dowels

Ø5.25±.03 SURFACE "A DIRECTCONNECT Turntable

OHSP-017

Flanged Output DIRECTCONNECT Turntable

- DIRECTCONNECT Turntable, easily removed, pin located
- High quality aircraft aluminum, Black anodize finish · Mounts through pinion with one screw & two dowels
- No machining required, DIRECTCONNECT Grippers mount directly

90° orientations

DB DC DD

DF

DH D.J

DK DM

DP



DIR STAN	ECTCONNECT DARD MOUNTING PATTER	DIMENSIONS
	Imperial (inches)	Metric (mm)
)B	.750	19.1
)C	1.500	38.1
DC	.1880 THRU	5 mm THRU
)F		C'bore for M5 Button head screws
ЭН		M5 THRU
)J		76.2
)K		10mm THRU
M		C'bored for M10 Button head screws
OP		M10 THRU

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Item	Otv	Name
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01	1	Body
02	1	Pinion Shaft
03	2	End Plates
04	1	Upper Bearing
05	1	Lower Bearing
06	1	Rack
07	1	Piston
08	1	Bearing Retainer
09	1	Hub
10*	1	Stop Puck
11	2	Gaskets
12	2	Urethane Bumpers
13	2	U-cups
14	1	Magnet
15	2	Bumper Washers
16	2	Bumper Screws
17	4	Retainer Screws
18	8	End Plate Screws
19	2	Roll Pins
20*	2	Fixed Orifices
21	2	Stop Screws
22	2	Stop Screw Locking Screws
23	2	Stop Puck Screws
24	2	Shock Block
25	2	Shocks
26	8	Shock Block Mounting
		Screws

*NOTES:

- Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.
- 2) Item #10 Quantity 1 for 180° rotations, all other rotations Quantity 2
- 3) Item #20 not in size -131

Assembly Procedure

- 1) Press the Upper Bearing #4 onto the Pinion #2.
- Install the Bearing Retainer #8 onto the Pinion #2 and press the Hub #9 onto the pinion: install the Stop Puck #10 onto the Hub with the stop puck Screws #23.
- 3) Assemble the Rack #6 to the Piston #7 with Roll Pins #19.
- 4) Grease the U-Cups #13 and install them onto the Piston #7.
- 5) Press the Magnet #14 into the Piston #7.
- Assemble the Bumper #12, Washers #15 and Bumper Screw #16 onto the Piston #7.
- 7) Lubricate the Body #1 bore and install the Piston Assembly into the body.
- 8) Press the Lower Bearing #5 into the Body #1.
- 9) Locate the Piston assembly so it is aligned with an outer edge of the body.

- 10) Lubricate the Pinion assembly and align the key with the same edge of the Body as the Piston and Press the Pinion into the Body.
- Rotate the Hub Assembly through the full travels and insure that the Piston is correctly located in the Body, adjust the travel of the Piston if necessary.
- 12) Grease the Gasket #11 and install the End Plate #3 onto the Body #1.
- 13) Install the 2 Orifices #20 into the Body #1 screw them in until they bottom.
- 14) Install the Bearing Retainer Screws #17.

-A Option Assembly Procedure:

- 1) Install the Shock Absorber #25 in to the Shock Blocks #24, use
- ¹ Teflon[®] tape to seal and tighten the lock nut if shock comes with one.
- 2) Screw the Shock Block onto the Body using the



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(4) (10) 9) 8 Ð 2 7 A (21) 6 (20 (24 (25 -A Option Shown Shock Absorbers Warning: Removal of Orfices will void warranty

DRF SERIES ASSEMBLED VIEW

liem	ųly	Name
01	1	Body
02	1	Pinion Shaft
04	1	Upper Bearing
06	1	Rack
07	1	Piston
08	1	Upper Bearing Retainer
09	1	Hub
10*	2	Stop Pucks
20	2	Fixed Orifices
21	2	Stop Screws
24	2	Shock Blocks
25	2	Shocks

*NOTES:

1) Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

- 2) Item #10 Quantity 1 for 180° rotations,
- all other rotations Quantity 2.

Accessory Installation & Adjustment Instructions



lter	n Qty	Name
50	1	Soc Head Cap Screw
51	1	Blank Turntable
52	1	DIRECTCONNECT Turntable
54	2	Dowel Pins
56	1 or 2	Adjustable Flow Control
57	1 or 2	Magneto Resistive Sensor, with Quick Disconnect
58	1 or 2	Plumbing Fitting, Push-in straight
59	1 or 2	Plumbing Fitting, Push-in 90° Elbow
60	1 or 2	Magneto Resistive Sensor, 90° barrel,
		with Quick Disconnect

Magneto Resistive Sensors

1) Insert sensors #57 or #60 from either end of the profile slots and set the sensor with the integrated slotted screw set.

Plumbing Fittings

- 1) Plumbing fittings #58 & #59 can be used in any airport.
- 2) Flow controls #56 can be inserted and used in any airport.

Turntable

- 1) Insert the two Dowel Pins #54 into the hub (slip fit).
- 2) Attach the turntable #51 or #52, onto the dowel Pins.
- 3) Put thread lock on the Socket Head Screw #50, insert it through the Pinion and tighten.



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Rotary Actuators-Light Duty, Flange

• **Tight spaces:** The "ultra thin" profile and bearing supported flange provide an extremely compact package for tight space applications. Payload can be connected directly to the flange without the need for extra bearing support.

- Precision applications: Zero backlash, preloaded ball bearings, and slip fit dowel pins make this a very precise and repeatable rotary actuator.
- Rotary Air Manifold Eliminates twisted airline.

Mounting Information:

Mounts and operates in any orientation



Payload attaches to flange with screws and locates by using dowel pins



Unit can operate inverted with payload attached to the flange.



Body mounts with screws and locates with dowel pins for accuracy

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type **Dynamic Seals** Valve Required to Operate

Imperial Metric 30-100 psi 2-7 bar **Dual Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements Air Filtration Air Lubrication Air Humidity

40 Micron or Better Not Necessary* Low Moisture Content (dry)

Temperature Operating Range Buna-N Seals (standard)

-30°~180° F -35°~80° C -20°~300° F -30°~150° C

Maintenance Specifications[†]

Viton Seals (optional)

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available *Addition of lubrication will greatly increase service life [†]See Maintenance Section

5 million cycles 10+ million cycles* Yes Yes

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Air pressure supplied to both cylinders simultaneously using internal porting, drives the piston racks in opposite directions.

- The piston racks simultaneously drive the pinion gear which is attached to the flange.
- The flange is supported in the body by a preloaded ball bearing
- Hardstops, located directly on the flange, reduce wear on internal drive components.

Designed and manufactured in the USA

Style-RR Rotary Actuator				
Size -18M	Style: RF Max. Payload: 1 Torque: 6.5 Weight:* 0.44 *Base unit.	Image: https://www.image.org/action/lbs/act		

Style-RR Rotary Actuator



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ROTARY ACTUATORS RR-18M FLANGE OUTPUT SERIES





Please see back cover for DE-STA-CO Global Locations. www.destaco.com



ROTARY ACTUATORS RR-28M FLANGE OUTPUT SERIES



Please see back cover for DE-STA-CO Global Locations. www.destaco.com





Please see back cover for DE-STA-CO Global Locations. www.destaco.com





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uen	ųty	Name
02	1	Flange/Turntable
03	2	Rack, Piston
04	1	Pinion
05	1	Lock Nut
06	2	Plug, Flow Control
08	1	Clamp Plate
09	1	Bearing, Radial
10	1 or 2	Striker
11	2	Puck
15	1 or 2	Sensor
21	1 or 2	Push-in Fitting
22	1 or 2	Barb Fitting
25	1	Sensor Coupler

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

Rotary Actuators-Medium Duty, Flange Output

• Tight spaces:

The "ultra thin" profile and bearing supported flange provide an extremely compact package for tight space applications. Payload can be connected directly to the flange without the need for extra bearing support.

- Precision applications: Zero backlash, preloaded ball bearings, and slip fit dowel pins make this a very precise and repeatable rotary actuator.
- **Rotary Air Manifold** Eliminates twisting airlines.

Mounting Information:



Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate Imperial Metric 40-100 psi 3-7 bar Dual Double Acting Internally Lubricated Buna-N 4-way, 2-position

40 Micron or Better

Air Quality Requirements

Air	Filtration
Air	Lubrication
Air	Humidity

Not Necessary* Low Moisture Content (dry)

 Temperature Operating Range

 Buna-N Seals (standard)
 -30°~180° F
 -35°~80° C

 Viton Seals (optional)
 -20°~300° F
 -30°~150° C

 Temperature range is limited by internal shock absorber
 (RR-36 and RR-46 only)
 -32°~150° F
 -0°~66° C

Maintenance Specifications[†]

Expected Life	
with Shock Absorbers	1 million cycles
without Shock Absorbers	5 million cycles
w/ Preventative Maintenance	10+ million cycles*
Field Repairable	Yes
Seal Repair Kits Available	Yes
*Addition of lubrication will greatly increase service life See Maintenance Section	,





. The piston racks simultaneously drive the pinion gear which is attached to the

• The flange is supported in the body by a preloaded ball bearing

flange.

Designed and manufactured in the USA

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ROTARY ACTUATORS RR-36M FLANGE OUTPUT SERIES BASE UNIT





Specifications	RR-36	RR-36M
Maximum Payload	8.0 lbs.	3.6 Kg
Maximum Payload Inertia	.0414 inlbssec2	.00468 N-m-sec
Maximum Rotation	180°	180°
Maximum Torque Mid-Stroke @ 100 PSI	65 in-lbs.	7.4 N-m
Maximum Torque End of Stroke @ 100 PSI .	32 in-lbs.	3.7 N-m
Weight of Base Unit	2.9 lbs.	1.3 Kg
Pressure Range	40-100 psi	3-7 bar
Bore Ø (2X)	1.0 in.	25.40 mm
Displacement	2.05 in ³ .	33.6 cm ³
Temperature Range		
Standard Seals	32°~150° F	0°~66° C
Viton Seals	32°~150° F	0°~66° C
Actuation Time (180° @ 80PSI/5.5 Bar)	0.35 sec.	0.35 sec.
Actuation Time (90° @ 80PSI/5.5 Bar)	0.25 sec.	0.25 sec.
End Stop Repeatability	±0.02°	±0.02°
End Stop Adjustability	60°	60°
Over-Travel (each direction)	4°	4°
Valve required to actuate	4-way, 2-position	

2x 1/8 NPT (G 1/8) ADJUSTABLE END STOPS (STANDARD) FLOW CONTROLS (STANDARD) (COUNTER-CLOCKWISE) Ø 4.000 [Ø 101.6] А 1.06 [27] CLOCKWISE ę Ģ MAX. .500 [12.7] Ô ۲ $| \odot |$ ۲ 1.720 [43.7] .72 [18] \oplus .59 [15] 6 .47 [12] ۲ 6 .58 [15] 1.04 [26.4] 1.25 SENSOR MNTG HOLES 4X 1/4-20 X .44 DP [M6 X 11 DP] А 1.62 [41] VIEW AA ¢ Ф H-₽ 2.500 [63.5] 3.000 [76.2] -Æ 2X Ø .2500 SF X .38 DP [Ø6H7 X 9 DP] - 2.5000 [63.50]-UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW -4.624 [117.4]- \bigcirc Imperial in. Metric [mm] Ģ ₽⊕ € $\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$ Dimensions are Third Angle Projection All Dowel Holes are SF (Slip Fit). Metric Threads Course Pitch symmetrical about centerline Locational Tolerance ±.0005" or [±.013mm]

Loading Information

Maximum Moment My

Maximum Payload W

Maximum Inertia J

How to Order: (Order Accessories separately from Basic Model)

RR-36 See Next Page



34 Nm

75 in.-1bs.

8 lbs.

0.0414 in-lb-sec2 .00468 N-m-sec2

8 Nm

3.64 Kg

300 in.-1bs.

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Please see back cove	for DE-STA-CO Global I	Locations. www.des	taco.com









RR-36M ROTARY ACTUATOR OPTIONS -S, -M, OPTIONAL MID-STOP, ROTARY MANIFOLD

Specifications	RR-36	RR-36M
Weight (base unit)	2.9 lbs.	1.3 Kg
Weight Adder for Mid-Position Stop	0.4 lbs.	0.18 Kg
Weight Adder for Rotary Manifold	0.1 lbs.	0.04 Kg
Pressure Range	40-100 psi	3-7 bar
Bore Ø of Mid-Position Stop 2X	1.064 in.	27 mm
Mid-Stop Repeatability	±.5°	±.5°
Displacement of Mid-Position Stop	1.200 in ³ .	19.66 cm ³
Temperature Range		
Standard Seals	32°~150° F	0°~66° C
Viton Seals	32°~150° F	0°~66° C
Valve required to actuate Mid-Stop	3-wav. 2-	position



MID-POSITION STOP VIEW SHOWN



How to Order: (Order Accessories separately from Basic Model)

METRIC MID-STOP ROTARY MANIFOLD

BASIC MODEL ROTATION (See below)

DEGREE OF ROTATION 45°,90°, 135° or 180°

(consult factory for intermediate degrees of rotation)

SENSOR ACCESSORIES	MODEL CODE	ORDER#	QTY/UNIT
Sensor Mounting Kit (Mounts 2 Sensors)		OSMK-024	1
NPN Inductive Sensor with Quick Disconne	ct*	OISN-014	1 or 2
PNP Inductive Sensor with Quick Disconner	ct*	OISP-014	1 or 2
Quick Disconnect 2M Cable Length*		CABL-010	1 or 2
Quick Disconnect 5M Cable Length*		CABL-013	1 or 2
PNEUMATIC ACCESSORIES			
Standard Base Unit Seal Repair Kit		SLKT-016	1
Viton Base Unit Seal Repair Kit	-V	SLKT-016V	1
Standard Manifold Seal Repair Kit	-M	SLKT-061	1
Viton Manifold Seal Repair Kit	-M-V	SLKT-061V	1
Standard Mid-Stop Seal Repair Kit	-S	SLKT-062	1
Viton Mid-Stop Seal Repair Kit	-S-V	SLKT-062V	1
*Sensor and cable sold separately.			

VITON SEALS



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ROTARY ACTUATORS RR-46M FLANGE OUTPUT SERIES BASE UNIT







	Stat	ic	Dyna	amic
Loading Capacity	y [†] Imperial	Metric	Imperial	Metric
Maximum Tension T	200 lbs	890 N	40 lbs	178 N
Maximum Compression C	1000 lbs	4448 N	200 lbs	890 N
Maximum Moment $\mathbf{M}_{\mathbf{X}}$	500 in1bs.	57 Nm	100 in1bs.	11 Nm
Maximum Moment My	500 in1bs.	57 Nm	100 in1bs.	11 Nm
Maximum Payload W			15 lbs.	6.8 Kg
Maximum Inertia J			0.0970 in-lb-sec ²	.01096 N-m-sec

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RR-46M ROTARY ACTUATOR OPTIONS -S, -M, OPTIONAL MID-STOP, ROTARY MANIFOLD



MID POSITION STOP OPTION

RR-46M

2.3 Kg

0.19 Kg

0.17 Kg

3-7 bar

33.37 mm

35.95 cm³

0°~66° C

±.5°

3-way, 2-position

€ All Dowel Holes are SF (Slip Fit).

Locational Tolerance ±.0005" or [±.013mm]

Metric [mm]

VITON SEALS

OTY/UNIT

1

1 or 2

1 or 2

1 or 2

1 or 2

1

1

1

1

1

1

ORDER#

OISP-014

-f

32°~150° F

1/8 NPT

1.13 [29]

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> ROTARY MANIFOLD OPTION







17

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ltem	Qty	Name
01	1	Body, Main
02	1	Turntable
03	1	Pinion
04	2	Rack, Piston
05	1	Inner Bearing Ring
06	1	Ring, Outer Bearing
08	1	Plate, Ported End
10	2	Flow Control
11	1	Bearing
12	1	Shock Absorber
17	1	Plate, End
24	2	Stop Adjustment Screws

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



4

Accessory Installation & Adjustment Instructions



Please see back cover for DE-STA-CO Global Locations. www.destaco.com



RR-36 & 46 Options Exploded View



Item Qty Name

RR-36&46-S				
(Mid	Pos	ition Stop Option)		
13	2	Piston, Midstop		
16	1	Body, Midstop		
30	2	Mid-Ston Adjustment Scrows		

RR-36&46-M

(Kot	ary N	Aanifold Option)	
09	1	Manifold,Rotary	
15	1	Manifold	
31	2	Dowel Pin	
32	2	Dowel Pin	

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Manifold Option Assembly Procedure

- Lubricate and install 8 small o-rings.
 (4 in the pinion, 4 in the rotary manifold body).
- manifold body).2) Install 5 large 0-rings on the rotary manifold.
- 3) Press dowel pin into rotary manifold
- Install rotary manifold in manifold body.
- 5) Attach manifold assembly to rotary actuator body.

Mid-Stop Option Assembly Procedure

- 1) Lubricate and install o-rings.
- 2) Install mid-stop pistons, adjustment
- screws, seal washers, and hex nuts in rotary actuator body.
- 3) Attach mid-stop body to rotary actuator body.
- 4) Install flow controls.

Mid-Stop Adjustment Procedure

- 1) Remove mid-stop body from actuator base.
- Remove the two mid-stop pistons from the mid-stop body and insert them into their respective cylinder bores in the actuator base.
 Back off both mid-stop adjustment
- 3) Back off both mid-stop adjustment screws (#30) while pushing the midstop pistons firmly into the cylinder bores. The face of the pistons should seat against the actuator base. If not, then continue to back out the stop screws.
- Turn the turntable to the desired position and advance the mid-stop adjustment screws until both screws touch the main piston faces
- Re-attach the two mid-stop pistons to the mid-stop body and fasten midstop body back onto actuator base.

SK Seal Repair Kit Order #'s See Product Data Sheets



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Seal Kit Items Thread Locker

Item Qty Name

RR-36&46-S

(Mid Position Stop Option)			
13	2	Piston, Midstop	
16	1	Body, Midstop	
30	2	Mid-Stop Adjustment Screws	

RR-36&46-M

(Rot	(Rotary Manifold Option)				
09	1	Manifold,Rotary	_		
15	1	Manifold			
31	2	Dowel Pin			
32	2	Dowel Pin			

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Valve 1:

- Actuate Port A to Rotate CW.
- Actuate Port B to Rotate CCW.
- Neutral (Center) position when actuating Valve 2 for mid-position stop.

Valve 2:

Port A Open to Exhaust for Normal Operation.

Actuate Port A for Mid-Position Stop. Valve1 Must be in Neutral (Center) Position

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Third Angle Projection





Rotary Actuators-

• Tight spaces:

The "Ultra Thin" profile and bearing supported flange provide an extremely compact package for tight space applications. Payload can be connected directly to the flange without the need for extra bearing support.

- Large Payload, High Torque: The RR-55, RR-66, RR-76 are design for heavy-duty industrial and foundry applications
- Precision applications: Zero backlash, preloaded ball bearings, and slip fit dowel pins make this a very precise and repeatable rotary actuator.
- Rotary Air Manifold Eliminates twisting airlines.
- Pneumatic/Hydraulic Operation: The RR-76 can be used for either pneumatic or hydraulic operation.

Mounting Information:



Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type **Dynamic Seals** Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Dual Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements A

Air Filtration	40 Micron or Better
Air Lubrication	Not Necessary*
Air Humidity	Low Moisture Content (dry)
	,

Temperature Operating Range -30°~180° F Buna-N Seals (standard) -35°~80° C Viton Seals (optional) -20°~300° F -30°~150° C

Maintenance Specifications[†]

Expected Life	
with Shock Absorbers	1 million cycles
without Shock Absorbers	5 million cycles
w/ Preventative Maintenance	10+ million cycles*
Field Repairable	Yes
Seal Repair Kits Available	Yes
*Addition of lubrication will greatly increase service life *See Maintenance Section	

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• The flange is supported in the body by a preloaded ball bearing

Designed and manufactured in the USA

RR SERIES 3.43

RR-56M

13 Kg 35 N-m

5.3 Kg

RR-66M

34 Kg

82 N-m 11.8 Kg

RR-76M

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ROTARY ACTUATORS RR-56M FLANGE OUTPUT SERIES BASE UNIT





30 lbs. 13.64 Kg Maximum Inertia J (with Shock Absorbers) 0.2549 in-lb-sec2 .0288 N-m-sec2 ⁺Max. payload based on -A shock option. Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com

Metric

712 N

1779 N

23 Nm

23 Nm

۲

Imperial

160 lbs

400 lbs

200 in.-Ibs.

200 in - lbs

Dynamic

Static

1000 in.-Ibs. 113 Nm

1000 in.-Ibs. 113 Nm

800 lbs

2000 lbs

Metric

3559 N

8896 N

Loading Capacity Imperial

Maximum Tension T

Maximum Compression C

Maximum Moment Mx

Maximum Moment My

Maximum Payload Wt



RR-56M ROTARY ACTUATOR OPTIONS -S, -M, OPTIONAL MID-STOP, ROTARY MANIFOLD



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

ROTARY ACTUATORS RR-66M FLANGE OUTPUT SERIES BASE UNIT





Loading Information

How to Order: (Order Accessories separately from Basic Model)

RR-66 See Next Page



Loading Capacity	Si Imperial	t atic Metric	Dy Imperial	namic Metric
Maximum Tension T	1000 lbs	4448 N	200 lbs	890 N
Maximum Compression C	3500 lbs	15569 N	700 lbs	3114 N
Maximum Moment Mx	2000 in1bs.	226 Nm	400 in1bs.	45 Nm
Maximum Moment My	2000 in1bs.	226 Nm	400 in1bs.	45 Nm
Maximum Payload W ⁺			75 lbs.	34 Kg
Maximum Inertia J (with Sh	nock Absorber	rs)⁺ 1	.025 in-lb-sec	² .1158 N-m-sec ²
[†] May navload based on -A sh	ock ontion			

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RR-66M ROTARY ACTUATOR OPTIONS -S, -M, OPTIONAL MID-STOP, ROTARY MANIFOLD



Please see back cover for DE-STA-CO Global Locations. www.destaco.com









RR-56 & 66 Series Assembled View



ltem	Qty	Name
01	1	Body, Main
02	1	Flange
03	1	Pinion
04	2	Rack, Piston
05	1	Ring, Inner Bearing
06	1	Ring, Outer Bearing
07	1	End Plate
08	1	Ported End Plate
10	1	Washer, Thrust
11	2	Bearing, Thrust
13	1	Bearing, Needle
14	1	Bearing, Needle
16	1	Cap

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

C RR-56 & 66 **T** SERIES **G** MAINTENANCE

Accessory Installation & Adjustment Instructions

- 1) Install sensors and brackets as shown,
- Install targets so when a turntable is at each end of stroke, a target is aligned with a sensor





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Item Qty Name

RR-5	6 &	66-S ((Midstop)
12	1	Body,	Mid-Stop	

2	1	Body, Mid-Stop
7	0	Distan Mist Otan

17	2	Piston,	Mid-Stop

2 Mid-Stop Adjustment Screws 30

RR-56-M (Rotary Manifold)

09	1	Manifold, Rotary
19	1	Manifold
31	4	Dowel Pin

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Manifold Option Assembly Procedure

- 1) Lubricate and install 12 small o-rings. (6 in the pinion, 6 in the rotary manifold.
- 2) Install 7 O-rings on the rotary manifold.
- 3) Press 1/8" dia. dowel pin into manifold.
- 4) Install rotary manifold in manifold block.
- 5) Attach manifold block to rotary actuator body.

Mid-Stop Option Assembly Procedure

- 1) Lubricate and install o-rings.
- 2) Install mid-stop pistons, adjustment screws, seal washers, and hex nuts in rotary actuator body.
- 3) Attach mid-stop body to rotary actuator body.
- 4) Install flow controls.

Mid-Stop Adjustment Procedure

- 1) Remove mid-stop body from actuator base.
- 2) Remove the two mid-stop pistons from the mid-stop body and insert them into their respective cylinder bores in the actuator base.
- 3) Back off both mid-stop adjustment screws (#30) while pushing the midstop pistons firmly into the cylinder bores. the face of the pistons should seat against the actuator base. If not, then continue to back out the stop screws.
- Turn the turntable to the desired position and advance the mid-stop adjustment screws until both screws touch the main piston faces.
- 5) Re-attach the two mid-stop pistons to the mid-stop body and fasten midstop body back onto actuator base.





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RR-56 & 66 Options Assembled View



7	1	Plate, End
20	2	Shock Absorber

NOTE: Contact the Robohand Sales Department for a complete spare parts

list with order numbers and prices.





ROTARY ACTUATORS RR-76M FLANGE OUTPUT SERIES BASE UNIT



Note: Shock Absorbers "Option -A" are recommended for most applications. All specifications provided are with this option



Specifications	RR-76	RR-76M
Maximum Payload [†]	200 lbs.	91 Kg
Maximum Payload Inertia ⁺	4.95 inlbssec ²	0.5596 N-m-sec2
Maximum Rotation	180°	180°
Max. Torque Mid-Position @ 100 PSI	1900 in-lbs.	215 N-m
Max. Torque End of Stroke @ 100 PSI	950 in-lbs.	107 N-m
Weight of Base Unit	53 lbs.	24 Kg
Pressure Range	40-100 psi	3-7 bar
Bore Ø (2X)	3.250 in.	82.55 mm
Displacement	62.6 in ³ .	1026 cm ³
Temperature Range - Viton® Seals	20°~300° F	-30°~150° C
Shock Absorber Temperature Max	160° F	71° C
Actuation Time (180° @ 80PSI/5.5 Bar)	1.4 sec.	1.4 sec.
Actuation Time (90° @ 80PSI/5.5 Bar)	0.8 sec.	0.8 sec.
End Stop Repeatability	±0.02°	±0.02°
End Stop Adjustability*	20°	20°
Over-Travel (each direction)	4°	4°
Valve required to actuate	4-way, 2-posi	tion

*Any adjustment of the End Stop Adjustment Screw must be accompanied by an equal adjustment of the Shock Absorbers to prevent bottoming of the pistons against the Shock Absorbers. *Max. payload based on -A shock option.

Hydraulic Specifications	RR-76	RR-76M
Actuation Time (180° @ 80PSI/5.5 Bar)	4.8 sec.	4.8 sec.
Actuation Time (90° @ 80PSI/5.5 Bar)	2.4 sec.	2.4 sec.
Mid Stop Actuation Time (80PSI/5.5 Bar)	4.1 sec.	4.1 sec.







UNLESS OTHERWISE NOTED ALL					
TOLERAN	CES ARE AS	SHOWN BELOW			
Ģ	\Rightarrow	\bullet			
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]			
\oplus	Imperial in	Metric [mm]			
Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .000 \end{array}$				

Loading Information



	Sta	tic	Dynamic	
Loading Capacity	Imperial	Metric	Imperial	Metric
Maximum Tension T	2000 lbs	8896 N	1000 lbs	4448 N
Maximum Compression C	4500 lbs	20017 N	2000 lbs	8896 N
Maximum Moment $\mathbf{M}_{\mathbf{X}}$	4000 in1bs.	452 Nm	2000 in1bs.	226 Nm
Maximum Moment My	4000 in1bs.	452 Nm	2000 in1bs.	226 Nm
Maximum Payload W ⁺			200 lbs.	91 Kg
Maximum Inertia J ⁺			4.952 in-lb-sec ²	0.5596 N-m-sec2
⁺ Max, payload based on -A shock option.				

How to Order: (Order Accessories separately from Basic Model)

RR-76 See Next Page

SERIES

Please see back cover for DE-STA-CO Global Locations. www.destaco.com


RR-76M ROTARY ACTUATOR OPTIONS -S, -A, -M, -H OPTIONAL MID-STOP, ROTARY MANIFOLD

SERIES

3.53



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Lightweight Machine Oil G

Teflon® Based Grease

www.comoso.com



SK

Seal Kit Items Thread Locker KRYTOX

Krytox™ Lubricant





Item Qty Name

1

CLUE

Super Bonder $\Rightarrow \oplus$

Third Angle Projection

Body, Main

Flange

01

02

	Hom	Otre N	omo
	ntem	QLY N	ame
	01	1	Body, Main
	<u>02</u>	1	Flange
	03	1	Pinion
	04	2	Rack, Piston
	05	1	Ring, Inner Bearing
	06	1	Ring, Outer Bearing
	07	1	End Plate
	16	1	Plug
\sim	20	1	Bearing, Needle
	21	1	Bearing, Needle
	22	1	Washer, Thrust
	<u>23</u>	2	Bearing, Thrust
	24	1	0-Ring
	<u>31</u>	1	Ported End Plate
	NOTE Depail list w	E Conta rtment ith orde	ct the Robohand Sales for a complete spare parts er numbers and prices.
(24)/			

Accessory Installation & Adjustment Instructions

- Install sensors and brackets as shown,
 Install targets so when a turntable is at
 - each end of stroke, a target is aligned with a sensor





Please see back cover for DE-STA-CO Global Locations. www.destaco.com







Item Qty Name

RR-5	i6 &	66-S (Midstop)
12	1	Body, Mid-Stop
13	2	Piston, Mid-Stop
30	2	Mid-Stop Adjustment Screws

RR-56-M (Rotary Manifold)

09	1	Manifold, Rotary	•
11	1	Manifold	
31	4	Dowel Pin	

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Manifold Option Assembly Procedure

- 1) Lubricate and install 10 small O-rings. 2) Press 1/8" dia. dowel pin into
- manifold. 3) Install rotary manifold into pinion
- with shoulder screws. 4) Attach manifold block to rotary
- actuator body.

Mid-Stop Option

- Assembly Procedure 1) Lubricate and install o-rings.
- 2) Install mid-stop pistons, adjustment screws, seal washers, and hex nuts in rotary actuator body.
- 3) Attach mid-stop body to rotary actuator body.
- 4) Install flow controls.

Mid-Stop Adjustment Procedure

- 1) Remove mid-stop body from actuator base.
- 2) Remove the two mid-stop pistons from the mid-stop body and insert them into their respective cylinder bores in the actuator base.
- 3) Back off both mid-stop adjustment screws (#30) while pushing the mid-stop pistons firmly into the cylinder bores. the face of the pistons should seat against the actuator base. If not, then continue to back out the stop screws.
- 4) Turn the turntable to the desired position and advance the mid-stop adjustment screws until both screws touch the main piston faces.
- 5) Re-attach the two mid-stop pistons to the mid-stop body and fasten midstop body back onto actuator base.





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7	1	Plate, End
20	2	Shock Absorber

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.





			S	G						E	5							45)
			5				D			R		3							
			B			Y		Q							R			5	
									6	R									
8		C	S							R		3							-
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	A					R											B		-
			S				D			R		3							
						Y		0							P			5	
						R											B		
							D					3							
			B			Y									P				

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WWW.COMOSO.COM

Linear Motion Slides

DLB DRECKCONNECT

See **4.8**

See **4.20**

- **Internally Powered Series** DESIGN ADVANTAGES -B
- Built-in Repairable Cylinder
- Compact for Extremely Small Spaces
- Shortest Strokes
- Very Rigid

DESIGN ADVANTAGES -L

- Built-in Repairable Cylinder
- Longer Strokes in Compact Space Saving Package
- Very Rigid



Externally Powered Series

DESIGN ADVANTAGES -T

- Disposable Air Cylinder with Sensor Magnet
- Low Cost
- Long Strokes
- Carefree Maintenance
- **DESIGN ADVANTAGES -A**
- Disposable Air Cylinder with Adjustable Air Cushions
- and Sensor Magnet · Inexpensive Alternative to Shock Absorbers for Light Pavloads

DESIGN ADVANTAGES -N

- NFPA or VDMA Style Cylinders with Adjustable Air **Cushions and Sensor Magnet**
- Inexpensive Alternative to Shock Absorbers for Light Pavloads

DESIGN ADVANTAGES -R

- Position Control in Event of Loss of Air Pressure
- Safety Locking Feature
- VDMA Style Locking Cylinder with Adjustable Air Cushions and Sensor Magnet
- Exhaust Air (from Locking Mechanism) may be Plumbed Away for Contaminant Free Operation

DESIGN ADVANTAGES -U

- Customer Supplies Cylinder. NFPA or VDMA Mounting Kits Available
- Least Expensive
- Design Flexibility

Preferred Market:
 Global



Internally Powered Series

DESIGN ADVANTAGES -B, -E

- Built-in Repairable Cylinder
- Compact for Extremely Small Spaces
 Can Be Used as a Lift Table (-B)
- Greater Shaft Support (-E)
- · Shortest Strokes · Lightest Weight

DESIGN ADVANTAGES -I

• Built-in Repairable Cylinder • Longer Strokes · Compact Design for Small Spaces



See **4 32**

See 4.56

DRECTCONNECT

Externally Powered Series

- DESIGN ADVANTAGES -T
- Disposable Air Cylinder
- with Sensor Magnet
- Low Cost
- Long Strokes

Carefree Maintenance **DESIGN ADVANTAGES -A**

- Disposable Air Cylinder with Adjustable Air Cushions and Sensor Magnet
- Inexpensive Alternative to Shock Absorbers for Light Payloads

DESIGN ADVANTAGES -N

- NFPA or VDMA Style Cylinders with Adjustable Air Cushions and Sensor Magnet
- Adjustable Air Cushions Replace Shock Absorbers for Light Payloads

DESIGN ADVANTAGES -R

- · Position Control in Event of Loss of Air Pressure
- Safety Locking Feature
- VDMA Style Locking Cylinder with Adjustable Air Cushions and Sensor Magnet
- Exhaust Air (from Locking Mechanism) may be Plumbed Away for Contaminant Free Operation

DESIGN ADVANTAGES -U

- Customer Supplies Cylinder. NFPA or VDMA Mounting Kits Available
- Least Expensive
- Design Flexibility

Preferred Market:
 Globa

DLM

DIRECTCONNECT

Mini Ball Rail

- **Slide Series DESIGN ADVANTAGES**
- Multiple Air Port Positions
- Manifold Air Porting
- · Retract and extend stroke adjustments
- for precise positioning with infinite stroke adjustability • Double Bearing Option for greater load

See 4.70

- Multiple DIRECTCONNECT Mounting Locations
- . Thru Mounting on tool plate and body

Preferred Market:
Global

Destaco-Robohand Slide Product Selector

	Base Slide Thruster Slide Lift/Block Thruster	0 - 25 (lls. [0 - 1111/l] 25 - 60 (lls. [111 - 223/l] 50 - 100 (lls. [222 - 445/l] 100 - 1500 (lls. [445 - 578/l] 150 - 200 (lls. [678 - 930/l] 200 - 300 lls. [980 - 1335/l] 300+ lls. [1335+ N]	0 - 2 in. [0 - 50.8mm] 2 - 4 in. [50.8 - 10.2mm] 4 - 6 in. [102 - 15.2mm] 6 - 8 in. [152 - 203mm] 8 - 10 in. [203 - 254mm] 10 - 12 in. [254 - 356mm] 11 - 16 in. [205 - 356mm] 12 - 14 in. [305 - 406mm] 12 - 14 in. [305 - 406mm] 12 - 22 in. [304 - 457mm] 22 - 22 in. [504 - 610mm] 23 - 24 in. [558 - 610mm] 24 in. + [610+ mm]	0 - 10 (hs. [0 - 5Kg] 10 - 25 (hs. [5 - 11Kg] 2 - 25 - 50 (hs. [11 - 23Kg] 50 - 100 (hs. [23 - 45Kg] 100 - 150 (hs. [45 - 68Kg] 150 (hs. + [88 + Kg]	 20 - 100 psi [1.5 - 7 bar] 40 - 100 psi [3 - 7 bar] Internal (Repairable) External (Replaceable) External (ISO) 	External (NFPA) External (VDMA) External (VDMA) Locking Customer Supplied	Preloaded Ball Bushing Composite Bushings Roller Bearings Bronze Bushings	Inductive Sensors Magneto Resistive Sensors	Shock Absorbers w/Stops Bumpers and Collars Independent End Stops	Air Cushioned Cylinder	Telescopic Airlines
Model #	Slide	Force Range	Maximum Stroke	Payload	Pressure	Type	Bearings				
RASE SLIDE	- INTE	RNALLY POWERED -	SHORT RODY								
DLB-10-B	•				• •		• •	•			•
DLB-12-B	•				• •		• •	•	• •		•
DLB-16-B	•				• •		• •	•	• •		•
DLB-20-B	•				• •		• •	•	• •		٠
DLB-25-B	•				• •		• •	•	• •		•
BASE SLIDE	E - INTEI	RNALLY POWERED -	LONG BODY								
DLB-10-L	•			_	• •		• •	•	• •		٠
DLB-12-L	•				• •		• •	•	• •		٠
DLB-16-L	•				• •		• •	•	• •		•
DLB-20-L	•				• •		••	•	• •		•
DLD-2J-L						_		-		_	_
BASE SLIDE	E-EXTER	NALLY POWERED									
DLB-10-T, A, N, U	•				• • •	• •	• •	• •	• •	•	٠
DLB-12-T, A, N, U	•				• • •	• •	• •	• •	• •	•	٠
DLB-16-T, A, N, U	•				• • •	• •	••	••	• •	•	•
DLB-20-1, A, N, N, N, U			21	6			•••		••••		•
								-		-	_
THRUSTER	SLIDE -	INTERNALLY POWE	RED - SHORT BODY								
DLT-06-B, E	• •				• •		•	• •	• • •		
DLT-08-B, E	••				• •		•	••	•••		•
DLI-10-B, E DIT-12-B, F											
DLT-16-B. E					• •		• •	••	• • •		•
DLT-20-B, E	• •				• •		• •	• •	• • •		•
DLT-25-B, E	• •				• •		• •	• •	• • •		٠
THRUSTER	SLIDE -	INTERNALLY POWF	RED -LONG BODY								
DLT-06-L	•				• •		•	• •			
DLT-08-L	•				• •		•	• •	• • •		
DLT-10-L	•				• •		• •	• •	• • •		٠
DLT-12-L	•				• •		• •	• •	• • •		٠
DLT-16-L	•				• •		• •	• •	• • •		٠
DLT-20-L DI T-25-I					•••		••	••	•••		•
51. 10 1											_
THRUSTER	SLIDE -	EXTERNALLY POWE	RED								
DLT-06-T, U	•				• • •	•	•	• •	• • •		
DLI-08-1, U					• • •	•	•	•••	•••		
DLT-12-T. A. N. II	•					• •	••	•••		•	•
DLT-16-T, A, N, U	•				• • •	• •	• •	• •		•	•
DLT-20-T, A, N, R, U	•				•		• •	• •	• • •	•	•
DLT-25-T, A, N, R, U	•		▶ 2	6	• •	• • • •	• •	• •	• • •	•	•

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www.comoso.com	

Destaco-Robohand Parallel Gripper Product Selector

	Base Slide Thruster Slide Lift/Block Thruster	0 - 25 lbs. [0 - 111N] 25 - 50 lbs. [111 - 223N] 50 - 100 lbs. [223 - 445N] 100 - 150 ls. [445 - 673N] 150 - 200 lbs. [678 - 880N] 200 - 300 lbs. [890 - 1335N] 300+ lbs. [1335+ N]	0 - 2 in. [0 - 50.8mm] 2 - 4 in. [50.8 - 102mm] 4 - 6 in. [102 - 152mm] 4 - 6 in. [102 - 152mm] 6 - 8 in. [152 - 203mm] 8 - 10 in. [203 - 254mm] 10 - 12 in. [254 - 356mm] 110 - 12 in. [356 - 406mm] 12 - 14 in. [305 - 356mm] 22 - 24 in. [568 - 558mm] 22 - 24 in. [558 - 610mm] 24 in. + [610 + mm]	0 - 10 lbs. [0 - 5kg] 10 - 25 lbs. [5 - 11kg] 25 - 50 lbs. [11 - 23kg] 50 - 100 lbs. [23 - 45kg] 100 - 150 lbs. [45 - 68kg] 150 lbs. + [68 + Kg]	20 - 100 psi [1.5 - 7 bar] 40 - 100 psi [3 - 7 bar]	Internal (Repairable) External (Replaceable) External (ALC) External (NFPA) External (VDMA) External (VDMA) Customer Supplied	Preloaded Ball Bushing Composite Bushings Roller Bearings Bronze Bushings	Inductive Sensors Magneto Resistive Sensors	Shock Absorbers w/Stops Bumpers and Collars Independent End Stops Air Cushioned Cylinder Telescopic Airlines
Model #	Type of Slide	Maximum Thrust Force Range	Maximum Stroke	Maximum Payload	Operating Pressure	Cylinder Type	Bearings		
MINI BALL	RAIL SLII	DE						_	
DLM-07M-12	• • •				•	•	•	•	•
DLM-07M-25					•	•	•	•	•
DLM-07M-38	• • •				•	•	•	•	•
DLM-07M-50					•	•	•	•	•
DLM-09M-25	• • •				•	•	•	•	•
DLM-09M-50					•	•	•	•	•
DLM-09M-75	• • •				•	•	•	•	•
DLM-09M-100	• • •				•	•	•	•	•
DLM-12M-25	• • •				•	•	•	•	•
DLM-12M-50	• • •				•	•	•	•	•
DLM-12M-75	• • •				•	•	•	•	•
DLM-12M-100					•	•	•	•	•



A full line of individual Base Slides,



7 sizes; both

quickly & easily mount together

Single icons represent various 4 screw, 2 dowel mounting patterns. Mated icons represent a DIRECTCONNECT



DIRECTCONNECT mounting selection is achieved by matching mating icons



Simply match any **CONNECT**

appropriate mate to identify a

icon to its

Combine 2, 3, or more units together to create an unlimited variety of Pick and Place units to suit your application needs!

create an almost unlimited array









Block Thrusters, and Thruster Slides that...



WITHOUT ADAPTER PLATES to...



DIRECTCONNECT. mounting patterns are common and standard on all styles and sizes

of multi-axis Pick and Place devices!



between different sizes

in multiple orientations

DIRECTCONNECT

DIRECTCONNECT

Modular Automation Applications

The following applications represent only some of the unlimited variety of automation solutions made possible with DIRECTCONNECT. Configurations shown include individual components used in single axis applications as well as combinations of units connected *WITHOUT ADAPTER PLATES* to create multi-axis modular automation devices.



Individual Block Thrusters used independently to perform press and eject operations.

The Block Thruster's compact design is ideal in applications where space is limited.



An overhead gantry created using an inverted Base Slide and Block Thruster with the Base Flange option. The externally powered Base Slide can provide long strokes while the Block Thruster offers a low profile package.



A three axis pick and place created using a Base Slide and two Thrusters. The system allows a single escapement station to feed two conveyor lines. All positions are precisely located with Hard Stops or Shocks. This set-up also allows for a "reject" position.



Mounting a Thruster to a Base Slide on the same axis is used to achieve a three or four position box motion pick and place. Retracting both Thruster and Base Slide puts the system at a home "pick" position (1). Extending both the horizontal Base Slide and Thruster allows the part to be placed in the inner turntable nest (2). The Slide returns to the "pick" position and the horizontal Thruster is extended allowing the part to be placed in the outer turntable nest. All three positions are precisely located with hard stops or shocks. A fourth "reject" position could be simply added by extending the Base Slide while the Thruster is retracted.



vertical Block Thruster upward. A part picked from here could be placed in one of the three remaining positions. Position (2) is achieved by keeping the Base Slide in the raised position while retracting the vertical Thruster. Position (3) is attained by lowering the Base Slide while extending

the vertical Thruster.

Position (4) is obtained by retracting the vertical Thruster. All positions can be precisely located by using Hard Stops for accurate location of picking and placing.



A more elaborate box motion pick and place using Block Thrusters to achieve part transfer between multi-level conveyors. Due to space limitations the application of Block Thrusters is a good choice.



A combination of Thrusters used independently and together for various functions.

A simple box motion pick and place utilizing a larger horizontal Thruster (1) for increased rigidity and smaller vertical Thruster (2) where deflection is not as much of a concern.

An individual Block Thruster (3) used to eject defective (hole missing) parts and another Block Thruster (4) used as a conveyor stop. All units are compact and mount easily into a small area.



Machine load/unload application utilizes 3 or 4 positions in the horizontal axis for picking the billet (1), inserting/removing the finished part from the lathe (2) and placing the finished part on the conveyor (3). A fourth position could be utilized for a "reject" position. This pick and place device uses a Base Slide and a Thruster mounted in the same axis. The Thruster is a longer stroke version with its actual usable stroke reduced using adjustable collars (4). Vertical motion for the pick and place is accomplished using a Block Thruster.

A right angle rotary is used to make the axis change between the billet and the machine axis. All components are standard, off-the-shelf, and quickly & easily designed and assembled.

Internally Powered **Base Slides**





Compact design: This design is used for short strokes in limited space applications. Internal piston design reduces the mounting foot print over externally powered slides by up to 50%

DIRECTCONNECT mounting patterns: These slides have DIRECTCONNECT mounting patterns that connect to other slides without the need for adapter plates.

Payload attaches with screws

through clearance and

counterbored holes in body and

locates using slip fit dowel pin

holes

Mounting Information:

Mounts and operates in any orientation



Payload attaches to tapped holes in body with screws and locates using slip fit dowel pin holes



End blocks mount with screws and locate with slip fit dowel pin holes



Technical Specifications:

Pneumatic Specifications Pressure Operating Range* Cylinder Type Dynamic Seals Valve Required to Operate

Metric Imperial 40-100 psi 3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements Air Filtration

Air Lubrication

40 Micron or Better Not Necessary** Low Moisture Content (dry)

Air Humidity **Temperature Operating Range**

Buna-N Seals (standard) -30°~180° F Viton[®] Seals (optional) -20°~300° F

-35°~80° C -30°~150° C

million cycles⁺ No No

Maintenance Specifications[†]

Expected Life	
Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycl
Field Repairable	No
Seal Repair Kits Available	No

Application Restrictions

Flow controls, shock absorbers and urethane bumpers recommended for nearly all applications. Use composite bushing in dirty or gritty environments. Never use silicone based lubricants with composite bushings.

*Higher pressure possible. Consult factory with application details. **Addition of lubrication will greatly increase service life

⁺See Maintenance Section

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Designed and manufactured in the USA







	BU					SHOCK ADSOLDEI
	DL	B-LIM-F	<u>s</u>		5	Adjustable Hard Stop
		SIZE	ARING	VITON® S	EALS	INDUCTIVE SENSOR ACCESSORIES
	SIZE	10, 12, 16				Inductive Sensor PNP Qk. Disconnect
	METRIC	M				Inductive Sensor NPN Qk. Disconnect
	STYLE	B Short body slide with b	ouilt-in repairable	e cylinder		Quick Disconnect 2M Cable Length
	BEARING	B Linear ball bearings C Composite bushings		y oy in a co		Quick Disconnect 5M Cable Length
	STROKE	(inches)				PNEUMATIC ACCESSORIES
	DLB-10	1-2 @ 1" increments				1/8 NPT Telescopic Airlines (up to 2")
	DLB-12	1-2 @ 1" increments	Custom stro	kes available.		1/8 NPT Telescopic Airlines (up to 3")
	DLB-16	1-3 @ 1" increments	Please con	suit factory.		#10-32 Adjustable Flow Control
	DI B-10M	(mm) 25 50				G1/8 Telescopic Airlines (up to 50mm)
	DLB-10M	25.50				G1/8 Telescopic Airlines (up to 80mm)
	DLB-16M	25, 50, 80				M5 Adjustable Flow Control
\leq	VITON [®]	Viton [®] Seals				Cylinder Seal Repair Kit
	SHAFTING	S Corrosion resistant sha	afting			Viton® Cylinder Seal Repair Kit
		SAMPLE ORDER:	DLB-12M-	B-C-25		*Sensor and cable sold separately

Ex: Base Slide, Size 12 Metric, Short Body Style w/Built-in Cylinder, Composite Bushings, 25mm Stroke

OTAL-037

OTAL-038

VLVF-007

OTAL-043

OTAL-044

VLVF-008

SLKT-101

SLKT-101V

OTAL-037

OTAL-038

VLVF-007

OTAL-043

OTAL-044

VLVF-008

SLKT-103

SLKT-103V

OTAL-037 1, 2, 3 or 4

OTAL-038 1, 2, 3 or 4

OTAL-043 1, 2, 3 or 4

OTAL-044 1, 2, 3 or 4

1 or 2

1 or 2

1

1

VLVF-007

VLVF-008

SLKT-103

SLKT-103V



SHORT BODY SLIDE DLB -10 M, 12 M, 16 M -B **BUILT-IN REPAIRABLE CYLINDER**

Loading Specifications Table - Style DLB-10M, 12M,16M -B

	10	10M	12	12M	16	16M
Maximum Payload (W) horizontal motion w/Shock Absorbers	15 lbs.	6.8 kg	30 lbs.	13.6 kg	45 lbs.	20.4 kg
Maximum Payload (W) vertical motion w/Shock Absorbers	7 lbs.	3.1 kg	15 lbs.	6.8 kg	22 lbs.	9.9 kg
Maximum Payload (W) horizontal motion w/Urethane Bumpers	5 lbs.	2.2 kg	10 lbs.	4.5 kg	15 lbs.	6.8 kg
Maximum Total Applied Load + Payload (F+W)	25 lbs.	111 N	40 lbs.	178 N	70 lbs.	311N
Total Maximum Moment about any Axis (M)	75 inlbs.	8.4 N-m	150 inlbs.	16.9 N-m	300 inlbs.	33.9 N-m
F=Externally applied force W=Weight of payload	F H M	(L	F T M	Sho Fi	ock Absorbers a low Controls ar	and 'e

000

W=Weight of payload F+W=Total force

M=Maximum moment

Specifications	DLB-10	DLB-10M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar.	29 lbs.	129 N
Weight (Basic Unit)	2.08 lbs.	0.93 kg
Additional Weight per Stroke ().08 lbs./in.	1.4g/mm
Cylinder Bore Diameter	3/4"	19mm
Shaft Diameter	0.375"	9.5mm

Specifications	DLB-12	DLB-12M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar.	57 lbs.	254 N
Weight (Basic Unit)	3.83 lbs.	1.7 kg
Additional Weight per Stroke	0.12 lbs./in.	2.1g/mm
Cylinder Bore Diameter	1.0"	25mm
Shaft Diameter	0.472"	12mm

Specifications DLB-16 DLB-16M Maximum Air Pressure 100 psi 6.9 bar Thrust Force @ 80psi/5.5bar. 57 lbs. 254 N Weight (Basic Unit) 5.19 lbs. 2.4 kg Additional Weight per Stroke .. 0.19 lbs./in. 3.3g/mm Cylinder Bore Diameter 1.0" 25mm Shaft Diameter630" 16mm

recommended for

nearly all applications

Accessory

ry Mounting Technical Data	
Shock Absorbers • Full stroking piston rod • Built-in hard stop • Allen wrench adjustable • Order	Adjustable Hard Stops • For precision (+/- 001") hard stop end point positioning • Allows for stop adjustment independent of shock absorber hard stop • Allen wrench adjustable • Or of the store of
 Inductive Proximity Sensors 8mm diameter Threaded quick disconnect with built-in LED output PNP and NPN available Quick Disconnect Cable Threaded coupling with knurled head for secure electrical connections 2 meter cable length 5 meter cable length 	 Telescoping Airlines Eliminate flexing air lines Self aligning air tube design extends useful seal life Modular stackable design. Up to (4) modules can be stacked Modular stackable design up to (4) modules can be stacked Modular stackable design. Up to (4) modules can be stacked Modular stackable design. Up to (4) modules can be stacked Modular stackable design. Up to (4) modules can be stacked Modular stackable design. Up to (4) modules can be stacked Modular stackable design. Up to (4) modules can be stacked Modular stackable design. Up to (4) modules can be stacked Modular stackable design. Up to (4) modules can be stacked User air ports per module DLB-10 7.0" 4.7 2.5 5.77 3.60 DLB-10 7.0" 4.7 2.5 5.77 3.60 DLB-16 .95" 4.7 2.5 5.77 3.60 DLB-10 17.8mm 11.9 63.5 14.7 91.4 DLB-12M 24.1mm 11.9 63.5 14.7 91.4 DLB-12M 24.1mm 11.9 63.5 14.7 91.4 DLB-16M 24.1mm 11.9 63.5 14.7 91.4

DLB SERIES

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SHORT BODY SLIDE DLB -20M, 25M -B **BUILT-IN REPAIRABLE CYLINDER**



QTY/SLIDE

1 or 2

1, 2, 3 or 4

1, 2, 3 or 4

1 or 2

1, 2, 3 or 4

1, 2, 3 or 4

1 or 2

1

1



DM

DK

DJ

Ex: Base Slide, Size 20, Short Body Style w/Built-in Cylinder, Composite Bushings, 3 Inch Stroke, Viton® Seals

4.12



SHORT BODY SLIDE DLB -20M, 25M -B **BUILT-IN REPAIRABLE CYLINDER**

Loading Specifications Table - Style DLB-20M, 25M -B

	20	20M	25	25M
Maximum Payload (W) horizontal motion using Shock Absorbers	60 lbs.	27.2 kg	100 lbs.	45.3 kg
Maximum Payload (W) vertical motion using Shock Absorbers	30 lbs.	13.6 kg	50 lbs.	22.0 kg
Maximum Payload (W) horizontal motion using Urethane Bumpers	20 lbs.	9.1 kg	25 lbs.	11.3 kg
Maximum Total Applied Load + Payload (F+W)	100 lbs.	444 N	150 lbs.	667 N
Total Maximum Moment about any Axis (M)	600 inIbs.	67.7 N-m	1200 inlbs.	135.5 N-m

F=Externally applied force W=Weight of payload **F**+**W**=Total force M=Maximum moment



Specifications	DLB-20	DLB-20M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	126 lbs.	560 N
Weight (Basic Unit)	13.0 lbs.	5.9 kg
Additional Weight per Stroke	0.32 lbs./in.	5.54g/mm
Cylinder Bore Diameter	1-1/2"	38mm
Shaft Diameter	0.787"	20mm

Accessory Mounting Technical Data



Shock Absorbers and **Flow Controls are** recommended for nearly all applications

Specifications	DLB-25	DLB-25M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	126 lbs.	560 N
Weight (Basic Unit)	18.2 lbs.	8.2 kg
Additional Weight per Stroke	0.47 lbs./in.	8.4g/mm
Cylinder Bore Diameter	1-1/2"	38mm
Shaft Diameter	0.984"	25mm

DIRECTCONNEC



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LONG BODY SLIDE DLB -10M, 12M, 16M -L BUILT-IN REPAIRABLE CYLINDER

DLB SERIES

DIRECTCONNEC





	P	ORE DIA.	JDY SIZE	HAFT DIA		BAS	SIC U	NIT D	ובוווו	ISIO	NS					STAN	IDARD MOUNTING PATTL	ERN FOR ALL SIZES
MODEL #	A	B	C	D	E	F	G	н	J	K	L	М	N	R	S		Imperial (inches)	Metric (mm)
DLB-10	3/4	3.50	.375	5.50	7.63	6.3975	7.228	3.485	3.0600	1.178	1.245	.813	N/A	.594	2.375	DB	.750	19.1
DLB-12	1	4.00	.472	6.50	8.63	7.3975	8.228	3.985	3.5000	1.615	1.657	.813	.375	.813	2.750	DC	1.500	38.1
DLB-16	1	4.75	.630	7.50	9.63	8.3975	9.228	4.735	4.2500	1.615	1.657	.813	.375	.813	3.250	DD	.1880 X .25 DP	5mm H7 X 6 DP
DLB-10M DLB-12M	19 25	88.9 101.6	9.5 12	139.7 165.1	193.8 219.2	162.50 187.90	183.6 209.0	88.5 101.2	77.72 88.90	29.9 41.0	31.6 42.1	20.7 20.7	N/A 9.5	15.09 20.65	60.33 69.85	DF DH	Clearance for #10 #10-32 X .34DP	Clearance for M5 M5 X 8.5DP 3H7 X 2 DP
DLB-16M	25	120.7	16	190.5	244.6	213.30	234.4	120.3	107.95	41.0	42.1	20.7	9.5	20.65	82.55	DU	#4-40 X .25 DP	M3 X 6 DP

How to Order: Basic Unit	Accessories: (Order Separately)	DLB-10M	DLB-12M	DLB-16M	QTY/SLIDE
BASIC MODEL METRIC STYLE STROKE SHAFTING DLB- M- DLB M- SIZE BEARING VITON* SEALS SIZE BEARING VITON* SEALS SIZE BEARING VITON* SEALS SIZE Dubber SIZE BEARING VITON* SEALS SIZE Composite busines Composite busines Composite busines Composite busines Custom strokes available. DB-10 1-4 @ 1" increments DB-12 1-5 @ 1" increments DLB-16 1-6 @ 1" increments DLB-16 25, 50, 80, 100 DLB-12 25, 50, 80, 100, 125 DLB-10 25, 50, 80, 100, 125, 150 VITON* Viton* seals STROKE (mm) Viton* seals SHAFTING S Corrosion resistant shafting	SHOCK/STOP ACCESSORIES Shock Absorber Adjustable Hard Stop INDUCTVE SENSOR ACCESSORIES* Inductive Sensor NPN Qk. Disconnect Inductive Sensor NPN Qk. Disconnect Quick. Disconnect 2M Cable Length Quick. Disconnect 2M Cable Length PNEUMATIC ACCESSORIES 1/8 NPT Telescopic Airlines (up to 4") 1/8 NPT Telescopic Airlines (up to 5") 1/8 NPT Telescopic Airlines (up to 6") #10-32 Adjustable Flow Control G1/8 Telescopic Airlines (up to 100mm) G1/8 Telescopic Airlines (up to 100mm) G1/8 Telescopic Airlines (up to 125mm) G1/8 Telescopic Airlines (up to 160mm) M5 Adjustable Flow Control Cylinder Seal Repair Kit Viton® Cylinder Seal Repair Kit Viton® cylinder Seal Repair Kit	SHOK-028 DLT-1023 OISP-011 OISN-011 CABL-010 CABL-010 CABL-013 OTAL-049 OTAL-050 OTAL-050 OTAL-050 OTAL-051 OTAL-052 OTAL-045 VLVF-008 SLKT-101 SLKT-101V	SHOK-010 DLT-1023 OISP-011 OISN-011 CABL-010 CABL-013 OTAL-049 OTAL-050 OTAL-050 OTAL-050 OTAL-051 OTAL-051 OTAL-052 OTAL-045 VLVF-008 SLKT-103 SLKT-103V	SHOK-010 DLT-1023 OISP-011 OISN-011 CABL-010 CABL-013 OTAL-049 OTAL-050 OTAL-050 OTAL-050 OTAL-051 OTAL-051 OTAL-052 OTAL-045 VLVF-008 SLKT-103 SLKT-103V	1 or 2 1 or 2 1 or 2 1 or 2 1 or 2 1 or 2 1 or 2 1, 2, 3 or 4 1, 3 or 5 1, 5
SAMPLE ORDER: DLB-12M-L-C-25-V					

Ex: Base Slide, Size 12 Metric, Long Body Style w/Built-in Cylinder, Composite Bushings, 25mm Stroke, Viton® Seals



LONG BODY SLIDE DLB -10M, 12M, 16M -L **BUILT-IN REPAIRABLE CYLINDER**

Loading Specifications Table - Style DLB -010M, 12M, 16M -L

	10	10M	12	12M	16	16M
Maximum Payload (W) horizontal motion w/Shock Absorbers	15 lbs.	6.8 kg	30 lbs.	13.6 kg	45 lbs.	20.4 kg
Maximum Payload (W) vertical motion w/Shock Absorbers	7 lbs.	3.1 kg	15 lbs.	6.8 kg	22 lbs.	9.9 kg
Maximum Payload (W) horizontal motion w/Urethane Bumpers	5 lbs.	2.2 kg	10 lbs.	4.5 kg	15 lbs.	6.8 kg
Maximum Total Applied Load + Payload (F+W)	25 lbs.	111 N	40 lbs.	178 N	70 lbs.	311 N
Total Maximum Moment about any Axis (M)	75 inlbs.	8.4 N-m	150 inlbs.	16.9 N-m	300 inIbs.	33.9 N-m

F=Externally applied force W=Weight of payload **F**+**W**=Total force M=Maximum moment





Shock Absorbers and Flow Controls are recommended for nearly all applications

Specifications	DLB-10	DLB-10M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar.	29 lbs.	129 N
Weight (Basic Unit)	3.34 lbs.	1.5 kg
Additional Weight per Stroke	0.08 lbs./in.	1.4g/mm
Cylinder Bore Diameter	3/4"	19mm
Shaft Diameter	0.375"	9.5mm

Specifications	DLB-12	DLB-12M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar.	57 lbs.	254 N
Weight (Basic Unit)	5.13 lbs.	2.3 kg
Additional Weight per Stroke	0.12 lbs./in.	2.1g/mm
Cylinder Bore Diameter	1.0"	25mm
Shaft Diameter	0.472"	12mm

Specifications	DLB-16	DLB-16M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar.	57 lbs.	254 N
Weight (Basic Unit)	7.30 lbs.	3.3 kg
Additional Weight per Stroke	0.19 lbs./in.	3.3g/mm
Cylinder Bore Diameter	1.0"	25mm
Shaft Diameter	0.630"	16mm

Accessory Mounting Technical Data

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Please see back cover for DE-STA-CO Global Locations. www.destaco.com

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/						INDUCTIVE SENSOR ACCESSORIES [†]
	CITE	DEADU				Inductive Sensor PNP Qk. Disconnect
	312E	BEAKI	NG	VIIUN° SEA	ILƏ	Inductive Sensor NPN Qk. Disconnect
						Quick. Disconnect 2M Cable Length
SIZE	20, 25					Quick. Disconnect 5M Cable Length
TRIC	м					PNEUMATIC ACCESSORIES
YLE	L Long body slide with	th built-in		1/8 NPT Telescopic Airlines (up to 6")		
RING	B Linear ball bearing	S				1/8 NPT Telescopic Airlines (up to 12")
	C Composite bushing	js				1/8 NPT Adjustable Flow Control
OKE	(inches)		Custom str	rokes available		G1/8 Telescopic Airlines (up to 160mm
B-20	1-6 @ 1" increments	5	Please co	onsult factory.		G1/8 Telescopic Airlines (up to 300mm
B-25	1-1 @ 1" increments	5		should laber ji		G1/8 Adjustable Flow Control
OKE	(mm)	- 400				Cylinder Seal Repair Kit
201VI	25, 50, 80, 100, 12	5,100 5,160 1	75			Viton [®] Cylinder Seal Repair Kit
	V Viton [®] coolo	J, 100, 1	/5			*Sensor and cable sold separately
UN						
TING	S Corrosion resistant	t shafting				
	SAMPLE ORDE	R. DI B	-20M-I	-C-80-V		

UKVEK: DI -2UIVI-L-6-8U-V Ex: Base Slide, Size 20 Metric, Long Body Style w/Built-in Cylinder, Composite Bushings, 80mm Stroke, Viton® Seals **OTAL-039**

OTAL-040

VLVF-004

OTAL-045

OTAL-046

VLVF-005

SLKT-105

SLKT-105V

(up to 160mm)

(up to 300mm)

OTAL-039

OTAL-040

VLVF-004

OTAL-045

OTAL-046

VLVF-005

SLKT-105

SLKT-105V

1, 2, 3 or 4

1, 2, 3 or 4

1 or 2

1, 2, 3 or 4

1, 2, 3 or 4

1 or 2

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LONG BODY SLIDE DLB -20M, 25M -L **BUILT-IN REPAIRABLE CYLINDER**

Loading Specifications Table - Style DLB -20M, 25M -L

	20	20M	25	25M
Maximum Payload (W) horizontal motion using Shock Absorbers	60 lbs.	27.2 kg	100 lbs.	45.3 kg
Maximum Payload (W) vertical motion using Shock Absorbers	30 lbs.	13.6 kg	50 lbs.	22.0 kg
Maximum Payload (W) horizontal motion using Urethane Bumpers	20 lbs.	9.1 kg	25 lbs.	11.3 kg
Maximum Total Applied Load + Payload (F+W)	100 lbs.	444 N	150 lbs.	667 N
Total Maximum Moment about any Axis (M)	600 inlbs.	67.7 N-m	1200 inlbs.	135.5 N-m

F

w

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F=Externally applied force W=Weight of payload **F**+**W**=Total force M=Maximum moment



Specifications	DLB-20	DLB-20M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	126 lbs.	560 N
Weight (Basic Unit)	15.6 lbs.	7.1 kg
Additional Weight per Stroke	0.32 lbs./in.	5.6g/mm
Cylinder Bore Diameter	1-1/2"	38mm
Shaft Diameter	0.787"	20mm

Accessory Mounting Technical Data

Shock Absorbers and **Flow Controls are** recommended for nearly all applications

Specifications	DLB-25	DLB-25M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	126 lbs.	560 N
Weight (Basic Unit)	21.4 lbs.	9.7 kg
Additional Weight per Stroke).47 lbs./in.	8.4g/mm
Cylinder Bore Diameter	1-1/2"	38mm
Shaft Diameter	0.984"	25mm

DIRECTCONNEC

°°°° 0 **Inductive Proximity Sensors** • For precision (+/-.001") hard stop end point positioning 8mm diameter · Allows for stop adjustment independent of shock Threaded quick disconnect with built-in LED output PNP and NPN available **Quick Disconnect Cable** Threaded coupling with knurled head for secure electrical connections • 2 meter cable length 5 meter cable length

Telescoping Airlines

Shock Absorbers

· Full stroking piston rod

Adjustable dampening

Built-in hard stop

Position adjustable

- · Eliminate flexing air lines
- · Self aligning air tube design extends useful seal life • Modular stackable design. Up to (4) modules can be

E + MAX AIRLINE STROKE

- stacked
- · Modules can be mounted on either side of slide
- 1/8 NPT or G1/8 pipe threads
- (2) user air ports per module

	A	В	C	D	E	F	
DLB-20	2.03"	.10	2.1	.577	3.60	1.25	
DLB-25	1.82"	.10	1.9	.577	3.60	1.25	
DLB-20M	51.6mm	2.5	53.8	14.7	91.4	31.8	
DLB-25M	46.2mm	2.5	48.3	14.7	91.4	31.8	

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

F MAX

Flow Controls for Cylinders

• 1/8 NPT or G1/8 pipe threads

cylinder speed

• Thumb screw adjust with locking nut for adjusting

www.comoso.com

Adjustable Hard Stops

absorber hard stop

· Allen wrench adjustable







DLB-B & L Series Assembled View

Item Qty Name

01	1	Body
02	2	Guide Shaft
03	2	Air Tube
04	2	End Block
05	2	Adapter, Internally Powered
06	1	Piston
07	2	Cap, Rod End
08	6	Stop Button
09	8	Shock Pad, Urethane
10	4	Bushing

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

NOTE: For accessory mounting information see Product Data Sheets.





DLB SERIES

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Externally Powered Base Slides

Cylinder options:

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Externally powered base slides are available in a wide range of cylinder options. Choose from replaceable/disposable, replaceable with adjustable cushions, NFPA with adjustable cushions, ISO/Metric, VDMA, locking VDMA, or non-powered for use with customer supplied cylinders.

DIRECTCONNECT mounting patterns:

These slides have DIRECTCONNECT mounting patterns that connect to other slides without the need for adapter plates.

Mounting Information:

Payload attaches to tapped holes in body with screws Payload attaches and locates with screws through using slip clearance and fit dowel counterbored holes in pin holes body and locates using slip fit dowel pin holes

Mounts and operates in any orientation

End blocks mount with screws and locate with slip fit dowel pin holes

Technical Specifications:

Pneumatic Specifications Pressure Operating Range* Cylinder Type Dynamic Seals Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements Α

Air Filtration Air Lubrication Air Humidity	40 Micron or Better Not Necessary** Low Moisture Content (dry)

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F -35°~80° C -20°~300° F -30°~150° C Viton Seals (optional)

Maintenance Specifications

Expected Life	
Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycles [†]
Field Repairable	No
Seal Repair Kits Available	No
•	

Application Restrictions

Flow controls, shock absorbers and urethane bumpers recommended for nearly all applications. Use composite bushing in dirty or gritty environments. Never use silicone based lubricants with composite bushings.

*Higher pressure possible. Consult factory with application details. **Addition of lubrication will greatly increase service life [†]See Maintenance Section



• When air pressure is applied to the cylinder the slide body moves.

Designed and manufactured in the USA

BASE SLIDE DLB -10M, 12M, 16M -T, A **REPLACEABLE CYLINDER WITH OR W/O ADJUST. AIR CUSHIONS**



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DLB SERIES 4.22

UNLESS OTHERWISE NOTED) ALL TOLERANCES ARE AS SHOWN BELOW $$	_

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Ģ	$\Rightarrow \oplus$	•	\oplus	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	$\begin{matrix} [0.] = [\pm .25] \\ [0.0] = [\pm .13] \\ [0.00] = [\pm .013] \end{matrix}$

																	el runneu	• DIMENSIONS
	0	RE DIA.	DY SIZE	HAFTDIA	v	BAS	SIC U	NIT D		NSIO	NS					STA	NDARD MOUNTING PA	TTERN FOR ALL SIZES
MODEL #	A	B	C	D	Е	F	G	н	J	K	L	м	N	R	S	np	Imperial (inches)	Metric (mm)
DLB-10	3/4	3.50	.375	2.91	5.63	4.3975	5.228	3.485	3.060	1.178	1.245	.813	N/A	.594	2.375	DC	1.500	38.1
DLB-12	1 ¹ /16	4.00	.472	2.88	6.13	4.8975	5.728	3.985	3.500	1.615	1.657	.813	.375	.813	2.750	DD	.1880 x .25 DP	5mm H7 x 6 DP
DLB-16	11/16	4.75	.630	2.88	6.88	5.6475	6.478	4.735	4.250	1.615	1.657	.813	.375	.813	3.250	DF	Clearance for #10	Clearance for M5
DLB-10M	20	88.9	9.5	88.0	149.4	118.05	139.1	88.5	77.7	29.9	31.6	20.7	N/A	15.09	60.33	DH	#10-32 x .34 DP	M5 x 8.5 DP
DLB-12M	25	101.6	12	91.5	162.1	130.75	151.8	101.2	88.9	41.0	42.1	20.7	9.5	20.65	69.85	DQ	.0940 x .078 DP	3H7 x 2 DP
DI R-16M	25	120.7	16	01 5	181 1	1/0.80	170.0	120.3	107.0	/10	121	20.7	05	20.65	82 55	DU	#4-40 X .25 DP	M3 X 6 DP

How t	to Order: Basic	Unit	Accessories: (Order Separately	/) DLB-10M	DLB-12M	DLB-16M	QTY/SLIDE
BA	SIC MODEL METRIC	STYLE STROKE	SHOCK/STOP ACCESSORIES Shock Absorber Adjustable Hard Stop INDUCTIVE SENSOR ACCESSORIES † Inductive Sensor PNP Ok. Disconnect	SHOK-028 DLT-1023 OISP-011	SHOK-010 DLT-1023 0ISP-011	SHOK-010 DLT-1023 0ISP-011	1 or 2 1 or 2 1 or 2
	SIZE	BEARING SHAFTING	Inductive Sensor NPN Qk. Disconnect	OISN-011	OISN-011	OISN-011	1 or 2
SIZE	10, 12, 16		Quick, Disconnect 5M Cable Length	CARL-010	CARL-010	CARL-010	1 or 2
METRIC	M		Quick. Dioconnool on ouble Longer	UADE UIU		UNDE UTU	1012
STYLE	T Replaceable cylinder w/o a A Replaceable cylinder with	adjustable air cushions (Not avail. in metric) adjustable air cushions	MAGNETIC SENSOR ACCESSORIES ⁺ ** Magneto Resistive Sensor PNP Qk. Disc.	OHSP-005	OHSP-005	OHSP-005	1 or 2
BEARING	B Linear ball bearings		Magneto Resistive Sensor NPN Qk. Disc. Quick. Disconnect 2M Cable Length	OHSN-005 CABL-010	OHSN-005 CABL-010	OHSN-005 CABL-010	1 or 2 1 or 2
STROKE DLB-10	(inches) 1-12 @ 1" increments	Custom strokes available. Please consult factory.	Quick. Disconnect 5M Cable Length PNEUMATIC ACCESSORIES	CABL-013	CABL-013	CABL-013	1 or 2
DLB-12	1-16 @ 1" increments		1/8 NPT Telescopic Airlines (up to 6")	OTAL-039	OTAL-039	OTAL-039	1,2,3 or 4
DLB-10			1/8 NPT Telescopic Airlines (up to 12")	OTAL-040	OTAL-040	OTAL-040	1,2,3 or 4
DI R-10M	(11111) 25, 50, 80, 100, 125, 160 ,	200, 250, 300	1/8 NPT Telescopic Airlines (up to 18)	01AL-041 0TA1-042	01AL-041 0TAL-042	01AL-041 0TAI -042	1,2,3 or 4
DLB-12M	25, 50, 80, 100, 125, 160,	200, 250, 300, 320, 360, 400	1/8 NPT Adjustable Flow Control	VLVF-004	VLVF-004	VLVF-004	1 or 2
DLB-16M	25, 50, 80, 100, 125, 160,	200, 250, 300, 320, 360, 400, 500	G1/8 Telescopic Airlines (up to 160mm)	OTAL-045	OTAL-045	OTAL-045	1,2,3 or 4
SHAFTING	S Corrosion resistant shaftin	g	G1/8 Telescopic Airlines (up to 300mm)	OTAL-046	OTAL-046	OTAL-046	1,2,3 or 4
	CAMDI E ADRED. F	N P-10M-A-P-25	G1/8 Telescopic Airlines (up to 400mm)	0TAL-047	0TAL-047	0TAL-047	1,2,3 or 4
Fy: Base Slide S	JAIVIFLE URUER: L Size 10 Metric Replaceable Cylinder w/Adiu	JLD-IUWI-A-D-23	G1/8 Adjustable Flow Control	VLVF-005	VLVF-005	VLVF-005	1 or 2
2. 2400 0100, 0			*Sensor and cable sold separately **Piston magnet sta	ndard			



BASE SLIDE DLB -10M, 12M, 16M -T, A **REPLACEABLE CYLINDER WITH OR W/O ADJUST. AIR CUSHIONS**



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PNP and NPN available

Quick Disconnect Cable Threaded coupling with knurled head for secure electrical

> C D Е F G

1.25

1.25 .577 3.60

31.8

31.8 14.7

31.8 14.7 91.4 63.5 25.4 10.9

.577 3.60 2.5 1.00

577

147 914 635

3 60 25 1 00 43

91.4

2.5

63 5 254 10.9

1.00 .43

254

connections

A В

.70" .47

95"

.95' .47

17.8mm 11.9

24.1mm 11.9

24.1mm 11.9

DLB-10

DI B-12

DLB-16

DI B-10M

DI B-12M

DLB-16M

· 2 meter cable length

• 5 meter cable length

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Inductive Proximity Sensors

8mm diameter

connections

· 2 meter cable length

• 5 meter cable length

Threaded quick disconnect with built-in LED output

Quick Disconnect Cable

• Threaded coupling with knurled

head for secure electrical

PNP and NPN available

BASE SLIDE DLB -20, 25 -T, A Replaceable Cylinder with or W/O Adjust. Air Cushions





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BASE SLIDE DLB -20, 25 -T, A REPLACEABLE CYLINDER WITH OR W/O ADJUST. AIR CUSHIONS



Specifications	DLB-20
Maximum Air Pressure	100 psi
Thrust Force @ 80psi/5.5bar	130 lbs.
Weight (Basic Unit -T, -A)	12.6 lbs.
Additional Weight per Stroke	0.38 lbs./in.
Cylinder Bore Diameter	1-1/2"
Shaft Diameter	0.787"
Maximum Moment Load	600 inlbs.

Accessory Mounting Technical Data



Shock Absorbers and Flow Controls are recommended for nearly all applications (W) in this range use Single Shock in both directions (W) in this range use Bumpers or Cushioned Cyl

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications	DLB-25
Maximum Air Pressure	100 psi
Thrust Force @ 80psi/5.5bar	130 lbs.
Weight (Basic Unit -T, -A)	17.7 lbs.
Additional Weight per Stroke	0.53 lbs./in.
Cylinder Bore Diameter	1-1/2"
Shaft Diameter	0.984"
Maximum Moment Load	1200 inlbs.



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DIRECTCONNEC

BASE SLIDE DLB -10M, 12M, 16M -N, U REPAIRABLE (NFPA STYLE) CYLINDER W/FIXED AIR CUSHIONS

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D + STROKE

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A DIA. BORE

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UN	LESS	OTHEF	RWISE	NOTE	D ALL	TOLER	ANCES	ARE A	IS SHO	WN BE	LOW						DIRE	CTCONNECT
Dimensions are symmetrical abo centerline	e 1 Dut	→ Third Angle Projection	- e All Do ±	wel Holes Locationa .0005" ol	s are SF (al Tolerand r [±.013n	Slip Fit). N ce nm]	Aetric Threa Course Pite	ads ch 0	$\begin{array}{l} \text{Imperial} \\ 0.00 = \pm \\ 0.000 = \pm \\ .0000 = \pm \end{array}$	in. .01 .005 .0005	[0.] = [0.0] = [0.00] =	[mm] [±.25] [±.13] [±.013]					DI Stan Patte	MENSIONS IDARD MOUNTING IRN FOR ALL SIZES
	B	OPE DIA.	JOY SIZE	HAFT DIA		BAS	ic ui	VIT D	IMEN	ISION	IS		_				DB DC	Imperial (inches) .750 1.500
MODEL # DLB-10 DLB-12 DLB-16	A 3/4 1 ¹ /8 1 ¹ /8	B 3.50 4.00 4.75	C .375 .472 .630	D 3.44 3.44 3.44	E 5.63 6.13 6.88	F 4.3975 4.8975 5.6475	G 5.228 5.728 6.478	H 3.485 3.985 4.735	J 3.0600 3.5000 4.2500	K 1.178 1.615 1.615	L 1.245 1.657 1.657	₩ .813 .813 .813	N/A .375 .375	R .594 .813 .813	S 2.375 2.750 3.250		DD .1 DF C DH # DQ .(DU #	Clearance for #10 #10-32 x .34 DP .0940 x .078 DP #4-40 X .25 DP

E + STROKE

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How to Order: Basic Unit	Accessories: (Order Separately)	DLB-10	DLB-12	DLB-16	QTY/SLIDE	
BASIC MODEL METRIC STYLE STROKE	SHOCK/STOP ACCESSORIES Shock Absorber Adjustable Hard Stop	SHOK-028 DLT-1023	SHOK-010 DLT-1023	SHOK-010 DLT-1023	1 or 2 1 or 2	
SIZE BEARING SHAFTING	INDUCTIVE SENSOR ACCESSORIES ¹ Inductive Sensor PNP Qk. Disconnect Inductive Sensor NPN Qk. Disconnect Quick. Disconnect 2M Cable Length Quick. Disconnect 5M Cable Length	OISP-011 OISN-011 CABL-010 CABL-013	OISP-011 OISN-011 CABL-010 CABL-013	OISP-011 OISN-011 CABL-010 CABL-013	1 or 2 1 or 2 1 or 2 1 or 2 1 or 2	
STYLE N Repairable NFPA cylinder w/fixed air cushions (Not available in Metric) U Non-powered unit (Without cylinder. Metric Units: Mount VDMA cylinder directly. NPPA not available. DMA not available.) BEARING B Linear ball bearings	MAGNETIC SENSOR ACCESSORIES [†] ** Magneto Resistive Sensor PNP Qk. Disc. Magneto Resistive Sensor NPN Qk. Disc. Quick. Disconnect 2M Cable Length Quick. Disconnect 5M Cable Length	OHSP-005 OHSN-005 CABL-010 CABL-013	0HSP-005 0HSN-005 CABL-010 CABL-013	0HSP-005 0HSN-005 CABL-010 CABL-013	1 or 2 1 or 2 1 or 2 1 or 2 1 or 2	
C Composite bushings STROKE (inches) DLB-10 1-12 @ 1" increments DLB-12 1-16 @ 1" increments DLB-16 1-20 @ 1" increments	PNEUMATIC ACCESSORIES NFPA Cylinder Mounting Kit (-U only) 1/8 NPT Telescopic Airlines (up to 6") 1/8 NPT Telescopic Airlines (up to 12") 1/8 NPT Telescopic Airlines (up to 18") 1/9 NPT Telescopic Airlines (up to 18")	0DLT-001 0TAL-039 0TAL-040 0TAL-041	0DLT-002 0TAL-039 0TAL-040 0TAL-041	0DLT-002 0TAL-039 0TAL-040 0TAL-041	1 1,2,3 or 4 1,2,3 or 4 1,2,3 or 4	
STROKE (mm) DLB-10M 25, 50, 80, 100, 125, 160, 200, 250, 300 DLB-12M 25, 50, 80, 100, 125, 160, 200, 250, 300, 320, 360, 400 DLB-16M 25, 50, 80, 100, 125, 160, 200, 250, 300, 320, 360, 400, 500 SHAFFING S corresion resistant shafting	1/8 NPT Ielescopic Airlines (up to 24") 1/8 NPT Adjustable Flow Control 'Sensor and cable sold separately **Piston magnet star	OTAL-042 VLVF-004 ndard	OTAL-042 VLVF-004	VLVF-004	1,2,3 or 4 1 or 2	
SAMPLE ORDER: DLB-10-N-B-6 Ex: Base Slide, Size 10, Repairable Cylinder w/Fixed Air Cushions, Linear Ball Bushings, 6 Inch Stroke						



BASE SLIDE DLB -10M, 12M, 16M -N, UNREPAIRABLE (NFPA STYLE) CYLINDER W/ADJ. AIR CUSHIONS

16 in.



W=Weight of payload (lbs. or N) F+W=Total force (lbs. or N)



Loading Curves

DLB-12-N.U

N Ibs.

178 40

156 **35**





5 = 1 = 5

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Shock Absorbers and Flow Controls are recommended for nearly all applications
(W) in this range use Single Shock in both directions
(W) in this range use Bumpers or Cushioned

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications	DLB-10
Maximum Air Pressure	100 psi
Thrust Force @ 80psi/5.5bar	29 lbs.
Weight (Basic Unit -N)	2.01 lbs.
Additional Weight per Stroke	0.08 lbs./in.
Cylinder Bore Diameter	3/4"
Shaft Diameter	0.375"
Maximum Moment Load	75 inIbs.

Specifications	DLB-12
Maximum Air Pressure	100 psi
Thrust Force @ 80psi/5.5bar	71 lbs.
Weight (Basic Unit -N)	3.79 lbs.
Additional Weight per Stroke	0.16 lbs./in.
Cylinder Bore Diameter	1-1/8"
Shaft Diameter	0.472"
Maximum Moment Load	150 inIbs.

Specifications	DLB-16
Maximum Air Pressure	100 psi 71 lbs
Weight (Basic Unit -N)	5.09 lbs.
Additional Weight per Stroke	0.24 lbs./in. 1-1/8"
Shaft Diameter	0.630"
Maximum Moment Load	300 inlbs.

Accessory Mounting Technical Data



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Ex: Base Slide, Size 20, Repairable NFPA Cylinder w/Adjustable Air Cushions, Linear Ball Bushings, Inch Stroke

G1/8 Male to 1/8 NPT Adapter

*Piston magnet standard

PLFT-025

PLFT-025

1 or 2



BASE SLIDE DLB -20M, 25M -N, R, U **REPAIRABLE (NFPA/VDMA) CYLINDER W/ ADJ. AIR CUSHIONS**



Specifications	DLB-20	DLB-20M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	117 lbs.	443 N
Weight (Basic Unit -N, -R)	12.9 lbs.	5.9 kg
Additional Weight per Stroke -N, -R	0.53 lbs./in.	9.5 g/mm
Cylinder Bore Diameter -N	1-1/2"	32 mm
Cylinder Bore Diameter -R	32 mm	32 mm
Shaft Diameter	0.787"	20 mm
Maximum Moment Load	600 inIbs.	67.8 N-m
Min. Air Pressure to Release Cylinder Lock -R	60 psi	4 bar
Holding Force of Locking Mechanism -R	123 psi	550 N

Accessory Mounting Technical Data

available in 1 or 2 meter lengths



Shock Absorbers and Flow Controls are record nended for nearly all applications

(W) in this range use Single Shock in both directions (W) in this range use Bumpers or Cushioned Cylinder Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications D	LB-25 I	DLB-25M
Maximum Air Pressure 1	00 psi	6.9 bar
Thrust Force @ 80psi/5.5bar 1	17 lbs.	443 N
Weight (Basic Unit -N, -R) 1	8.0 lbs.	8.3 kg
Additional Weight per Stroke -N, -R 0.6	8 lbs./in. 1	2.1 g/mm
Cylinder Bore Diameter -N	1-1/2"	32 mm
Cylinder Bore Diameter -R	32 mm	32 mm
Shaft Diameter).984"	25 mm
Maximum Moment Load 120)0 inIbs.	135 N-m
Min. Air Pressure to Release Cylinder Lock -R	60 psi	4 bar
Holding Force of Locking Mechanism -R 1	23 psi	550 N

,°°°° °°° 0 c 0 MAX LINE STROKE A MAX BMAX Shock Absorbers **Adjustable Hard Stops Telescoping Airlines** • For precision (+/-.001") hard stop end point positioning • Full stroking piston rod · Eliminate flexing air lines Allows for stop adjustment independent of shock absorber hard stop · Self aligning air tube design extends useful seal life · Built-in hard stop Position adjustable Modular stackable design. Up to (4) modules can be Allen wrench adjustable stacked Adjustable dampening · Modules can be mounted on either side of slide • 1/8 NPT or G1/8 pipe threads • (2) user air ports per module **Flow Controls for Cylinders** · Thumb screw adjust with locking nut for adjusting cylinder speed •°°° °°° 1/4 NPT or G1/8 pipe threads 0 Q Q **Magneto Resistive Sensors Inductive Proximity Sensors** • For all externally mounted cylinders NFPA Cylinder Mounting Kit · Quick Disconnect with built in LED output • Used to mount standard face mounted NFPA cylinders to non-powered units (-U) Refer to accessories 8mm diameter Clamp-on mounting kit included · Threaded quick disconnect with built-in LED output mounting section. • PNP and NPN available · PNP and NPN available **Quick Disconnect Cable Quick Disconnect Cable** · Threaded coupling with knurled head for secure · Threaded coupling with knurled head for secure C D G A В Е F electrical connections electrical connections DLB-20 2.03" .10 1.40 .577 3.60 2.12 3.00 • 2 meter cable length • 2 meter cable length DLB-25 1.82" .10 1.40 .577 3.60 1.90 3.00 • 5 meter cable length 5 meter cable length DLB-20M 51.6mm 2.5 31.8 14.7 91.4 53.8 76.2 Quick disconnect cable extensions cords Quick disconnect cable extensions cords available in 1 or 2 meter lengths

NRECTCONNE

48.3 76.2

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

DLB-25M

46.2mm 2.5 31.8 14.7 91.4



Item Qty Name



Please see back cover for DE-STA-CO Global Locations. www.destaco.com


LOCKING CYLINDER -R CYLINDER VALVE 5 WAY, 3 POS (external pilot) PLUMBING DIAGRAM F ⊣ Main Supply \oplus �⊕ C -EXHAUST PORT G1/8 ô Ð Auxiliary 占 Supply LOCK VALVE 3 WAY, 2 POS (internal pilot) 4

- Lock valve must be maintained energized during cylinder motion, otherwise lock is engaged and cylinder valve shifts to mid position.
- Cylinder valve must be maintained energized during extend or retract. Also, keep energized at end of stroke until change of direction is desired.
- 3) Mid-position of 5/3 cylinder valve may be pressurized outlets if the combinaton of pressure load on the cylinder and inertia effects of the attached load do not exceed the holding force rating of the locking device, including allowance for wear.
- DO NOT use cylinder lines for any logic functions - pressure levels vary too much.

Item Qty Name

01	1	Cylinder
02	1	Body, Internally Powered
03	2	Guide Shaft
04	2	End Block
05	1	Coupling, Externally Powered
07	4	Bushing
08	8	Shock Pad, Urethane
30	4	Dowel Pin

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

NOTE: For accessory mounting, see product data sheets.





DLT SERIES

4.32

Internally Powered lock Thrusters B

Compact design:

This design is used for short strokes in limited space applications. Internal piston design reduces overall length.

Lift table:

The block thruster can be used as a power lift table by attaching an optional mounting flange.

DIRECTCONNECT mounting patterns:

These slides have DIRECTCONNECT mounting patterns that connect to other slides without the need for adapter plates.



Mounting Information:

Mounts and operates in any orientation











mounting

flange.

Body mounts with screws and locate with slip fit dowel pin holes on side or bottom using DIRECTCONNECT mounting patterns.

Technical Specifications:

Pneumatic Specifications Pressure Operating Range* Cylinder Type **Dynamic Seals** Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

Air Quality Requirements A

Air Filtration	40 Micron or Better
Air Lubrication	Not Necessary**
Air Humidity	Low Moisture Content (dry)

Temperature Operating Range

Buna-N Seals (standard) -30°~180° F -35°~80° C -20°~300° F -30°~150° C Viton[®] Seals (optional)

Maintenance Specifications

Expected Life	
Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycles [†]
-ield Repairable	Yes
Seal Repair Kits Available	Yes

Application Restrictions

Flow controls, shock absorbers and urethane bumpers recommended for nearly all applications. Use composite bushing in dirty or gritty environments. Never use silicone based lubricants with composite bushings.

*Higher pressure possible. Consult factory with application details. **Addition of lubrication will greatly increase service life ⁺See Maintenance Section

Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com



 The tooling is attached to two hardened steel shafts which are supported by and move in four linear bushings located in the body.

Designed and manufactured in the USA



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

BLOCK THRUSTER DLT -06M, 08M -B BUILT-IN REPAIRABLE CYLINDER





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4.34

Quick Disconnect 2 M Cable Length CABL-010 CABL-010 CABL-013 CABL-013 Quick Disconnect 5 M Cable Length 1 STYLE B Block thruster with built-in repairable cylinder MAGNETIC SENSOR ACCESSORIES ** * **BEARING C** Composite bushings OHSP-017 OHSP-017 Magneto Resistive Sensor PNP Qk. Disc.[†] 1 or 2 Magneto Resistive Sensor NPN Qk. Disc.⁺ OHSN-017 OHSN-017 1 or 2 STROKE (inches) Quick Disconnect 2 M Cable Length CABL-010 CABL-010 1 or 2 DLT-06 .25, .5, 1, 1.25 Quick Disconnect 5 M Cable Length CABL-013 CABL-013 1 or 2 DLT-08 .25, .5, 1, 1.5, 1.75 PNEUMATIC ACCESSORIES STROKE Custom strokes available. (mm) 6, 12, 25, 30 #10-32 Adjustable Flow Control VLVF-007 VLVF-007 1 or 2 Please consult factory. DIT-06M 6, 12, 25, 30, 40, 44 M5 Adjustable Flow Control VLVF-008 **VLVF-008** 1 or 2 DLT-08M Cylinder Seal Repair Kit **SLKT-108 SLKT-108** VITON[®] V Viton[®] seals Viton[®] Seal Repair Kit SLKT-108V SLKT-108V 1 SHAFTING S Corrosion resistant shafting **MOUNTING ACCESSORIES** Base Flange Kit (Imperial & Metric) ODLT-015 ODLT-016 1 SAMPLE ORDER: DLT-06-B-C-1.5-V

Ex: Thruster, Size 06, Block Style, Composite Bushings, 1.5 Inch Stroke, Viton® Seals

*Requires Universal Mounting Kit *Sensor and cable sold separately **Piston magnet standard





F=Externally applied force (lbs. or N) W=Weight of payload (lbs. or N) F+W=Total deflection force (lbs. or N) M=Maximum moment (in.-lb. or N-m)



Specifications	DLT-06	DLT-06M
Maximum Air Pressure	100 psi	7 bar
Thrust Force @ 80psi/5.5bar	20 lbs.	89 N
Weight (Basic Unit)	0.34 lbs.	0.15 kg
Cylinder Bore Diameter	0.563"	14.3 mm
Shaft Diameter	0.236"	6 mm
Max (M) Vertical Motion	5 in -lbs	0 6 N-m

Accessory Mounting Technical Data





Shock Absorbers and Flow Controls are recomme led for nearly all applications

Use Double Shocks in both directions Use Single Shock in both directions Use Bumpers or Cushioned Cylinder

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications	DLT-08	DLT-08M
Maximum Air Pressure	100 psi	7 bar
Thrust Force @ 80psi/5.5bar	20 lbs.	89 N
Weight (Basic Unit)	0.65 lbs.	0.30 kg
Cylinder Bore Diameter	0.563"	14.3 mm
Shaft Diameter	0.315"	8 mm
Max (M) Vertical Motion	10 inIbs.	1.1 N-m

4.35

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

BLOCK THRUSTER DLT -10M, 12M, 16M -B **BUILT-IN REPAIRABLE CYLINDER**





0.00

J

1.740

1.985

2.360

44.2

50.4

59.9

BASIC UNIT DI

н

3.490

3.985

4.735

88.6

101.2

120.3

F

1.19

1.63

1.63

30.2

41.4

41.4

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW $\Rightarrow \oplus$ \oplus Metric [mm] E € Imperial in. $0.00 = \pm .01$ [0.] = [±.25] Dimensions are All Dowel Holes are SF (Slip Fit). Third Angle Projection Metric Threads Course Pitch symmetrical about centerline Locational Tolerance ±.0005" or [±.013mm] 0.0

BODY SIZE

C

.375

.472

.630

9.5

12.0

16.0

BORE DIA.

A

3/4

1

1

19

25

25

MODEL #

DLT-10

DLT-12

DLT-16

DLT-10M

DLT-12M

DLT-16M

B

3.50

4.00

4.75

88.9

101.6

120.7

SHAFT DIA

D

3.000

3.625

4.375

76.2

92.1

111.1

Е

1.313

1.313

1.375

33.4

33.4

34.9

$0.\pm = 00$ $0.\pm = 00$	05 005	[0.0] = [0.00] = [0.00]	±.13] ±.013]			DIF	RECTCONNEC	DIMENSIONS
						STA	NDARD MOUNTING PAT Imperial (inches)	TERN FOR ALL SIZES Metric (mm)
VIENS	SION	S				DA	.375	9.5
K	L	М	N	P	S	DC	1.500	38.1
1.178	.584	.813 813	2.75	0.37	2.375	DD	.1880 x .25 DP #10-32 x .34 DP	5mm H7 x 6 DP M5 x 8 5 DP
1.615	.802	.813	4.03	0.37	3.250	DF	Clearance for #10	Clearance for M5
29.9	14.8	20.7	69.7	9.4	60.33	DG DQ	Clearance for #10 .0940 x .078 DP	Clearance for M5 3H7 x 2 DP
41.0 41.0	20.4 20.4	20.7 20.7	83.3 102 4	9.4 9.4	69.85 82.55	DS	Clr & C'bore for #4	Clr & C'bore for M3

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DC

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DD

How to	Order: Basic Un i	it	Accessories: (Order Separately	y) DLT-10M	DLT-12M	DLT-16MQ	TY/THRUSTER
BASIC N	nodel metric styli	STROKE SHAFTING	SHOCK/STOP ACCESSORIES Universal Mounting Kit (Shock, Stop or Sensor) Shock Absorber* Adjustable Hard Stop*	0SAK-055 SH0K-028 DLT-1023	0SAK-057 SH0K-010 DLT-1023	OSAK-059 Shok-010 DLT-1023	1 or 2 1 or 2 1 or 2
	SIZE BEARIN	IG VITON® SEALS	Inductive Sensor PNP Qk. Disconnect*	OISP-011	OISP-011	OISP-011	1
SIZE	10 12 16		Quick Disconnect 2 M Cable Length	CABL-010	CABL-010	CABL-010	1
METRIC	M		Quick Disconnect 5 M Cable Length	CABL-013	CABL-013	CABL-013	1
STYLE	B Block thruster with built-in rep	pairable cylinder	Magnetic Sensor Accessories***	0HSP_017	0HSP_017		1 or 2
BEARING	B Linear ball bearings		Magneto Resistive Sensor NPN Qk. Disc. ⁺	OHSN-017	OHSN-017	OHSN-017	1 or 2
0000	C Composite bushings		Quick Disconnect 2 M Cable Length	CABL-010	CABL-010	CABL-010	1
STROKE	(Inches)		Quick Disconnect 5 M Cable Length	CABL-013	CABL-013	CABL-013	1
DLI-10 DIT-12	.5-2 @ .5 increments	Queters studies susible	1/8 NPT Telescopic Airlines (up to 2")	0TA1_027	0TAI -027	0TA1_027	1 2 3 or /
DLT-16	.5-3 @ .5" increments	Custom strokes available.	1/8 NPT Telescopic Airlines (up to 2")	0TAL-037	0TAL-037	OTAL-037	1. 2. 3 or 4
STROKE	(mm)	Tiease consult factory.	#10-32 Adjustable Flow Control	VLVF-007	VLVF-007	VLVF-007	1 or 2
DLT-10M	12, 25, 40, 50		G1/8 Telescopic Airlines (up to 50mm)	OTAL-043	OTAL-043	OTAL-043	1, 2, 3 or 4
DLT-12M	12, 25, 40, 50		G1/8 Telescopic Airlines (up to 80mm)	0TAL-044	0TAL-044	OTAL-044	1, 2, 3 or 4
DLI-16M	12, 25, 40, 50, 65, 75		M5 Adjustable Flow Control	VLVF-008	VLVF-008	VLVF-UU8	1 or 2
VITON®	Viton [®] seals		Viton [®] Seal Renair Kit	SLK1-100	SLK1-102	SLK1-102	
SHAFTING	S Corrosion resistant shafting		MOUNTING ACCESSORIES		VARIATULY	ULA TULY	•
		10_R_C_1 5_V	Base Flange Kit (Imperial)	ODLT-005	ODLT-007	ODLT-009	1
Ev.	JAIVIFLE UNDER: ULI	- IU-D-U-I.J-V	Base Flange Kit (Metric)	ODLT-006	ODLT-008	ODLT-010	1
EX	. Thiuster, size TU, DIUCK Style, CUMPOSILE BUSI	ings, 1.5 mult Sliuke, viluit- Seals	*Requires Universal Mounting Kit *Sensor and cable so	ld separately **Pis	ton magnet standar	ď	



DLT-10M-B Deflection Curves Inches (mm) N Ibs. 111 25 89 2 14 W MAX FORCE+PAYLOAD 67 1 44 1 22 5 0 0 .5 13 1.5 37 2 ir STROKE F=Externally applied force (lbs. or N) W=Weight of payload (lbs. or N)

F+W=Total deflection force (lbs. or N) M=Maximum moment (in.-lb. or N-m)

Specifications	DLT-10	DLT-10N
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar.	35 lbs.	155 N
Weight (Basic Unit)	1.81 lbs.	0.82 kg
Cylinder Bore Diameter	3/4"	19mm
Shaft Diameter	0.375"	9.5mm
Max (M) Vertical Motion	25 in-lbs.	2.8N-m
Shaft Diameter Max (M) Vertical Motion	0.375" 25 in-lbs.	9.5mm 2.8N-m



DLT-12 DLT-12M

1"

0.472"

6.9 bar

275 N

1.31 kg

25mm

12mm

5.6N-m

W

1111

Specifications

Maximum Air Pressure 100 psi

Thrust Force @ 80psi/5.5bar. 62 lbs.

Weight (Basic Unit) 2.88 lbs.

Max (M) Vertical Motion 50 in-lbs.

Cylinder Bore Diameter

Shaft Diameter

BLOCK THRUSTER DLT -10M, 12M, 16M -B **BUILT-IN REPAIRABLE CYLINDER**

DLT-16[M]-B



Shock Absorbers and Flow Controls are recomme ded for nearly all applications (W) in this range use Single Shock in retract direction (W) in this range use B

₹.

LOAD

0BC

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications	DLT-16	DLT-16M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar.	62 lbs.	275 N
Weight (Basic Unit)	4.38 lbs.	1.99 kg
Cylinder Bore Diameter	1"	25mm
Shaft Diameter	0.630"	16mm
Max (M) Vertical Motion	100 in-lbs.	11.3N-m

Accessory Mounting Technical Data



'n SER 4.37



BLOCK THRUSTER DLT -20M, 25M -B **BUILT-IN REPAIRABLE CYLINDER**



Metric (mm)

5mm H7 x 6DP

M10 x 14.2 DP

Clearance for M10

Clearance for M10

QTY/THRUSTER

1 or 2

1 or 2

1 or 2

1

1 or 2

1 or 2

1

1

1, 2, 3 or 4

1. 2. 3 or 4

1 or 2

1, 2, 3 or 4

1, 2, 3 or 4

1 or 2

1

1

1

Clearance for M5

19.1

38 1

762 8mm H7 x 9.4 DP

CABL-010

CABL-013

OHSP-017

OHSN-017

CABL-010

CABL-013

OTAL-049

OTAL-050

VLVF-004

OTAL-051

OTAL-052

VLVF-005

SLKT-104

SLKT-104V

ODLT-013

ODLT-014



METRIC M

BEARING

STROKE

STROKE

DLT-20

STYLE B Block thruster with built-in repairable cylinder

Custom strokes available.

Please consult factory.

B Linear ball bearings

C Composite bushings

.5-4 @ .5" increments

DLT-20M **12, 25, 40, 50, 65, 75, 85, 100** DLT-25M **12, 25, 40, 50, 65, 75, 85, 100, 115, 125**

SAMPLE ORDER: DLT-20-B-C-2.5-V

Ex: Thruster, Size 20, Block Style, Composite Bushings, 2.5 Inch Stroke, Viton® Seals

(inches)

(mm)

VITON[®] V Viton[®] seals

DLT-25 .5-5 @ .5" increments

SHAFTING S Corrosion resistant shafting

£

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

Quick Disconnect 2 M Cable Length

Quick Disconnect 5 M Cable Length **MAGNETIC SENSOR ACCESSORIES****

Quick Disconnect 2 M Cable Length

Quick Disconnect 5 M Cable Length

1/8 NPT Telescopic Airlines (up to 4")

1/8 NPT Telescopic Airlines (up to 5")

G1/8 Telescopic Airlines (up to 100mm)

G1/8 Telescopic Airlines (up to 125mm)

1/8 NPT Adjustable Flow Control

G1/8 Adjustable Flow Control

Viton[®] Cylinder Seal Repair Kit

MOUNTING ACCESSORIES Base Flange Kit (Imperial)

Cylinder Seal Repair Kit

Base Flange Kit (Metric)

PNEUMATIC ACCESSORIES

Magneto Resistive Sensor PNP Qk. Disc.¹

Magneto Resistive Sensor NPN Qk. Disc.⁺

CABL-010

CABL-013

OHSP-017

OHSN-017

CABL-010

CABL-013

OTAL-049

OTAL-050

VLVF-004

OTAL-051

OTAL-052

VLVF-005

SLKT-104

SLKT-104V

ODLT-011

ODLT-012

*Requires Universal Mounting Kit *Sensor and cable sold separately **Piston magnet standard



DLT-20M-B



Specifications	ULI-20	DLI-20M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	140 lbs.	622 N
Weight (Basic Unit)	11.2 lbs.	5.1 kg
Cylinder Bore Diameter	1-1/2"	38mm
Shaft Diameter	0.787"	20mm
Max (M) Vertical Motion	250 inlbs.	28.2N-m

Accessory Mounting Technical Data



5 in. 127mr

BLOCK THRUSTER DLT -20M, 25M -B

2.5 63

STROKE

(W) in this range use Bu

Shock Absorbers and Flow Controls are recommended for nearly all applications

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical

applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Deflection Curves Inches (mm)

.002" (.05)

Maximum Air Pressure

Thrust Force @ 80psi/5.5bar.....

Weight (Basic Unit).....

Cylinder Bore Diameter.....

Shaft Diameter.....

Max (M) Vertical Motion 500 in.-lbs.

DLT-25M-B

N Ibs.

667 150

556 125

445 100

334 75

222 50

111 25

0 0

(W) in this range use Single Shock in retract direction

Specifications

≥ t

ORCE+PAYLOAD

BUILT-IN REPAIRABLE CYLINDER

WMAX

3.5 89

DLT-25

100 psi

140 lbs.

15.7 lbs.

1-1/2"

0.984"

4.5 114

DLT-25M

6.9 bar

622 N

7.2 kg

38mm

25mm

56.4N-m

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ers or Cu

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

www.comoso.com

4.39

Internally Powered Thruster Slide

DLT SERIES

4.40

Compact design: This design is used for

short & medium length strokes in limited space applications. Internal air cylinder design reduces overall length to a minimum.

DIRECTCONNECT mounting patterns: These slides have DIRECTCONNECT mounting

patterns that connect to other slides without the need for adapter plates.

Mounting Information:

Mounts and operates in any orientation



Body can be mounted from the back using the directconnect pattern of threaded mounting and dowel pin holes



Body mounts with screws and locate with slip fit dowel pin holes on side using DIRECTCONNECT mounting patterns.



Body back mounts with screws from the front using the clearance and counterbored **DIRECTCONNECT** pattern and located with dowel holes.



Payload attaches to tooling plate directconnect mounting pattern with screws and locates using slip fit dowel pin holes.

Technical Specifications:

Pneumatic Specifications	Imperial Metric
Pressure Operating Range*	40-100 psi 3-7 bar
Cylinder Type	Double Acting
Dynamic Seals	Internally Lubricated Buna-N
Valve Required to Operate	4-way, 2-position
Air Quality Requirements Air Filtration Air Lubrication	40 Micron or Better Not Necessary**

Air Filtration	40 Micron or Better
Air Lubrication	Not Necessarv**
Air Humidity	Low Moisture Content (drv)

Temperature Anerating Range

Buna-N Seals (standard)	-30°~180° F	-35°~80° C
Viton [®] Seals (optional)	-20°~300° F	-30°~150° C
,		

Maintenance Specifications[†]

Expected Life	
Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycles [†]
Field Repairable	Yes
Seal Repair Kits Available	Yes

Application Restrictions

Flow controls, shock absorbers and urethane bumpers recommended for nearly all applications. Use composite bushing in dirty or gritty environments.

Never use silicone based lubricants with composite bushings.

*Higher pressure possible. Consult factory with application details.

**Addition of lubrication will greatly increase service life ⁺See Maintenance Section

Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com



Designed and manufactured in the USA

www.comoso.com

See **4.52** Page

SHORT BODY THRUSTER DLT -06M, 08M -E **BUILT-IN REPAIRABLE CYLINDER**





Ex: Thruster, Size 06, Short Body Style, Composite Bushings, 1.5 Inch Stroke, Viton® Seals



W=Weight of payload (lbs. or N)

Specifications

F+W=Total deflection force (lbs. or N)

M=Maximum moment (in.-lb. or N-m)

Maximum Air Pressure

Thrust Force @ 80psi/5.5 bar.....

Weight (Basic Unit)

Cylinder Bore Diameter.....

Shaft Diameter.....

Max (M) Vertical Motion.....

SHORT BODY THRUSTER DLT -06M, 08M -E **BUILT-IN REPAIRABLE CYLINDER**



DLT-08M-E Loading Curves N Ibs. 53 12 45 10 ş +PAYLOAD (F-35 27 W MAX ORCE+ 18 2 9 0 .25 **.5** 13 1.5 1.75 in. ſ .75 1.25 STROKE

Shock Absorbers and Flow Controls are recommended for nearly all applications

Use Double Shocks in both directions Use Single Shock in both directions

w

DLT-06M

7 bar

84 N

0.15 kg

14.3 mm

6 mm

0.6 N-m

DLT-06

100 psi

20 lbs.

0.34 lbs.

0.563

0.236'

5 in.-lbs.

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications	DLT-08	DLT-08M
Maximum Air Pressure	100 psi	7 bar
Thrust Force @ 80psi/5.5 bar	20 lbs.	89 N
Weight (Basic Unit)	0.65 lbs.	0.30 kg
Cylinder Bore Diameter	0.563"	14.3 mm
Shaft Diameter	0.315"	8 mm
Max (M) Vertical Motion	10 inIbs.	1.1 N-m

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IRECTONNE

8M

Accessory Mounting Technical Data



- 2 meter cable length
- 5 meter cable length

- · 2 meter cable length
- 5 meter cable length

	A	В	C	D	E
DLT-06	.236"	.470	.250	.310	.270
DLT-08 DLT-06M	.230 6mm	.630 12.0	.250 6.4	.310 7.9	.270
DLT-08M	6mm	16.0	6.4	7.9	6.9

Use Bumpers or Cushion

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

SHORT BODY THRUSTER DLT -10M, 12M, 16M -E **BUILT-IN REPAIRABLE CYLINDER**





TOLERANCES ARE AS SHOWN BELOW

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All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

Metric [mm]

 $\triangleright \odot$

Third Angle Projection

Imperial in.





Metric Threads Course Pitch	³ 0	$0.00 = \pm .000$ $0.00 = \pm .000$)1)05	[0.] = [± [0.0] = [:	:.25] ±.13]												
	0.0	0000 = ±.0	0005	[0.00] = [:	±.013]										DI ST/	RECTCONNECT	DIMENSIONS TERN FOR ALL SIZES
	P	ORE DIA.	DY SIZE	HAFT DIA.		BAS	C UN	IT DI	MEN	SION	S				DA	Imperial (inches) .375	Metric (mm) 9.5
MODEL #	A	B	C	E	F	G	н	J	K	L	М	Ν	Р	S	DB	.750	19.1
DLT-10	3/4	3.50	.375	1.313	1.19	.82	3.490	1.740	1.178	.584	.813	2.75	.37	2.375	DC	1.500	38.1
DLT-12	1	4.00	.472	1.313	1.63	.82	3,985	1,985	1.615	.802	.813	3.28	.37	2,750	DD	.1880 x .25 DP	5mm H7 x 6 DP
DIT-16	1	4 75	630	1 375	1.63	76	4 735	2 360	1 615	802	813	4 03	37	3 250	DE	#10-32 x .34 DP	M5 x 8.5 DP
DEI 10	· ·	1.70	.000	1.010	1.00		1.1 00	2.000	1.010	.002	.010	1.00	.07	0.200	DF	Clearance for #10	Clearance for M5
DLT-10M	19	88.9	9.5	33.4	30.2	20.8	88.6	44.2	29.9	14.8	20.7	69.7	9.4	60.33	DG	Clearance for #10	Clearance for M5
DLT-12M	25	101.6	12.0	33.4	41.4	20.8	101.2	50.4	41.0	20.4	20.7	83.3	9.4	69.85	DQ	.0940 x .078 DP	3H7 x 2 DP
DIT-16M	25	1207	16.0	34.9	414	19.3	120.3	59.9	41.0	20.4	20.7	102.4	94	82 55	DS	Clr & C'bore for #4	Clr & C'bore for M3

How to Order: Basic Unit	Accessories: (Order Separately)	DLT-10M	DLT-12M	DLT-16M ()TY/THRUSTER
BASIC MODEL METRIC STYLE STROKE SHAFTING DLT - M-EV-S SIZE BEARING VITON° SEALS	SHOCK/STOP ACCESSORIES Universal Mounting Kit (Shock, Stop or Sensor) Urethane Bumper/Clamp Collar Kit Urethane Bumper/Clamp Collar Kit (-10M) Urethane Bumper/Clamp Collar Kit (-12M) Shock Absorber* Adjustable Hard Stop*	OSAK-055 OSAK-056 OSAK-065 SHOK-028 DLT-1023	OSAK-057 OSAK-058 OSAK-066 SH0K-010 DLT-1023	OSAK-059 OSAK-060 SH0K-010 DLT-1023	1,2,3 or 4 1 1 1,2,3 or 4 1,2,3 or 4
SIZE 10, 12, 16 METRIC M STYLE E Short body thruster with built-in repairable cylinder BEARING B Linear ball bearings C Composite bushings	INDUCTIVE SENSOR ACCESSORIES [†] Inductive Sensor PNP Qk. Disconnect* Inductive Sensor NPN Qk. Disconnect* Quick. Disconnect 2M Cable Length [†] Quick. Disconnect 5M Cable Length [†]	OISP-011 OISN-011 CABL-010 CABL-013	OISP-011 OISN-011 CABL-010 CABL-013	0ISP-011 0ISN-011 CABL-010 CABL-013	1 or 2 1 or 2 1 or 2 1 or 2 1 or 2
STROKE (inches) DLT-10 1-2 @ 1" increments DLT-12 1-2 @ 1" increments DLT-16 1-3 @ 1" increments Plase consult factory.	Magneto Resistive Sensor PNP Qk. Disc. [†] Magneto Resistive Sensor NPN Qk. Disc. [†] Quick. Disconnect 2M Cable Length [†] Quick. Disconnect 5M Cable Length [†] PNEUMATIC ACCESSORIES	OHSP-017 OHSN-017 CABL-010 CABL-013	0HSP-017 0HSN-017 CABL-010 CABL-013	OHSP-017 OHSN-017 CABL-010 CABL-013	1 or 2 1 or 2 1 or 2 1 or 2 1 or 2
DL1-10M 25, 50 DL7-12M 25, 50, 75 VITON V Viton® seals SHAFTING S Corrosion resistant shafting	1/8 NPT Telescopic Airlines (up to 2") 1/8 NPT Telescopic Airlines (up to 3") #10-32 Adjustable Flow Control G1/8 Telescopic Airlines (up to 50mm) G1/8 Telescopic Airlines (up to 80mm) M5 Adjustable Flow Control	0TAL-037 0TAL-038 VLVF-007 0TAL-043 0TAL-044 VIVE-008	0TAL-037 0TAL-038 VLVF-007 0TAL-043 0TAL-044 VIVE-008	0TAL-037 0TAL-038 VLVF-007 0TAL-043 0TAL-044 VLVE-008	1,2,3 or 4 1,2,3 or 4 1 or 2 1,2,3 or 4 1,2,3 or 4 1,2,3 or 4
SAMPLE ORDER: DLT-10-E-C-1-V	Cylinder Seal Repair Kit Viton [®] Cylinder Seal Repair Kit	SLKT-100 SLKT-100V	SLKT-102 SLKT-102V	SLKT-102 SLKT-102V	1

Ex: Thruster, Size 10, Short Body Style, Composite Bushings, 1 inch Stroke, Viton® Seals

*Requires Universal Mounting Kit *Sensor and cable sold separately **Piston magnet standard

Dimensions are

symmetrical about

centerline

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DLT-16M





SHORT BODY THRUSTER DLT -10M, 12M, 16M -E **BUILT-IN REPAIRABLE CYLINDER**



Specifications DLT-10M **DLT-10** Maximum Air Pressure..... 100 psi 6.9 bar Thrust Force @ 80psi/5.5bar. 35 lbs. 155 N Weight (Basic Unit) 1.87 lbs. .84 kg Additional Weight per Stroke .. 0.08 lbs./in. 1.5g/mm Cylinder Bore Diameter 3/4" 19mm Shaft Diameter 0.375" 9.5mm

Specifications	DLT-12	DLT-12M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar.	62 lbs.	275 N
Weight (Basic Unit)	2.98 lbs.	1.35 kg
Additional Weight per Stroke	0.12 lbs./in.	2.2g/mm
Cylinder Bore Diameter	1"	25mm
Shaft Diameter	0.472"	12mm

DLT-16 DLT-16M Specifications Maximum Air Pressure 100 psi 6.9 bar Thrust Force @ 80psi/5.5bar. 62 lbs. 275 N Weight (Basic Unit) 4.56 lbs. 2.07 kg Additional Weight per Stroke .. 0.20 lbs./in. 3.5q/mm Cylinder Bore Diameter 1" 25mm Shaft Diameter 0.630' 16mm

2.5

Accessory Mounting Technical Data



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

SHORT BODY THRUSTER DLT -20M, 25M -E **BUILT-IN REPAIRABLE CYLINDER**





	52. 20	50	150.5	20	00.1	00
G	How to) Or	der:	Basi	ic U	nit
EN	BASIC DL	MODI	3L MI	etric M -	ST	YLE
		SI	ZE		BEAI	RING
	SIZE	20, 2	5			
	METRIC	М				
	STYLE	E Sho	rt body t	hruster	with b	uilt-in
	BEARING	B Line C Com	ar ball b posite b	earings oushings	5	
G	STROKE DLT-20 DLT-25	(inche 1-4 @ 1-5 @	s) 2 1" incr 2 1" incr	ements ements		Cue
	STROKE	(mm)				Ple
	DLT-20M DLT-25M	25, 50 25, 50), 75, 10 D, 75, 10)0)0, 125		
	VITON [®]	V Vito	n® seals			
	SHAFTING	S Corr	osion re	sistant s	shaftin	g
	Ex:	SA Thruster, S	MPLE ize 20, Sho	t Body Style	ER:)LT- Ball Bus
						I

DLT SERIES

4.46

Init	Accessories: (Order Separately)	DLT-20M	DLT-25M	QTY/THRUSTEI
	C Universal Mounting Kit			
TLE STRUKE SHAFTING	(Shock Stop or Sensor)	0SAK-061	UCVK-U63	123 or 4
	Urethane Bumper/Clamp Collar Kit	05AK-067	05AK-005	1, 2, 3 61 4
	Shock Absorber (adjustable dampening)*	SHOK-029	SHOK-029	1. 2. 3 or 4
	Adjustable Hard Stop*	DLT-1023	DLT-1023	1, 2, 3 or 4
RING VITON [®] SEALS			1010	., _, • • • •
	Inductive Sensor PNP Ok Disconnect*	NISP_011	0160-011	1 or 2
	Inductive Sensor NPN Ok Disconnect*	0ISN-011	0ISN-011	1 or 2
	Ouick Disconnect 2M Cable Length †	CABL-010	CABL-010	1 or 2
	Quick, Disconnect 5M Cable Length †	CABL-013	CABL-013	1 or 2
uilt-in repairable cylinder	MAGNETIC SENSOR ACCESSORIES**	0	0	
	Magneto Besistive Sensor PNP Ok Disc t	OHSP-017	0HSP-017	1 or 2
	Magneto Resistive Sensor NPN Ok Disc.*	OHSN-017	OHSN-017	1 or 2
	Ouick Disconnect 2M Cable Length †	CABL-010	CABL-010	1 or 2
	Quick, Disconnect 5M Cable Length †	CABL-013	CABL-013	1 or 2
Custom strokes available.		0.122 010	0	
Please consult factory.	1/8 NPT Telescopic Airlines (up to 4")	0101-049	0TAI -049	1 2 3 or 4
	1/8 NPT Telescopic Airlines (up to 4)	OTAL-049	OTAL-049	1, 2, 3 or 4
	1/8 NPT Adjustable Flow Control	VLVF-004	VLVF-004	1 or 2
	G1/8 Telescopic Airlines (up to 100mm)	0TAL-051	0TAL-051	1. 2. 3 or 4
a	G1/8 Telescopic Airlines (up to 125mm)	0TAL-052	0TAL-052	1, 2, 3 or 4
9	G1/8 Adjustable Flow Control	VLVF-005	VLVF-005	1 or 2
	Cylinder Seal Repair Kit	SLKT-104	SLKT-104	1
ULI-2U-E-B-4-V	Viton [®] Cylinder Seal Repair Kit	SLKT-104V	SLKT-104V	1
Ball Bushings, 4 Inch Stroke, Viton® Seals	*Requires Universal Mounting Kit *Sensor and cable sold se	eparately **Piston ma	gnet standard	

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SHORT BODY THRUSTER DLT -20M, 25M -E **BUILT-IN REPAIRABLE CYLINDER**

DLT-20M-E



Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	140 lbs.	622 N
Weight (Basic Unit)	11.6 lbs.	5.2 kg
Additional Weight per Stroke	0.31 lbs./in.	5.5g/mm
Cylinder Bore Diameter	1-1/2"	38mm
Shaft Diameter	0.787"	20mm

DLT-25 M-E Loading Curves N Ibs. 667 **150** 556 125 ¥ W мах + PAYLOAD 445 100 334 75 =ORCE -222 50 111 25 0 .5 1.5 3.5 4.5 1 ż 2.5 5 in. 127mn 25 38 50 64 80 102 114 STROKE

Shock Absorbers and Flow Controls are recommended for nearly all applications (W) in this range use Single Shock in both directions (W) in this range use Ure

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications	DLT-25	DLT-25M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	140 lbs.	622 N
Weight (Basic Unit)	16.4 lbs.	7.42 kg
Additional Weight per Stroke	0.47 lbs./in.	8.4g/mm
Cylinder Bore Diameter	1-1/2"	38mm
Shaft Diameter	0.984"	25mm

Accessory Mounting Technical Data (For detailed information refer to option specification pages at end of catalog)



4.47

G + MAX. AIRLINE STROKE

G

3.60

3.60

91.4



DLT-25M

12.7mm 44.5

12.7 22.4 17.0 14.7 91.4







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F=Externally applied force (lbs. or N)

F+W=Total deflection force (lbs. or N)

M=Maximum moment (in.-lb. or N-m)

Cylinder Bore Diameter.....

Shaft Diameter.....

Max (M) Vertical Motion.....

W=Weight of payload (lbs. or N)

LONG BODY THRUSTER DLT -06M, 08M -L **BUILT-IN REPAIRABLE CYLINDER**

Shock Absorbers and Flow Controls are recommended for nearly all applications Use Single Shock in both directions Use Double Shocks in both directions Use Bumpers or Cushioned Cylinder

	~~~~~		exceed 1/2 of the recommended payload due to the additional acceleration e			
Specifications	DLT-06	DLT-06M	Specifications			
Maximum Air Pressure	100 psi	7 bar	Maximum Air Pressure			
Thrust Force @ 80psi/5.5bar	20 lbs.	89 N	Thrust Force @ 80psi/5.5bar			
Weight (Basic Unit)	0.61 lbs.	0.28 ka	Weight (Basic Unit)			

#### DLT-08 DLT-08M 100 psi 7 bar ..... 89 N 20 lbs. . . . . . . . . . . . 0.44 kg Weight (Basic Unit)..... 0.96 lbs. 14.3 mm Cylinder Bore Diameter..... 0.563" Shaft Diameter..... 0.315' 8.0 mm Max (M) Vertical Motion ..... 10 in.-Ibs. 1.3 N-m

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4.49

![](_page_450_Picture_10.jpeg)

### Accessory Mounting Technical Data

![](_page_450_Picture_12.jpeg)

**Urethane Bumpers & Clamp Collars** 

- Urethane Bumpers for shock absorption and noise dampening · Adjustable Clamp Collars for end of stroke position
- adjustment
- Kit contains (2) Collars and (2) Shock Pads for adjustment of travel in one direction
- (1) Kit required for extend (kit for retract comes standard)

![](_page_450_Picture_18.jpeg)

#### **Adjustable Hard Stops**

- For precision (+/-.001") end point positioning of retract position
- · Allows for end stop position adjustment independent of shock absorber hard stop
- · Allen wrench adjustable
- **Shock Absorbers**
- Full stroking piston rod
- Built-in hard stop

F

w

14.3 mm

6 mm

0.6 N-m

0.563

0.236'

5 in.-lbs

 Position adjustable · Adjustable dampening

![](_page_450_Picture_27.jpeg)

**Universal Mounting Kit** 

- Kit mounts (1) Shock Absorber or (1) Adjustable Hard Stop
- Kit includes (1) Mounting Bracket, (1) Hardened Tool Steel Target and Hardware
- Target allows for unlimited retract stroke adjustment (no extend position adjustment). Fine adjustment is achieved using Adjustable Hard Stop or Shock
- Absorber · Mounting Bracket keys into body for secure positioning and excellent rigidity
- · Four possible mounting positions

![](_page_450_Picture_34.jpeg)

#### **Inductive Proximity Sensors**

- 4mm diameter
- Threaded quick disconnect with built-in LED output PNP and NPN available
- **Quick Disconnect Cable**
- Threaded coupling with knurled head for secure electrical connections
- 2 meter cable length
- 5 meter cable length

![](_page_450_Picture_42.jpeg)

**Magneto Resistive Sensors** 

- No mounting kit required (slot mounted)
- Threaded quick disconnect with built-in LED output • PNP and NPN available
- · Low profile
- **Quick Disconnect Cable**
- · Threaded coupling with knurled head for secure
- electrical connections
- 2 meter cable length • 5 meter cable length

	A	В	C	D	E
DLT-06	.236"	.47	.250	.31	.27
DLT-08	.236"	.63	.250	.31	.27
DLT-06M	6.0 mm	12.0	6.4	7.9	6.9
DLT-08M	6.0 mm	16.0	6.4	7.9	6.9

VIRECTCONNEC

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Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

![](_page_451_Figure_0.jpeg)

![](_page_451_Picture_1.jpeg)

6

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-DD

5mm H7 x 6 DP M5 x 8.5 DP

Clearance for M5

Clearance for M5

3H7 x 2 DP Clr & C'bore for M3

DD

DE

DF

DG

DQ

DS

.1880 x .25 DP

#10-32 x .34 DP

Clearance for #10

Clearance for #10

Clr & C'bore for #4

.0940 x .078 DP

![](_page_451_Figure_2.jpeg)

	BORE DA BON SITE SHAFT DIA BASIC UNIT DIMENSIONS															
NODEL #	A	В	C	D	E	F	G	H	J	K	L	М	N	P	Q	S
DLT-10	.75	3.50	.375	2.00	1.313	1.19	0.82	3.490	1.740	1.178	.584	.813	4.75	0.38	0.38	2.375
)LT-12	1	4.00	.472	2.50	1.313	1.63	0.82	3.985	1.985	1.615	.802	.813	5.78	0.37	0.36	2.750
DLT-16	1	4.75	.630	2.75	1.375	1.63	0.76	4.735	2.360	1.615	.802	.813	6.78	0.37	0.36	3.250
DLT-10M	19	88.9	9.5	50.8	33.4	30.2	20.8	88.6	44.2	29.9	14.8	20.7	120.7	9.6	9.6	60.33
DLT-12M	25	101.6	12.0	63.5	33.4	41.4	20.8	101.2	50.4	41.0	20.4	20.7	146.8	9.4	9.1	69.85
DLT-16M	25	120.7	16.0	69.9	34.9	41.4	19.3	120.3	59.9	41.0	20.4	20.7	172.2	9.4	9.1	82.55

How to Order: Basic Unit	Accessories: (Order Separately)	DLT-10M	DLT-12M	DLT-16M	QTY/THRUSTER
BASIC MODELMETRICSTYLESTROKESHAFTINGDLT	SHOCK/STOP ACCESSORIES Universal Mounting Kit (Shock, Stop or Sensor) Urethane Bumper/Clamp Collar Kit Urethane Bumper/Clamp Collar Kit (-10M) Urethane Bumper/Clamp Collar Kit (-12M) Shock Absorber* Adjustable Hard Stop* INDUCTIVE SENSOR ACCESSORIES' INDUCTIVE SENSOR ACCESSORIES' Inductive Sensor PNP Qk. Disconnect* Inductive Sensor NPN Qk. Disconnect* Inductive Sensor NPN Qk. Disconnect* Quick Disconnect 5M Cable Length 1 MAGNETIC SENSOR ACCESSORIES'* Magneto Resistive Sensor NPN Qk. Disc.1 Magneto Resistive Sensor NPN Qk. Disc.? Quick Disconnect 5M Cable Length 1 Quick Disconnect 5M Cable Length 1 Quick Disconnect 5M Cable Length 1 Quick Disconnect SM Cable Length 1 PHEUMATIC ACCESSORIES 1/8 NPT Telescopic Airlines (up to 3") 1/8 NPT Telescopic Airlines (up to 3") 1/8 NPT Telescopic Airlines (up to 80mm) G1/8 Telescopic Airlines (up to 80mm) G1/8 Telescopic Airlines (up to 160mm) M5 Adjustable Flow Control	OSAK-055 OSAK-056 OSAK-056 SHOK-028 DLT-1023 OISP-011 OISN-011 CABL-010 CABL-010 CABL-013 OHSP-017 OHSN-017 CABL-010 CABL-013 OTAL-038 OTAL-038 OTAL-045 VLVF-008	OSAK-057 OSAK-058 OSAK-058 SHOK-010 DLT-1023 OISP-011 OISN-011 CABL-010 CABL-013 OHSP-017 OHSN-017 CABL-010 CABL-013 OTAL-038 OTAL-038 OTAL-045 VLVF-008	OSAK-059 OSAK-060 SHOK-010 DLT-1023 OISP-011 OISN-011 CABL-010 CABL-010 CABL-013 OHSP-017 OHSN-017 CABL-010 CABL-013 OTAL-038 OTAL-038 OTAL-045 VLVF-008	1, 2, 3 or 4 1 1 1, 2, 3 or 4 1, 2, 3 or 4 1, 2, 3 or 4 1 or 2 1  2, 3 or 4 1, 2, 3 or 4 1 or 2 1 or 4 1 or 2 1 or 2 1 or 2 1 or 2 1 or 4 1 or 4 1 or 2 1 or 4 1 or
SAMPLE ORDER: DLT-10M-L-C-25-V Ex: Thruster, Size 10 Metric, Long Body Style, Composite Bushings, 25mm Stroke, Viton [®] Seals	Cylinder Seal Repair Kit Viton [®] Cylinder Seal Repair Kit *Requires Universal Mounting Kit - Sensor and cable sol	SLKT-100 SLKT-100V	SLKT-102 SLKT-102V stop magnet standar	SLKT-102 SLKT-102V	1

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![](_page_452_Picture_0.jpeg)

#### LONG BODY THRUSTER DLT -10M, 12M, 16M -L BUILT-IN REPAIRABLE CYLINDER

![](_page_452_Figure_2.jpeg)

![](_page_452_Figure_3.jpeg)

![](_page_452_Figure_4.jpeg)

Shock Absorbers and Flow Controls are recommended for nearly all applications
(W) in this range use Single Shock in both directions
(W) in this range use Urethane Bu

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications	DLT-10	DLT-10M
Maximum Air Pressure Thrust Force @ 80psi/5.5bar . Weight (Basic Unit) Additional Weight per Stroke . Cylinder Bore Diameter	100 psi 35 lbs. 1.95 lbs. 0.08 lbs./in. 3/4"	6.9 bar 155 N 0.88 kg 1.4g/mm 19mm
Shaft Diameter	0.375"	9.5mm

 Specifications
 DLT-12
 DLT-12M

 Maximum Air Pressure
 100 psi
 6.9 bar

 Thrust Force @ 80psi/5.5bar
 62 lbs.
 275 N

 Weight (Basic Unit)
 3.21 lbs.
 1.46 kg

 Additional Weight per Stroke
 0.12 lbs/in.
 2.2g/mm

 Cylinder Bore Diameter
 1"
 25mm

 Shaft Diameter
 0.472"
 12mm

w↓ M

Specifications	DLT-16	DLT-16M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	62 lbs.	275 N
Weight (Basic Unit)	. 4.81 lbs.	2.03 kg
Additional Weight per Stroke	0.20 lbs./in.	3.5g/mm
Cylinder Bore Diameter	1"	25mm
Shaft Diameter	0.630"	16mm

#### **Accessory Mounting Technical Data**

![](_page_452_Figure_11.jpeg)

DLT SERIES

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

![](_page_453_Figure_0.jpeg)

![](_page_453_Picture_1.jpeg)

![](_page_453_Figure_2.jpeg)

How t	o Order: Basic U	nit	Accessories: (Order Separately)	DLT-20M	DLT-25M	QTY/THRUSTER
DACIC			SHOCK/STOP ACCESSORIES			
DAJIC	MODEL METRIC STT	LE SINUKE SHAFIN	Universal Mounting Kit			
			(Shock, Stop or Sensor)	<b>OSAK-061</b>	<b>OSAK-063</b>	1, 2, 3 or 4
UL	▋▕▋▏▌		Urethane Bumper/Clamp Collar Kit	<b>OSAK-062</b>	<b>OSAK-064</b>	1
		7 - 7 -	Shock Absorber (adjustable dampening)*	SHOK-029	SHOK-029	1, 2, 3 or 4
	SIZE BEAR	ING VITON [®] SEA	LS Adjustable Hard Stop*	DLT-1023	DLT-1023	1, 2, 3 or 4
			INDUCTIVE SENSOR ACCESSORIES [†]			
SIZE	20, 25		Inductive Sensor PNP Qk. Disconnect*	<b>OISP-011</b>	<b>OISP-011</b>	1 or 2
METRIC	м		Inductive Sensor NPN Qk. Disconnect*	OISN-011	<b>OISN-011</b>	1 or 2
METHIO			Quick Disconnect 2M Cable Length ⁺	CABL-010	CABL-010	1 or 2
STYLE	L Long body thruster with bui	lt-in repairable cylinder	Quick Disconnect 5M Cable Length ⁺	CABL-013	CABL-013	1 or 2
READING	P Linear ball bearings		MAGNETIC SENSOR ACCESSORIES ^{†**}			
DEANING	<b>C</b> Composite hushings		Magneto Resistive Sensor PNP Qk. Disc. [†]	OHSP-017	OHSP-017	1 or 2
			Magneto Resistive Sensor NPN Qk. Disc. ⁺	OHSN-017	OHSN-017	1 or 2
STROKE	(inches)		Quick Disconnect 2M Cable Length ⁺	CABL-010	CABL-010	1 or 2
DLI-20	<b>1-6</b> @ 1" increments	Custom strokes available.	Quick Disconnect 5M Cable Length ⁺	CABL-013	CABL-013	1 or 2
DLI-25	I-7 @ 1 ^a increments	Please consult lactory.	PNEUMATIC ACCESSORIES			
STROKE	(mm)		1/8 NPT Telescopic Airlines (up to 6")	0TAL-039	0TAL-039	1, 2,3 or 4
DLT-20M	25, 50, 75, 100, 125, 160		1/8 NPT Telescopic Airlines (up to 12")	OTAL-040	<b>OTAL-040</b>	1, 2,3 or 4
DLT-25M	<b>25, 50, 75, 100, 125, 160,</b> 1	75	1/8 NPT Adjustable Flow Control	VLVF-004	VLVF-004	1 or 2
VITON®	V Viton [®] seals		G1/8 Telescopic Airlines (up to 160mm)	0TAL-045	0TAL-045	1, 2,3 or 4
mon			G1/8 Telescopic Airlines (up to 300mm)	0TAL-046	0TAL-046	1, 2,3 or 4
SHAFTING	S Corrosion resistant shafting		G1/8 Adjustable Flow Control	VLVF-005	VLVF-005	1 or 2
			Cylinder Seal Repair Kit	SLKT-104	SLKT-104	1
	SAMPLE ORDER: D	JLT-2U-L-B-2-V	Viton [®] Cylinder Seal Repair Kit	SLKT-104V	SLKT-104V	1
E	x: Thruster, Size 20, Long Body Style, Linear B	all Bushings, 2 Inch Stroke, Viton® Seals	*Requires Universal Mounting Kit *Sensor and cable sold	separately **Piston mag	net standard	

**DLT SERIES** 

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

![](_page_454_Picture_0.jpeg)

#### LONG BODY THRUSTER DLT -20M, 25M -L **BUILT-IN REPAIRABLE CYLINDER**

![](_page_454_Figure_2.jpeg)

Specifications	<b>DLI-20</b>	DLI-201VI
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	140 lbs.	622 N
Weight (Basic Unit)	12.0 lbs.	5.5 kg
Additional Weight per Stroke	0.31 lbs./in.	5.5g/mm
Cylinder Bore Diameter	1-1/2"	38mm
Shaft Diameter	0.787"	20mm

#### Accessory Mounting Technical Data

![](_page_454_Figure_5.jpeg)

#### Shock Absorbers and Flow Controls are recomme nded for nearly all applications (W) in this range use Single Shock in both directions (W) in this range use Ure

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications	DLT-25	DLT-25M
Maximum Air Pressure	100 psi	6.9 bar
Thrust Force @ 80psi/5.5bar	140 lbs.	622 N
Weight (Basic Unit)	17.4 lbs.	7.9 kg
Additional Weight per Stroke	0.47 lbs./in.	8.4g/mm
Cylinder Bore Diameter	1-1/2"	38mm
Shaft Diameter	0.984"	25mm

12.7mm 44.5

12.7 23.4 17.0 14.7 91.4

íŕ 4.53

![](_page_454_Figure_11.jpeg)

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

![](_page_455_Figure_0.jpeg)

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

G

Teflon® Based Grease GLUE

Super Bonder  $\Rightarrow$ 

-(•)

Third Angle Projection

www.comoso.com

0

Lightweight Machine Oil

KRYTOX

Krytox™ Lubricant

SK

Seal Kit Items Thread Locker

![](_page_456_Picture_0.jpeg)

#### Item Qty Name

01	1	Body
02	4	Bushing
03	1	Tooling Plate
04	1	Nut, Stover
05	1	Piston Rod
06	1	Piston
07	1	Cap, Plug End
08	1	Cap, Rod End
09	2	Shock Pad, Urethane
10	1	Guide Shaft
11	2	Collar, Split
15	1	Shock Pad, Urethane
40	1	Magnet

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices. **NOTE:** For accessory mounting, see product data sheets

![](_page_456_Figure_5.jpeg)

![](_page_456_Figure_6.jpeg)

![](_page_456_Picture_7.jpeg)

## **Externally Powered Thruster Slide**

#### **Cylinder options:**

Externally powered thruster slides are available in a wide range of cylinder options. Choose from replaceable/disposable, replaceable with adjustable cushions, NFPA with adjustable cushions, ISO/metric, VDMA, Locking VDNA, or non-powered for customer supplied cylinders.

#### DIRECTCONNECT mounting patterns:

These slides have DIRECTCONNECT mounting patterns that connect to other slides without the need for adapter plates.

#### Mounting Information:

#### Mounts and operates in any orientation

![](_page_457_Figure_8.jpeg)

Body can be back mounted with screws from the front using the clearance and counterbored **DIRECTCONNECT** pattern and located with dowel holes.

![](_page_457_Picture_10.jpeg)

![](_page_457_Figure_11.jpeg)

Body mounts with screws and locate with slip fit dowel pin holes on side using DIRECTCONNECT mounting patterns.

![](_page_457_Picture_13.jpeg)

![](_page_457_Picture_14.jpeg)

Payload attaches to tooling plate DIRECTCONNECT mounting pattern with screws and locates using slip fit dowel pin holes.

#### **Technical Specifications:**

**Pneumatic Specifications** Pressure Operating Range* Cylinder Type Dynamic Seals Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

#### **Air Quality Requirements**

Air Filtration	-
Air Lubrication	
Air Humidity	

#### 40 Micron or Better Not Necessary** Low Moisture Content (dry)

+ million cycles[†] No No

#### **Temperature Operating Range**

Buna-N Seals (standard) -30°~180° F -35°~80° C -30°~150° C -20°~300° F Viton[®] Seals (optional)

#### **Maintenance Specifications**

Expected Life	
Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycl
Field Repairable	No
Seal Repair Kits Available	No
•	

#### **Application Restrictions**

Flow controls, shock absorbers and urethane bumpers recommended for nearly all applications. Use composite bushing in dirty or gritty environments.

Never use silicone based lubricants with composite bushings. *Higher pressure possible. Consult factory with application details. **Addition of lubrication will greatly increase service life [†]See Maintenance Section

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![](_page_458_Picture_0.jpeg)

 The tooling plate is attached to two hardened steel shafts which are supported by and move in four linear bushings located in the body.

#### **Designed and manufactured in the USA**

See **4.66** 

![](_page_459_Figure_0.jpeg)

![](_page_459_Picture_1.jpeg)

M3 x 6 DP Clr & C'bore for M3 Clr & C'bore for M3

![](_page_459_Figure_2.jpeg)

		OF DIA.	NY SIZE	NETDIA		RAS	IC III	NIT D	) III I	NSIO	NS				STA	NDARD MOUNTING
MODEL #	ABI	B	SU St	D	E	F	G	н	J	K	L	м	R	S	DΛ	Imperial (inches)
DLT-06 DLT-08	0.563 0.563	2.00 2.50	0.236 0.315	2.16 2.16	0.783 0.783	0.88 0.88	0.66 0.41	1.980 2.470	.990 1.235	0.875 0.875	.365 .365	0.470 0.470	.390 .390	1.375 1.750	DB DQ	.750 .0940 x .078 DP
DLT-06M DLT-08M	16 16	50.8 64.0	6.0 8.0	54.9 54.9	19.9 19.9	22.4 22.4	16.7 10.4	50.3 62.7	25.1 31.4	22.2 22.2	9.3 9.3	11.9 11.9	9.9 9.9	34.93 44.45	DK DS DT	Clr & C'bore for #4 Clr & C'bore for #4

How to	o Order: Basic Un	nit	Accessories: (Order Separately)	DLT-06M	DLT-08M	QTY/THRUSTER
BAS	SIC MODEL METRIC S	TYLE STROKE	SHOCK/STOP ACCESSORIES Universal Mounting Kit (Shock or Stop) Shock Absorber (2 Max. on <b>-06</b> )* Adjustable Hard Stop* Urethane Bumper/Stop Collar Kit	OSAK-069 Shok-030 DLT-0623 OSAK-067	OSAK-070 SHOK-030 DLT-0623 OSAK-068	1, 2, 3, or 4 1, 2, 3, or 4 1, 2, 3, or 4 1, 2, 3, or 4 1 or 2
	SIZE BE	ARING SHAFTING	INDUCTIVE SENSOR ACCESSORIES [†]			
			Inductive Sensor Mounting Kit	<b>OSMK-076</b>	<b>OSMK-077</b>	1
			Inductive Sensor PNP Qk. Disconnect †	<b>OISP-014</b>	<b>OISP-014</b>	1
SIZE	06, 08	Oversized guide shafts available.	Inductive Sensor NPN Qk. Disconnect †	OISN-014	OISN-014	1
METRIC	м	Please consult factory.	Quick. Disconnect 2M Cable Length [†]	CABL-010	CABL-010	1
			Quick. Disconnect 5M Cable Length †	CABL-013	CABL-013	1
STYLE	T Replaceable cylinder U Non-powered unit (Without cylin	nder. Directly mounts replaceable style cylinders)	MAGNETIC SENSOR ACCESSORIES**			
BEARING	Composite bushings		Magneto Resistive Sensor PNP Qk. Disc. †	OHSP-005	OHSP-005	1 or 2
OTDOVE			Magneto Resistive Sensor NPN Qk. Disc. †	OHSN-005	OHSN-005	1 or 2
DIT OF		Custom strokes available	Quick. Disconnect 2M Cable Length †	CABL-010	CABL-010	1 or 2
DLT-08	.5, 1, 1.5, 2, 2.5, 3, 4, 5, 6, 7	<b>Please consult factory.</b>	Quick. Disconnect 5M Cable Length $^{\rm t}$	CABL-013	CABL-013	1 or 2
STROKE	(mm)		PNEUMATIC ACCESSORIES			
DLT-06M	10, 25, 40, 50, 75, 100, 125	, 160	#10-32 Adjustable Flow Control (Imperial) ⁺⁺	VLVF-007	VLVF-007	1 or 2
DLT-08M	10, 25, 40, 50, 75, 100, 125	, 160, 175, 200	M5 Adjustable Flow Control (Metric) ⁺⁺	VLVF-008	VLVF-008	1 or 2
SHAFTING	S Corrosion resistant shafting		#10-32 Retract Port Standoff (Imperial)	PLFT-070	PLFT-070	1
	_		M5 Retract Port Standoff (Metric)	PLFT-071	PLFT-071	1
	SAMPLE ORDER: DL	T-08M-T-B-25	*Sensor and cable sold separately *Piston magnet standard	**Requires Port Standoff		

**DLT SERIES** 4.58

# DIRECTCONNEC

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Ex: Thruster, Size 8 Metric, Replaceable Cylinder, Linear Ball Bushings, 25mm Stroke

![](_page_460_Picture_0.jpeg)

![](_page_460_Figure_1.jpeg)

F=Externally applied force (lbs. or N) W=Weight of payload (lbs. or N) F+W=Total deflection force (lbs. or N) M=Maximum moment (in.-lb. or N-m)

![](_page_460_Figure_3.jpeg)

Specifications	DLT-06	DLT-06M
Maximum Air Pressure	100 psi	7 bar
Thrust Force @ 80psi/5.5 bar	20 lbs.	111 N
Weight (Basic Unit)	0.53 lbs.	0.24 kg
Additional Weight Per Stroke	0.05 lb/in	0.88 g/mm
Cylinder Bore Diameter	0.563"	16 mm
Shaft Diameter	0.236"	6 mm
Max (M) Vertical Motion	5 inIbs.	0.6 N-m

#### Accessory Mounting Technical Data

![](_page_460_Figure_6.jpeg)

#### LINEAR THRUSTER DLT -06M, 08M -T, U **REPLACEABLE CYLINDER**

![](_page_460_Figure_8.jpeg)

Shock Absorbers and Flow Controls are recommended for nearly all applications Use Single Shock in both directions Use Double Shocks in both directions Use Bumpers or Cushioned Cylinder

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications	DLT-08	DLT-08M
Maximum Air Pressure	100 psi	7 bar
Thrust Force @ 80psi/ 5.5 bar	20 lbs.	89 N
Weight (Basic Unit)	0.88 lbs.	0.40 kg
Additional Weight Per Stroke	0.07 lb/in	1.43 g/mm
Cylinder Bore Diameter	0.563"	16 mm
Shaft Diameter	0.315"	8.0 mm
Max (M) Vertical Motion	10 inIbs.	1.3 N-m

![](_page_460_Figure_15.jpeg)

	A	В	C	D	E	F
DLT-06	.236"	.47	.250	.31	.27	1.82
DLT-08	.236"	.63	.250	.31	.27	1.82
DLT-06M	6 mm	12.0	6.4	7.9	6.9	46.2
DLT-08M	6 mm	16.0	6.4	7.9	6.9	46.2

#### LINEAR THRUSTER DLT -10M, 12M, 16M -T, A **REPLACEABLE CYLINDER WITH OR Ŵ/O ADJ. AIR CUSHIONS**

![](_page_461_Picture_1.jpeg)

![](_page_461_Figure_2.jpeg)

**BASIC UNIT DIMENSIONS** 

H

3.490

3.985

4.735

88.6

101.2

120.3

J

1.740

1.985

2.360

44.2

50.4

59.9

K

1.178

1.615

1.615

29.9

41.0

41.0

L

.584

.802

.802

14.8

20.4

20.4

М

.813

.813

.813

20.7

20.7

20.7

S

2.375

2,750

3.250

60.33

69.85

82.55

#### DIRECTCONNECT DIMENSIONS STANDARD MOUNTING PATTERN FOR ALL SIZES

-DD

0

	Imperial (inches)	Metric (mm)
DA	.375	9.5
DB	.750	19.1
DC	1.500	38.1
DD	.1880 X .25 DP	5 mm H7 X 6 DP
DE	#10-32 X .34 DP	M5 X 8.5 DP
DF	Clr & C'bore for #10	Clr & C'bore for M5
DG	Clr & C'bore for #10	Clr & C'bore for M5
DQ	.0940 x .078 DP	3H7 x 2 DP
DS	Clr & C'bore for #4	Clr & C'bore for M3

How to Order: Basi	c Unit	Accessories: (Order Separately)	DLT-10M	DLT-12M	DLT-16M (	TY/THRUSTER
BASIC MODEL MET	RIC STYLE STROKE	SHOCK/STOP ACCESSORIES Universal Mounting Kit (Shock, Stop or Sensor) Urethane Bumper/Clamp Collar Kit Urethane Bumper/Clamp Collar Kit (-10M) Urethane Bumper/Clamp Collar Kit (-12M) Shock Absorber* Adjustable Hard Stop*	0SAK-055 0SAK-056 0SAK-065 SH0K-028 DLT-1023	OSAK-057 OSAK-058 OSAK-066 SHOK-010 DLT-1023	OSAK-059 OSAK-060 SHOK-010 DLT-1023	1, 2, 3 or 4 1 or 2 1 or 2 1 or 2 1, 2, 3 or 4 1, 2, 3 or 4
SIZE 10, 12, 16 METRIC M STYLE T Replaceable cylinder	Oversized guide shafts available. Please consult factory. w/o adjustable air cushions (Not avail. in metric)	Inductive Sensor ACCESSORIES' Inductive Sensor PNP Qk. Disconnect* Quick. Disconnect 2M Cable Length † Quick. Disconnect 5M Cable Length †	OISP-011 OISN-011 CABL-010 CABL-013	0ISP-011 0ISN-011 CABL-010 CABL-013	0ISP-011 0ISN-011 CABL-010 CABL-013	1 or 2 1 or 2 1 or 2 1 or 2 1 or 2
BEARING B Linear ball bearings C Composite bushings STROKE (inches)		MAGNETIC SENSOR ACCESSORIES [†] ** Magneto Resistive Sensor PNP Qk. Disc. [†] Magneto Resistive Sensor NPN Qk. Disc. [†] Quick. Disconnect 2M Cable Length [†] Ouick. Disconnect 5M Cable Length [†]	OHSP-005 OHSN-005 CABL-010 CABL-013	0HSP-005 0HSN-005 CABL-010 CABL-013	0HSP-005 0HSN-005 CABL-010 CABL-013	1 or 2 1 or 2 1 or 2 1 or 2
DLI-10 <b>1-12</b> @ 1" increments DLT-12 <b>1-16</b> @ 1" increments DLT-16 <b>1-20</b> @ 1" increments STROKE (mm)	Custom strokes available. Please consult factory.	PNEUMATIC ACCESSORIES 1/8 NPT Telescopic Airlines (up to 6") 1/8 NPT Telescopic Airlines (up to 12") 1/8 NPT Telescopic Airlines (up to 18")	OTAL-039 OTAL-040 OTAL-041	OTAL-039 OTAL-040 OTAL-041	0TAL-039 0TAL-040 0TAL-041	1, 2, 3 or 4 1, 2, 3 or 4 1, 2, 3 or 4
DLT-10M         25, 50, 80, 100, 125,           DLT-12M         25, 50, 80, 100, 125,           DLT-16M         25, 50, 80, 100, 125,           SHAFTING         S Corrosion resistant s	160, 200, 250, 300 160, 200, 250, 300, 320, 360, 400 160, 200, 250, 300, 320, 360, 400, 500 hafting	1/8 NPT Telescopic Airlines (up to 24") 1/8 NPT Adjustable Flow Control G1/8 Telescopic Airlines (up to 160mm) G1/8 Telescopic Airlines (up to 300mm) C1/8 Telescopic Airlines (up to 300mm)	OTAL-042 VLVF-004 OTAL-045 OTAL-046 OTAL-047	OTAL-042 VLVF-004 OTAL-045 OTAL-046 OTAL-047	OTAL-042 VLVF-004 OTAL-045 OTAL-046	1, 2, 3 or 4 1 or 2 1, 2, 3 or 4 1, 2, 3 or 4 1, 2, 3 or 4
SAMPLE ORDE Ex: Thruster, Size 10 Metric, Replaceable Cylinder	R: DLT-10M-A-B-25 w/Adjustable Air Cushions, Linear Ball Bushings, 25mm Stroke	G1/8 Telescopic Airlines (up to 450mm) G1/8 Adjustable Flow Control *Requires Universal Mounting Kit "Sensor and cable sol	OTAL-048 VLVF-005 d separately **P	OTAL-048 VLVF-005 iston magnet stand	OTAL-048 VLVF-005 ard	1, 2, 3 or 4 1, 2, 3 or 4 1 or 2

BODY SIZE

C

.375

.472

.630

9.5

12.0

16.0

BORE DIA.

B

3.50

4.00

4.75

88.9

101.6

120.7

A

3/4

**1**¹/16

**1**¹/16

20

25

25

**MODEL #** 

DLT-10

DLT-12

DLT-16

DLT-10M

DLT-12M

DLT-16M

SHAFT DIA

D

2.91

2.88

2.88

88.0

91.5

91.5

Е

1.313

1.313

1.375

33.4

33.4

34.9

F

1.19

1.63

1.63

30.2

41.4

41.4

G

.82

.82

.76

20.8

20.8

19.3

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![](_page_462_Picture_0.jpeg)

#### LINEAR THRUSTER DLT -10M, 12M, 16M -T, A **REPLACEABLE CYLINDER WITH OR W/O ADJ. AIR CUSHIONS**

'n і. П Г

![](_page_462_Figure_2.jpeg)

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

DLT-16M

33.3

11.1 11.4 8.6 14.7

11.1mm

91.4

28.4

#### LINEAR THRUSTER DLT -20, 25 -T, A Replaceable Cylinder with or W/O Adj. Air cushions

![](_page_463_Picture_1.jpeg)

![](_page_463_Figure_2.jpeg)

STYLE T Replaceable cylinder w/o adjustable air cushions

**BEARING B** Linear ball bearings

DLT-20 1-24 @ 1" increments

DLT-25 1-26 @ 1" increments

SHAFTING S Corrosion resistant shafting

STROKE (inches)

C Composite bushings

A Replaceable cylinder with adjustable air cushions

SAMPLE ORDER: DLT-20-A-B-8

Ex: Thruster, Size 20, Replaceable Cylinder w/Adjustable Air Cushions, Linear Ball Bushings, 8 inch Stroke

Custom strokes available. Please consult factory.

1/8 NPT Adjustable Flow Control

MAGNETIC SENSOR ACCESSORIES[†] **

Magneto Resistive Sensor PNP Qk. Disc.¹

Magneto Resistive Sensor NPN Qk. Disc.¹

Quick. Disconnect 2M Cable Length 1

Quick. Disconnect 5M Cable Length ⁺

1/8 NPT Telescopic Airlines (up to 6")

1/8 NPT Telescopic Airlines (up to 12")

1/8 NPT Telescopic Airlines (up to 18")

1/8 NPT Telescopic Airlines (up to 24")

PNEUMATIC ACCESSORIES

OHSP-005

OHSN-005

CABL-010

CABL-013

**OTAL-039** 

OTAL-040

**OTAL-041** 

**OTAL-042** 

**VLVF-004** 

*Requires Universal Mounting Kit *Sensor and cable sold separately **Piston magnet standard

OHSP-005

OHSN-005

CABL-010

CABL-013

**OTAL-039** 

**OTAL-040** 

**OTAL-041** 

**OTAL-042** 

VLVF-004

1 or 2

1 or 2

1 or 2

1 or 2

1,2,3 or 4

1,2,3 or 4

1,2,3 or 4

1,2,3 or 4

1 or 2

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

![](_page_464_Picture_0.jpeg)

#### LINEAR THRUSTER DLT -20, 25 -T, A REPLACEABLE CYLINDER WITH OR W/O ADJ. AIR CUSHIONS

![](_page_464_Figure_2.jpeg)

F=Externally applied force (lbs. or N) W=Weight of payload (lbs. or N) F+W=Total deflection force (lbs. or N)

Specifications	DLT-20
Maximum Air Pressure	100 psi
Thrust Force @ 80psi/5.5bar	140 lbs.
Weight (Basic Unit -T, -A)	12.7 lbs.
Additional Weight per Stroke	0.38 lbs./in.
Cylinder Bore Diameter	1-1/2"
Shaft Diameter	0.787"

w

#### 

![](_page_464_Figure_6.jpeg)

Use Double Shocks in both directions Use Single Shock in both directions Use Bouble Shocks in both directions Use Single Shock in both directions Use Boupers or Cushioned C

Shaded shock absorption ranges of horizontal payload (W) @ 80psi, flow controls fully open. For vertical applications do not exceed 1/2 of the recommended payload due to the additional acceleration effect of gravity.

Specifications	DLT-25
Maximum Air Pressure	100 psi
Thrust Force @ 80psi/5.5bar	140 lbs.
Weight (Basic Unit -T, -A)	17.6 lbs.
Additional Weight per Stroke	0.53 lbs./in.
Cylinder Bore Diameter	1-1/2"
Shaft Diameter	0.984"

#### Accessory Mounting Technical Data

![](_page_464_Figure_11.jpeg)

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#### LINEAR THRUSTER DLT -10M, 12M, 16M -N, U **REPAIRABLE (NFPA STYLE) CÝLINDÉR W/FIXED AIR CUSHIONS**

![](_page_465_Picture_1.jpeg)

1 or 2

![](_page_465_Figure_2.jpeg)

SIZE

ŝ

4.64

![](_page_465_Figure_4.jpeg)

![](_page_466_Picture_0.jpeg)

#### LINEAR THRUSTER DLT -10, 12, 16 -N, U REPAIRABLE (NFPA STYLE) CYLINDER W/FIXED AIR CUSHIONS

![](_page_466_Figure_2.jpeg)

![](_page_466_Figure_3.jpeg)

DIRECTCONNECT

54 H H S

4.65

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#### LINEAR THRUSTER DLT -20M, 25M -N, R, U REPAIRABLE (NFPA/VDMA) CYLINDER W/ADJ. AIR CUSHIONS

![](_page_467_Picture_1.jpeg)

![](_page_467_Figure_2.jpeg)

				DEI-ZOIM	DEI-ZUIII	QI I/INNUSIEN
BAS	SIC MODEL METRIC S	STYLE STROKE	SHOCK/STOP ACCESSORIES Universal Mounting Kit (Shock, Stop or Sensor) Urethane Bumper/Clamp Collar Kit Shock Absorber (adjustable dampening)* Adjustable Hard Stop*	OSAK-061 OSAK-062 SH0K-029 DLT-1023	0SAK-063 0SAK-064 SH0K-029 DLT-1023	1, 2, 3 or 4 1 or 2 1, 2, 3 or 4 1, 2, 3 or 4
	SIZE BE	ARING SHAFTING	Inductive Sensor PNP Qk. Disconnect* Inductive Sensor NPN Qk. Disconnect* Quick. Disconnect 2M Cable Length †	OISP-011 OISN-011 CABL-010	OISP-011 OISN-011 CABL-010	1 or 2 1 or 2 1 or 2
SIZE	20, 25 M	Oversized guide shafts available. Please consult factory.	Quick. Disconnect 5M Cable Length † Cable Extension Cord 1M Length Cable Extension Cord 2M Length	CABL-013 CABL-015 CABL-016	CABL-013 CABL-015 CABL-016	1 or 2 1 or 2 1 or 2
STYLE	N Repairable NFPA/VDMA cylir R Repairable locking VDMA cy U Non-powered unit (Without cylir	nder w/adjustable air cushions linder w/adjustable air cushions nder. NFPAVDMA cylinder mounting kits available)	MAGNETIC SENSOR ACCESSORIES: ** Magneto Resistive Sensor PNP Qk. Disc.† Magneto Resistive Sensor NPN Qk. Disc.† Quick. Disconnect 2M Cable Length † Quick. Disconnect 2M Cable Length †	0HSP-020 0HSN-020 CABL-010 CABL-012	0HSP-020 0HSN-020 CABL-010 CABL-012	1 or 2 1 or 2 1 or 2
BEARING	<b>B</b> Linear ball bearings <b>C</b> Composite bushings		Cable Extension Cord 1M Length Cable Extension Cord 2M Length	CABL-015 CABL-015 CABL-016	CABL-015 CABL-015 CABL-016	1 or 2 1 or 2 1 or 2
Stroke DLT-20 DLT-25	(inches) <b>1-24</b> @ 1" increments <b>1-26</b> @ 1" increments	Custom strokes available. Please consult factory.	NFPA Cylinder Mounting Kit (-U only) 1/8 NPT Telescopic Airlines (up to 6") 1/8 NPT Telescopic Airlines (up to 12") 1/8 NPT Telescopic Airlines (up to 12")	0DLT-003 0TAL-039 0TAL-040 0TAL-041	0DLT-003 0TAL-039 0TAL-040 0TAL-041	1 1, 2, 3 or 4 1, 2, 3 or 4 1, 2, 3 or 4
<b>Stroke</b> DLT-20M DLT-25M	(mm) 25, 50, 80, 100, 125, 160, 20 25, 50, 80, 100, 125, 160, 20	00, 250, 300, 320, 360, 400, 500 00, 250, 300, 320, 360, 400, 500	1/8 NPT Telescopic Airlines (up to 10') 1/8 NPT Telescopic Airlines (up to 24") 1/4 NPT Adjustable Flow Control VDMA Cylinder Mounting Kit ( <b>-U</b> Metric only) 61/8 Telescopic Airlines (up to 160mm)	0TAL-041 0TAL-042 VLVF-006 0DLT-004 0TAL-045	0TAL-041 0TAL-042 VLVF-006 0DLT-004 0TAL-045	1, 2, 3 or 4 1, 2, 3 or 4 1 or 2 1 1, 2, 3 or 4
SHAFTING	S Corrosion resistant shafting		G1/8 Telescopic Airlines (up to 300mm) G1/8 Telescopic Airlines (up to 450mm) G1/8 Telescopic Airlines (up to 600mm) G1/8 Adjustable Flow Control	0TAL-046 0TAL-047 0TAL-048 VLVF-005	0TAL-046 0TAL-047 0TAL-048 VLVF-005	1, 2, 3 or 4 1, 2, 3 or 4 1, 2, 3 or 4 1, 2, 3 or 4 1 or 2
Ex: Thruster, Siz	SAMPLE ORDER: D ee 20, Repairable NFPA Cylinder w/Adjustable.	LT-20-N-B-12 Air Cushions, Linear Ball Bushings, 12 Inch Stroke	1/8 NPT Adjustable Flow Control G1/8 Male to 1/8 NPT Adapter *Requires Universal Mounting Kit 'Sensor and cable sold se	VLVF-004 PLFT-025 parately. **Piston magne	VLVF-004 PLFT-025 et standard	1 or 2 1 or 2

4.66

Please see back cover for DE-STA-CO Global Locations. www.destaco.com


#### LINEAR THRUSTER DLT -20M, 25M -N, R, U REPAIRABLE (NFPA/VDMA) CYLINDER W/ADJ. AIR CUSHIONS



#### **Accessory Mounting Technical Data**



Urethane Bumpers & Clamp Collars • Urethane Bumpers for shock absorption and noise

- dampening • Adjustable Clamp Collars for end of stroke position
- adjustment • Kit contains (2) Collars and (2) Shock Pads for



**Inductive Proximity Sensors** 

**Ouick Disconnect Cable** 

Threaded Quick Disconnect with built-in LED output

 Threaded coupling with knurled head for secure electrical connections

8mm diameter

• PNP and NPN available

• 2 meter cable length

 5 meter cable length
 Quick disconnect cable extensions cords available

in 1 or 2 meter lengths





**Magneto Resistive Sensors** 

Quick Disconnect with built-in LED output

**Universal Mounting Kit** 

Clamp-on Mounting Kit included

#### PNP and NPN available

- Straight Quick Disconnect Cable
   Threaded coupling with knurled head for security
- Threaded coupling with knurled head for secure electrical connections
- 2 meter cable length
- 5 meter cable length
  Quick disconnect cable extensions cords
- available in 1 or 2 meter lengths

 NFPA/VDMA Cylinder Mounting Kit
 Used to mount standard sleeve-nut face mounted NFPA and VDMA cylinders to non-powered units



**Adjustable Hard Stops** 

- For precision (+/-.001") end point positioning
- Allows for end stop position adjustment independent of
- shock absorber hard stop
- Allen wrench adjustable
- **Shock Absorbers**
- Full stroking piston rod
- Built-in hard stop
  Position adjustable
- Adjustable

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Dampening

**Telescoping Airlines** 

- Eliminate flexing air lines
- Self aligning air tube design extends useful seal life

+ MAX

STROKE

- Modular stackable design. Up to (4) modules can be stacked
- 1/8 NPT or G1/8 pipe threads
   (2) user air ports per module
- (2) user air ports per module
- Flow Controls
- Thumb screw adjust with locking nut for adjusting cylinder speed
- 1/4 NPT, G1/8 pipe threads or 1/8 NPT

	A	В	C	Е	F	G	H
DLT-20	.500"	1.50	.500	67	.577	3.60	1.38
DLT-25	.500"	1.75	.500	.67	.577	3.60	1.38
DLT-20M	12.7mm	38.1	12.7	17.0	14.7	91.4	35.1
DLT-25M	12.7mm	44 5	12.7	17.0	14 7	91.4	35.1

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#### **DLT-T, A, N, R, U Series Exploded View**

Item Qty Name

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#### LOCKING CYLINDER -R **CYLINDER VALVE** 5 WAY, 3 POS (external pilot) PLUMBING DIAGRAM ⊣ Main Supply **₫**\$ $\Phi \Phi$ 0 -EXHAUST PORT G1/8 ộ $\oplus$ Auxiliary 占 Supply LOCK VALVE 3 WAY, 2 POS (internal pilot) 4

- Lock valve must be maintained energized during cylinder motion, otherwise lock is engaged and cylinder valve shifts to mid position.
- 2) Cylinder valve must be maintained energized during extend or retract. Also, keep energized at end of stroke until change of direction is desired.
- 3) Mid-position of 5/3 cylinder valve may be pressurized outlets if the combinaton of pressure load on the cylinder and inertia effects of the attached load do not exceed the holding force rating of the locking device, including allowance for wear.
- D0 NOT use cylinder lines for any logic functions - pressure levels vary too much.

#### Item Qty Name

01	1	Body, Externally Powered
02	1	Cylinder
03	1	Tooling Plate
04	1	Shaft, Extender
05	4	Bushing
06	2	Guide Shaft
30	1	Nut. Stover

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

**NOTE:** For accessory mounting, see product data sheets





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# Mini Ball Rail Slides DLM DIRECTCONNECT Modular Series



- Multiple Air Port Positions: Tapped air ports on each side, rear and bottom standard.
- Manifold Air Porting: Bottom air ports can be manifold O-ring sealed.
- **Stroke Adjustments:** Retract and extend adjustments for precise positioning with infinite stroke adjustability.
- Double Bearing Option: Longer strokes available with double bearings for greater load and moment capacity.



- Multiple Mounting Locations: DIRECTCONNECT[™] tapped and dowel mounting, on tool plate and body.
- Thru Mounting: Both side thru-body mounting. DIRECTCONNECT[™] thru tapped and dowel mounting, on tool plate and body.
- **Sensing:** Adjustable Magnetoresistive Sensors thru full stroke range. Can sense up to 8 positions.
- Precision Hard Stop Option: Delrin[®] extend and retract internal stops available as an option for increased repeatability.

#### **Mounting Information:**

slip fit dowel holes.

design for new projects.

Note: The new DLM series replaces our MPS

product line. The MPS series information is still available on our website and are available for

sale. We encourage you to consider the new DLM



**Technical Specifications:** 

Pneumatic Specifications Pressure Operating Range Cylinder Type	Imperial Metric 20-100 psi 1.4-7 ba Double Acting	ar		
Dynamic Seals Valve Required to Operate	Internally Lubricated Buna 4-way, 2-position	-N		
<b>Air Quality Requirements</b> Air Filtration Air Lubrication Air Humidity	40 Micron or Better Not Necessary* Low Moisture Content (dry	<b>y</b> )		
Temperature Operating Range Buna-N Seals (standard)-30°~180° F-35°~80° C				
Maintenance Specifications				
Normal Application w/ Preventative Maintenand Field Repairable	ce 5 million cycles to 10+ million cycles* Yes			
Seal Repair Kits Available Yes				
<ul> <li>Application Restrictions</li> <li>Machining operations generating chips</li> <li>Environments with loose particulate</li> </ul>				

*Addition of lubrication will greatly increase service life.

**DLM SERIES** 

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and dowel holes.



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**SERIES** 4.71







Ex: DLM-07M Mini Ball Rail Slide, -12 Body Size, 10mm Stroke, Precision Stops

**DLM SERIES** 



Specifications	DLM-07M	-12
Thrust Force <b>F</b> @ 100 psi, 7 bar	15 lbs.	66 N
Max. Stroke	0.50 in.	12 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	0.28 lbs.	0.13 Kg
Maximum Payload W	1.0 lbs.	0.45 Kg
Maximum Payload (-P Option)	0.5 lbs.	0.23 Kg
Cylinder Bore Ø	0.437 in.	11 mm
Temperature Range	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.07 sec.	
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-way, 2-p	osition

#### MINI BALL RAIL SLIDE DLM-07M-12 DIRECTCONNECT MODULAR SERIES



Flow Controls are recommended for nearly all applications

Loading Capacity DLM-07M-12	Static	Dynamic
Maximum Tensile T	110 lbs. [490 N]	67 lbs. [301 N]
Maximum Compressive C	110 lbs. [490 N]	67 lbs. [301 N]
Maximum Moment Mx	45 in1bs. [5.1 Nm]	27 in1bs. [3.1 Nm]
Maximum Moment My	28 in1bs. [3.2 Nm]	16 inIbs. [1.9 Nm]
Maximum Moment Mz	28 in1bs. [3.2 Nm]	16 inIbs. [1.9 Nm]
Distance to Bearing Centerline ${\rm L}$	2.10 in.	[53 mm]

#### **Accessory Mounting Technical Data**









Ex: DLM-07M Mini Ball Rail Slide, -25 Body Size, 15mm Stroke, Double Ball Bearings



Specifications	DLM-07N	-25
Thrust Force <b>F</b> @ 100 psi, 7 bar	15 lbs.	66 N
Max. Stroke	1.00 in.	25 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	0.35 lbs.	0.16 Kg
Maximum Payload W	1.0 lbs.	0.45 Kg
Maximum Payload (-P Option)	0.5 lbs.	0.23 Kg
Cylinder Bore Ø	0.437 in.	11 mm
Temperature Range	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.07 :	sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-wav. 2-p	osition

#### **MINI BALL RAIL SLIDE DLM-07M-25** DIRECTCONNECT MODULAR SERIES



Flow Controls are recommended for nearly all applications

Loading Capacity	Static	Dynamic	
DLM-07M-25			
Maximum Tensile <b>T</b>	110 lbs. [490 N]	67 lbs. [301 N]	
Maximum Compressive C	110 lbs. [490 N]	67 lbs. [301 N]	
Maximum Moment <b>M</b> x	45 in1bs. [5.1 Nm]	27 in1bs. [3.1 Nm]	
Maximum Moment My	28 in1bs. [3.2 Nm]	16 inIbs. [1.9 Nm]	
Maximum Moment Mz	28 in1bs. [3.2 Nm]	16 inIbs. [1.9 Nm]	
Distance to Bearing Centerline L	2.39 in. [	61 mm]	
DLM-07M-25-D			
Maximum Tensile <b>T</b>	220 lbs. [980 N]	135 lbs. [602 N]	
Maximum Compressive C	220 lbs. [980 N]	135 lbs. [602 N]	
Maximum Moment Mx	90 in1bs. [10.2 Nm]	54 in1bs. [6.2 Nm]	
Maximum Moment My	56 in1bs. [6.4 Nm]	33 in1bs. [3.8 Nm]	
Maximum Moment Mz	56 in1bs. [6.4 Nm]	33 inIbs. [3.8 Nm]	

#### 2.87 in. [73 mm]

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#### Accessory Mounting Technical Data



Distance to Bearing Centerline L

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Specifications	DLM-07N	-38
Thrust Force <b>F</b> @ 100 psi, 7 bar	15 lbs.	66 N
Max. Stroke	1.50 in.	38 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	0.43 lbs.	0.20 Kg
Maximum Payload W	1.0 lbs.	0.45 Kg
Maximum Payload (-P Option)	0.5 lbs.	0.23 Kg
Cylinder Bore Ø	0.437 in.	11 mm
Temperature Range	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.07	sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-way. 2-r	osition

#### MINI BALL RAIL SLIDE DLM-07M-38 DIRECTCONNECT MODULAR SERIES





Мx

Flow Controls are recommended for nearly all applications

Loading Capacity DLM-07M-38	Static	Dynamic
Maximum Tensile <b>T</b>	110 lbs. [490 N]	67 lbs. [301 N]
Maximum Compressive C	110 lbs. [490 N]	67 lbs. [301 N]
Maximum Moment <b>M</b> _X	45 in1bs. [5.1 Nm]	27 inIbs. [3.1 Nm]
Maximum Moment My	28 in1bs. [3.2 Nm]	16 inIbs. [1.9 Nm]
Maximum Moment Mz	28 in1bs. [3.2 Nm]	16 inIbs. [1.9 Nm]
Distance to Bearing Centerline L	2.90 in. [	74 mm]

#### DLM-07M-38-D

Maximum Tensile <b>T</b>	220 lbs. [980 N]	135 lbs. [602 N]
Maximum Compressive C	220 lbs. [980 N]	135 lbs. [602 N]
Maximum Moment <b>M_X</b>	90 in1bs. [10.2 Nm]	54 in1bs. [6.2 Nm]
Maximum Moment <b>My</b>	56 in1bs. [6.4 Nm]	33 in1bs. [3.8 Nm]
Maximum Moment Mz	56 in1bs. [6.4 Nm]	33 in1bs. [3.8 Nm]
Distance to Bearing Centerline L	3.38 in. [86 mm]	

#### Accessory Mounting Technical Data



**DLM SERIES** 

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Specifications	DLM-07M	-50
Thrust Force <b>F</b> @ 100 psi, 7 bar	15 lbs.	66 N
Max. Stroke	2.00 in.	50 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	0.50 lbs.	0.23 Kg
Maximum Payload W	1.0 lbs.	0.45 Kg
Maximum Payload (-P Option)	0.5 lbs.	0.23 Kg
Cylinder Bore Ø	0.437 in.	11 mm
Temperature Range:	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.07	sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-way, 2-p	osition

#### MINI BALL RAIL SLIDE DLM-07M-50 DIRECTCONNECT MODULAR SERIES



Мx

Flow Controls are recommended for nearly all applications

Loading Capacity DLM-07M-50	Static	Dynamic
Maximum Tensile T	110 lbs. [490 N]	67 lbs. [301 N]
Maximum Compressive C	110 lbs. [490 N]	67 lbs. [301 N]
Maximum Moment $\mathbf{M}_{\mathbf{X}}$	45 in1bs. [5.1 Nm]	27 in1bs. [3.1 Nm]
Maximum Moment My	28 in1bs. [3.2 Nm]	16 inIbs. [1.9 Nm]
Maximum Moment Mz	28 in1bs. [3.2 Nm]	16 inIbs. [1.9 Nm]
Distance to Bearing Centerline L	3.37 in. [8	36 mm]

#### DLM-07M-50-D

Maximum Tensile <b>T</b>	220 lbs. [980 N]	135 lbs. [602 N]
Maximum Compressive C	220 lbs. [980 N]	135 lbs. [602 N]
Maximum Moment <b>M</b> x	90 in1bs. [10.2 Nm]	54 in1bs. [6.2 Nm]
Maximum Moment <b>My</b>	56 in1bs. [6.4 Nm]	33 in1bs. [3.8 Nm]
Maximum Moment Mz	56 in1bs. [6.4 Nm]	33 in1bs. [3.8 Nm]
Distance to Bearing Centerline L	3.86 in. [98 mm]	

#### Accessory Mounting Technical Data



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Specifications	DLM-09M	-25
Thrust Force <b>F</b> @ 100 psi, 7 bar	31 lbs.	138 N
Max. Stroke	1.00 in.	25 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	1.08 lbs.	0.49 Kg
Maximum Payload W	2.0 lbs.	0.90 Kg
Maximum Payload (-P Option)	1.0 lbs.	0.45 Kg
Cylinder Bore Ø	0.630 in.	16 mm
Temperature Range:	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.10 s	Sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-way, 2-p	osition

#### MINI BALL RAIL SLIDE DLM-09M-25 DIRECTCONNECT MODULAR SERIES



Flow Controls are recommended for nearly all applications

Loading Capacity DLM-09M-25	Static	Dynamic
Maximum Tensile T	165 lbs. [735 N]	92 lbs. [413 N]
Maximum Compressive C	165 lbs. [735 N]	92 lbs. [413 N]
Maximum Moment Mx	84 in1bs. [9.6 Nm]	47 in1bs. [5.4 Nm]
Maximum Moment My	56 in1bs. [6.4 Nm]	31 in1bs. [3.6 Nm]
Maximum Moment Mz	56 in1bs. [6.4 Nm]	31 in1bs. [3.6 Nm]
Distance to Bearing Centerline L	3.40 in. [8	36 mm]

#### **Accessory Mounting Technical Data**



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Ex: DLM-09M Mini Ball Rail Slide, -50 Body Size, 50mm Stroke, Double Ball Bearings



Specifications	DLM-09M	-50
Thrust Force <b>F</b> @ 100 psi, 7 bar	31 lbs.	138 N
Max. Stroke	2.00 in.	50 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	1.41 lbs.	0.64 Kg
Maximum Payload W	2.0 lbs.	0.90 Kg
Maximum Payload (-P Option)	1.0 lbs.	0.45 Kg
Cylinder Bore Ø	0.630 in.	16 mm
Temperature Range	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.10 s	Sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-way, 2-p	osition

#### MINI BALL RAIL SLIDE DLM-09M-50 DIRECTCONNECT MODULAR SERIES



Static

165 lbs. [735 N]

165 lbs. [735 N]

84 in.-1bs. [9.6 Nm]

56 in.-1bs. [6.4 Nm]

56 in.-1bs. [6.4 Nm]

330 lbs. [1470 N]

330 lbs. [1470 N]

169 in.-Ibs. [19.2 Nm]

113 in.-Ibs. [12.8 Nm]

113 in.-Ibs. [12.8 Nm]

4.13 in. [105 mm]

4.75 in. [121 mm]

Loading Capacity

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

DLM-09M-50-D Maximum Tensile T

Distance to Bearing Centerline L

Maximum Compressive C

Maximum Moment  $\mathbf{M}_{\mathbf{X}}$ 

Maximum Moment My

Maximum Moment Mz

Distance to Bearing Centerline L

DLM-09M-50 Maximum Tensile T

Dynamic

92 lbs. [413 N]

92 lbs. [413 N]

47 in.-Ibs. [5.4 Nm]

31 in.-Ibs. [3.6 Nm]

31 in.-Ibs. [3.6 Nm]

185 lbs. [826 N]

185 lbs. [826 N]

95 in.-Ibs. [10.8 Nm]

63 in.-1bs. [7.2 Nm]

63 in.-1bs. [7.2 Nm]

**DLM SERIES** 

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#### Accessory Mounting Technical Data



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Ex: DLM-09M Mini Ball Rail Slide, -75 Body Size, 75mm Stroke, Double Ball Bearings, Precision Stops



Specifications	DLM-09M	-75
Thrust Force <b>F</b> @ 100 psi, 7 bar	31 lbs.	138 N
Max. Stroke	3.00 in.	150 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	1.78 lbs.	0.81 Kg
Maximum Payload W	2.0 lbs.	0.90 Kg
Maximum Payload (-P Option)	1.0 lbs.	0.45 Kg
Cylinder Bore Ø	0.630 in.	16 mm
Temperature Range	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.10 :	Sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-way, 2-p	osition

#### **MINI BALL RAIL SLIDE DLM-09M-75** DIRECTCONNECT MODULAR SERIES



Static

165 lbs. [735 N]

165 lbs. [735 N]

84 in.-1bs. [9.6 Nm]

56 in.-1bs. [6.4 Nm]

56 in.-1bs. [6.4 Nm]

330 lbs. [1470 N]

330 lbs. [1470 N]

169 in.-Ibs. [19.2 Nm]

113 in.-Ibs. [12.8 Nm]

113 in.-Ibs. [12.8 Nm]

4.95 in. [126 mm]

5.58 in. [142 mm]

Loading Capacity

Maximum Compressive C

Maximum Moment  $\mathbf{M}_{\mathbf{X}}$ 

Maximum Moment My

Maximum Moment Mz

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

Distance to Bearing Centerline L

DLM-09M-75-D Maximum Tensile T

Distance to Bearing Centerline L

DLM-09M-75 Maximum Tensile T

**Dvnamic** 

92 lbs. [413 N]

92 lbs. [413 N]

47 in.-1bs. [5.4 Nm]

31 in.-Ibs. [3.6 Nm] 31 in.-Ibs. [3.6 Nm]

185 lbs. [826 N]

185 lbs. [826 N] 95 in.-Ibs. [10.8 Nm]

63 in.-Ibs. [7.2 Nm]

63 in.-Ibs. [7.2 Nm]

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Accessory Mounting Technical Data



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Ex: DLM-09M Mini Ball Rail Slide, -100 Body Size, 85mm Stroke, Double Ball Bearings, Precision Stops



Specifications	DLM-09M	-100
Thrust Force <b>F</b> @ 100 psi, 7 bar	31 lbs.	138 N
Max. Stroke	4.00 in.	200 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	2.13 lbs.	0.97 Kg
Maximum Payload W	2.0 lbs.	0.90 Kg
Maximum Payload (-P Option)	1.0 lbs.	0.45 Kg
Cylinder Bore Ø	0.630 in.	16 mm
Temperature Range:	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.10	sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-way, 2-r	osition

#### **MINI BALL RAIL SLIDE DLM-09M-100** DIRECTCONNECT MODULAR SERIES

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Flow Controls are recommended for nearly all applications

Loading Capacity DLM-09M-100	Static	Dynamic
Maximum Tensile T	165 lbs. [735 N]	92 lbs. [413 N]
Maximum Compressive C	165 lbs. [735 N]	92 lbs. [413 N]
Maximum Moment Mx	84 in1bs. [9.6 Nm]	47 in1bs. [5.4 Nm]
Maximum Moment My	56 in1bs. [6.4 Nm]	31 in1bs. [3.6 Nm]
Maximum Moment Mz	56 in1bs. [6.4 Nm]	31 in1bs. [3.6 Nm]
Distance to Bearing Centerline L	6.10 in. [1	55 mm]

#### DLM-09M-100-D

Maximum Tensile T	330 lbs. [1470 N]	185 lbs. [826 N]
Maximum Compressive C	330 lbs. [1470 N]	185 lbs. [826 N]
Maximum Moment <b>M</b> x	169 inIbs. [19.2 Nm]	95 inIbs. [10.8 Nm]
Maximum Moment My	113 inIbs. [12.8 Nm]	63 in1bs. [7.2 Nm]
Maximum Moment Mz	113 inIbs. [12.8 Nm]	63 in1bs. [7.2 Nm]
Distance to Bearing Centerline L	6.72 in. [1	71 mm]

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#### Accessory Mounting Technical Data



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#### MINI BALL RAIL SLIDE DLM-012M-25 DIRECTCONNECT MODULAR SERIES







Specifications	DLM-12M	-25
Thrust Force <b>F</b> @ 100 psi, 7 bar	51 lbs.	230 N
Max. Stroke	1.00 in.	25 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	1.18 lbs.	0.54 Kg
Maximum Payload W	4.0 lbs.	1.81 Kg
Maximum Payload (-P Option)	2.0 lbs.	0.90 Kg
Cylinder Bore Ø	0.813 in.	22 mm
Temperature Range:	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.14 s	Sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-way, 2-p	osition

#### MINI BALL RAIL SLIDE DLM-12M-25 DIRECTCONNECT MODULAR SERIES



Flow Controls are recommended for nearly all applications

Loading Capacity DLM-12M-25	Static	Dynamic
Maximum Tensile T	273 lbs. [1214 N]	181 lbs. [808 N]
Maximum Compressive C	273 lbs. [1214 N]	181 lbs. [808 N]
Maximum Moment Mx	182 in1bs. [20.6 Nm]	121 inIbs. [13.7 Nm]
Maximum Moment <b>My</b>	104 inIbs. [11.8 Nm]	69 in1bs. [7.9 Nm]
Maximum Moment Mz	104 inIbs. [11.8 Nm]	69 in1bs. [7.9 Nm]
Distance to Bearing Centerline L	3.45 in. [i	38 mm]

#### **Accessory Mounting Technical Data**



Please see back cover for DE-STA-CO Global Locations. www.destaco.com WWW.COMOSO.COM







Ex: DLM-12M Mini Ball Rail Slide, -50 Body Size, 45mm Stroke, Double Ball Bearings, Precision Stops



Specifications	DLM-12N	-50
Thrust Force <b>F</b> @ 100 psi, 7 bar	51 lbs.	230 N
Max. Stroke	2.00 in.	50 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	1.43 lbs.	0.65 Kg
Maximum Payload W	4.0 lbs.	1.81 Kg
Maximum Payload (-P Option)	2.0 lbs.	0.90 Kg
Cylinder Bore Ø	0.813 in.	22 mm
Temperature Range:	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.14 s	Sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-wav. 2-p	osition

#### MINI BALL RAIL SLIDE DLM-12M-50 DIRECTCONNECT MODULAR SERIES



Flow Controls are recommended for nearly all applications

Loading Capacity	Static	Dynamic
DLM-12M-50		
Maximum Tensile T	273 lbs. [1214 N]	181 lbs. [808 N]
Maximum Compressive C	273 lbs. [1214 N]	181 lbs. [808 N]
Maximum Moment <b>M</b> x	182 in1bs. [20.6 Nm]	121 in1bs. [13.7 Nm]
Maximum Moment My	104 inIbs. [11.8 Nm]	69 in1bs. [7.9 Nm]
Maximum Moment Mz	104 inIbs. [11.8 Nm]	69 in1bs. [7.9 Nm]
Distance to Bearing Centerline L	4.10 in. [1	04 mm]
DI M_12M_50_D		

#### DLM-12M-50-D

Maximum Tensile <b>T</b>	546 lbs. [2429 N]	363 lbs. [1617 N]
Maximum Compressive C	546 lbs. [2429 N]	363 lbs. [1617 N]
Maximum Moment <b>M_X</b>	364 in1bs. [41.2 Nm]	95 in1bs. [27.4 Nm]
Maximum Moment <b>My</b>	208 in1bs. [23.6 Nm]	139 inIbs. [15.8 Nm]
Maximum Moment Mz	208 in1bs. [23.6 Nm]	139 inIbs. [15.8 Nm]
Distance to Bearing Centerline L	4.82 in. [	122 mm]

## **191**

DIRECTCONNE

#### Accessory Mounting Technical Data



Please see back cover for DE-STA-CO Global Locations. www.destaco.com







Ex: DLM-12M Mini Ball Rail Slide, -75 Body Size, 65mm Stroke, Precision Stops



Specifications	DLM-12M	-75
Thrust Force <b>F</b> @ 100 psi, 7 bar	51 lbs.	230 N
Max. Stroke	3.00 in.	150 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	1.80 lbs.	0.82 Kg
Maximum Payload W	4.0 lbs.	1.81 Kg
Maximum Payload (-P Option)	2.0 lbs.	0.90 Kg
Cylinder Bore Ø	0.813 in.	22 mm
Temperature Range	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.14 s	Sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-wav. 2-p	osition

#### MINI BALL RAIL SLIDE DLM-12M-75 DIRECTCONNECT MODULAR SERIES



Flow Controls are recommended for nearly all applications

Loading Capacity	Static	Dynamic
DLM-12M-75		
Maximum Tensile <b>T</b>	273 lbs. [1214 N]	181 lbs. [808 N]
Maximum Compressive C	273 lbs. [1214 N]	181 lbs. [808 N]
Maximum Moment <b>M</b> x	182 inIbs. [20.6 Nm]	121 inIbs. [13.7 Nm]
Maximum Moment <b>My</b>	104 inIbs. [11.8 Nm]	69 in1bs. [7.9 Nm]
Maximum Moment Mz	104 inIbs. [11.8 Nm]	69 in1bs. [7.9 Nm]
Distance to Bearing Centerline L	5.21 in. [1	32 mm]
DLM-12M-75-D		

#### Maximum Tensile T 546 lbs. [2429 N] 363 lbs. [1617 N] Maximum Compressive C 546 lbs. [2429 N] 363 lbs. [1617 N] Maximum Moment $\mathbf{M}_{\mathbf{X}}$ 364 in.-Ibs. [41.2 Nm] 242 in.-1bs. [27.4 Nm] Maximum Moment My 208 in.-Ibs. [23.6 Nm] 139 in.-Ibs. [15.8 Nm] 139 in.-Ibs. [15.8 Nm] Maximum Moment Mz 208 in.-1bs. [23.6 Nm] Distance to Bearing Centerline L 5.92 in. [150 mm]

## **4.93**

#### **Accessory Mounting Technical Data**



DIRECTCONNECT

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Specifications	DLM-12N	I-100
Thrust Force <b>F</b> @ 100 psi, 7 bar	51 lbs.	230 N
Max. Stroke	4.00 in.	200 mm
Stroke Reduction (return)	0.19 in.	5 mm
Weight	2.25 lbs.	1.02 Kg
Maximum Payload W	4.0 lbs.	1.81 Kg
Maximum Payload (-P Option)	2.0 lbs.	0.90 Kg
Cylinder Bore Ø	0.813 in.	22 mm
Temperature Range:	-30°~180° F	-35°~80° C
Actuation per 25mm of travel	0.14 s	Sec.
Linear accuracy per 25mm of travel	±0.0001 in.	±0.005 mm
Repeatability (-P Option)	±0.003 in.	±0.08 mm
Pressure Range	20-100 psi	1.4-7 bar
Valve required to actuate	4-way, 2-p	osition

#### MINI BALL RAIL SLIDE DLM-12M-100 DIRECTCONNECT MODULAR SERIES



Flow Controls are recommended for nearly all applications

Loading Capacity DLM-12M-100	Static	Dynamic
Maximum Tensile <b>T</b>	273 lbs. [1214 N]	181 lbs. [808 N]
Maximum Compressive C	273 lbs. [1214 N]	181 lbs. [808 N]
Maximum Moment M _X	182 in1bs. [20.6 Nm]	121 inIbs. [13.7 Nm]
Maximum Moment <b>My</b>	104 inIbs. [11.8 Nm]	69 in1bs. [7.9 Nm]
Maximum Moment Mz	104 inIbs. [11.8 Nm]	69 in1bs. [7.9 Nm]
Distance to Bearing Centerline L	6.07 in. [1	54 mm]

#### DLM-12M-100-D

Maximum Tensile T	546 lbs. [2429 N]	363 lbs. [1617 N]
Maximum Compressive C	546 lbs. [2429 N]	363 lbs. [1617 N]
Maximum Moment Mx	364 in1bs. [41.2 Nm]	242 in1bs. [27.4 Nm]
Maximum Moment My	208 in1bs. [23.6 Nm]	139 inIbs. [15.8 Nm]
Maximum Moment Mz	208 in1bs. [23.6 Nm]	139 inIbs. [15.8 Nm]
Distance to Bearing Centerline L	6.79 in. [172 mm]	

### WIG 84.95

#### Accessory Mounting Technical Data



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#### DLM SERIES EXPLODED VIEW





161	i Qiy	Name
01	1	Body
02	1	Piston Shaft
02	1	Tool Plate Ton
00	1	Tool Plate Face
05	1	Shaft End Can
00	1	Guide Bail Bearing
00	1 or 2	Bearing Block
08	1	Ston
00	1	Adjustment Stud
10	1	Piston
11	2	Shock Pad
12	2	Piston II-Cun
13	1	Teflon Bing
14	1	Piston Screw
$\frac{11}{15}$	1	Magnet
16	1	Piston Washer
17	1	Jam Nut
18	1	Fnd Cap U-Cup
19	2	Stop 0-Bing
20	1	Shaft End Cap O-Ring
21	2	Cap Retaining Ring
22	1	Stop Set Screw
23	2	Adjustment Stud
		Set Screw
24	8	Plug Set Screw
25	2	Port Plug Set Screw
26	1	Tool Plate Screw
27	3-9	Rail Screw
28	4 or 8	Bearing Screw
29	2	Face Plate Dowel
30	1	Piston Spacer

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

#### **Assembly Procedure**

1) Install set screw plugs in appropriate ports in body using thread sealer

- 2) Attach Rail to Body
- 3) Attach Tool Plate Face to Tool Plate Top
- 4) Glue Magnet to Piston
- 5) Lube and install seals in Piston, Stop and End Cap
- 6) Install Stop Pad (retract) and Washer in Piston
- 7) Attach Nut to Shaft
- 8) Attach Piston to Shaft with End Cap, Spacer and Stop Pad (extend)
- 9) Install Stop from front of Body 10) Install Dog Point Set Screw
- 11) Install Adjustment Studs
- 12) Install Piston Assembly
- 13) Install Bearing Block
- 14) Install Tool Plate Assembly







**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

> Seal Kit Items

Thread Locker Krytox[™] Lubricant

#### **DLM SERIES ASSEMBLED VIEW**

iten	n Qty	Name
01	1	Body
02	1	Piston Shaft
03	1	Tool Plate Top
04	1	Tool Plate Face
05	1	Shaft End Cap
06	1	Guide Rail Bearing
07	1 or 2	Bearing Block
08	1	Stop
09	1	Adjustment Stud
10	1	Piston
11	2	Shock Pad
12	2	Piston U-Cup
13	1	Teflon Ring
14	1	Piston Screw
15	1	Magnet
16	1	Piston Washer
17	1	Jam Nut
18	1	End Cap U-Cup
19	2	Stop O-Ring
20	1	Shaft End Cap O-Ring
21	2	Cap Retaining Ring
22	1	Stop Set Screw
23	2	Adjustment Stud Set Screw
24	8	Plug Set Screw
25	2	Port Plug Set Screw
26	1	Tool Plate Screw
27	3-9	Rail Screw
28	4 or 8	Bearing Screw
29	2	Face Plate Dowel
30	1	Piston Spacer

Third Angle Projection

Super Bonder

#### **Accessory Installation & Adjustment Instructions**

	Item       Qty       Name         1       1       Body         31       1-4       Sensor         Assembly Procedure       Name         1) Install sensor in profile slots as shown         2) Once adjusted for end stroke, lock in position with integrated set screws
Wrench Sizes - Imperial [Metric]       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •       •	<ul> <li>Stroke and Position Adjustment Procedure</li> <li>1) Tool Plate position can be adjusted up to 5mm by loosening Jam Nut (17) and unthreading Shaft (2) from Tool Plate Face (4).</li> <li>Caution. Do not exceed 5mm. Shaft may completely unthread from Tool Plate Face. There is no limit and it is the responsibility of the installer/adjuster not to exceed 5mm from factory settings. Retighten Jam Nut upon attaining desired location.</li> <li>2) Retract stroke can be adjusted up to 5mm by loosening Adjustment Stud Set Screws (23) and then turning Adjustment Stud (9). Maximum and minimum limits are integral to this</li> </ul>
Model         Nut         Flats on Shaft           -07         9/32 [7]         1/8 [3]           -09         13/32 [10]         7/32 [6]           -12         9/16 [13]         5/16 [8]	adjustment and cannot be exceeded. Retighten Set Screw upon attaining desired location.
SK THEEAD > KHYTOX > O	

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

Lightweight Machine Oil Teflon[™] Based Grease



Inductive Sensing, Composite Bearings, Opposing Tool Plates, Dual Support, Spring Retract/Extend and more...

Drawings are for concept only. Contact Robohand Tech Support with project requirements.







# Feed Escapements

#### **RFE Series** Feed Escapement

- Finger locking mechanism ensures that only one finger can be retracted at one time for proper part feeding
- Square shaft prevents shaft from rotating
- Unit can be mounted using the top, bottom, or face surface

Preferred Market: 
 Global





# **Feed Escapements**

#### Part separation:

- A feed escapement is the most effective mechanism for separating components fed from a track or conveyor.
- Failsafe locking fingers: This feature eliminates the premature retraction of the extended finger by utilizing a locking key design. This will minimize part jamming and multiple parts feeding at a time.

#### Mounting Information:

Escapements can be mounted & operated in any orientation



#### **Technical Specifications:**

**Pneumatic Specifications** Pressure Operating Range Cylinder Type **Dynamic Seals** Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Dual Double Acting** Internally Lubricated Buna-N 4-way, 2-position

**Air Quality Requirements** Air Fil

40
No
Low Mois

Micron or Better t Necessary* sture Content (dry)

**Temperature Operating Range** -30°~180° F Buna-N Seals (standard) -35°~80° C Viton[®] Seals (optional) -20°~300° F -30°~150° C

#### Maintenance Specifications[†]

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available *Addition of lubrication will greatly increase service life See Maintenance Section

5 million cycles 10+ million cycles* Yes Yes

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#### FEED ESCAPEMENTS RFE-11M NON-ROTATING FINGER SERIES



111 N

RFE-11M

25 lbs.



**Specifications** 

Thrust Force @ Maximum PSI .....

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2X [M5] AIR PORTS

STROKE ADJUSTMENT SCREWS (STANDARD)

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2X 1Ø 5 H7 X 5 DP1

1.85 [47]

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## FEED ESCAPEMENTS RFE-12M **NON-ROTATING FINGER SERIES**

Specifications	RFE-12M			
Thrust Force @ Maximum PSI	50 lbs.	222 N		
Stroke	1.000 in.	25.40 mm		
Stroke Adjustability	0.75 in.	19 mm		
Weight	0.85 lbs.	0.39 Kg		
Pressure Range	40-100 psi	3-7 bar		
Cylinder Bore Ø	0.787 in.	20 mm		
Rod Ø	0.313 in.	7.95 mm		
Displacement	0.487 in ³ .	8.0 cm ³		
Temperature Range				
Standard Seals	-30°~180° F	-35°~80° C		
Viton [®] Seals	-20°~300° F	-30°~150° C		
Actuation Time	0.60 sec.	0.60 sec.		
Parts Escaped per Minute	100	100		
Valve required to actuate	4-way, 2-	position		



SENSOR SLOT



#### UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

How to Order: (Order Accessories separately from Basic Model)

RFE-12M - T

q Dimensions are symmetrical about centerline

1.000 [25.4] MAX. .250 [6.4] MIN. STROKE

1.000 [25.4]

4X [M5] THRU

1.750 2.0000 [44.5] [50.80]

FINGER SIDE MOUNTING STD. FINGER TOP MOUNTING OPTIONAL -T

4X [M5 X 7 DP]

.375 [9.5]

1.750

[44.5]

0  $\Rightarrow$ All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm] Third Angle Projection

**BASIC MODEL** 

Ð Metric Threads Course Pitch

-

Imperial in.

 $\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$ 

**VITON® SEALS** 

## Metric [mm]

#### **Loading Information**



Loading Capacity	Static	Dynamic
Maximum Moment Mx	150 inlbs. [17 Nm]	15.0 inlbs. [1.70 Nm]
Maximum Moment My	150 inIbs. [17 Nm]	15.0 inlbs. [1.70 Nm]
Maximum Moment Mz	150 inlbs. [17 Nm]	15.0 inlbs. [1.70 Nm]

2.99 [76]

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3.365 [85.5]

TYPICAL BOTH SIDES

-6.39 [162] MAX LENGTH

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.500 [12.7] -

.938 [23.8]

625 [15.9]

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- 2.000 [50.8]

2X [Ø 7.95 X 4.6 DP] C'BORE CLEARANCE FOR [M4] SHCS.

.500 [12.7]

.187 [4.8]

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## **Thrust Force of Cylinders**

Thrust Force	Extend	Retract
Thrust Force @ 100 PSI	50 lbs. [216 N]	40 lbs. [182 N]
Thrust Force @ 80 PSI	40 lbs. [173 N]	32 lbs. [146 N]
Thrust Force @ 60 PSI	30 lbs. [130 N]	25 lbs. [109 N]
Thrust Force @ 40 PSI	20 lbs. [86 N]	16 lbs. [73 N]
Thrust Force @ 20 PSI	10 lbs. [43 N]	8 lbs. [36 N]



**RFE SERIES** 5.5

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## FEED ESCAPEMENTS RFE-13M **NON-ROTATING FINGER SERIES**

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4.28 [109]



**RFE Series Exploded View** 

**RFE SERIES** 

5.7







ltem	Qty	Name
01	1	Body
02	2	Finger
03	2	Piston
04	2	Сар
05	1	Cover, Finger
07	1	Shuttle Slug
30	2	Stop, Screw
32	2	Jam Nut
33	2	Dowel Pin
34	2	SSS,Cup Point
40	2	Magnet, Ring

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

## **Accessory Installation & Adjustment Instructions**



# **Robotic End Effectors**



- Heady duty, spring loaded locking mechanism prevents separation in the event of loss of air pressure
- · Support for optional pneumatic, fluid or electrical interface modules

Preferred Market: 
 Global



See 6.2



- ISO bolt patterns eliminate need for adapter plates
- Heady duty, spring loaded locking mechanism prevents separation in the event of loss of air pressure
- Highly configurable modular design accommodates up to 4 optional modular interfaces

Preferred Market: 
 Global

#### RCW Lateral & Angular **Alignment Series**

- Compensate for inaccuracy or misalignment between parts and machine in both lateral and angular axis
- · Increases assembly speed while reducing wear and parts jamming
- · Improves quality and reduces costs by avoiding damage of parts

Preferred Market: A NA + SA



## **KA/CH Series Horizontal Compliance**

- Compensate for misalignment relative to the robot axis or handling arm
- · Pneumatic or hydraulic operation
- Optional tool re-centering or tool release, sensor probe, adaption interface, and Viton[®] seals for high temperature operation

KA Preferred Market: ▲ NA ◆ SA CH Preferred Market: 
 Global

## ULS/AU Series Emergency Stop Module

- · Detects abnormal forces or shocks and aborts operation
- · Provides protection to robot, tooling, and it's surroundings
- · Manual re-adjustment is required except for vertical collision

ULS Preferred Market: A NA + SA AU Preferred Market: 
 Global



See 6.70. 6.80

See 6.90, 6.100 Page

## AUR Series Resettable Emergency **Stop Module**

- Detects abnormal forces or shocks and aborts operation
- · Provides protection to robot, tooling, and it's surroundings
- · Pneumatically assisted to facilitate repositioning after collision

Preferred Market: A NA + SA



See 6.110

ROBOTIC END Effectors

6.1

See 6.22

See 6.58

## **QC Series Tool Changer Medium Loads**

#### • Robotic applications:

Perfect for those flexible/multiple tooling applications utilizing one Robot. This product was designed with exceptional repeatability, high rigidity & load capacity to make it ideal for any robotic application.

#### • Automation applications: End effector tooling and interchangeable fixturing can be changed quickly and easily to accommodate many different styles of parts on the same assembly machine or machining center.

#### **Mounting Information:**

Robot side has

**DC SERIES** 

6.2





Tool side has counterbored holes for mounting and two dowel pins for hole location (size 30 has pilot boss)



#### **Technical Specifications:**

**Pneumatic Specifications** Pressure Operating Range Cylinder Type Valve Required to Operate Imperial Metric 40-100 psi 3-7 bar Double Acting, Spring Assist 4-way, 2-position (except 0C-30)

-35°~80° C

#### Air Quality Requirements Air Filtration

40 Micron or Better Not Necessary* Low Moisture Content (dry)

Temperature Operating RangeBuna-N Seals (standard)-30°~180° F

#### Maintenance Specifications⁺

Expected Life

Air Lubrication

Air Humidity

Normal Application	5 million cycles
w/ Preventative Maintenance	10+ million cycles**
Field Repairable	Yes
Seal Repair Kits Available	Yes
See Maintenance Section.	fo

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#### Application Restrictions

- Dirty or gritty environments
- Machining operations generating chips
  Environments with loose particulate

#### See Maintenance Section for:

Exploded views and spare parts list	6.18
Drawing sections and assembly procedures	6.19
QC Series cross-reference	6.20
Tool Changer terminology	6.56

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Style-QC Re	obot Half	F	
Size-30	Style: Max. Payload: Max. Moment: Weight:	QC 30 lbs. 200 in-lbs. 0.50 lbs.	- <b>30</b> 13.6 Kg 22.6 Nm 0.23 Kg
U		See Page	.4
Style-TP To	ol Half		
Size-30	Style: Max. Payload: Max. Moment: Weight:	TP- 30 lbs. 200 in-lbs. 0.25 lbs.	<b>-30</b> 13.6 Kg 22.6 Nm 0.11 Kg
		See Page	<b>.5</b>
<b>Style-QC</b> Re	obot Half		
Size-60	Style: Max. Payload: Max. Moment: Weight:	QC 60 lbs. 780 in-lbs. 1.9 lbs.	<b>-60</b> 27 Kg 88.1 Nm 0.86 Kg
	-1.11-16	See Page	<b>.6</b>
Tyle-TP TO	OI HAIT Style:	TP	-60
01ZE-60	Max. Payload: Max. Moment: Weight:	60 lbs. 780 in-lbs. 0.90 lbs.	27 Kg 88.1 Nm 0.41 Kg
		See Page	<b>.7</b>
Style-QC Re	obot Half	1	
Size-60 10-	-Port		
	Style: Max. Payload: Max. Moment: Weight:	<b>QC-60</b> 60 lbs. 780 in-lbs. 1.9 lbs.	1 <b>0-Port</b> 27 Kg 88.1 Nm 0.86 Kg
	ol Holf	See Page	8.6
izo_60 10.	Dort		
	Style: Max. Payload: Max. Moment: Weight:	<b>TP-60</b> 60 lbs. 780 in-lbs. 0.90 lbs.	<b>10-Port</b> 27 Kg 88.1 Nm 0.41 Kg
		See Page	<b>.9</b>
Style-QC Re	<b>obot Half</b>	Ē	
Size-150	Style: Max. Payload: Max. Moment: Weight:	<b>QC-</b> 150 lbs. 1900 in-lbs. 4.8 lbs.	1 <b>50</b> 68 Kg 215 Nm 2.2 Kg
		See Page	<b>5.10</b>
Style-TP To	ol Half		
Size-150	Style: Max. Payload: Max. Moment: Weight:	<b>TP-</b> 150 lbs. 1900 in-lbs. 2.3 lbs.	1 <b>50</b> 68 Kg 215 Nm 1.0 Kg
1		See Page	6.11
<b>Options and</b>	Access	ories	
		See Page	.12

**IC SERIES** 

6.3

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#### TOOL CHANGER QC-30 ROBOT ADAPTER MODULE

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6.4





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TD 20

#### TOOL CHANGER TP-30 TOOLING ADAPTER MODULE



IP-30						
13.6 Kg						
lbs 22.6 Nm		SS OTHERV	VISE NOTED ALL TOLE	RANCES AR	E AS SHOWN B	ELOW ———
s 0.11 Kg	G	ÞΦ	<b>A</b>	<b>(</b> )	Imperial in.	Metric [mm]
s 0.34 Kg	Dimensions are	Third Angle	All Dowel Holes are SF (Slip Fit).	ৰ্শ Metric Threads	$0.00 = \pm .01$	[0.] = [±.25]
80°F -35°~80°C	symmetrical about	Projection	Locational Tolerance	Course Pitch	$0.000 = \pm .005$ $0.0000 = \pm .0005$	$[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$
$11 \text{ In.} \pm 0.025 \text{ Inm}$	Centernine		±.0005 01 [±.01511111]		0.0000 - 2.0000	[0.00] = [±.010]
)	13.6 Kg 13.6 Kg 10s 22.6 Nm 10s 0.11 Kg 180° F -35°~80° C 11 in. ±0.025 mm	13.6 Kg -lbs 22.6 Nm unles 0.11 Kg is 0.34 Kg 180° F -35°~80° C Dimensions are symmetrical about centerline	IP-30         13.6 Kg           Ibs         22.6 Nm           vs         0.11 Kg           vs         0.34 Kg           180° F         -35°~80° C           01 in.         ±0.025 mm	13.6 Kg 13.6 Kg 13.6 Kg 13.6 Kg 14 S 15 S 15 S 15 S 16 S 16 S 17 S 18 S	13.6 Kg -lbs 22.6 Nm is 0.11 Kg is 0.34 Kg 180° F -35°~80° C D1 in. ±0.025 mm 13.6 Kg UNLESS OTHERWISE NOTED ALL TOLERANCES AR Dimensions are symmetrical about centerline Dimensions are symmetrical about symmetrical about symmetrica	13.6 Kg 13.6 Kg 1bs 22.6 Nm 1s 0.11 Kg 180° F $-35^{\circ} \sim 80^{\circ}$ C 11 in. $\pm 0.025$ mm 13.6 Kg UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN B UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN B Dimensions are Symmetrical about centerline UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN B Dimensions are Symmetrical about centerline UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN B Dimensions are Symmetrical about centerline UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN B Dimensions are Symmetrical about centerline UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN B Dimensions are Symmetrical about centerline UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN B Dimensions are Symmetrical about centerline

#### Loading Information How to Order: (Order Accessories separately from Basic Model) Z **BASIC MODEL** PORT Мxv М TP - 30 W SIZE I/O BLOCK PORT BLANK Imperial Μ Metric **Loading Capacity** Metric Imperial I/O BLOCK E15 15 Pin I/O Block with Micro D-Sub Connector, w/1.2M Cordset Maximum Tensile T 70 lbs. 311 N D15 2X 15 Pin I/O Block with Micro D-Sub Conn, w/1.2M Cordset 445 N Maximum Compressive C 100 lbs. E12 12 Pin I/O Block with Turck M12 Connector, w/o Cordset Maximum Moment Mx 200 in.- lbs. 22.6 Nm 0 without I/O Block Maximum Moment My 200 in.-lbs. 22.6 Nm Maximum Moment Mz 200 in.-lbs. 22.6 Nm **REPLACEMENT I/O MODULE ACCESSORIES** ORDER # QTY/UNIT 15 Pin I/O Block with Micro D-Sub Connector, w/1.2M Cordset KE15-TP30 1 QC30 AT READY TO COUPLE POSITION WITH TP30 12 Pin I/O Block with Turck M12 Connector, w/o Cordset KE12-TP30 1 Straight Male Cordset 1.2M for E15 CABL-024 1 90° Male Cordset 2M for E12 CABL-023 1 MAXIMUM GAP FOR A QC30 -TO COUPLE WITH A TP30 0.06 [1.6] ۲ 1.56 [39.7] WHEN ۲ ۲ COUPLED ٠ • E⊫ ł

#### TOOL CHANGER QC-60 ROBOT ADAPTER MODULE





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**OC SERIES** 



#### TOOL CHANGER TP-60 TOOLING ADAPTER MODULE

**OC SERIES** 

6.7



#### TOOL CHANGER QC-60 10-PORT ROBOT ADAPTER MODULE

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## **TOOL CHANGER TP-60 10-PORT** TOOLING ADAPTER MODULE





specifications	IP-00 IU-P	URI							
Maximum Payload	60 lbs	27 Kg							
Maximum Moment Rating	780 in-Ibs	88 Nm	UNLES	S OTHERN	VISE NOTED ALL TOLE	RANCES AR	E AS SHOWN B	ELOW ———	
Weight of <b>TP</b> Unit only	0.90 lb	0.41 Kg 1.27 Kg	Ģ	₽⊕	<del>•</del>	¢	Imperial in.	Metric [mm]	
Temperature Range	-30°~180° F	-35°~80° C	Dimensions are symmetrical about	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance	Metric Threads	$0.00 = \pm .01$ $0.000 = \pm .005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$	
Repeatability	$\pm \ 0.001$ in.	±0.025 mm	centerline	110j000011	±.0005" or [±.013mm]		$0.0000 = \pm .0005$	$[0.00] = [\pm .013]$	

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#### Loading Information

TD CO 40 DODT

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#### HOW to Urder: (Order Accessories separately from Basic Model)

			<b>POR</b> Blan	T: k NPT port	BASIC I/O BI E15	MODEL TP - 60 SIZE OCK 15 Pin I/O Block	PORT 1 I/O BLOCK k with D-Sub Connecto	<b>OP</b> r and User Plu	ug, w/o Cable	
Loading Capacity	Imperial	Metric	M	BSPP ports BSPT ports	G15* E12	15 Pin I/O Block	k Non-Recessed,w/D-S k w/Turk M12 Connect	ub Connector	r and User Plug, v et	w/o Cable
Maximum Tensile T	100 lbs.	445 N	~	Doi i porto	Ō	without I/O Blog	ck	, 11/0 001400		
Maximum Compressive C	120 lbs.	534 N			*For pre	vious installations only.	New Installations use E15.			
Maximum Moment M _X	780 inIbs.	88.1 Nm								
Maximum Moment My	780 inIbs.	88.1 Nm	REP	LACEMENT I/O		LE ACCESSORIE	S		ORDER #	OTY/UNIT
Maximum Moment Mz	780 inIbs.	88.1 Nm	15 P	in I/O Block with	D-Sub (	Connector and Us	er Plug, w/o Cable		KE15-TP60	1
			15 Pi	in I/O Block Non	-Recesse	ed, w/D-Sub Conr	nector, User Plug, w/o C	Cable	KG15-TP60	1
QC60 AT	READY TO COU	PLE	12 P	in I/O Block with	Turck M	12 Connector, w/	/o Cordset		KE12-TP60	1
POSI	IION WITH TP60		Strai	ght Female D-Si	ub User F	Plug, w/o Cable, S	Solder Type for E15/G15	j	ELCT-047	1
MAXIMUM GAP FOR A QC60 TO COUPLE WITH A TP60 0.13 [3.2]			90° I	Male Cordset 2N	1 for E12				CABL-023	1

## **TOOL CHANGER QC-150 ROBOT ADAPTER MODULE**

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WITH A TP150 0.16 [4.0]



**SLKT-393** 

**SLKT-390** 

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**ADAPTER PLATES** 

Face Seal Repair Kit

**PNEUMATIC ACCESSORIES** 

Consult Factory

Seal Repair Kit

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WITH A TP150 0.16 [4.0]

## **TOOL CHANGER TP-150 TOOLING ADAPTER MODULE**



#### **OPTIONAL ELECTRIC MODULE**





Module kits above include: Flat for module mounting, straight plug (without cable), locating pins and hardware.

C SERIES 00 SERIES 6.12



**MODULE FOR QC-150** 

SEPARATE

KE19-QC150

ELCT-043

PREMOUNTED

E19

**ACCESSORIES:** 



 Connector, without Cable
 Image: Connector, without Cable

 19 pin 5A Module with Industrial User Connector, without Cable
 MODULE FOR TP-150

 PREMOUNTED
 SEPARATE

 E19
 KE19-TP150

 19 pin 5A Module with Industrial User Connector, without Cable

 Straight female plug (w/o cable), solder type, cable clamp

Module kits above include: Flat for module mounting, straight plug (without cable), locating pins and hardware.

#### **OPTIONAL ELECTRIC MODULE**





Module kits above include: Flat for module mounting, straight plug (without cable), locating pins and hardware.





2 X 1/4" Air ports Module, Face Seal (PN14, PP14, PT14) For QC/TP-60 & QC/TP-150

Maximum Working Pressure: 10 bar

**ROBOT HALF MODULES:** 

**TOOL HALF MODULES:** 



Module kits above include: Flat for module mounting, seals, locating pins and hardware.

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Maximum Working Pressure: 10 bar

Flat for module mounting not shown: See QC or TP dawings.

ROBOT HALF MODULES:

TOOL HALF MODULES:

#### How to Order Modules: **How to Order Modules: BASIC MODEL** PORT MODULE **BASIC MODEL** PORT MODULE E15 - PP18 - PP18 E15 I/O BLOCK I/O BLOCK SIZE SIZE **MODULES FOR QC-60 MODULES FOR TP-60** PREMOUNTED SEPARATE PREMOUNTED SEPARATE **PN18 KPN18-QC60** 4 x 1/8" NPT Pneumatic Ports, 10 bar **PN18 KPN18-TP60** 4 x 1/8" NPT Pneumatic Ports, 10 bar KPP18-QC60 4 x 1/8" BSPP Pneumatic Ports, 10 bar **KPP18-TP60** 4 x 1/8" BSPP Pneumatic Ports, 10 bar **PP18 PP18** KPT18-QC60 4 x 1/8" BSPT Pneumatic Ports, 10 bar KPT18-TP60 4 x 1/8" BSPT Pneumatic Ports, 10 bar **PT18 PT18 MODULES FOR TP-150 MODULES FOR QC-150** PREMOUNTED SEPARATE PREMOUNTED SEPARATE **PN18** KPN18-QC150 4 x 1/8" NPT Pneumatic Ports, 10 bar **PN18** KPN18-TP150 4 x 1/8" NPT Pneumatic Ports, 10 bar **PP18** KPP18-QC150 4 x 1/8" BSPP Pneumatic Ports, 10 bar **PP18** KPP18-TP150 4 x 1/8" BSPP Pneumatic Ports, 10 bar KPT18-QC150 4 x 1/8" BSPT Pneumatic Ports, 10 bar KPT18-TP150 4 x 1/8" BSPT Pneumatic Ports, 10 bar PT18 PT18 **ACCESSORIES: SLKT-391** Seal Repair Kit

Module kits above include: Flat for module mounting, seals, locating pins and hardware.



#### 2 x 3/8" Fluid Ports Module, Non Spilling, Double Shut-Off (HP38, HN38, HT38) For QC/TP-60 & QC/TP-150



Flat for module mounting not shown: See QC or TP dawings.

Maximum Working Pressure: 100 bar

**ROBOT HALF MODULES:** 

TOOL HALF MODULES:



Module kits above include: Flat for module mounting, couplings, locating pins and hardware.





lte	m Qty	Name	
Rot	oot Side		
1	1	Body	
2	1	Piston	
3	1	Ball retainer	
4	1	Ring	
5	2	Bushing	
6	4 to 6	Ball	
10	1	Ring, O-Ring	
11	1	Ring, O-Ring	
12	1	Piston, O-ring	
13	1	Piston, O-ring	
14	4	Body, O-Ring	
15	1	Spring	

Ring, Pin (QC-150 only)

Sensor, (QC-150 only - optional)

Sensor, SS screw (QC-150 only)

Retainer, O-Ring

Retainer, Washer

Body, SHC screw

Body, SHC screw

Sensor Connector, (QC-150 only - optional)

Module, SHC Screw

I/O Module

ohi2	

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1

1

2

14 <u>15</u>

16

17

<u>18</u>

19

20

<u>25</u> 26

27

30

31

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101	1	Body	
102	1	Locking Pin	
103	1	Centering Pin	
104	1	Diamond Pin	
105	3	Pin, Screw	
106	1	I/O Module	
107	2	Module, SHC screw	

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.





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#### Assembly Procedure - Robot Side

- 1) Install the air port plugs (#19) and (#20) with thread-locker into the body (#1)
- 2) Lubricate and install seals (#12) and (#13) into the piston (#2)
- 3) Insert the springs (#15) into the body
- 4) Insert the piston sub-assembly into the body
- 5) Lubricate and install seals (#10) and (#11) into the ring (#4)
- 6) Insert the pin (#16) into the ring (#4)
- 7) Insert the ring sub-assembly into the body
- 8) Insert the balls (#6) into the ball retainer (#3)
- 9) Insert the ball and retainer sub-assembly into the body
- 10) Fasten the ball retainer with washer (#17) and screws (#18) with thread-locker
- 11) Press in the bushings (#5) into the body
- 12) Mount the O-Ring (#14) into the body
- 13) For QC150 with latch sensor only, fully insert the sensor (#25) into the body and slightly pull it back (0.5 to 1 mm). Fasten the sensor (#25) with screw (#27). Plug in male connector (#26) with the female connector of the I/O block (#30)
- 14) Mount the I/O block (#30) into the body and fasten with screw (#31)

#### Assembly Procedure - Tool Side

- 1) Insert the locking pin (#102) into the body #101 and fasten with screws (#105) with thread-locker
- 2) Press in the diamond pin (#104) into the body
- 3) Press in the pin (#103) into the body
- 4) Mount the I/O block (#106) into the body and fasten with screw (#107)

#### **QC Series Assembled View**

Iter	n Qty	Name
Rot	oot Side	
1	1	Body
2	1	Piston
3	1	Ball retainer
4	1	Ring
5	2	Bushing
6	4 to 6	Ball
<u>10</u>	1	Ring, O-Ring
11	1	Ring, O-Ring
12	1	Piston, O-ring
<u>13</u>	1	Piston, O-ring
14	4	Body, O-Ring
15	1	Spring
<u>16</u>	1	Ring, Pin (QC-150 only)
<u>17</u>	1	Retainer, O-Ring
<u>18</u>	1	Retainer, Washer
<u>19</u>	1	Body, SHC screw
20	1	Body, SHC screw
<u>25</u>	1	Sensor, (QC-150 only - optional)
26	1	Sensor Connector,
		(QC-150 only - optional)
<u>27</u>	1	Sensor, SS screw (QC-150 only)
30	1	I/O Module
31	2	Module, SHC Screw

#### **Tool Side**

101	1	Body
102	1	Locking Pin
103	1	Centering Pin
104	1	Diamond Pin
105	3	Pin, Screw
106	1	I/O Module
107	2	Module. SHC screw

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

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## **QC Series Cross Reference**



New Product #	Old Product #	Description
<b>Robot Half Size 30</b> QC-30-E15 QC-30-D15 QC-30M-E15	QC2336-0-0-0 QC1862-0-0-0 QC1956-0-0-0	Robot Half, Imperial, 15 Pin I/O Module Robot Half, Imperial, Double 15 Pin I/O Module Robot Half, Metric, 15 Pin I/O Module
QC-30M-E12	QC7499-0-0-0	Robot Haif, Metric, 12 Pin I/U Module
Tool Half Size 30 TP-30-E15 TP-30-D15 TP-30M-E15 TP-30M-E12	TP2337-0-0 TP1506-0-0 TP1957-0-0 TP7500-0-0	Tool Half, Imperial, 15 Pin I/O Module Tool Half, Imperial, Double 15 Pin I/O Module Tool Half, Metric, 15 Pin I/O Module Tool Half, Metric, 12 Pin I/O Module
Accessories Size 30		
E15-QC30 E12-QC30 E15-TP30 E12-TP30 CABL-024 SLKT-387 SLKT-388	502678 507494 502679 507495 903319 KQC30-OR KQC30-HW	15 Pin I/O Block with Micro D-Sub Connector 12 Pin I/O Block with Turck M12 Connector 15 Pin I/O Block with Micro D-Sub Connector 12 Pin I/O Block with Turck M12 Connector Straight Male Cordset 1.2M for E15 Seal Repair Kit, QC30 Face Sealing Repair Kit, QC30
Robot Half Size 60		
QC-60-E15 QC-60-G15 QC-60M-E15 QC-60M-E12 QC-60M-G15 QC-60A-E15 QC-60A-G15 QC-60-E15-10P QC-60M-E15-10P QC-60A-E15-10P	QC6675-0-0-0 QC2166-0-0-0 QC7592-0-0-0 QC7592-0-0-0 QC4588-0-0-0 QC6708-0-0-0 QC1980-0-0-0 QC6923-0-0-0 QC7079-0-0-0 QC7078-0-0-0	Robot Half, NPT, 15 Pin I/O Module Robot Half, NPT, 15 Pin Non-Recessed I/O Module Robot Half, Metric, 15 Pin I/O Module Robot Half, Metric, 12 Pin I/O Module Robot Half, Metric, 15 Pin Non-Recessed I/O Module Robot Half, BSPT, 15 Pin I/O Module Robot Half, BSPT, 15 Pin Non-Recessed I/O Module Robot Half, NPT, 15 Pin I/O Module, 10 Ports Robot Half, Metric, 15 Pin I/O Module, 10 Ports Robot Half, BSPT, 15 Pin I/O Module, 10 Ports
Tool Half Size 60		
TP-60-E15 TP-60-G15 TP-60M-E15 TP-60M-E12 TP-60M-G15 TP-60A-E15 TP-60A-G15 TP-60-E15-10P TP-60M-E15-10P TP-60A-E15-10P	TP6676-0-0-0 TP2093-0-0-0 TP6705-0-0-0 TP7593-0-0-0 TP4591-0-0-0 TP6709-0-0-0 TP1981-0-0-0 TP6924-0-0-0 TP7081-0-0-0 TP7080-0-0-0	Tool Half, NPT, 15 Pin I/O Module Tool Half, NPT, 15 Pin Non-Recessed I/O Module Tool Half, Metric, 15 Pin I/O Module Tool Half, Metric, 12 Pin I/O Module Tool Half, Metric, 15 Pin Non-Recessed I/O Module Tool Half, BSPT, 15 Pin I/O Module Tool Half, BSPT, 15 Pin Non-Recessed I/O Module Tool Half, NPT, 15 Pin I/O Module, 10 Ports Tool Half, Metric, 15 Pin I/O Module, 10 Ports Tool Half, BSPT, 15 Pin I/O Module, 10 Ports Tool Half, BSPT, 15 Pin I/O Module, 10 Ports
Accessories Size 60 SLKT-389	KQC60-OR	Seal Repair Kit, QC60
<b>Robot Half Size 150</b> QC-150-E15 QC-150-G15	QC6677-0-0-0 QC2292-0-0-0 QC6577_052_0_0	Robot Half, NPT, 15 Pin I/O Module Robot Half, NPT, 15 Pin Non-Recessed I/O Module Robot Half, NPT, 15 Pin Non-Recessed I/O Module
QC-150-E15-LP QC-150-G15-LP QC-150-E15-LN QC-150-G15-LN QC-150M-E15 QC-150M-G15 QC-150M-G15-LP QC-150M-E15-LP QC-150M-E15-LN QC-150M-G15-LN	QC6677-052-0-0 QC62292-052-0-0 QC6677-050-0-0 QC6706-0-0-0 QC6706-0-0-0 QC4593-0-0-0 QC6706-052-0-0 QC6706-052-0-0 QC6706-050-0-0 QC6706-050-0-0	Robot Half, NPT, 15 Pin I/O Module, PNP Latch sensor Robot Half, NPT, 15 Pin I/O Module, NPN Latch sensor Robot Half, NPT, 15 Pin I/O Module, NPN Latch sensor Robot Half, NPT, 15 Pin Non-Recessed I/O Module, NPN Latch sensor Robot Half, Metric, 15 Pin I/O Module Robot Half, Metric, 15 Pin Non-Recessed I/O Module Robot Half, Metric, 15 Pin I/O Module, PNP Latch sensor Robot Half, Metric, 15 Pin I/O Module, NPN Latch sensor Robot Half, Metric, 15 Pin Non-Recessed I/O Module, PNP Latch sensor Robot Half, Metric, 15 Pin Non-Recessed I/O Module, NPN Latch sensor Robot Half, Metric, 15 Pin Non-Recessed I/O Module, NPN Latch sensor
QC-150A-E15 QC-150A-E15 QC-150A-G15 QC-150A-E15-LP QC-150A-G15-LP QC-150A-E15-LN QC-150A-G15-LN	QC6710-0-0-0 QC3066-0-0-0 QC6710-052-0-0 QC3066-052-0-0 QC6710-050-0-0 QC3066-050-0-0	Robot Half, BSPT, 15 Pin I/O Module Robot Half, BSPT, 15 Pin Non-Recessed I/O Module Robot Half, BSPT, 15 Pin I/O Module, PNP Latch sensor Robot Half, BSPT, 15 Pin Non-Recessed I/O Module, PNP Latch sensor Robot Half, BSPT, 15 Pin I/O Module, NPN Latch sensor Robot Half, BSPT, 15 Pin Non-Recessed I/O Module, NPN Latch sensor Robot Half, BSPT, 15 Pin Non-Recessed I/O Module, NPN Latch sensor

**QC SERIES** 

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New Product #	Old Product #	Description
Tool Half Size 150		
TP-150-F15	TP6678-0-0-0	Tool Half NPT 15 Pin I/O Module
TP-150-G15	TP2293-0-0-0	Tool Half, NPT 15 Pin Non-Becessed I/O Module
TP-150M-F15	TP6707-0-0-0	Tool Half, Metric 15 Pin //O Module
TP-150M-G15	TP4595-0-0-0	Tool Half, Metric, 15 Pin Non-Recessed I/O Module
TP-150A-F15	TP6711-0-0-0	Tool Half, BSPT, 15 Pin I/O Module
TP-150A-G15	TP2259-0-0-0	Tool Half, BSPT, 15 Pin Non-Recessed I/O Module
Modules Size 60 and	150	
KG15-QC60	502675	15 Pin I/U Block (Non-Recessed) with D-Sub Connector - QC side
KE15-QC60	506671	15 Pin I/O Block with D-Sub Connector - QC side
	502676	15 PIN I/U BIOCK (NON-Recessed) With D-Sub Connector - IP side
KE15-1P00	500073 0F26	15 PIN I/O BIOCK WILL D-Sub Connector - 17 Side
		26 pm 5A Module with Industrial Connector - QC side
		20 pin 5A Module with Industrial Connector - OC side
KE19-0000	TF10	19 pm 54 Module with Industrial Connector - TP side
KE10-0C60	0F10	10 nin 13A Module with Industrial Connector - OC side
KE10-TP60	TF10	10 pin 13A Module with Industrial Connector - TP side
KG15-0C150	502675	15 Pin I/O Block (Non-Recessed) with D-Sub Connector - QC side
KF15-0C150	506671	15 Pin I/O Block with D-Sub Connector - QC side
KE26-QC150	QE26	26 pin 5A Module with IndustrialConnector - QC side
KE26-TP150	TE26	26 pin 5A Module with Industrial Connector - TP side
KE19-QC150	QE19	19 pin 5A Module with Industrial Connector - QC side
KE19-TP150	TE19	19 pin 5A Module with Industrial Connector - TP side
KE10-QC150	QE10	10 pin 13A Module with Industrial Connector - QC side
KE10-TP150	TE10	10 pin 13A Module with Industrial Connector - TP side
KPN18-QC60	QNPT18	4 x 1/8 NPT Pneumatic Ports Module - QC side
KPP18-QC60	QBSPP18	4 x 1/8 BSPP Pneumatic Ports Module - QC side
KPT18-QC60	QBSPT18	4 x 1/8 BSPT Pneumatic Ports Module - QC side
KPN18-TP60		4 x 1/8 NPT Pneumatic Ports Module - TP side
		4 X 1/8 BSPP Pheumatic Ports Module - 1P side
		4 X 1/0 DOFT FILEUTIALIC FULLS MOULIE - IF SILE 2 x 1/4 NDT Projumatic Ports Module - OC side
KPP14-0C60	0RSPP14	2 x 1/4 RSPP Pneumatic Ports Module - QC side
KPT14-QC60	QBSPT14	2 x 1/4 BSPT Pneumatic Ports Module - QC side
KPN14-TP60	TNPT14	2 x 1/4 NPT Pneumatic Ports Module - TP side
KPP14-TP60	TBSPP14	2 x 1/4 BSPP Pneumatic Ports Module - TP side
KPT14-TP60	TBSPT14	2 x 1/4 BSPT Pneumatic Ports Module - TP side
KPN18-QC150	QNPT18	4 x 1/8 NPT Pneumatic Ports Module - QC side
KPP18-QC150	QBSPP18	4 x 1/8 BSPP Pneumatic Ports Module - QC side
	QBSP118	4 x 1/8 BSPT Pneumatic Ports Module - UC side
KPN 18-1P150 KDD19 TD150		4 X 1/8 NPT PHEUMALIC PORS MODULE - TP SIDE
KPT18-TP150	TRSPT18	4 x 1/8 BSPT Pneumatic Ports Module - This side
KPN14-0C150	0NPT14	2 x 1/4 NPT Pneumatic Ports Module - QC side
KPP14-QC150	QBSPP14	2 x 1/4 BSPP Pneumatic Ports Module - QC side
KPT14-QC150	QBSPT14	2 x 1/4 BSPT Pneumatic Ports Module - QC side
KPN14-TP150	TNPT14	2 x 1/4 NPT Pneumatic Ports Module - TP side
KPP14-TP150	TBSPP14	2 x 1/4 BSPP Pneumatic Ports Module - TP side
KPT14-TP150	TBSPT14	2 x 1/4 BSPT Pneumatic Ports Module - TP side
KHN38-QC60	QQD38	2 x 3/8 NPT Fluid Ports Module - QC side
KHN38-1P60	10038	2 X 3/8 NP1 Fluid Ports Module - 1P side
		2 X 3/8 NPT Fluid Ports Module - QU Side
	TQD30 502262	2 X 3/0 NPT Fluid Polls Module - TP Side Straight Formale D. Sub Hear Diag (w/a cable) Solder Type for E15/C15 (AC 60/150 & TD 60/150)
FI CT-041	902303	Straight Female Plug (w/o cable) for F10-0060/150
FI CT-042	904834	Straight Male Plug (w/o cable) for F10-TP60/150
ELCT-043	902484	Straight Female Plug (w/o cable) for E19-QC60/150
ELCT-044	902486	Straight Male Plug (w/o cable) for E19-TP60/150
ELCT-045	904837	Straight Female Plug (w/o cable) for E26-QC60/150
ELCT-046	904833	Straight Male Plug (w/o cable) fór E26-TP60/150

# **RQC Series Modular Tool Changer-High Loads**

- **Robotic applications:** Perfect for those flexible/multiple tooling applications utilizing one Robot. This product was designed with exceptional repeatability, high rigidity & load capacity to make it ideal for any robotic application.
- Automation applications: End effector tooling and interchangeable fixturing can be changed quickly and easily to accommodate many different styles of parts on the same assembly machine or machining center.
- Highly configurable, modular design: The Modular RQC series easily accommodates up to 4 optional modular interfaces offering a high level of flexibility.

#### **Mounting Information:**

Robot half has counterbored holes for mounting with a dowel pin hole, a raised boss for location, and features a ISO9409-1 mounting pattern



Tool half has tapped holes, two dowel pin holes for accurate location of payload, and features a ISO9409-1 mounting pattern



#### **Technical Specifications:**

<b>Pneumatic Specifications</b> Pressure Operating Range Cylinder Type Valve Required to Operate	<b>Imperial</b> 60-100 psi Double Acting, 4-way, 2-	<b>Metric</b> 4-7 bar Spring Assist position
<b>Air Quality Requirements</b> Air Filtration Air Lubrication Air Humidity	40 Micron Not Nece Low Moisture (	n or Better ssary* Content (dry)
<b>Temperature Operating Ra</b> Buna-N Seals (standard)	<b>nge</b> -30°~180° F	-35°~80° C
Maintenance Specification Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available 'See Maintenance Section. *Addition of lubrication will greatly increase	s [†] 5 million ce 10+ million Yes Yes service life	cycles on cycles*† S
Application Restrictions <ul> <li>Dirty or gritty environments</li> <li>Machining operations generies</li> <li>Environments with loose page</li> </ul>	ating chips	

#### See Maintenance Section for:

Exploded views and spare parts list	6.54
Drawing Sections and assembly procedures	6.55
Tool Changer terminology	6.56
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Style-RQC Re	obot Ha	lf	
Size-200	Style: Max. Payload: Max. Moment: Weight:	RQC- 200 lbs. 7200 in-lbs. 4.7 lbs.	200 90 Kg 810 Nm 2.1 Kg
Style - RTP To	ol Half	Page <b>6</b>	.24
Size-200	Style: Max. Payload: Max. Moment: Weight:	RTP- 200 lbs. 7200 in-lbs. 2 lbs. See Page	200 90 Kg 810 Nm 0.9 Kg
Style-RQC Ro	obot Ha	lf	
Size-400	Style: Max. Payload: Max. Moment: Weight:	<b>RQC-</b> 400 lbs. 14000 in-lbs. 8 lbs.	<b>400</b> 180 Kg 1580 Nm 3.6 Kg
No CO.4		See <b>6</b> Page <b>6</b>	.28
Style-RTP To	ol Half		
Size-400	Style: Max. Payload: Max. Moment: Weight:	RTP- 400 lbs. 14000 in-lbs. 2.4 lbs.	<b>400</b> 180 Kg 1580 Nm 1.1 Kg
00		See <b>6</b> Page <b>6</b>	.30
Style-RQC Re	obot Ha	lf	
Size-800	Style: Max. Payload: Max. Moment: Weight:	RQC- 800 lbs. 22000 in-lbs. 11.8 lbs.	800 360 Kg 2490 Nm 5.3 Kg
102.00		See <b>6</b> Page <b>6</b>	.32
Style-RTP To	ol Halt		
Size-800	Style: Max. Payload: Max. Moment: Weight:	RTP- 800 lbs. 22000 in-lbs. 4 lbs.	800 360 Kg 2490 Nm 1.8 Kg
		See <b>6</b> Page <b>6</b>	.34
Style-RQC R	obot Ha	lf	
Size-1200	Style: Max. Payload: Max. Moment: Weight:	<b>RQC-</b> 1 1200 lbs. 30000 in-lbs. 14.1 lbs.	200 550 Kg 3390 Nm 6.4 Kg
		See <b>6</b> Page <b>6</b>	.36
Style-RTP To	ol Half		
Size-1200	Style: Max. Payload: Max. Moment: Weight:	RTP-1 1200 lbs. 30000 in-lbs. 4.3 lbs.	200 550 Kg 3390 Nm 1.9 Kg
		See 6 Page 6	.38
Options and	Access	ories See 6	.40

9.00 MODULAR RI SERIES

## **TOOL CHANGER RQC-200 ROBOT ADAPTER MODULE**



Specifications	RQC-200		
Maximum Payload	200 lbs	90 Kg	
Maximum Moment	7,200 in-lbs	810 Nm	
Weight of <b>RQC</b> Unit only	4.7 lb	2.1 Kg	
Weight of Coupled Units	6.7 lbs	3 Kg	
Pressure Range (locked cylinder)	60~100 psi	4~7 bar	
Bore Ø	2.09 in.	53 mm	
Displacement	2.52 in ³ .	41.3 cm ³	
Temperature Range	-30°~180° F	-35°~80° C	
Repeatability	± 0.001 in.	±0.025 mm	
Valve required to actuate	4-way, 2-p	osition	



symmetrical about

centerline



Metric [mm]  $0.00 = \pm .01$  $0.000 = \pm .005$  $0.0000 = \pm .0005$ Metric Threads Course Pitch

## Locational Tolerance ±.0005" or [±.013mm]





2 x [M5

x 10 DP1

0.31

8

SIDE D

(Identical to Side B)

for Modules

(See Detail)





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**PORT:** 

Ν

М

A

LO

LP*

**CP**[†]

LN*

**CN**[†]

LD*

SIDE A:

0

FN

FP

FT

#### **TOOL CHANGER RQC-200 OPTIONAL MODULES FOR ROBOT ADAPTER**



## **TOOL CHANGER RTP-200 TOOL ADAPTER MODULE**



Specifications	RTP-200	)
Maximum Payload	200 lbs	90 Kg
Maximum Moment	7,200 in-lbs	810 Nm
Weight of <b>RTP</b> Unit only	2 lb	0.9 Kg
Weight of Coupled Units	6.7 lbs	3 Kg
Temperature Range	-30°~180° F	-35°~80° C
Repeatability	± 0.001 in.	$\pm 0.025 \text{ mm}$



	UNLESS OTHERWISE	NOTED ALL	TOLERANCES A	re as shown i	Below ——
Ç	$\Rightarrow \oplus$	$\bullet$	$\oplus$	Imperial in.	Metric [mm]

Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$	





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SIDE A:

0

FN

FP

FT

0

E19[†]

G19

FN FP

FT

VN

VP

VT

#### **TOOL CHANGER RTP-200 OPTIONAL MODULES FOR TOOLING ADAPTER**



## TOOL CHANGER RQC-400 ROBOT ADAPTER MODULE

MODULAR RQC Series

6.28

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz



Specifications	RQC-400	
Maximum Payload	400 lbs	180 Kg
Maximum Moment	14,000 in-lbs	1580 Nm
Weight of <b>RQC</b> Unit only	8 lb	3.6 Kg
Weight of Coupled Units	10.4 lbs	4.7 Kg
Pressure Range (locked cylinder)	60~100 psi	4~7 bar
Bore Ø	2.87 in.	73 mm
Displacement	4.93 in ³ .	80.9 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Repeatability	± 0.001 in.	±0.025 mm
Valve required to actuate	4-way, 2-pc	osition



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800 lbs.

14000 in.- lbs.

14000 in.-lbs.

14000 in.-lbs.

3560 N

1580 Nm

1580 Nm

1580 Nm



#### TOOL CHANGER RQC-400 OPTIONAL MODULES FOR ROBOT ADAPTER



#### TOOL CHANGER RTP-400 TOOL ADAPTER MODULE



Specifications	RTP-400		
Maximum Payload	400 lbs	180 Kg	
Maximum Moment	14,000 in-lbs	1580 Nm	
Weight of <b>RTP</b> Unit only	2.4 lb	1.1 Kg	
Weight of Coupled Units	10.4 lbs	4.7 Kg	
Temperature Range	-30°~180° F	-35°~80° C	
Repeatability	± 0.001 in.	±0.025 mm	



## UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Ψ	$\forall \forall \forall$	➡	V	imperiarin.	
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	

#### **Loading Information**



Please see back cover for DE-STA-C0 Global Locations. www.destaco.com



#### TOOL CHANGER RTP-400 OPTIONAL MODULES FOR TOOLING ADAPTER

6.31



## TOOL CHANGER RQC-800 ROBOT ADAPTER MODULE

MODULAR RQC Series

6.32

Maximum Moment My

Maximum Moment Mz



Specifications	RQC-800		
Maximum Payload	800 lbs	360 Kg	
Maximum Moment	22,000 in-lbs	2490 Nm	
Weight of <b>RQC</b> Unit only	11.8 lb	5.3 Kg	
Weight of Coupled Units	15.8 lbs	7.1 Kg	
Pressure Range (locked cylinder)	60~100 psi	4~7 bar	
Bore Ø	3.15 in.	80 mm	
Displacement	5.83 in ³ .	95.6 cm ³	
Temperature Range	-30°~180° F	-35°~80° C	
Repeatability	± 0.001 in.	$\pm 0.025 \text{ mm}$	
Valve required to actuate	4-way, 2-position		



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22000 in.- lbs.

22000 in.-lbs.

2490 Nm

2490 Nm


## TOOL CHANGER RQC-800 OPTIONAL MODULES FOR ROBOT ADAPTER



Please see back cover for DE-STA-CO Global Locations. www.destaco.com

# TOOL CHANGER RTP-800 TOOL ADAPTER MODULE



Specifications	RTP-80	D
Maximum Payload	800 lbs	360 Kg
Maximum Moment	22,000 in-lbs	2490 Nm
Weight of <b>RTP</b> Unit only	4 lb	1.8 Kg
Weight of Coupled Units	15.8 lbs	7.1 Kg
Temperature Range	-30°~180° F	-35°~80° C
Repeatability	± 0.001 in.	±0.025 mm



	ес атцери	VICE MATER ALL TALE	DANFEC AD	ре ле силилі d	
UNLE	33 UIRENV	VIJE NUTED ALL TULE	NANGEJ AN	ie aj jhuwn d	ELUW
Ģ	$\Rightarrow \oplus$	$\bullet$	$\oplus$	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	



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## TOOL CHANGER RTP-800 OPTIONAL MODULES FOR TOOLING ADAPTER



**NOTE:** Only one module can be mounted per side (except 2E19, 2G19, and HISRxx which are composed of 2 modules)

User Plugs Not Shown.

low	OTCET: (Order Accessories separately from Basic Model)	For de	tailed sensing and module information see pages 8.40 - 8.51
	BASIC MODEL SIDE A	SIDE C	
	SIZE SIDE E	s SID	ED
OIDL A.	No optional modulo		No optional modulo
EN	$6 \times 1/4$ " NPT air ports module face seal 10 har	DN	6 x 1//" NPT air ports module face seal 10 bar
FP	6 x 1/4" RSPP air ports module, face seal 10 har	PP	6 x 1/4" RSPP air ports module, face seal 10 bar
FT	6 x 1/4" BSPT air ports module, face seal, 10 bar	PT	6 x 1/4" BSPT air ports module, face seal 10 bar
••		HN	4 x 3/8" NPT fluid ports module, 100 bar
SIDE C:		HP	4 x 3/8" BSPP fluid ports module, 100 bar
0	No optional module	HT	4 x 3/8" BSPT fluid ports module, 100 bar
E19 [†]	19 pin. 3 Amp. 48 VDC Module w/Turck M12 connector. w/o Cordset	RN*	6 x 1/4" NPT air ports module, single shut-off flat face, 10 bar
2E19***	*2x 19 pin. 3 Amp. 48 VDC Module w/Turck M12 connector. w/o Cordset	RP*	6 x 1/4" BSPP air ports module, single shut-off flat face, 10 bar
G19	19 pin. 5 Amp. 120 VDC Module w/Industrial User Conn., w/o Cable	RT*	6 x 1/4" BSPT air ports module, single shut-off flat face, 10 bar
2G19**	* 2x 19 pin, 5 Amp, 120 VDC Module w/Industrial User Conn., w/o Cable	SN	6 x 1/4" NPT air ports module, double shut-off flat face, 10 bar
[†] Cordset or	plug are sold separately. ***Not compatible with CD, CP or CN sensing option.	SP	6 x 1/4" BSPP air ports module, double shut-off flat face, 10 bar
		ST	6 x 1/4" BSPT air ports module, double shut-off flat face, 10 bar
ELECTRI	CAL ACCESSORIES:	VN	$2 \times 3/4$ " vacuum + $4 \times 1/4$ " air NPT ports module, face sealing
ELCT-04	90° Male Plug, w/o Cable, Solder Type, Cable Clamp for G19	VP	2 x 3/4" vacuum + 4 x 1/4" air BSPP ports module, face sealing
CABL-0	31 90° Male Cordset with 2M Cable for E19	VT	2 x 3/4" vacuum + 4 x 1/4" air BSPT ports module, face sealing
		Wxx**	Servo Gun and Welding Gun Module (Pin and Socket) - Consult factory
		HI	Welding Gun module (3 x 180 Amp spring loaded pins)
		SRxx**	Servo Gun Module (with spring loaded pins)
		HISRxx**	* Servo Gun and Welding Gun module (with spring loaded pins)
		* Used with SN	, SP, or ST modules on robot half.
		** vov ara attribu	ited according to the quotemer wiring diagram. Consult featory

** xx are attributed according to the customer wiring diagram. Consult far

⁺⁺ SRxx module can be mounted on the HI module to use with electric welding gun.

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#### www.comoso.com

# TOOL CHANGER RQC-1200 ROBOT ADAPTER MODULE

MODULAR RQC Series

6.36



Specifications	RQC-120	0
Maximum Payload	1200 lbs	550 Kg
Maximum Moment	30,000 in-lbs	3390 Nm
Weight of <b>RQC</b> Unit only	14.1 lb	6.4 Kg
Weight of Coupled Units	18.4 lbs	8.3 Kg
Pressure Range (locked cylinder)	60~100 psi	4~7 bar
Bore Ø	3.74 in.	95 mm
Displacement	9.38 in ³ .	153.7 cm ³
Temperature Range	-30°~180° F	-35°~80° C
Repeatability	± 0.001 in.	$\pm 0.025 \text{ mm}$
Valve required to actuate	4-way, 2-po	sition





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W

Imperial

1800 lbs.

2400 lbs.

30000 in.-lbs.

30000 in.- lbs.

30000 in.-lbs.

Metric

8000 N

10700 N

3390 Nm

3390 Nm

3390 Nm

, ¦ C

**Loading Capacity** 

Maximum Compressive C

Maximum Moment Mx

Maximum Moment My

Maximum Moment Mz

Maximum Tensile T



## TOOL CHANGER RQC-1200 OPTIONAL MODULES FOR ROBOT ADAPTER



PNEUMATIC ACCESSORIES: SLKT-404 RQC-1200 Standard Seal Repair Kit

# TOOL CHANGER RTP-1200 TOOL ADAPTER MODULE

MODULAR RQC Series

6.38



Specifications	RTP-120	0
Maximum Payload	1200 lbs	550 Kg
Maximum Moment	30,000 in-lbs	3390 Nm
Weight of <b>RTP</b> Unit only	4.3 lb	1.9 Kg
Weight of Coupled Units	18.4 lbs	8.3 Kg
Temperature Range	-30°~180° F	-35°~80° C
Repeatability	± 0.001 in.	±0.025 mm





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## **TOOL CHANGER RTP-1200 OPTIONAL MODULES FOR TOOLING ADAPTER**



How to Order: (Order Accessories separately from Basic Model)

For detailed sensing and module information see pages 8.40 - 8.51

Servo Gun and Welding Gun Module (Pin and Socket) - Consult factory

Welding Gun module (3 x 180 Amp spring loaded pins)

Servo Gun Module (with spring loaded pins) HISRxx**** Servo Gun and Welding Gun module (with spring loaded pins)



SIDE A:		SIDE B	AND/OR D:
0	No optional module	0	No optional module
FN	6 x 1/4" NPT air ports module, face seal, 10 bar	PN	6 x 1/4" NPT air ports module, face seal, 10 bar
FP	6 x 1/4" BSPP air ports module, face seal, 10 bar	PP	6 x 1/4" BSPP air ports module, face seal, 10 bar
FT	6 x 1/4" BSPT air ports module, face seal, 10 bar	PT	6 x 1/4" BSPT air ports module, face seal, 10 bar
		HN	4 x 3/8" NPT fluid ports module, 100 bar
SIDE C:		HP	4 x 3/8" BSPP fluid ports module, 100 bar
0	No optional module	HT	4 x 3/8" BSPT fluid ports module, 100 bar
E19 [†]	19 pin, 3 Amp, 48 VDC Module w/Turck M12 connector, w/o Cordset	RN*	6 x 1/4" NPT air ports module, single shut-off flat face, 10 bar
2E19***	*2x 19 pin, 3 Amp, 48 VDC Module w/Turck M12 connector, w/o Cordset	RP*	6 x 1/4" BSPP air ports module, single shut-off flat face, 10 bar
G19	19 pin, 5 Amp, 120 VDC Module w/Industrial User Conn., w/o Cable	RT*	6 x 1/4" BSPT air ports module, single shut-off flat face, 10 bar
2G19 ***	2x 19 pin, 5 Amp, 120 VDC Module w/Industrial User Conn., w/o Cable	SN	6 x 1/4" NPT air ports module, double shut-off flat face, 10 bar
[†] Cordset or p	olug are sold separately. ***Not compatible with CD, CP or CN sensing option.	SP	6 x 1/4" BSPP air ports module, double shut-off flat face, 10 bar
		ST	6 x 1/4" BSPT air ports module, double shut-off flat face, 10 bar
ELECTRI	CAL ACCESSORIES:	VN	2 x 3/4" vacuum + 4 x 1/4" air NPT ports module, face sealing
ELCT-04	90° Male Plug, w/o Cable, Solder Type, Cable Clamp for G19	VP	2 x 3/4" vacuum + 4 x 1/4" air BSPP ports module, face sealing
CABL-03	90° Male Cordset with 2M Cable for E19	VT	2 x 3/4" vacuum + 4 x 1/4" air BSPT ports module, face sealing

6.39

** xx are attributed according to the customer wiring diagram. Consult factory. ⁺⁺ SRxx module can be mounted on the HI module to use with electric welding gun.

* Used with SN, SP, or ST modules on robot half.

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Wxx** HI

SRxx**

#### www.comoso.com



# E19/G19 Modules connecting with latch/unlatch sensors



	RESERVED PINS NUMBERS ON E19 / G19		
	RQC 200 & 400	RQC 800 & 1200	
LP or LN (Inductive)	<b>R:</b> + 10-30 VDC <b>L:</b> Common <b>M:</b> Lock <b>N:</b> Unlock	R: + 10-30 VDC L: Common M: Lock N: Unlock P: Ready to Couple	
LD (Dry contact)	L: Common M: Lock N: Unlock	L: Common M: Lock N: Unlock P: Ready to Couple	







### **19 Pin Module 3 Amp - 48 VDC (E19)** For RQC/RTP- 200/400/800/1200



Module kits above include: Indexing sleeves and hardware. * Cordset sold separately.







Module kits above include: 90° plug (without cable), indexing sleeves and hardware.

6.43





#### 6 x 1/8" Air Ports Module, Face Seal (FN, FP or FT) For RQC/RTP-200 & RQC/RTP-400

Module kits above include: Seals, indexing sleeves and hardware.

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**TOOL HALF MODULES:** 

**SIDE A** 

FN

**SIDE B** 

800

SIZE

SIDE C

SIDE D

Maximum working pressure: 10 bar

#### **ROBOT HALF MODULES:**



Module kits above include: Seals, indexing sleeves and hardware.

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Maximum working pressure: 10 bar

#### **ROBOT HALF MODULES:**



Module kits above include: Couplings, indexing sleeves and hardware.

#### TOOL HALF MODULES:







# 6 x 1/4" Air Ports Module, Single Shut-Off Flat Face (RN, RP or RT) or Double Shut-Off Flat Face (SN, SP or ST)



**TOOL HALF MODULES:** 

How to Order Modules: RTP-800/1200				
BASIC N	IODEL	SIDE A	SIDE C	
RTP	- 1200	S1	r S	T
	SIZE	SIDE	B SID	ED
PREMOUNTED	SEPARATE			
SN	KSN-RTP800	6 x 1/4" NPT	Air Ports, Self S	Sealing, 10 bar
SP	KSP-RTP800	6 x 1/4" BSP	P Air Ports, Self	Sealing, 10 bar
ST	KST-RTP800	6 x 1/4" BSP	FAir Ports, Self	Sealing, 10 bar
RN	KRN-RTP800	6 x 1/4" NPT	Air Ports, w/o S	Self Sealing, 10 bar
RP	KRP-RTP800	6 x 1/4" BSPF	P Air Ports, w/o	Self Sealing, 10 bar
RT	KRT-RTP800	6 x 1/4" BSP	Γ Air Ports, w/o	Self Sealing, 10 bar

Module kits above include: Couplings, indexing sleeves and hardware.

SH N H

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#### 2 x 3/4" Vacuum Ports Module, Face Seal (VN, VP or VT) For RQC/RTP-200 & RQC/RTP-400

**ROBOT HALF MODULES:** 

**TOOL HALF MODULES:** 



Module kits above include: Seals, indexing sleeves and hardware.



### **ARV Robot Half/Tool Half 4-Port Vacuum Module**



for RQC/RTP-800



3 = 13 = 13 6.48



Module kits above include: Couplings, indexing sleeves and hardware.





**TOOL HALF MODULES:** 

#### 2 x 3/4" Vacuum Ports Module, Face Seal (VN, VP or VT) For RQC/RTP-800 & RQC/RTP-1200

#### **ROBOT HALF MODULES:**

How to O	rder Mo	dules: RQC-800/1200
BASIC MODE	L PORT	SIDE A SIDE C
RQC-	1200 A	-LPVTVT
	SIZE	SENSING SIDE B SIDE D
PREMOUNTED	SEPARATE	
VN	KVN-RQC800	2 x 3/4" Vacuum and
VD		4 X 1/4" Air NPT Ports, Face Sealing
VP	KVF-NUGOUU	4 x 1/4" Air BSPP Ports, Face Sealing
VT	KVT-RQC800	2 x 3/4" Vacuum and
		4 x 1/4" Air BSPT Ports, Face Sealing
ACCESSORIES:		
	SLKT-409	2 x 3/4" Vacuum and
		4 x 1/4" Air Module Seal Repair Kit

#### **BASIC MODEL** SIDE A SIDE C - VT - VT **RTP** 1200 SIZE **SIDE B SIDE D** PREMOUNTED SEPARATE KVN-RTP800 2 x 3/4" Vacuum and VN 4 x 1/4" Air NPT Ports, Face Sealing 2 x 3/4" Vacuum and VP KVP-RTP800 4 x 1/4" Air BSPP Ports, Face Sealing VT KVT-RTP800 2 x 3/4" Vacuum and 4 x 1/4" Air BSPT Ports, Face Sealing

How to Order Modules: RTP-800/1200

9 MODULAR RQC 56 SERIES

Module kits above include: Seals, indexing sleeves and hardware.







Maximum working pressure: 100 bar

#### **ROBOT HALF MODULES:**

MODULAR RQC Series

6.50

How to C	<b>Order M</b>	odules: RO	<b>IC-800/1</b>	200
BASIC MOD	EL POR	T SID	E A SI	DE C
RQC-	800	1-LP-	- HP -	- HP
	SIZE	SENSING	SIDE B	SIDE D
PREMOUNTED	SEPARATE			
HN	KHN-RQC80	<b>0</b> 4 x 3/8" NPT	Fluid Ports, 100	bar
HP	KHP-RQC80	0 4 x 3/8" BSPF	P Fluid Ports, 10	) bar
HT	KHT-RQC80	0 4 x 3/8" BSPT	Fluid Ports, 10	) bar

Module kits above include: Couplings, indexing sleeves and hardware.

**TOOL HALF MODULES:** 

How to Order I	Modules: RTP-800/1200
BASIC MODEL	SIDE A SIDE C
RTP - 800	D HP HP
SIZE	SIDE B SIDE D
PREMOUNTED SEPARA	TE
HN KHN-RTP	BOO 4 x 3/8" NPT Fluid Ports, 100 bar
HP KHP-RTP	<b>BOO</b> 4 x 3/8" BSPP Fluid Ports, 100 bar
HT KHT-RTP	4 x 3/8" BSPT Fluid Ports, 100 bar

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# Servo Module (SRxx) For RQC/RTP-800 & RQC/RTP-1200

**ROBOT HALF MODULES:** 



*SRxx module can be mounted on the HI module to use with electric welding gun. Order HISRxx.

Module kits above include: Plugs, seals, indexing sleeves and hardware.



#### PREMOUNTED SEPARATE

SRxx^{†*} KSRxx-RTP800^{†*} Servo Gun Module (with spring loaded pins) ¹The xx is replaced by two digits depending on wiring request. Wiring may depend on robot and welding gun specifications. Please consult factory

*SRxx module can be mounted on the HI module to use with electric welding gun. Order HISRxx

MODULAR RQC Series

6.52



#### 3 Contacts Module 180 Amp - 630 VAC (HI) For RQC/RTP-800 & RQC/RTP-1200

Module kits above include: Straight plug (without cable, crimp contacts), seals, indexing sleeves and hardware.

# ARV-Auto Release Venturi Vacuum

# Module

• Providing a quick change in vacuum technology

The ARV vacuum module generates vacuum at the tool changer level, which is distributed across (4) ports, then piped independently to end effector vacuum cups.

• Key Features

Single "line-in" air connection

Standard Built-in Silencer (Decibel Level: 72 dBA @ 3 feet) Eliminates the need for individual venturis on each vacuum port

Multiple tools can be supplied vacuum by one ARV vacuum module Will supply vacuum for up to 5 cups

per vacuum channel

Lifetime warranty on venturis

See page 6.48 for dimensions and ordering information Robot Sid



# Also Available for Clean Room Applications:





**RPE Electic Gripper** 



Parts Handlers



**Med-Redi Indexers** 



**Med-Redi Conveyors** 

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ltem	Qty	Name
Rob	ot Half	
01	1	Body
02	1	Piston
03	1	Pin Retainer
04	6	Pin
05	1	Ram
06	2	Sensing Pin
07	2	Stop
08	1	Bracket
09	2	Bushing
10	1	Pin
11	1	Target
20	1	Body, O-Ring
21	1	Body, Plug
22	1	Body, Plug
23	1	Piston, O-Ring
24	1	Retainer, O-Ring
25	1	Retainer, O-Ring
26	1	Piston, Pin
27	1	Piston, Screw
<u>28</u>	2 to 5	Body, Spring
29	1	Body, Pin
30	2	Retainer, SHC Screw
<u>31</u>	1	Target, Spring
32	2	Pin, O-Ring
<u>33</u>	2	Stop, Spring
<u>34</u>	2	Stop, SHC Screw
35	1	Bracket, O-Ring
<u>36</u>	1	Bracket, M12 Plug (optional)
<u>37</u>	3	Bracket, SHC Screw
38	1	Sensor Kit (optional)

#### Tool Half

101	1	Body	
102	1	Ring	
103	1	Diamond Pin	
104	1	Centering Pin	
105	1	Pin	
106	4	Lock Washer	
107	4	SHC Screw	_

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

SK Seal Repair Kit Order #'s See Product Data Sheets



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#### **Robot Half** 5 31 25 11 10 9 27 26 30 24 3 20 21 1 22 4 38 36 29 8 35 37 23 2 28 32 6 7 34 33

**Tool Half** 

# 

#### Assembly Procedure - Robot Half

- 1) Lubricate and install seal (#20) into the body #1
- 2) Install the air port plugs (#21) and (#22) with thread-locker into the body (#1)
- 3) Press in the bushings (#9) into the body
- Lubricate and install seals (#24) and (#25) sizes 800 and 1200 only into the pin retainer (#3)
- 5) Insert the pins (#4) into the pin retainer (#3)
- 6) Lubricate and install seal (#23) onto the piston #2
- 7) Press in the pin (#26) into the piston
- 8) Completely insert the piston (#2) into the pin retainer (#3)
- 9) Sizes 800 and 1200 only: press in the pin (#10) into target (#11) and install the spring (#31) and insert this sub assembly into the pin retainer
- 10) Locate and insert the ram (#5) into the piston and fasten with screw (#27) with thread-locker
- 11) Insert the springs (#28) into the body
- 12) Press in the pin (#29) into the body
- 13) Locate and insert the pin, pin retainer and piston sub-assembly into the body and fasten with screws (#30) with thread-locker

- 14) Lubricate and install seals (#32) into the sensing pins (#6)
- 15) Insert the sensing pins into the body
- 16) Install the springs (#33) on the sensing pins
- 17) Mount stops (#7) with screws (#34) with thread-locker
- 18) Lubricate and install seal (#35) onto the bracket (#8)
- 19) Mount the optional sensor kit (#38) to the bracket
- 20) Mount the optional M12 plug (#36) to the bracket (#8) and connect its connector to the sensor kit connector (#38)
- 21) Insert the sensor, plug and bracket sub assembly into the body and fasten with screws (#37)

#### **Assembly Procedure - Tool Half**

- 1) Insert the ring (#102) with pressed-in pin #105 into the body (#101) and fasten with lock washer (#106) and screws (#107) with thread-locker
- 2) Press in the diamond pin (#103) into the body
- 3) Press in the pin (#104) into the body

# **RQC Series Assembled View**

ltem	Qty	Name

#### **Robot Half**

01	1	Body
02	1	Piston
03	1	Pin Retainer
04	6	Pin
05	1	Ram
06	2	Sensing Pin
07	2	Stop
08	1	Bracket
09	2	Bushing
10	1	Pin
11	1	Target
20	1	Body, O-Ring
21	1	Body, Plug
22	1	Body, Plug
23	1	Piston, 0-Ring
24	1	Retainer, O-Ring
25	1	Retainer, O-Ring
26	1	Piston, Pin
27	1	Piston, Screw
28	2 to 5	Body, Spring
29	1	Body, Pin
30	2	Retainer, SHC Screw
31	1	Target, Spring
32	2	Pin, O-Ring
33	2	Stop, Spring
34	2	Stop, SHC Screw
35	1	Bracket, O-Ring
36	1	Bracket, M12 Plug (optional)
37	3	Bracket, SHC Screw
38	1	Sensor Kit (optional)

#### **Tool Half**

101	1	Body	
102	1	Ring	
103	1	Diamond Pin	
104	1	Centering Pin	
105	1	Pin	
106	4	Lock Washer	
107	4	SHC Screw	

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices

# Please see back cover for DE-STA-CO Global Locations. www.destaco.com

# **TOOL CHANGER TERMINOLOGY**



**Accuracy** – The actual positional differential of the locating dowels between two different Robot Halfs or Tool Halfs.

**Air Module** – Also called pneumatic ports. It refers to the component of the Tool Changer system that passes air through the QuickChange and Tool Plate to the End Effector. The air module is available in face-seal ports and is available with self-sealing or checked valves so that when the QuickChange uncouples, air does not leak and no extra valve is required to shut the air off.

**Alignment Pins** - Pins located on the tool plate that are used to align the Tool Changer to the Tool Plate during the coupling process. DE-STA-CO uses 2 alignment pins – one diamond shaped and one round. Alignment pins also limit moment about the Z axis.

**Checked Valves** – Valves designed for either fluid or pneumatic medium that have a self-sealing mechanism that automatically check the fluid when uncoupled. When a checked valve is used an additional valve is not required to shut-off the fluid or air upon disconnection.

**Deflection** – Defines the amount of movement (slop) expected under a given moment load. This measurement indicates the rigidity of the coupling mechanism.

**DeviceNet** – A communication protocol common to the North American automotive industry. A DeviceNet system communicates over a serial link (daisy chain) to each component on the system. A component can be anything from a proximity switch to a water saver to a robot controller. Each component has a specific address and can be polled for status by the system. A "communication bus" system like this eliminates the need for thousands of I/O wiring points because all the communication is done over a 5-wire (CAN HIGH, CAN LOW, V+, V-, and DRAIN) cable.

**Electrical Module** – Also called an I/O Block or I/O Module, it is a component within the QuickChange system. Electrical I/O (Input/Output) communication is done through this module. Also, internal switches for Couple/Uncouple/Ready-to-Couple may be wired to this module.

**Face-Seal Ports** – Refers to ports used to pass air or vacuum through the Tool Changer such as air for operating the retract feature of a spot weld gun or air to operate a venture vacuum pump on a material handling End Effector. The face-seal ports do not stop air or vacuum flow when the Tool Changer uncouples. They require an additional air valve to shut the air or vacuum off before uncoupling. Face-seal ports only have an 0-ring to prevent air or vacuum loss when the Tool Changer is coupled.

**Locking Mechanism** – The mechanism that locks the Tool Changer to the Tool Plate. It consists of a piston, ram and rollers (rolling pins).

**Manual Tool Changer** – A Tool Changer that requires manual intervention to couple or uncouple.

**Maximum Compression** – Refers to the maximum force that can be applied to the Tool Changer in a –Z direction. Not very important for most applications.

**Maximum Moment (Mx, My, Mz)** – A very important sizing rating because it takes into account the dynamic loads created by the motion of the robot. Mx, My and Mz are the moment created when rotating about the X, Y and Z axis respectively.

**Maximum Payload** – The maximum amount of weight the Tool Changer can handle. A payload rating is used to give the design engineer a general reference for the size of Tool Changer that should be used for an application.

**Maximum Tensile** – The maximum amount of pull away (something in tension) that the QuickChange can tolerate before failure.

**Moment Rating (N-M, In-Lbs)** – The rating given to a QuickChange to describe the maximum amount of moment that the unit can handle and still maintain the published repeatability and performance specifications.

**Offset** – Refers to total Coupled Height of the Tool Changer and Tool Plate. It is important in calculation of moment as a function of Robot Acceleration. The more offset you have, the more moment that will be created as the Robot accelerates. Offset may limit maximum Payload allowed.

**Payload** – Refers to the weight of the Tool Changer and/or End Effector and part to be handled by the robot.

**Payload Rating (Lbs, Kg)** – Refers to the maximum weight that the robot or Tool Changer can carry safely. Maximum Payload Rating is limited by and needs to consider Offset, weight and envelope size of the End Effector and part to be handled as well as robot acceleration in order to calculate proper moment load.

**Ready-To-Couple** – A switch that indicates the QuickChange is in the proper orientation to couple with the Tool Plate. It indicates that the Tool Changer is close enough to the Tool Plate to activate the Locking Mechanism. It is important for the robot controller to make decisions such as drop-off End Effector, Couple tool, Uncouple tool. Also refers to a switch that reads if the Tool Changer is in a Ready-to-couple position, that is, in close proximity to the Tool Plate (0.100 inch).

**Repeatability** – The ability to go back to a pre-programmed point. In the context of a Tool Changer this indicates the ability to couple with precision so that additional misalignment is not introduced into the tooling.

**Robot Acceleration** – Refers to the rate of increase in speed at which the robot will operate. Important for calculating maximum moment rating or maximum payload rating when considering offset, envelope size, weight of end effector and weight of part.

 ${\bf Self-Sealing}-{\sf A}$  port that seals itself when it uncouples from its mating half. Conversely, the port automatically opens when it couples with it mating half.

**Servo Module** – Refers to a component within the QuickChange system for special applications using a servo-powered spot weld gun or servopowered slide/cylinder. Electrical I/O (Input/Output) communication is also done through this module. Bolts on to the tool changer where the Electrical Module would normally mount.

**Water Module** – Refers to the component of the Gun Changer system that passes cooling water through the QuickChange and Tool Plate to and from the spot weld gun, transformer, kickless cables and shunts. The water module has self-sealing or checked ports so that when the QuickChange uncouples, water does not leak and no extra valve is required to shut the water off.

**Weld Module** – Also called a 200 Amp Module, it is a component within the Gun Changer system. Weld Current is passed from the Weld Controller to the transformer for use by the spot weld gun. The DE-STA-CO Weld Module is rated for the maximum current rating of 200 Amps at 100% duty cycle (constant power on).

**Vacuum Module** – Refers to the component of the Tool Changer system that passes vacuum and air through the QuickChange and Tool Plate to the End Effector. The vacuum module comes standard with face-seal ports. An extra valve is required to shut the vacuum and air off.



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# **Compliance** Wrist

- Robotic applications: Excellent for inserting components that may be misaligned or skewed with respect to mating components. Reduces part jamming which could transmit excessive forces back to the robot .
- Automation applications: For insertion applications where part positioning may be less than precise. Compliance in torsion, bending and lateral directions allow this devise to compensate for part placing inaccuracies.



### **Mounting Information:**



### **Technical Specifications:**

**Pneumatic Specifications** Pressure Operating Range Cylinder Type **Dynamic Seals** Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Double Acting** Internally Lubricated Buna-N 4-way, 2-position

#### **Air Quality Requirements**

Air Filtration	40 Micron or Better
Air Lubrication	Not Necessary*
Air Humidity	Low Moisture Content (dry)
	,

**Temperature Operating Range** Buna-N Seals (standard) -20°~180° F -30°~80° C

#### Maintenance Specifications⁺

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available *Addition of lubrication will greatly increase service life *See Maintenance Section

5 million cycles 10+ million cycles* Yes Yes



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6.9 BCW SERIES

# **COMPLIANCE WRIST RCW-50-3**

**RCW SERIES** 

6.60







# **COMPLIANCE WRIST RCW-80-3**



	importai	mouno
Torsional Stiffness about Z axis	248 in-lbs/deg	28 N-m/deg
Lateral Stiffness (X and Y axis)	228 lbf/in	40 N/mm
Axial Stiffness (compression Z axis)	9136 lbf/in	1600 N/mm
Insertion Point L Max	4 in.	100 mm

# **COMPLIANCE WRIST RCW-100-4**





# **29.9** RCW SERIES

# Loading Information





Loading Capacity [†]	Imperial	Metric	
Maximum Force F	34 lbs.	150 N	
Maximum Tension T	124 lbs.	550 N	
Maximum Compressive C	124 lbs.	550 N	
Maximum Moment Mx	177 inIbs.	20 Nm	
Maximum Moment My	177 inIbs.	20 Nm	
Maximum Moment Mz	177 inIbs.	20 Nm	
Maximum Payload W	8 lbs.	3.5 Kg	
Maximum Tension <b>T</b> Maximum Compressive <b>C</b> Maximum Moment <b>M</b> _X Maximum Moment <b>M</b> y Maximum Moment <b>M</b> z Maximum Payload <b>W</b>	124 lbs. 124 lbs. 177 inIbs. 177 inIbs. 177 inIbs. 8 lbs.	550 N 550 N 20 Nm 20 Nm 20 Nm 3.5 Kg	

# **Stiffness Information**

	Imperial	Metric	
Torsional Stiffness about Z axis	412 in-lbs/deg	46 N-m/deg	
Lateral Stiffness (X and Y axis)	286 lbf/in	50 N/mm	
Axial Stiffness (compression Z axis)	11991 lbf/in	2100 N/mm	
Insertion Point L Max	6 in.	150 mm	

# How to Order:

 $\Rightarrow \oplus$ 

Third Angle

Projection

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Dimensions are symmetrical about centerline



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

 $\bullet$ 

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]  $\odot$ 

Metric Threads Course Pitch Imperial in.

 $\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$ 

Metric [mm]

Please see back cover for DE-STA-CO Global Locations. www.destaco.com



# **COMPLIANCE WRIST RCW-100-6**

**RCW SERIES** 

6.63



#### www.comoso.com

# **COMPLIANCE WRIST RCW-125-6**

**RCW SERIES** 

6.64







# **COMPLIANCE WRIST RCW-160-6**



# **COMPLIANCE WRIST RCW-160-8**

**RCW SERIES** 

6.66









# **COMPLIANCE WRIST RCW-200-12**

Specifications	RCW-200	)-12
Maximum Payload	115 lbs	52 Kg
Misalignment Capability	±0.118 in.	±3 mm
Maximum Rotation	±1º	±1°
Weight	18.3 lbs.	8.3 Kg
Pressure Range (locked cylinder)	40-100 psi	3-7 bar
Temperature Range	-20°~180° F	-30°~80° C
Locking Force @ 80 PSI [5.5 bar]	400 lbs	1779 N
Valve required to actuate	4-way, 2-j	position

6760°

Metric [mm]

#### С Т M_Y, Loading Capacity[†] Imperial Metric 300 N Maximum Force F 68 lbs. Maximum Tension T 450 lbs. 2000 N Maximum Compressive C 450 lbs 2000 N Maximum Moment Mx 709 in.-Ibs. 80 Nm Maximum Moment My 709 in.-1bs. 80 Nm

# **Stiffness Information**

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Maximum Moment Mz

Maximum Payload W

	Imperial	Metric
Torsional Stiffness about Z axis	1632 in-lbs/deg	184 N-m/deg
Lateral Stiffness (X and Y axis)	570 lbf/in	100 N/mm
Axial Stiffness (compression Z axis)	36544 lbf/in	6400 N/mm
Insertion Point L Max	16 in.	400 mm

709 in.-1bs.

115 lbs.

80 Nm

52 Kg

# **COMPLIANCE WRIST RCW-300-12**

**RCW SERIES** 

6.68





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www.comoso.com




# **RCW Series Exploded View**

### Item Qty Name

01	1	Top Plate
02	Х	Flexible Element
03	1	Bottom Plate
04	1	Locking Cylinder
05	1	Overload Pin
06	1	Piston
07	1	Сар
08	1	Centering Cone

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



Seal Repair Kit Order #'s See Product Data Sheets



Δ GLUE SK 0 G  $\Rightarrow \oplus$ KRYTOX Seal Kit Items Thread Locker Krytox™ Lubricant Lightweight Machine Oil Teflon® Based Grease Super Bonder Third Angle Projection

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

# **Lateral Compliance Device – Pneumatic** Centering

### **Robotic applications:**

For inserting components that may be laterally misaligned with respect to mating parts. Reduces part jamming which could transmit excessive forces to the robot. Robot and tool side mounting

patterns are made to DIN robot mounting standards.

### Automation applications:

For insertion applications where part positioning may be less than precise. Compliance in lateral directions allows this device to compensate for part placing inaccuracies. Reduces jamming of mating components.



# **Mounting Information:**





The tool side has tapped holes for mounting and a pilot hole and dowel hole for positioning





### **Technical Specifications:**

**Pneumatic Specifications** Pressure Operating Range Cylinder Type Dynamic Seals Valve Required to Operate

Imperial Metric 40-100 psi 3-7 bar **Double Acting** Buna-N 4-way, 2-position

### **Air Quality Requirements**

Air Filtration Air Lubrication Air Humidity

40 Micron or Better Not Necessary* Low Moisture Content (dry)

5 million cycles

10+ million cycles*

-30°~80° C

-20°~180° F

**Temperature Operating Range** 

Buna-N Seals (standard)

Maintenance Specifications[†] Expected Life Normal Application

w/ Preventative Maintenance

### **Application Restrictions**

- · Dirty or gritty environments
- Machining operations generating chips
- · Environments with loose particulate
- *Addition of lubrication will greatly increase service life *See Maintenance Section



. In the locked position, the tool half is brought back on center with respect to the robot half with the use of cone centering which is actuated by the built in air cylinder.

200 Kg

25 mm

52 Kg

KA-80R

1 Kg 2mm

2.5 Kg 2mm

**KA-125** b 5 Kg in. 3.00mm

KA-160 11 Kg 4mm 3.2 Kg

ka series

6.71

2.0 Kg

# LATERAL ALIGNMENT KA-80R PNEUMATIC CENTERING SERIES





Please see back cover for DE-STA-CO Global Locations. www.destaco.com



# **LATERAL ALIGNMENT KA-100** PNEUMATIC CENTERING SERIES

2.5 Kg

±2 mm

0.82 Kg

3-7 bar

311 N

-30°~80° C

±0.03 mm

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QTY/UNIT

1

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	<b>KA SERIES</b>	
6	).7	4

UNLE	UNLESS UTHERWISE NUTED ALL TULERANCES ARE AS SHOWN BELOW					
Ģ	$\Rightarrow$	•	$\oplus$	Imperial in.	Metric [mm]	
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{l} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$		

### Loading Information





### **Loading Capacity** Imperial Metric Maximum Tensile T 90 lb 400 N Maximum Compressive C 90 lb 400 N Maximum Moment $\mathbf{M}_{\mathbf{X}}$ 265 in.-Ib 30.0 Nm Maximum Moment My 265 in.- lb 30.0 Nm Maximum Moment Mz 265 in.-Ib 30.0 Nm Maximum Payload W 5 lb 2.5 Kg

# How to Order:

**PNEUMATIC ACCESSORIES** 

Standard Seal Repair Kit

**BASIC MODEL** KA-100

> **ORDER** # **SLKT-132**

Please see back cover for DE-STA-CO Global Locations. www.destaco.com www.comoso.com

# LATERAL ALIGNMENT KA-125 PNEUMATIC CENTERING SERIES





Specifications	KA-125	
Maximum Payload	10 lbs	5 Kg
Misalignment Capability	±0.12 in.	±3 mm
Weight	4.4 lb	2.0 Kg
Pressure Range (locked cylinder)	40-100 psi	3-7 bar
Temperature Range	-20°~180° F	-30°~80° C
Locking Force @ 80 PSI [5.5 bar]	120 lbs	533 N
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-	position



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Ģ	$\Rightarrow \oplus$	•	$\oplus$	Imperial in.
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$

### Loading Information

**KA SERIES** 

6.74

### How to Order:

<u> </u>		W
C		
	Imperial	Metric

10 lb

### Loading Capacity Maximum Tensile T Maximum Compressive C Maximum Moment My Maximum Moment My Maximum Moment Mz Maximum Payload W

Imperial	Metric
180 lb	801 N
180 lb	801 N
530 inIb	59.9 Nm
530 inIb	59.9 Nm
530 inlb	59.9 Nm

5 Kg

# **BASIC MODEL**



PNEUMATIC ACCESSORIES Standard Seal Repair Kit ORDER # SLKT-133 QTY/UNIT

1







LATERAL /	ALIGNMENT	KA-160
PNEUMATIC	CENTERING	SERIES

Specifications	KA-160	
Maximum Payload	25 lbs	11 Kg
Misalignment Capability	±0.15 in.	±4 mm
Weight	7.0 lb	3.2 Kg
Pressure Range (locked cylinder)	40-100 psi	3-7 bar
Temperature Range	-20°~180° F	-30°~80° C
Locking Force @ 80 PSI [5.5 bar]	120 lbs	533 N
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-j	position



### UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Imperial in. Metric [mm]

 $\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$ 

С С
Dimensions are
symmetrical about
centerline





**KA SERIES** 6.75

QTY/UNIT

1

# **Loading Information**

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### How to Order:

Mz - 21 C I T M_{Y,X}

	W	ł

Loading Capacity	Imperial	Metric
Maximum Tensile T	225 lb	1001 N
Maximum Compressive C	225 lb	1001 N
Maximum Moment Mx	885 inIb	100.0 Nm
Maximum Moment My	885 inIb	100.0 Nm
Maximum Moment Mz	885 inIb	100.0 Nm
Maximum Payload W	25 lb	11 Kg

# **BASIC MODEL** KA-160

**PNEUMATIC ACCESSORIES ORDER** # Standard Seal Repair Kit SLKT-134

### LATERAL ALIGNMENT KA-200 PNEUMATIC CENTERING SERIES





### - unless otherwise noted all tolerances are as shown below -

ę	-
Dimensions are	
symmetrical about	
centerline	

Third Angle Projection All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

ices ak	e ag ghown r	
$\oplus$	Imperial in.	Metric [mm]
ric Threads urse Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	

### Loading Information

### **How to Order:**



**BASIC MODEL** 



PNEUMATIC ACCESSORIES Standard Seal Repair Kit ORDER # SLKT-135 **OTY/UNIT** 

1

Loading Capacity	Imperial	Metric	
Maximum Tensile T	360 lb	1601 N	
Maximum Compressive C	360 lb	1601 N	
Maximum Moment Mx	1327 inIb	150.0 Nm	
Maximum Moment My	1327 inIb	150.0 Nm	
Maximum Moment Mz	1327 inIb	150.0 Nm	
Maximum Payload W	90 lb	40 Kg	



# **LATERAL ALIGNMENT KA-300 PNEUMATIC CENTERING SERIES**

Specifications	KA-300	
Maximum Payload	440 lbs	200 Kg
Misalignment Capability	±0.98 in.	±25 mm
Weight	115 lb	52 Kg
Pressure Range (locked cylinder)	40-100 psi	3-7 bar
Temperature Range	-20°~180° F	-30°~80° C
Locking Force @ 80 PSI [5.5 bar]	725 lbs	3224 N
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	4-way, 2-	position





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Metric Threads Course Pitch

Imperial in.

 $\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$ 

Metric [mm]

# **Loading Information**

### **How to Order:**

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Third Angle Projection

0

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]



Dimensions are symmetrical about centerline

54 24 25

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6.78



### Item Qty Name

01	1	Robot Half
02	1	Tool Half
03	4	Way
04	1	Center Rail
05	1	Piston
06	1	Bushing
07	4	Roller Cage Half
08	4	Roller Cage Full
09	1	Сар
10	1	Retaining Ring
11	12	Socket Head Screw
12	4	Set Screw
13	1	0-Ring
14	1	0-Ring
15	1	0-Bing

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

### **Preload Adjustment**

- 1) Loosen the six socket head cap screws on the robot half (1) about 1/2 turn.
- Seat the way (3) that is furthest from the preload set screws (4) in position and using loctite on the threads, tighten those three screws to fasten the way in place.
- 3) Evenly advance the two preload set screws to a point where there is no play in the robot half.
- 4) Using loctite on the threads, tighten the remaining three screws to fasten the way (3) in place. NOTE: There is a possibility that when the second set of screws are tightened, the preload will increase - if this happens, loosen the three screws again and back off slightly and evenly on the two preload adjustment set screws.
- 5) Follow 1 thru 4 again to adjust the preload for the tool half (2).
- Be sure that the bearings glide freely - if the unit becomes choppy then the preload might be too tight.
- 7) As a check to see that the preload has been set properly, you should be able to push on the end of one of the nylon bearing cages with about 3 pounds, and that half will move without the bearing skidding.

SK Seal Repair Kit Order #'s See Product Data Sheets





# KA-100~300 Series Exploded View

**Centering Cone** 

Rail, Moveable

Top Plate

Rail, Fixed

Bearings

Shaft 1

Сар 1

Piston

**Bottom Plate** 

Center Plate



1

1

4

4

4

8 Stop

1

1

1





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# **Cylindrical Horizontal Compliance Devices**



- Flexibility of the tool: Cylindrical Horizontal compliance devices are used for inserting components that may be misaligned with the tool. They allow a horizontal displacement that compensates for part placing inaccuracies.
- For precision applications: The use of high quality components allow to get centering repeatability from 0.02mm and angular repeatability from +/- 10°.
- Harsh environments: The enclosed design of this series allows them to be used in harsh environments.
- Spring assist:

Due to the optional spring assist, compliance may be used in single acting mode.

### **Mounting Information:**

It is recommended to use the compliance in the vertical axis only



The compliance is located using a pilot boss and a dowel pin and assembled using 4 or 6 through body screws

Compliance can be operated using top manifold airport



Tooling is located using a centering and a dowel pin and assembled using 4 screws



Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic seals	Imperial Metric 30-100 psi 2-7 bar Double acting or double acting spring assist or single acting spring return Internally lubricated Buna-N seals
Valves Required to Operate Double Acting Single Acting (-RL or -RA op	4-way, 2 position otion) 3 way, 2 position
<b>Air Quality Requirements</b> Air Filtration Air Lubrication Air Humidity	40 Micron or Better Not Necessary* Low Moisture Content (dry)
Temperature Operating Range Joints Nitrile (standard)	-10°~180° F -25°~80° C
Maintenance Specifications Expected Life Normal Application w/ Preventative Maintenanc Field Repairable Seal Repair Kits Available	s 3 million cycles e 6+ million cycles Yes Yes Yes
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'Addition of lubrication will greatly increase service life "See Maintenance Section



- The two perpendicular slots of the crossed ring enables the tooling to keep its orientation.
- The spring assist option allows to center (RA) or to release (RL) the output flange in case of air failure. It also allows the use in single acting mode.

CH-50

CH-80

CH-110

CH-140

CH-165

### CH-50 CYLINDRICAL HORIZONTAL COMPLIANCE DEVICES



- I: Tool Plate Option	
[3.5] for [M3] SHC screws (16.0] 00.630 (02.5 H9]	[10.0] 0.394 0.394 0.079 [20 H7] ¢0.7874 [20 H7] ¢0.7874

Specifications	CH-50	
Centering force @100psi [7 bar]	74 lbs.	332 N
Maximum payload	4.4 lbs.	2 Kg
Misalignment Capability	±0.12 in.	±3 mm
Weight	0.43 lbs.	0.195 Kg
Pressure Range (without springs)	30-100 psi	2-7 bar
Pressure Range (with springs)	43-100 psi	3-7 bar
Cylinder bore	1.34 in.	34 mm
Displacement	0.32 in ³ .	5.2 cm ³
Actuation	0.07 sec. /0.	07 sec
Repeatability	±0.0008 in.	±0.02 mm
Angular repeatability	±10m	n

	ss otherv	VISE NOTED ALL TOLE	RANCES AR	E AS SHOWN B	ELOW —
Ģ	$\Rightarrow \oplus$	$\bullet$	$\oplus$	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	

Loading Information



			BASIC MODEL TOOL PLATE
C T Mx,y	× Mz		SPRING ASSIST MISALIGNMENT SPRING RA Tool Recentering RL Tool Release Leave Blank. No Spring Option (standard)
Loading Capacity	Imperial	Metric	MISALIGNMENT XX Special Misalignment x 10 (ie: 15 is for +/- 1.5mm)
Maximum Tensile <b>T</b>	17 lbs.	75 N	Leave Blank. Standard Capability
Maximum Breakaway Compressive C	17 lbs.	75 N	
Maximum Breakaway Moment Mx	17.7 inIbs.	2 Nm	
Maximum Breakaway Moment My	17.7 inIbs.	2 Nm	
Maximum Breakaway Moment Mz	8.8 in1bs.	1 Nm	

### Please see back cover for DE-STA-CO Global Locations. www.destaco.com



# CH-80 CYLINDRICAL HORIZONTAL COMPLIANCE DEVICES



6.83

SERIES

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# **CH-110** CYLINDRICAL HORIZONTAL COMPLIANCE DEVICES





MISALIGNMENT XX Special Misalignment x 10 (ie: 15 is for +/- 1.5mm) Leave Blank. Standard Capability

Please see back cover for DE-STA-CO Global Locations. www.destaco.com

Metric

190 N

190 N

12 Nm

12 Nm

18 Nm

Imperial

43 lbs.

43 lbs.

106 in.-Ibs.

106 in.-Ibs.

159 in.-Ibs.

Mx,y

Maximum Breakaway Compressive C

Maximum Breakaway Moment Mx

Maximum Breakaway Moment My

Maximum Breakaway Moment Mz

**Loading Capacity** 

Maximum Tensile T



# CH-140 CYLINDRICAL HORIZONTAL COMPLIANCE DEVICES



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6.85

# **CH-165** CYLINDRICAL HORIZONTAL COMPLIANCE DEVICES





Specifications	CH-165	
Centering force @100psi [7 bar]	931 lbs.	4140 N
Maximum payload	88.2 lbs.	40 Kg
Misalignment Capability	±0.47 in.	±12 mm
Weight	19.2 lbs.	8.7 Kg
Pressure Range (without springs)	30-100 psi	2-7 bar
Pressure Range (with springs)	60-100 psi	4-7 bar
Cylinder bore	4.72 in.	120 mm
Displacement	14.40 in ³ .	236 cm ³
Actuation	0.36 sec. /0.	36 sec.
Repeatability	±0.0024 in.	$\pm 0.06 \text{ mm}$
Angular repeatability	±20mn	



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW						
Ģ	$\Rightarrow \oplus$	$\bullet$	$\oplus$	Imperial in.	Metric [mm]	
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	$\begin{matrix} [0.] = [\pm.25] \\ [0.0] = [\pm.13] \\ [0.00] = [\pm.013] \end{matrix}$	

### **Loading Information**

**CH SERIES** 

6.86

# How to Order: (Order Accessories separately from Basic Model)







# CH Series Exploded View

### Item Qty Name

1	1	Body
2	1	Piston
3	1	Centering cone
4	1	Сар
5	1	Crossed ring
6	1	Output flange
7	1	Bottom case
8	2	Sleeve
9	4	Key
50	1	O-ring, Cap
51	2	O-ring, Cap
52	4	SS screw, Cap
<u>53</u>	2	SHC screw, Cap
54	1	O-ring, Piston
55	1	O-ring, Piston
56	1	O-ring, Centering cone
57	1	LHC screw, Piston
58	1	Washer, Piston
<u>61</u>	2	Pin, Key
62	2	Pin, Sleeve
65	2	Pin, Body
66	4	SHC screw, Flask
67	6	Spring

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

6.87

### **Assembly Procedures**

- 1) Press-in the bushing (#8) into the body (#1)
- 2) Insert the pins (#65) into the body (#1)
- 3) Lubricate and insert the pins (#62) into the bushings (#8)
  4) Lubricate and insert the keys (#9) into the pins (#62)
- 5) Lubricate and assemble the crossed ring (#5) onto the body (#1). The keys (#9) have to be positioned into the slots of the crossed ring
- 6) Insert the pins (#61) into the output flange (#6)
- 7) Lubricate and insert the keys (#9) into the pins (#61)
- 8) Assemble the sub assembly output flange and keys on the crossed ring (#5). The keys (#9) have to be positioned into the slots of the crossed ring
- 9) Mount the bottom case (#7) onto the body, positioning with the pins (#65).
- 10) Fasten the bottom case (#7) using the screws (#66) with thread locker
- 11) Insert the O-Ring (#56) into the centering cone (#3)
- 12) Insert the O-Ring (#54) into the inside groove of the piston (#2)

- 13) Insert the O-Ring (#55) into the outside groove of the piston (#2)
- 14) Assemble the piston (#2) with the centering cone (#3). For -RL option, the piston counterbore holes have to face the body counterbore holes. Opposite mounting for -RA option.
- 15) Fasten the centering cone (#3) with the piston (#2) using the washer (#58) and the screw (#57) with thread locker
- 16) For -RL option, insert the springs (#67) into the body and piston counterbore holes.
- 17) Insert the piston + centering cone sub assembly into the body
- 18) For –RA option, insert the springs (#67) into the cap and piston counterbore holes.
- 19) Insert the O-Ring (#50) into cap groove (#4)20) Insert the O-Ring (#51) into counterbore holes of the cap (#4)
- 21) Screw the SS screws into the cap (#4) with thread locker
- 22) Locate and insert the cap (#4) into the body (#1) using the screws (52) with thread locker.



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### item Qty Name

1	1	Body
2	1	Piston
3	1	Centering cone
4	1	Сар
5	1	Crossed ring
6	1	Output flange
7	1	Bottom case
8	2	Sleeve
9	4	Кеу
50	1	O-ring, Cap
51	2	O-ring, Cap
52	4	SS screw, Cap
53	2	SHC screw, Cap
54	1	O-ring, Piston
55	1	O-ring, Piston
56	1	O-ring, Centering cone
57	1	LHC screw, Piston
58	1	Washer, Piston
61	2	Pin, Key
62	2	Pin, Sleeve
65	2	Pin, Body
66	4	SHC screw, Flask
67	6	Spring

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



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# **Robot Load Limiters**



### • Robotic applications: Robots are designed to operate within certain load limits. The robot load limited protects the robot from overloads caused by collisions, excessive loading, or programming errors by providing a coupling that separates before the robots design limits are exceeded. A switch signals the robot to stop if a de-coupling occurs.

• Automation applications: For insertion applications, part picking and placing. The load limiter can protect the part, the fixture or the assembly machine from overload in compressive, bending or torsional overload situations.

### **Mounting Information:**



Robot side has counter

bored holes for mounting with a dowel hole and raised boss for location



The tool side has tapped holes for mounting and a pilot hole and dowel hole for positioning

### **Technical Specifications:**

Presure Operating Range Cylinder Type Valve Required to Operate	<b>Imperial</b> 40-100 psi Non-Conve 3-way, 2-p	<b>Metric</b> 3-7 bar entional position
<b>Air Quality Requirements</b> Air Filtration Air Lubrication Air Humidity	40 Micron Not Nece Low Moisture C	or Better ssary* Content (dry)
Temperature Operating Range	-20°~180° F	30°~80° C
Maintenance Specifications Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available	s ^t 5 million e 10+ millio Yes Yes	cycles n cycles
<ul><li>Application Restrictions</li><li>Dirty or gritty environments</li></ul>		

- · Machining operations generating chips
- Environments with loose particulate

*See Maintenance Section



 When the collision is cleared and the tool is manually returned to the normal orientation the sensor can reactivate the valve to re-pressurize the device.

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**Style-ULS Load Limiter** Style: Axial Breakaway: Weight: ULS-80 DS. 1068 N 240 lbs. 1.3 lbs. 0.59 Kg See 6.92 **Style-ULS Load Limiter** Style: Axial Breakaway: Weight: ULS-100 1468 N 0.85 Kg 330 lbs. 1.87 lbs. See 6.93 **Style-ULS Load Limiter** Style: Axial Breakaway: ULS-125 620 lbs. 2750 N Weight: 3.52 lbs. 1.6 Kg See 6.94 **Style-ULS Load Limiter** ULS-160 lbs. 5000 N Style: Axial Breakaway: 1125 lbs. Weight: 7.1 lbs. 3.2 Kg See 6.95 **Style-ULS Load Limiter** ULS-200 Style: Axial Breakaway: Weight: 1750 lbs. 21.56 lbs. 7784 N 9.8 Kg See 6.96 **Style-ULS Load Limiter** Style: Axial Breakaway: Weight: ULS-250 9000 N 16 Kg 2025 lbs. 35 lbs See **6.97 Style-ULS Load Limiter** Style: Axial Breakaway: ULS-300 2475 lbs. 11,000 N 53 lbs. 24 Kg Weight: See **6.98** 

**JLS SERIES** 

6.91

# ULS-80 ROBOT LOAD LIMITER SERIES





Specifications	ULS-8	0
Maximum Payload	8.8 lbs.	4.0 Kg
Rotational Compliance (X and Y axis)	10°	10°
Rotational Compliance (Z axis)	360°	360°
Axial Compliance (Z axis)	0.47 in.	12 mm
Weight	1.3 lbs.	0.59 Kg
Pressure Range (locked cylinder)	15-100 psi	1-7 bar
Temperature Range	-5°~160° F	-20°~70° C
Repeatability	±0.001 in.	±0.03 mm
Valve required to actuate	3-way, 2-	position



	<b>ULS SERIES</b>	
6	<b>).</b> 9	)

**Loading Information** 

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UNLE	39 UIDENV	VISE NUTED ALL TULE	NANGES AN	IE AS SHOWIN D	ELUW
F F	$\Rightarrow$	$\bullet$	$\oplus$	Imperial in.	Metric [mm]
Dimensions are symmetrical about centerline	Third Angle Projection	All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]	Metric Threads Course Pitch	$\begin{array}{c} 0.00 = \pm .01 \\ 0.000 = \pm .005 \\ 0.0000 = \pm .0005 \end{array}$	$\begin{array}{l} [0.] = [\pm .25] \\ [0.0] = [\pm .13] \\ [0.00] = [\pm .013] \end{array}$
How to Order: (Order Accessories separately from Basic Model)					

			BASIC MO	DEL	
	—x		ULS	<b>S-80</b>	
Мх, ч			PNEUMATIC ACCESSORIES	ORDER #	QTY/UNIT
Z			Standard Seal Repair Kit	SLKT-137	1
Loading Capacity at 90 psi 6 bar	Imperial	Metric			
Maximum Breakaway Compressive C	240 lbs.	1068 N			
Maximum Breakaway Moment Mx	210 inIbs.	24 Nm	Maximum Uverioad		
Maximum Breakaway Moment My	210 inIbs.	24 Nm			
Maximum Breakaway Moment <b>Mz</b>	210 inIbs.	24 Nm	N Ibs. AXIAL LOADING 1113 250 890 200 668 150 223 50 0 0 15 30 45 60 75 90 PSI 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Nm         in.lbs.         MOMENT LOA           28.2         250         22.6         200           11.3         100         5.6         50           0         0         15         30         45	DING

PRESSURE

PRESSURE

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### А Α Ŷ. Ø3.898 [Ø99.0] Ø1.9685 .118 .47 [Ø50h7] [3.0] [12] .709 [18.0] 1.339 Ð, [34.0] ł 2.362 ŧ [60.0] .118 [3.0] .315 Ø1.9685 [8.0] M5 AIR PORT [Ø50H7] (FITTING SUPPLIED FOR .25 [6] O.D. TUBING) Ø3.898 [Ø99.0]



# **ULS-100 ROBOT LOAD LIMITER SERIES**





### **UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW**

Dimensions are Third Angle All Dowel Holes are SF (Slip Fit). Metric symmetrical about Projection Locational Tolerance Cours centerline ±.0005" or [±.013mm]	$\rightarrow$ Imperial in.         Metric [mm]           'hreads $0.00 = \pm .01$ $[0.] = [\pm .25]$ $0.000 = \pm .005$ $[0.0] = [\pm .13]$ $0.000 = \pm .0005$ $[0.00] = [\pm .013]$
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### **Loading Information**



# How to Order: (Order Accessories separately from Basic Model)

**BASIC MODEL ULS-100** 

PNEUMATIC ACCESSORIES	ORDER #
Standard Seal Repair Kit	SLKT-138

SLKT-138	

QTY/UNIT

1

Maximum Overload



Loading Capacity at 90 psi 6 bar Imperial Metric Maximum Breakaway Compressive C 330 lbs. 1468 N Maximum Breakaway Moment Mx 350 in.-Ibs. 40 Nm Maximum Breakaway Moment My 350 in.-Ibs. 40 Nm Maximum Breakaway Moment Mz 40 Nm 350 in.-Ibs.

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**JLS SERIES** 6.93

# **ULS-125 ROBOT LOAD LIMITER SERIES**

**ULS SERIES** 

6.94



PRESSURE



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# ULS-160 ROBOT LOAD LIMITER SERIES



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PRESSURE

www.comoso.com

PRESSURE

# **ULS-200 ROBOT LOAD LIMITER SERIES**





### **Loading Information**



How	to Orde	(Order Accessorie	es separately from	Basic Mod



PNEUMATIC ACCESSORIES	
Standard Seal Repair Kit	

ORDER # QTY/UNIT **SLKT-141** 1

Loading Capacity at 90 psi 6 bar	Imperial	Metric	M
Maximum Breakaway Compressive C	1750 lbs.	7784 N	
Maximum Breakaway Moment Mx	4500 in1bs.	509 Nm	N
Maximum Breakaway Moment My	4500 in1bs.	509 Nm	8900
Maximum Breakaway Moment Mz	4500 in1bs.	509 Nm	





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**ULS SERIES** 6.96



## ULS-250 ROBOT LOAD LIMITER SERIES



Imperial	Metric
2025 lbs.	9000 N
5400 in1bs.	610 Nm
5400 in1bs.	610 Nm
5400 in1bs.	610 Nm
	Imperial 2025 lbs. 5400 in1bs. 5400 in1bs. 5400 in1bs.

# **Maximum Overload**



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## ULS-300 ROBOT LOAD LIMITER SERIES





Loading Information			How to Order: (Order Accessories separately from Basic Model)						
	v		BASIC MODEL ULS-300						
	~		PNEUMATIC ACCESSORIES Standard Seal Repair Kit	ORDER # SLKT-433	qty/unit 1				
Loading Capacity at 90 psi 6 bar Maximum Breakaway Compressive C	Imperial 2475 lbs.	Metric 11,000 N	Maximum Overload						
Maximum Breakaway Moment <b>Mx</b> Maximum Breakaway Moment <b>My</b> Maximum Breakaway Moment <b>Mz</b>	6195 mIbs. 6195 inIbs. 6195 inIbs.	700 Nm 700 Nm 700 Nm	N lbs. AXIAL LOADING 4900 2000 6675 1500 4450 1000 0 1 5 30 45 60 75 90 PS PRESSURE	Nm in.lbs. 904 8000 791 7000 678 6000 565 5000 565 5000 452 4000 113 1000 0 15 30 45 66 0 1 2 3 4 PRESSURE	6 75 90 PSI 5 6 Bar				

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# **ULS Series Exploded View**

### Item Qty Name

01	1	Body
02	1	Top Plate
03	1	Bottom Plate
04	1	Sensor
05	1	Pressure Plate

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



SK Seal Repair Kit Order #'s See Product Data Sheets





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# **Emergency Stop Modules**



Safety:

This module is used between a robot and the tooling. It protects the part, the fixture or the assembly machine for overload in compressive, bending or torsional overload situations.

- Wide deflecting motion: The wide deflecting motions coupled to the electric pressure sensor avoid expensive expenses and maintenance breakdowns.
- Variable trip point: Adjusting the pressure from 2 to 10 bars allow to set a precise trip point as required by the application.
- Compact and robust: These modules are designed for harsh environment applications.

### **Mounting Information:**

Modules can be mounted & operated in any orientation



The module is located using pilot boss and a dowel pin and assembled with 4 thru body screws



The tooling is located using pilot boss and a dowel pin and assembles with 3 or 4 screws Using the blank plate allows the customer to locate and assemble its tooling to their

convenience

### **Technical Specifications:**

Preumatic Specifications Pressure Operating Range Cylinder Type Dynamic seals

Imperial Metric 30-145 psi 2-10 bar Non-Conventional Internally lubricated Buna-N seals 0-145 PSI regulator

40 Micron or Better

Not Necessary*

Low Moisture Content (drv)

Valve Required to Operate

### **Air Quality Requirements**

Air Filtration Air Lubrication Air Humidity

### Temperature Operating Range

-30°~180° F -35°~80° C

### Maintenance Specifications

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available

5 million cycles 10+ million cycles Yes Yes

Addition of lubrication will greatly increase service life "See Maintenance Section

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- The conical seat in the output flange and the spherical pin are used to place the module in the home position.
- The pressure inside the chamber applies an effort on the output flange to keep it in the home position.
- When an outside force or moment applied to the output flange is higher then the preset force, the conical seat moves from the spherical pin generating an air leakage.
- The air leakage causes a pressure fall down in the module chamber which is detected by the sensor. The tool reset has to be done manually.



6.101





Specifications	AU-60							
Maximum Payload	4.0 lbs.	1.8 Kg						
Rotational Compliance (X and Y axis)	12°	12°						
Rotational Compliance (Z axis)	45°	45°						
Axial Compliance (Z axis)	0.28 in.	7 mm						
Weight	0.99 lbs.	0.45 Kg						
Pressure Range (locked cylinder)	30-145 psi	2-10 bar						
Cylinder bore	1.77 in.	45 mm		S OTHERV	VISE NOTED ALL TOLE	RANCES ARI	E AS SHOWN B	ELOW
Displacement	0.06 in. ³	1 cm ³	G	F- A	♠	$\oplus$	Imperial in.	Metric [mm]
Temperature Range	-30°~180° F	-35°~80° C	Dimensions are	Third Angle	All Dowel Holes are SF (Slip Fit).	¥≠ Metric Threads	$0.00 = \pm .01$	$[0.] = [\pm .25]$
Repeatability	±0.002 in.	±0.05 mm	symmetrical about	Projection	Locational Tolerance	Course Pitch	$0.000 = \pm .005$	$[0.0] = [\pm .13]$
Valve required to actuate	3-way, 2-p	osition	centerline		±.0005" or [±.013mm]		$0.0000 = \pm .0003$	$[0.00] = [\pm .013]$

### **Loading Information**

**AU SERIES** 

6.102









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# **AU-80 EMERGENCY STOP MODULES**





	A0 00							
Maximum Payload	10.0 lbs.	4.5 Kg						
Rotational Compliance (X and Y axis)	12°	12°						
Rotational Compliance (Z axis)	24°	24°						
Axial Compliance (Z axis)	0.334 in.	8.5 mm						
Weight	1.5 lbs.	0.68 Kg						
Pressure Range (locked cylinder)	30-145 psi	2-10 bar						
Cylinder bore	2.4 in.	61 mm	IINI ES	S OTHERV	VISE NOTED ALL TOLE	RANCES AR	F AS SHOWN B	FI OW
Displacement	0.99 in. ³	16.3 cm ³	C.	$ \land \land$		(†)	Imporial in	Motrio [mm]
Temperature Range	-30°~180° F	-35°~80° C	Ψ	Ψ	▼	Ŷ		
Repeatability	±0.0025 in.	±0.06 mm	Dimensions are symmetrical about	Third Angle Projection	All Dowel Holes are SF (Slip Fit).	Metric Threads	$0.00 = \pm .01$ $0.000 = \pm .005$	$[0.] = [\pm .25]$ $[0.0] = [\pm .13]$
Valve required to actuate	3-way, 2-p	osition	centerline	riojection	±.0005" or [±.013mm]	Course Flich	$0.0000 = \pm .0005$	$[0.00] = [\pm .013]$

### **Loading Information**





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# AU-110 EMERGENCY STOP MODULES





Specifications	AU-110	1						
Maximum Payload	18.8 lbs.	8.5 Kg						
Rotational Compliance (X and Y axis)	12°	12°						
Rotational Compliance (Z axis)	31°	31°						
Axial Compliance (Z axis)	0.531 in.	13.5 mm						
Weight	4.6 lbs.	2.1 Kg						
Pressure Range (locked cylinder)	30-145 psi	2-10 bar						
Cylinder bore	3.38 in.	86 mm	UNLES	S OTHERV	<b>VISE NOTED ALL TOLE</b>	RANCES ARE	E AS SHOWN B	ELOW
Displacement	2.22 in. ³	36.5 cm ³	G	$\rightarrow \oplus$	$\bullet$	$\oplus$	Imperial in.	Metric [mm]
Temperature Range	-30°~180° F	-35°~80° C	L Dimensions are		All Dowel Holes are SE (Slip Fit)	Matric Threads	$0.00 = \pm .01$	$[0.] = [\pm .25]$
Repeatability	±0.003 in.	±0.08 mm	symmetrical about	Projection	Locational Tolerance	Course Pitch	$0.000 = \pm .005$	$[0.0] = [\pm .13]$
Valve required to actuate	3-way, 2-p	osition	centerline		±.0005" or [±.013mm]		$0.0000 = \pm .0005$	$[0.00] = [\pm .013]$

### Loading Information





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# AU-140 **EMERGENCY STOP MODULES**





Specifications	AU-140	)							
Maximum Payload	38.6 lbs.	17.5 Kg							
Rotational Compliance (X and Y axis)	12°	12°							
Rotational Compliance (Z axis)	45°	45°							
Axial Compliance (Z axis)	0.63 in.	16 mm							ŝ
Weight	8.8 lbs.	4.0 Kg							<b>~</b>
Pressure Range (locked cylinder)	30-145 psi	2-10 bar							S S
Cylinder bore	4.25 in.	108 mm	UNLES	S OTHERV	<b>VISE NOTED ALL TOLE</b>	RANCES AR	E AS SHOWN B	ELOW	3
Displacement	3.31 in. ³	54.3 cm ³	G	$ \rightarrow   $	$\bullet$	$\oplus$	Imperial in.	Metric [mm]	
Temperature Range	-30°~180° F	-35°~80° C	Dimensions are		All Dowel Holes are SE (Slip Fit)	Motric Threads	$0.00 = \pm .01$	$[0.] = [\pm .25]$	
Repeatability	±0.004 in.	±0.1 mm	symmetrical about	Projection	Locational Tolerance	Course Pitch	$0.000 = \pm .005$	$[0.0] = [\pm .13]$	6.1
Valve required to actuate	3-way, 2-p	osition	centerline		±.0005" or [±.013mm]		$0.0000 = \pm .0005$	$[0.00] = [\pm .013]$	

# **Loading Information**





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# AU165 EMERGENCY STOP MODULES





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### **Adjustment Procedures**

For an easier adjustment, the blank plate (#2) can be disassembled. It is also advised to supply the module with two bar air pressure. 1) Unscrew the SS screws (#56) to release the

- cylindrical spacer (#8) 2) Unscrew the spherical pin (#4) to release the
- contact with the conical seats of the output flange (#3).
- 3) Line up the engraved "A" sign of the body (#1) and the output flange (#3)
- 4) Screw, simultaneously, by successive quarter of turn, the spherical pin (#4) till getting a contact into the conical seats of the output flange (#3). Repeat this operation until getting a minimal angular freedom.
- 5) Fasten the SS screws (#56) into the lateral tapped holes of the cap (#9).

# **AU Series Exploded View**

tem (	Qty N	lame
-------	-------	------

1	1	Body
2	1	Blank Plate
3	1	Output Flange
4	2	Spherical pin
5	1	Stop
7	1	Spring cap
8	2	Cylindrical spacer
9	1	Сар
52	1	Pin, Output flange
53	4	SHC screw, Flange
54	4	Hexagon CSKH screw, Stop
55	2	Pin, Stop
56	2	SS screw, Cylindrical pin
57	1	Spring
58	1	O-ring, Cap
59	6	SHC screw, Cap
60	1	Pin, Cap
61	1	O-ring, output flange
69	1	Electric pressure sensor

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

### **Assembly Procedures**

- 1) Locate the stop (#5) using the two pins (#55) into the body (#1)
- 2) Fasten the stop (#5) with (#54) screws with thread locker
- 3) Install the spring (#57) into the stop hole
- Insert the spring cap (#7) into the spring (#57)
- 5) Insert the O-Ring (#58) into the top groove of the body (#1)
- 6) Screw the spherical pin (#4) into the cap (#9)
- 7) Insert the cylindrical spacer (#8) into the lateral holes of the cap (#9)
- 8) Fasten the SS screws (#56) into the lateral tapped holes of the cap (#9)
- 9) Insert the O-Ring (#61) into the groove of the cap (#9)

ITENANCE

6.107

- 10) Insert the output flange (#3) into the cap (#9) lining up the engraved signs "Å"
- 11) Insert this subassembly into the body (#1) and locate it using (#60) pin
- 12) Fasten the cap (#9) with (#59) SH screws with thread locker
- Locate the blank plate (#2) onto the output flange (#3) using the dowel pin (#52)
- 14) Fasten the blank plate (#2) with (#53) SH screws with thread locker
- 15) Screw the electric pressure sensor (#69) in the body (#1)



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# Item Qty Name

1	1	Body
2	1	Blank Plate
3	1	Output Flange
4	2	Spherical pin
5	1	Stop
7	1	Spring cap
8	2	Cylindrical spacer
9	1	Сар
52	1	Pin, Output flange
53	4	SHC screw, Flange
54	4	Hexagon CSKH screw, Stop
55	2	Pin, Stop
56	2	SS screw, Cylindrical pin
57	1	Spring
58	1	O-ring, Cap
59	6	SHC screw, Cap
60	1	Pin, Cap
61	1	O-ring, output flange
69	1	Electric pressure sensor

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.



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# **Resettable Emergency Stop Modules**



### • Safety:

This module is used between a robot and the tooling. It protects the part, the fixture or the assembly machine for overload in compressive, bending or torsional overload situations.

- Resettable:
  - This module is equipped with a patented mechanism that helps to reset the tooling after an overload or collision.
- Wide deflecting motion: The wide deflecting motions coupled to the electric pressure sensor avoid expensive expenses and maintenance breakdowns.
- Variable trip point: Adjusting the pressure from 2 to 10 bars allow to set a precise trip point as required by the application.
- Compact and robust: These modules are designed for harsh environment applications.

# **Mounting Information:**

Modules can be mounted & operated in any orientation



The module is located using pilot boss and a dowel pin and assembled with 4 thru body screws



The tooling is located using 2 dowel pins and assembled with 4 screws

h



the customer to locate and assemble its tooling to their convenience

# **Technical Specifications:**

Pneumatic Specifications	Imperial	Metric
Pressure Operating Range	30-145 psi	2-10 bar
Cylinder Type	Non-Conv	entional
Dynamic seals	Internally Viton®	lubricated
Valve Required to Operate	0-145 PSI	regulator
Air Quality Requirements		
Air Filtration	40 Micron	or Better
Air Lubrication	Not Nece	ssarv*
Air Humidity	Low Moisture (	Content (dry)

### Temperature **Operating Range**

-30°~180° F -35°~80° C

# Maintenance Specifications^{*}

Expected Life Normal Application w/ Preventative Maintenance Field Repairable Seal Repair Kits Available

5 million cycles 10+ million cycles Yes Yes

Addition of lubrication will greatly increase service life See Maintenance Section

SELLES



- When an outside force or moment applied to the output flange is higher then the preset force, the conical seat moves from the spherical pin generating an air leakage.
- The air leakage causes a pressure fall down in the module chamber which is detected by the sensor.
- The module can be reset using the piston placed into the cylinder.





Specifications	AU-110	R						
Maximum Payload	18.8 lbs.	8.5 Kg						
Rotational Compliance (X and Y axis)	12°	12°						
Rotational Compliance (Z axis)	45°	45°						
Axial Compliance (Z axis)	0.531 in.	13.5 mm						
Weight	4.96 lbs.	2.25 Kg						
Pressure Range (locked cylinder)	30-145 psi	2-10 bar						
Cylinder bore	3.38 in.	86 mm	UNLES	SS OTHERV	<b>VISE NOTED ALL TOLE</b>	RANCES ARI	E AS SHOWN B	ELOW
Displacement	4.27 in. ³	70 cm ³	G	$ \rightarrow                                   $	$\bullet$	$\oplus$	Imperial in.	Metric [mm]
Temperature Range	-30°~180° F	-35°~80° C	Dimensions are	Third Angle	All Dowel Holes are SF (Slip Fit).	Metric Threads	$0.00 = \pm .01$	$[0.] = [\pm .25]$
Repeatability	±0.003 in.	±0.08 mm	symmetrical about	Projection	Locational Tolerance	Course Pitch	$0.000 = \pm .005$	$[0.0] = [\pm .13]$
Valve required to actuate	3-way, 2-µ	position	centerline		±.0005" or [±.013mm]		$0.0000 = \pm .0005$	$[0.00] = [\pm .013]$

# **Loading Information**

**AUR SERIES** 

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Specifications	AU-140	2							
Maximum Payload	38.6 lbs.	17.5 Kg							
Rotational Compliance (X and Y axis)	12°	12°							
Rotational Compliance (Z axis)	45°	46.8°							
Axial Compliance (Z axis)	0.689 in.	17.5 mm							E Contraction of the second se
Weight	10.47 lbs.	4.75 Kg							64
Pressure Range (locked cylinder)	30-145 psi	2-10 bar							S
Cylinder bore	4.25 in.	108 mm	UNLES	S OTHERV	VISE NOTED ALL TOLE	<b>BANCES ARE</b>	E AS SHOWN B	ELOW ——	<u> </u>
Displacement	9.76 in.3	160 cm ³	с.	Ъф		A	Imperial in	Metric [mm]	A
Temperature Range	-30°~180° F	-35°~80° C	Ľ	ΨΨ		Ψ.	$0.00 = \pm 01$	101 - (+ 25)	
Repeatability	±0.004 in.	±0.1 mm	symmetrical about	I hird Angle Projection	All Dowel Holes are SF (Slip Fit).	Metric Threads Course Pitch	$0.000 = \pm .001$ $0.000 = \pm .005$	$[0.0] = [\pm .23]$ $[0.0] = [\pm .13]$	6.113
Valve required to actuate	3-way, 2-p	osition	centerline	1.10,000001	±.0005" or [±.013mm]		$0.0000 = \pm .0005$	[0.00] = [±.013]	
Valve required to actuate	3-way, 2-p	osition	centerline		±.0005" or [±.013mm]		$0.0000 = \pm .0005$	[0.00] = [±.013]	



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# **Adjustment Procedures**

ur series Intenance

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For an easier adjustment, the blank plate (#2) can be disassembled. It is also advised to supply the module with two bar air pressure. 1) Unscrew the SS screws (#56) to release the

- cylindrical spacer (#8) 2) Unscrew the spherical pin (#4) to release the
- contact with the conical seats of the output flange (#3).
- 3) Line up the engraved "A" sign of the body (#1) and the output flange (#3)
- 4) Screw, simultaneously, by successive quarter of turn, the spherical pin (#4) till getting a contact into the conical seats of the output flange (#3). Repeat this operation until getting a minimal angular freedom.
- 5) Fasten the SS screws (#56) into the lateral tapped holes of the cap (#9).

1	1	Body
3	1	Output flange
4	2	Spherical pin
8	2	Cylindrical spacer
9	1	Сар
10	1	Cylinder
11	1	Piston
12	1	Cap
13	1	Stop ring
52	1	Pin, output flange
56	2	SS screw, Cylindrical pin
58	1	O-ring, cap
59	6	SHC screw, Cap
60	1	Pin, Body
61	1	<u>O-ring, Cap</u>
62	1	Retaining ring, cap
63	1	O-ring, Cylinder
64	4	Screw crimping bush,
		Cylinder
65	1	O-ring, Cap
66	1	O-ring, Piston
67	2	SHC screw, Output flange
68	4	LHC screw, Cylinder
69	1	Electric pressure sensor

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

## **Assembly Procedures**

1) Assemble the stop ring (#13) into the body counterbore hole (#1)

- Screw the spherical pin (#4) into the cap (#9)
- 3) Insert the cylindrical spacer (#8) into the lateral holes of the cap (#9)
- 4) Fasten the SS screws (#56) into the lateral tapped holes of the cap (#9)
- 5) Insert the O-Ring (#58) into the outside groove of the cap (#9)
- 6) Insert the O-Ring (#61) into the inside groove of the cap (#9)
- Mount the Screw crimping bush (#64) into the cylinder (#10)
- Insert the O-Ring (#63) into the groove of the cylinder (#10)
- 9) Insert the pin (#52) into the cylinder (#10) 10) Fit the cap (#9) between the cylinder

(#10) and the output flange (#3) and fasten the cylinder (#10) and the output flange (#3) using the SHC screws (#67) and (#68) with thread locker

- 11) Insert the pin (#60) into the body (#1)
- 12) Insert the subassembly built step 10 into the body (#1). The engraved signs of the body and the cap have to be aligned
- 13) Fasten the cap (#9) with (#59) SHC screws with thread locker
- 14) Insert the O-Ring (#66) onto the piston (#11)
- 15) Place the piston (#11) into the cylinder (#10)
- 16) Insert the O-Ring (#65) onto the cap (#12)
- 17) Assemble the cap (#12) into the cylinder(#10) using the retaining ring (#62)

SK		KRYTOX	0	G	GLUE	$\Rightarrow \Leftrightarrow$
Seal Kit	Thread	Krytox [™]	Lightweight Machine Oil	Teflon [®] Based	Super	Third Angle

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# **AUR Series Assembled View**

		- 10
8		9
3		(69)

# Item Qty Name

1	1	Body
3	1	Output flange
4	2	Spherical pin
8	2	Cylindrical spacer
9	1	Сар
10	1	Cylinder
11	1	Piston
12	1	Сар
13	1	Stop ring
52	1	Pin, output flange
56	2	SS screw, Cylindrical pin
58	1	O-ring, cap
59	6	SHC screw, Cap
60	1	Pin, Body
61	1	O-ring, Cap
62	1	Retaining ring, cap
63	1	O-ring, Cylinder
64	4	Screw crimping bush,
		Cylinder
65	1	O-ring, Cap
66	1	O-ring, Piston
67	2	SHC screw, Output flange
68	4	LHC screw, Cylinder
69	1	Electric pressure sensor

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

> AUR SERIES MAINTENANCE

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# **Engineering Resources** from DE-STA-CO Robohand

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- Receive custom solutions for your unique applications with our Custom Product program
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- Custom capabilities range, from adding a simple dowel hole to developing a solution from the beginning
- A minimum order quantity is not required, and for most special requests, receive a quote within 24 hours
- DE-STA-CO Robohand offers a level of expertise unmatched in the industry

- All custom solutions are priced competitively and delivered with complete CAD files
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- Nearly all custom solutions will be delivered within two to five weeks of your request











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March 2011