

Parker Servo Systems

P Series



The new Parker P Series servo system combines compact, flexible, advanced functionality drives with high performance motors for a superior servo system, providing unique value to machine builders.

The P-Series drives operate with a variety of machine control architectures and offer sophisticated servo capability. A number of different feedback types are supported to drive a wide range of linear and rotary servo motors. The best matches are the P-Series motors, which include absolute encoders and populate motor nameplate data back to the drives for simplified commissioning.

Accurate and easy to use inertia detection leads to fast set-up of tuning parameters and minimal settling time. Advanced filtering and vibration suppression features can be used to increase throughput and improve positioning performance.

For high speed, real-time network applications, the P-Series is available with EtherCAT, the fastest growing, most flexible industrial Ethernet



Contact Information:

Parker Hannifin Corporation
Electromechanical Automation Division
5500 Business Park Drive
Rohnert Park, CA 94928
phone: 800.358.9068 / 707.584.7558
fax: 707.584.8015
email: emn_support@parker.com

EtherCAT 



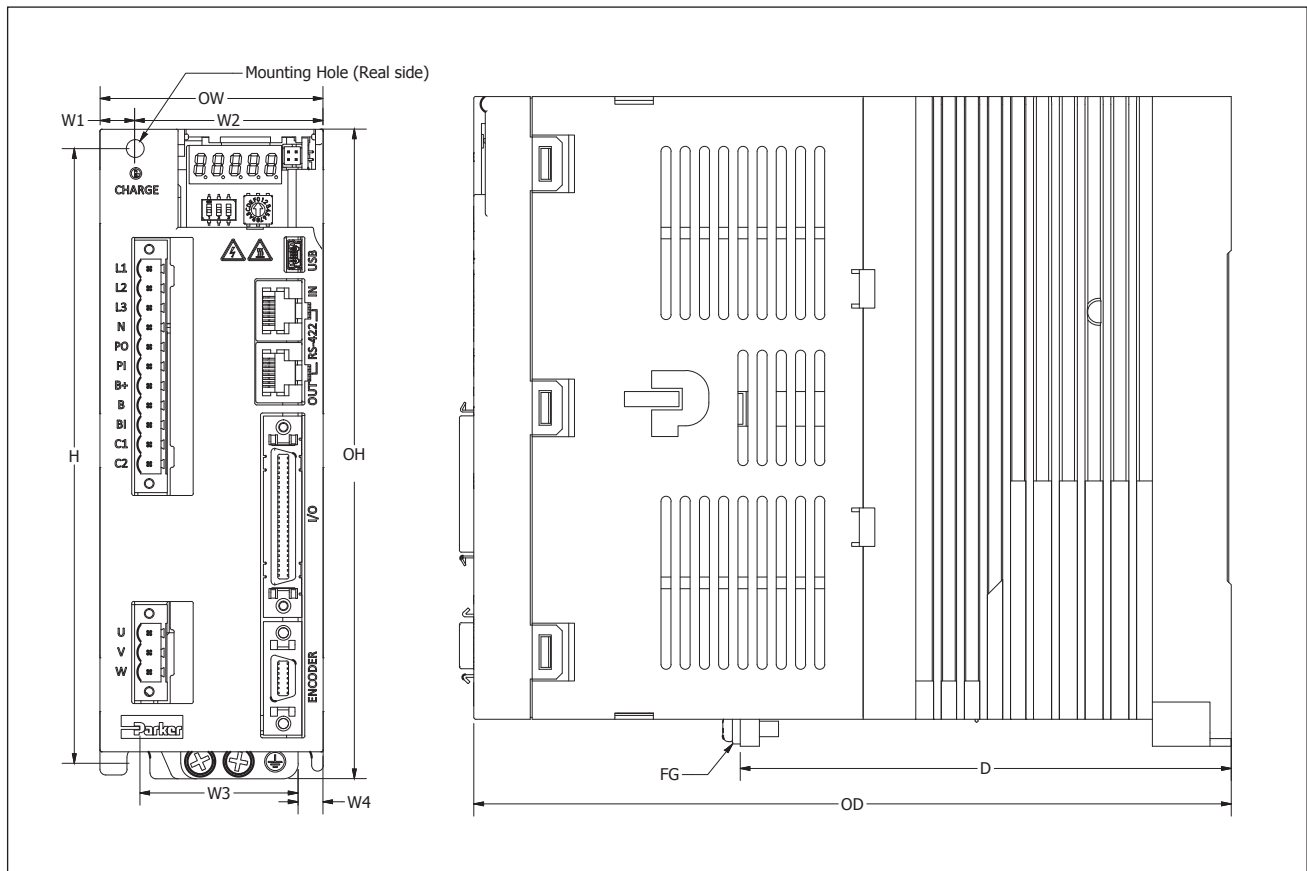
ENGINEERING YOUR SUCCESS.

P Series Servo Drive

Pulse Drive Specifications

Motor Output Power		PD-04P	PD-10P	PD-35P
	Shaft Power @ Continuous Current	400 Watts	1000 Watts	3500 Watts
	Shaft Power @ Peak Current	1200 Watts	3000 Watts	10500 Watts
Drive Output Power				
	Continuous Current (RMS)	3.0 Amps	6.75 Amps	16.7 Amps
	Peak Current (RMS)	9.0 Amps	20.25 Amps	50.1 Amps
	Bus Voltage	340VDC		
Drive Input Voltage		100-120VAC 50/60Hz 230 VAC, 1/3Ø, 50/60Hz	230 VAC, 1/3Ø, 50/60Hz	
Drive Control Voltage		100-120VAC 50/60Hz 230 VAC, 1Ø, 50/60Hz	230 VAC, 1Ø, 50/60Hz	230 VAC, 1Ø, 50/60Hz
Performance				
	Servo update	62.5µ seconds		
	Accuracy	± 1 encoder count ; encoder dependent		
	Commutation	Sinusoidal		
Control				
	Indexer Function	64 user defined profiles, relative/absolute moves, registration, sequences and I/O selection		
	Position Control	Step and direction, CW and CCW		
	Speed Control	+/- 10V, 1:5000		
	Torque Control	+/- 10V		
Feedback				
	Encoder Input	Quadrature Incremental encoder, BiSS-C (absolute) encoder, EnDAT 2.2, SinCos		
	Encoder Output	RS-422 compatible differential driver		
I/O				
	Digital input	16-channel, +24V common, user selectable functions		
	Digital output	8-channel, Differential (Isolated), user selectable functions		
	Analog input	2-channel, ±10V (max.), 12bits		
	Analog output	2-channel, ±10V (max.), selectable, 12bits		
Communications				
	USB	USB 2.0 for firmware upload and drive configuration		
	Serial	RS422 for PC or HMI interface, MODBUS-RTU		
	Standard	ANSI/ TIA/ EIA-422 standard		
	Baud Rate	9,600/ 19,200/ 38,400/ 57,600/ 115,200 bps		
	Configuration Software	Drive Support Tool		
Standards		CE (EMC, LVD UL/cUL recognized	CE (EMC, LVD) UL/cUL listed	CE (EMC, LVD) UL/cUL listed
Built-in Functions				
	Display	7 Segment LED, 5 digits for Status and Alarms		
	Node Selection	3 dip switches, 1 rotary for address 0-31		
	Dynamic Braking	Built-in, user selectable reaction		
	Internal Regeneration	100 ohm, 50W	40 ohm, 100W	12.6 ohm, 150W
	External Regeneration	50 ohm, 140W	30 ohm, 300W	30 ohm, 600W
Environmental				
	Temperature	0 - 50 °C (32 - 122 °F)		
	Humidity	0 - 90% non-condensing		
	Shock / Vibration	15g, 11msec half sign / 10-2,000Hz @ 2g		

Pulse Drive Dimensions



(Unit: mm)

		PD-04P	PD-10P	PD-35P
H	Height	158	158	158
OH	Overall Height	169	169	169
OW	Overall Width	38	58	88
W1	Width 1	6	10	44
W2	Width 2	26	48	44
W3	Width 3	32	42	78
W4	Width 4	6	6	5
D	Depth	107.7	127.7	112.5
OD	Overall Depth	173	197	198

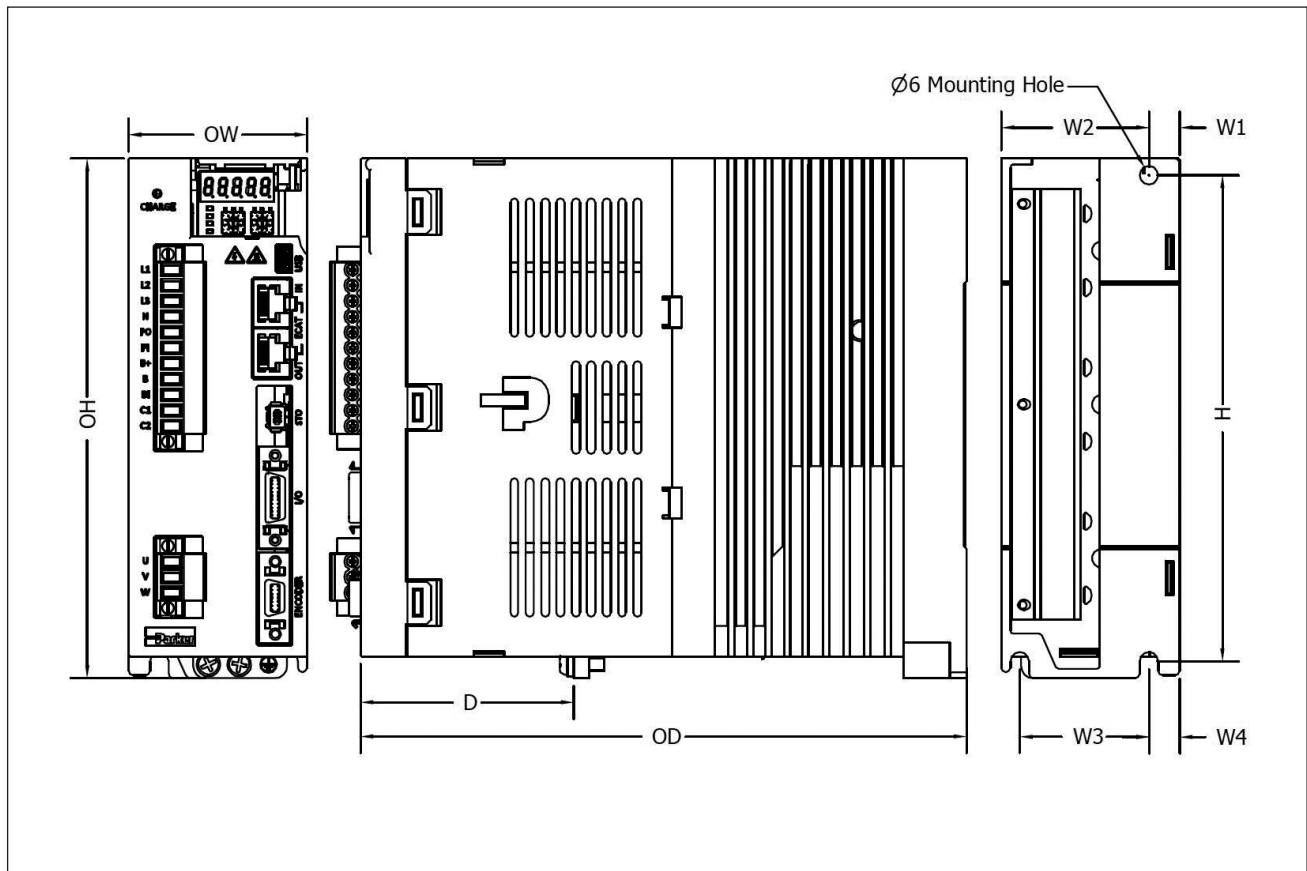
Solid Models Available for Download parkermotion.com/pseries

P Series Servo Drive

EtherCAT Drive Specifications

Motor Output Power		PD-04C	PD-10C	PD-35C
	Shaft Power @ Continuous Current	400 Watts	1000 Watts	3500 Watts
	Shaft Power @ Peak Current	1200 Watts	3000 Watts	10500 Watts
Drive Output Power				
	Continuous Current (RMS)	3.0 Amps	6.75 Amps	16.7 Amps
	Peak Current (RMS)	9.0 Amps	20.25 Amps	50.1 Amps
	Bus Voltage	340VDC		
Drive Input Voltage		100-120VAC 50/60Hz 230 VAC, 1/3Ø, 50/60Hz	230 VAC, 1/3Ø, 50/60Hz	
Drive Control Voltage		100-120VAC 50/60Hz 230 VAC, 1Ø, 50/60Hz	230 VAC, 1Ø, 50/60Hz	230 VAC, 1Ø, 50/60Hz
Performance				
	Servo update	62.5µ seconds		
	Accuracy	± 1 encoder count ; encoder dependent		
	Commutation	Sinusoidal		
EtherCAT				
	Supported Protocols	CoE, EoE, FoE		
	Drive Modes	Position Profile, Profile Velocity, Profile Torque, Interpolated Position, Homing Cyclic Synchronous Position, Velocity and Torque		
Feedback				
	Encoder Input	Quadrature Incremental encoder, BiSS-C (absolute) encoder, EnDAT 2.2, SinCos		
I/O				
	Digital input	8-channel, +24V common, user selectable functions		
	Digital output	4-channel, Differential (Isolated), user selectable functions		
	Safety	Safe Torque Off (STO) IEC61508		
Communications				
	USB	USB 2.0 for firmware upload and drive configuration		
	Configuration Software	Drive Support Tool		
Standards		CE (EMC, LVD UL/cUL recognized	CE (EMC, LVD) UL/cUL listed	CE (EMC, LVD) UL/cUL listed
Built-in Functions				
	Display	7 Segment LED, 5 digits for Status and Alarms		
	Dynamic Braking	Built-in, user selectable reaction		
	Internal Regeneration	100 ohm, 50W	40 ohm, 100W	12.6 ohm, 150W
	External Regeneration	50 ohm, 140W	30 ohm, 300W	30 ohm, 600W
Environmental				
	Temperature	0 - 50 °C (32 - 122 °F)		
	Humidity	0 - 90% non-condensing		
	Shock / Vibration	15g, 11msec half sign / 10-2,000Hz @ 2g		

EtherCAT Drive Dimensions



(Unit: mm)

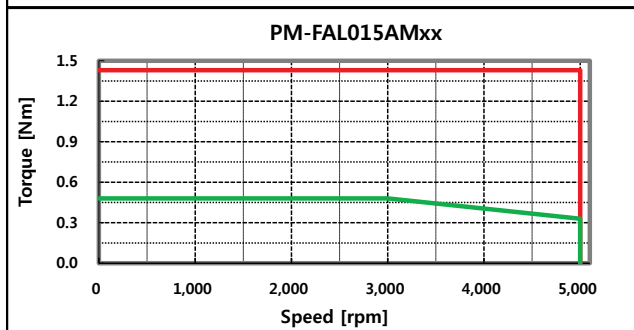
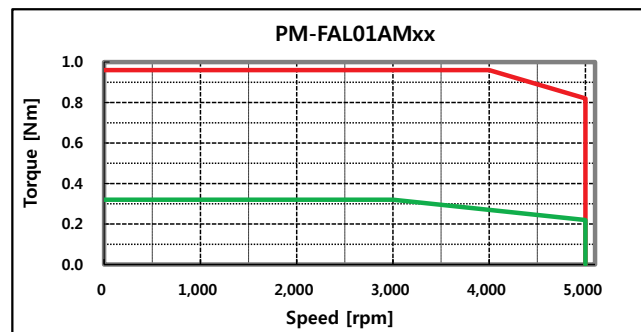
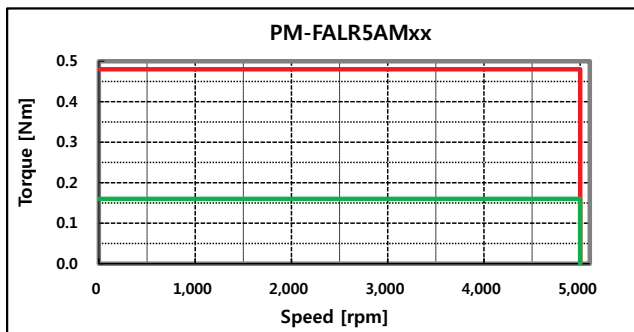
		PD-04C	PD-10C	PD-35C
H	Height	158	158	158
OH	Overall Height	169	169	169
OW	Overall Width	38	58	88
W1	Width 1	6	10	44
W2	Width 2	26	48	44
W3	Width 3	32	42	78
W4	Width 4	6	6	5
D	Depth	107.7	127.7	112.5
OD	Overall Depth	173	197	198

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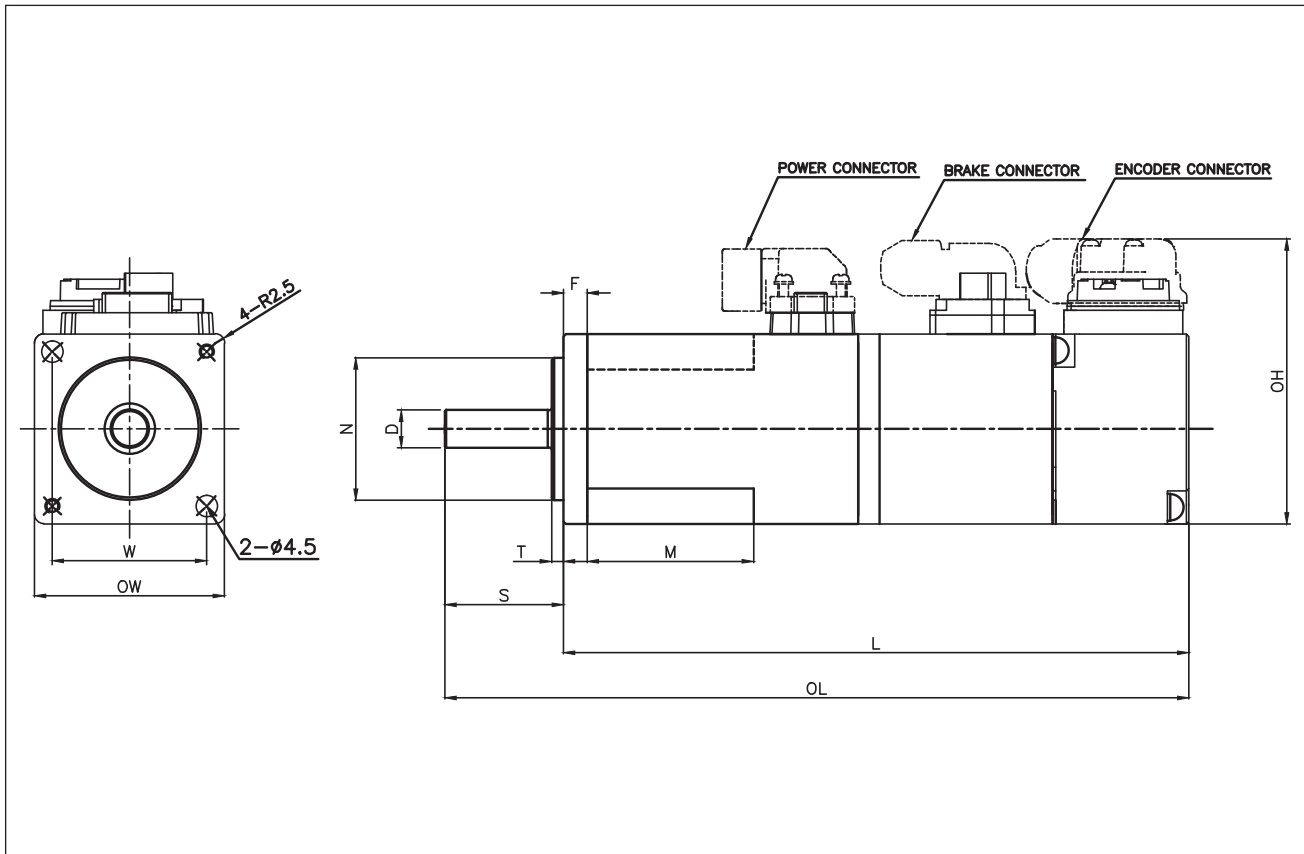
P Series Servo Motors

FAL Specifications

		PM-FALR5AM8	PM-FAL01AM8	PM-FAL015AM8
Rated Output Power	Watts	50	100	150
Rated Torque	N-m	0.16	0.32	0.48
	in-lb	1.4	2.8	4.2
Instantaneous Peak Torque	N-m	0.48	0.96	1.43
	in-lb	4.2	8.5	12.7
Rated Speed	rpm	3000	3000	3000
Peak Speed	rpm	5000	5000	5000
Rated Current	Arms	0.95	1.25	1.73
Peak Current	Arms	2.85	3.75	5.19
Inductance	mH	4.42	5.08	3.89
Resistance	ohms	5.57	4.64	3.52
Torque Constant	Nm/Arms	0.18	0.27	0.30
Moment of Inertia	kg-m ² x 10 ⁻⁴	0.02	0.05	0.06
	in-lb-sec ² x 10 ⁻⁴	0.18	0.44	0.53
Allowable Moment of Load Inertia		Motor Inertia x 30		x 20
Position Feedback		BiSS-C Interface – 18bit	262,144ppr	4096 revs
Weight	kg	0.4	0.5	0.7
	lb	0.8	1.1	1.5
Protection		IP67 (body and connectors, not shaft)		
Standards		CE (EMC, LVD), UL (pending)		
Environmental				
	Temperature	0 - 40 °C		
	Humidity	20-80% non-condensing		
	Shock / Vibration	5G (49m/s ²)		



FAL Dimensions



(Unit: mm)

	OW	OH	OL	L	N	W	D	F	M	S	T
PM-FALR5AM8N	40	60	103.2	78.2	30	32.5**	8	5	23	25	2.5
PM-FAL01AM8N			120.2	95.2					35		
PM-FAL015AM8N			140.2	115.2					35		
PM-FAL01AM8N2*			156.6	131.6					35		

Notes

- FAL series does not include keyway

* Includes Static Brake

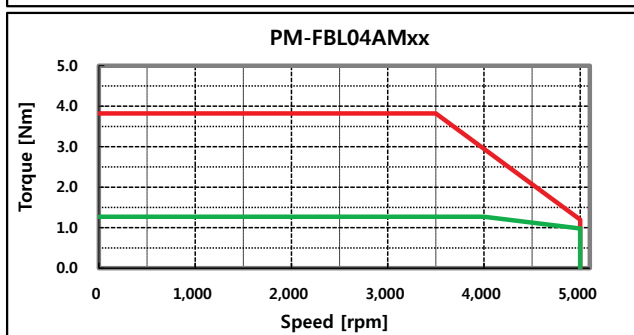
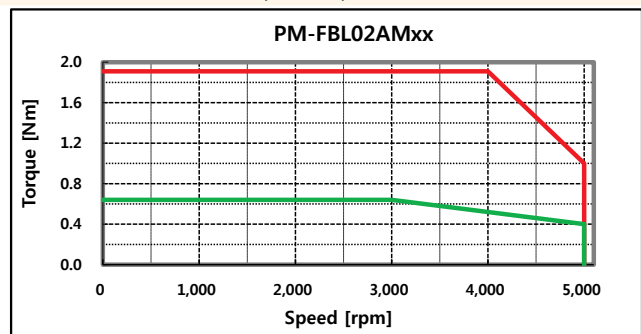
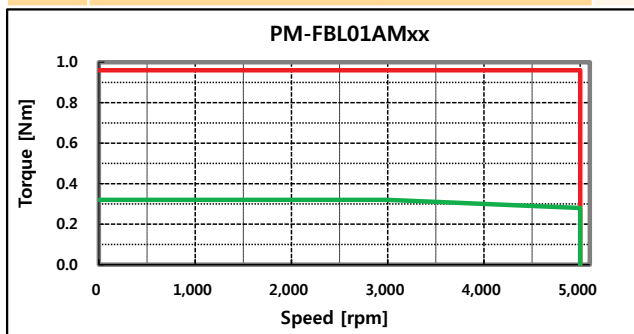
**Bolt Circle Diameter =46mm

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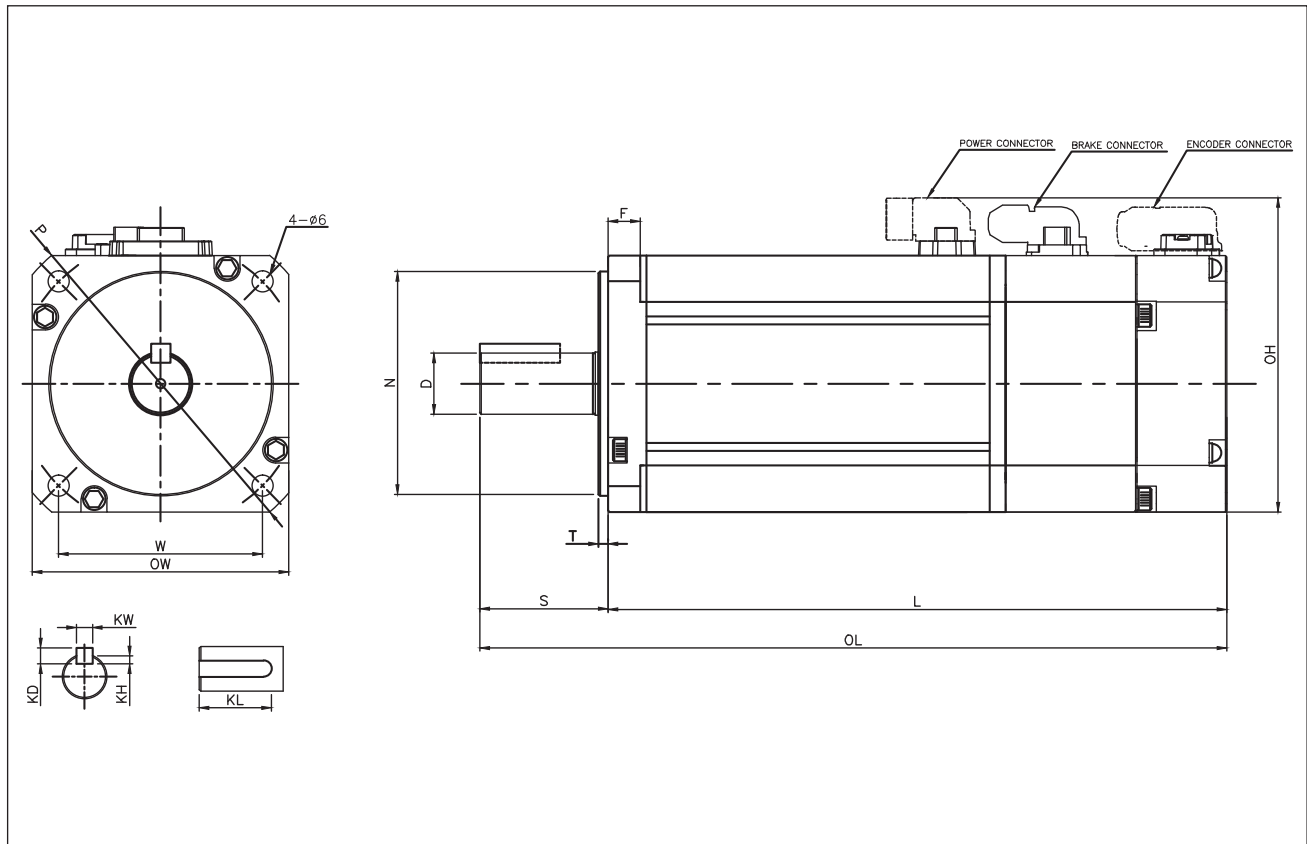
P Series Servo Motors

FBL Specifications

		PM-FBL01AM	PM-FBL02AM	PM-FBL04AM
Rated Output Power	Watts	100	200	400
Rated Torque	N-m	0.32	0.64	1.27
	in-lb	2.8	5.7	11.2
Instantaneous Peak Torque	N-m	0.96	1.91	3.82
	in-lb	8.5	16.9	33.8
Rated Speed	rpm	3000	3000	3000
Peak Speed	rpm	5000	5000	5000
Rated Current	Arms	0.95	1.45	2.60
Peak Current	Arms	2.86	4.35	7.80
Inductance	mH	10.46	9.03	5.68
Resistance	ohms	4.33	2.59	1.33
Torque Constant	Nm/Arms	0.36	0.47	0.52
Moment of Inertia	kg-m ² x 10 ⁻⁴	3.65	4.79	5.25
	in-lb-sec ² x 10 ⁻⁴	0.8	1.33	2.21
Allowable Moment of Load Inertia	Motor Inertia x 20			
Position Feedback	BiSS-C Interface – 19bit 524,288ppr 4096 revs			
Weight	kg	0.72	0.94	1.32
	lb	1.6	2.1	2.9
Standards	CE (EMC, LVD), UL (pending)			
Protection	IP67 (body and connectors, not shaft)			
Environmental				
Temperature	0 - 40 °C			
Humidity	20-80% non-condensing			
Shock / Vibration	5G (49m/s ²)			



FBL Dimensions



(Unit: mm)

	OW	OH	OL	L	N	W	D	F	S	T	KW	KH	KD	KL	P
PM-FBL01AMK	62	80	107.2	77.2	50	49.5**	14	6	30	3	5	3	5	22.5	80
PM-FBL02AMK			118.2	88.2											
PM-FBL04AMK			138.2	108.2											
PM-FBL01AMK2*			147.2	117.2											
PM-FBL02AMK2*			158.2	128.2											
PM-FBL04AMK2*			178.2	148.2											

Notes

* Includes Static Brake

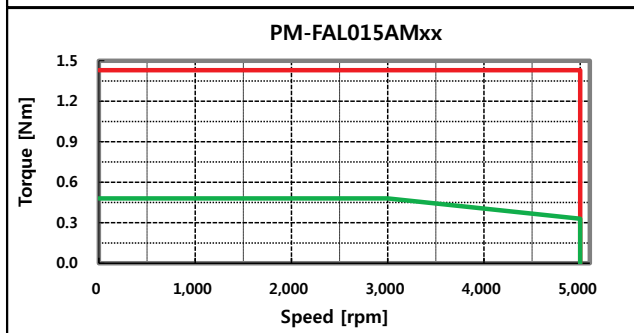
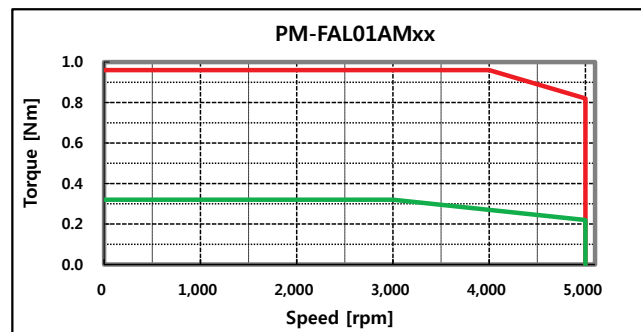
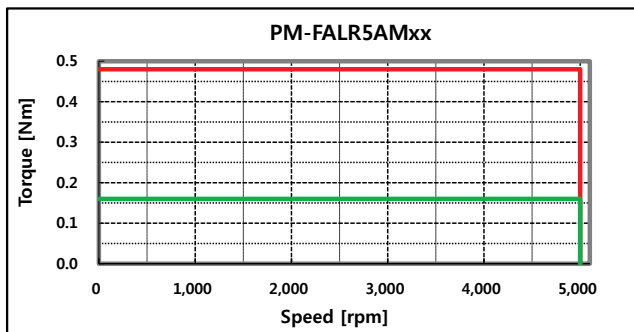
**Bolt Circle Diameter =70mm

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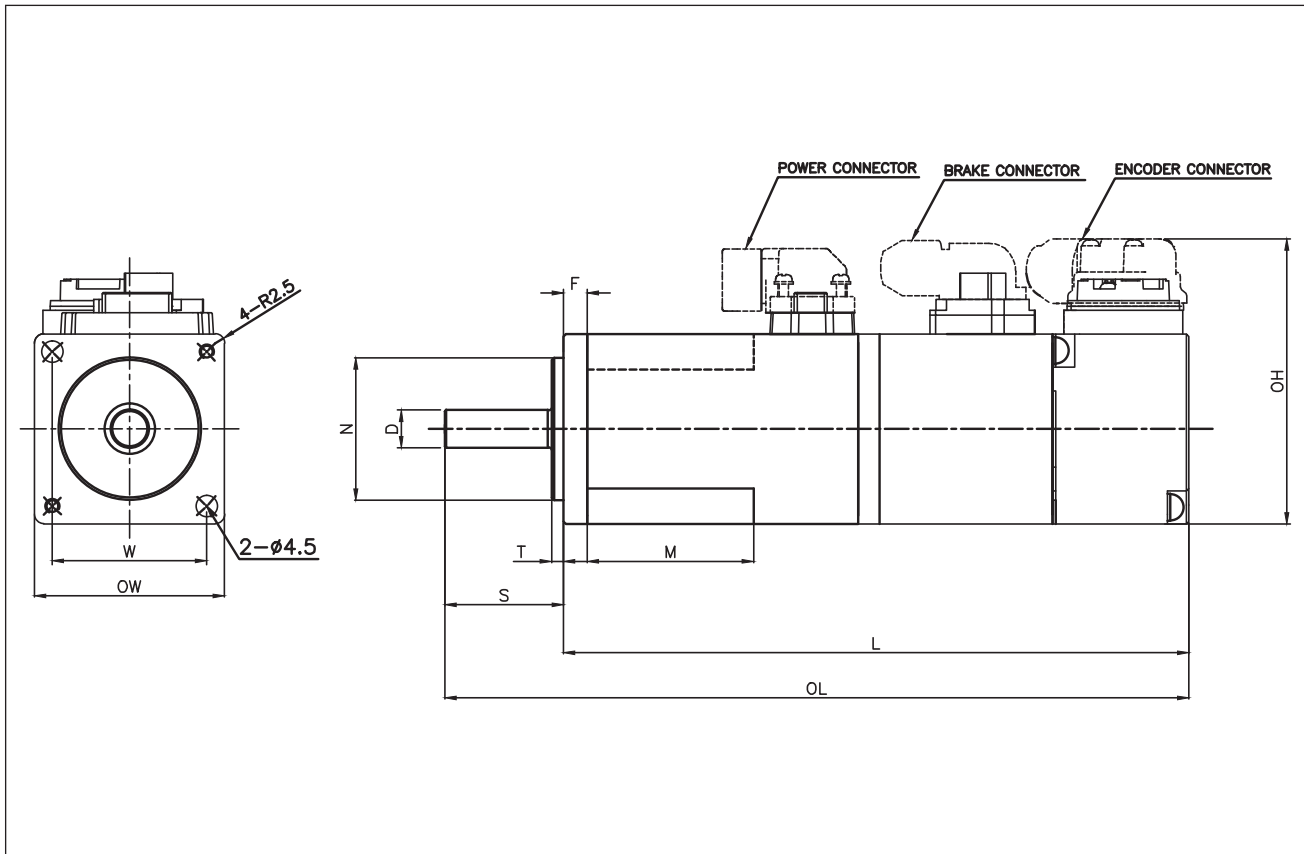
P Series Servo Motors

FAL Specifications

		PM-FALR5AM8	PM-FAL01AM8	PM-FAL015AM8
Rated Output Power	Watts	50	100	150
Rated Torque	N-m	0.16	0.32	0.48
	in-lb	1.4	2.8	4.2
Instantaneous Peak Torque	N-m	0.48	0.96	1.43
	in-lb	4.2	8.5	12.7
Rated Speed	rpm	3000	3000	3000
Peak Speed	rpm	5000	5000	5000
Rated Current	Arms	0.95	1.25	1.73
Peak Current	Arms	2.85	3.75	5.19
Inductance	mH	4.42	5.08	3.89
Resistance	ohms	5.57	4.64	3.52
Torque Constant	Nm/Arms	0.18	0.27	0.30
Moment of Inertia	kg-m ² x 10 ⁻⁴	0.02	0.05	0.06
	in-lb-sec ² x 10 ⁻⁴	0.18	0.44	0.53
Allowable Moment of Load Inertia		Motor Inertia x 30		x 20
Position Feedback		BiSS-C Interface – 18bit	262,144ppr	4096 revs
Weight	kg	0.4	0.5	0.7
	lb	0.8	1.1	1.5
Protection		IP67 (body and connectors, not shaft)		
Standards		CE (EMC, LVD), UL (pending)		
Environmental				
	Temperature	0 - 40 °C		
	Humidity	20-80% non-condensing		
	Shock / Vibration	5G (49m/s ²)		



FAL Dimensions



(Unit: mm)

	OW	OH	OL	L	N	W	D	F	M	S	T
PM-FALR5AM8N	40	60	103.2	78.2	30	32.5**	8	5	23	25	2.5
PM-FAL01AM8N			120.2	95.2					35		
PM-FAL015AM8N			140.2	115.2					35		
PM-FAL01AM8N2*			156.6	131.6					35		

Notes

- FAL series does not include keyway

* Includes Static Brake

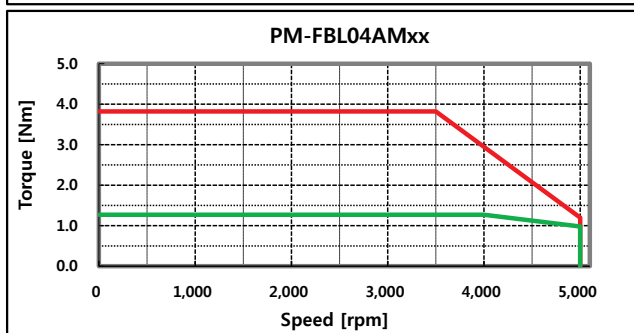
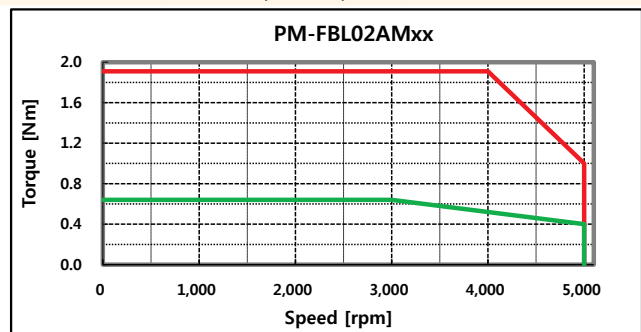
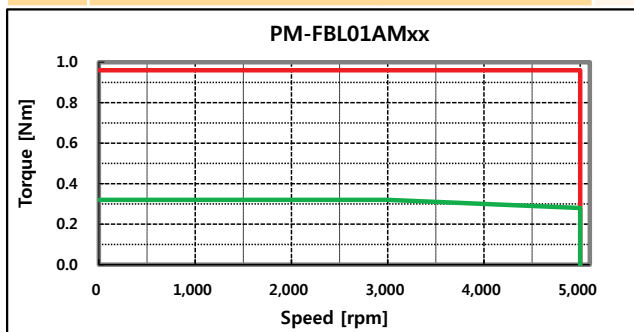
**Bolt Circle Diameter =46mm

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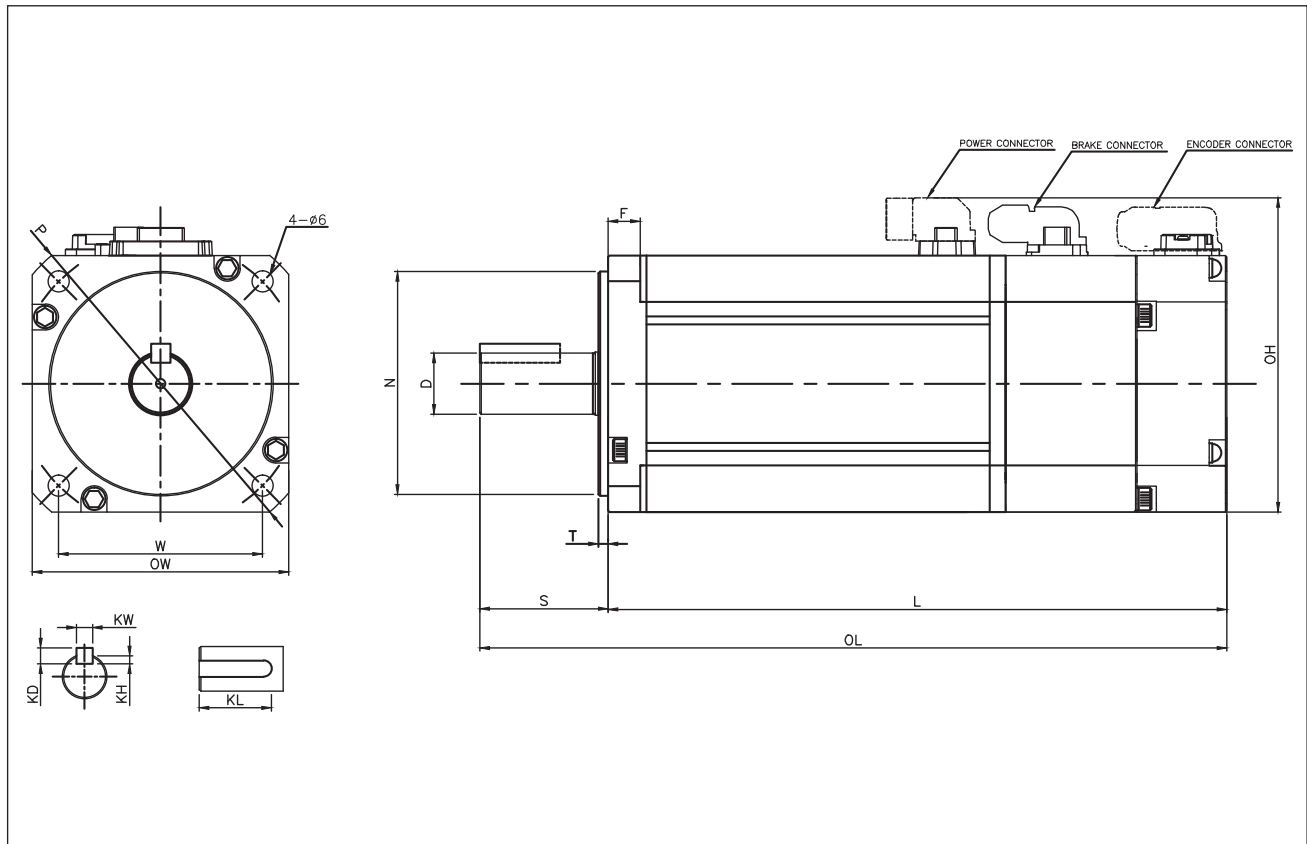
P Series Servo Motors

FBL Specifications

		PM-FBL01AM	PM-FBL02AM	PM-FBL04AM
Rated Output Power	Watts	100	200	400
Rated Torque	N-m	0.32	0.64	1.27
	in-lb	2.8	5.7	11.2
Instantaneous Peak Torque	N-m	0.96	1.91	3.82
	in-lb	8.5	16.9	33.8
Rated Speed	rpm	3000	3000	3000
Peak Speed	rpm	5000	5000	5000
Rated Current	Arms	0.95	1.45	2.60
Peak Current	Arms	2.86	4.35	7.80
Inductance	mH	10.46	9.03	5.68
Resistance	ohms	4.33	2.59	1.33
Torque Constant	Nm/Arms	0.36	0.47	0.52
Moment of Inertia	kg-m ² x 10 ⁻⁴	3.65	4.79	5.25
	in-lb-sec ² x 10 ⁻⁴	0.8	1.33	2.21
Allowable Moment of Load Inertia	Motor Inertia x 20			
Position Feedback	BiSS-C Interface – 19bit 524,288ppr 4096 revs			
Weight	kg	0.72	0.94	1.32
	lb	1.6	2.1	2.9
Standards	CE (EMC, LVD), UL (pending)			
Protection	IP67 (body and connectors, not shaft)			
Environmental				
Temperature	0 - 40 °C			
Humidity	20-80% non-condensing			
Shock / Vibration	5G (49m/s ²)			



FBL Dimensions



(Unit: mm)

	OW	OH	OL	L	N	W	D	F	S	T	KW	KH	KD	KL	P
PM-FBL01AMK	62	80	107.2	77.2	50	49.5**	14	6	30	3	5	3	5	22.5	80
PM-FBL02AMK			118.2	88.2											
PM-FBL04AMK			138.2	108.2											
PM-FBL01AMK2*			147.2	117.2											
PM-FBL02AMK2*			158.2	128.2											
PM-FBL04AMK2*			178.2	148.2											

Notes

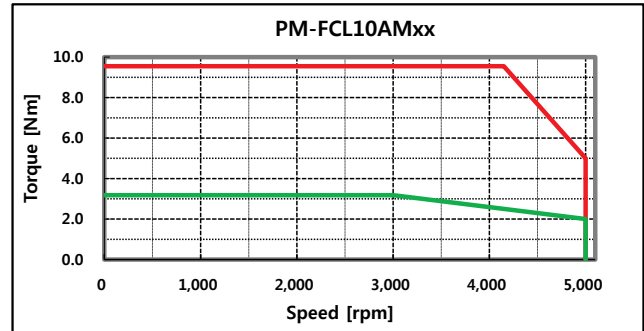
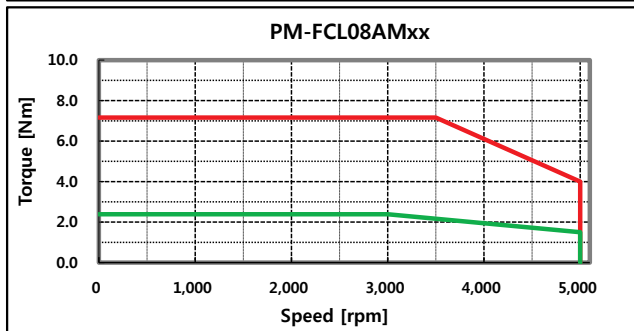
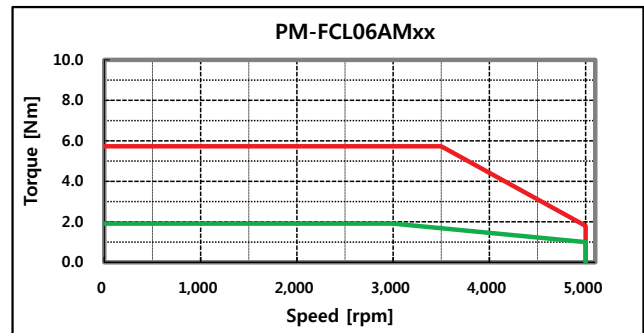
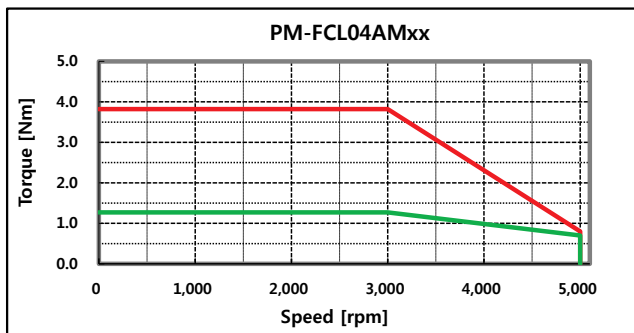
- * Includes Static Brake
- **Bolt Circle Diameter =70mm

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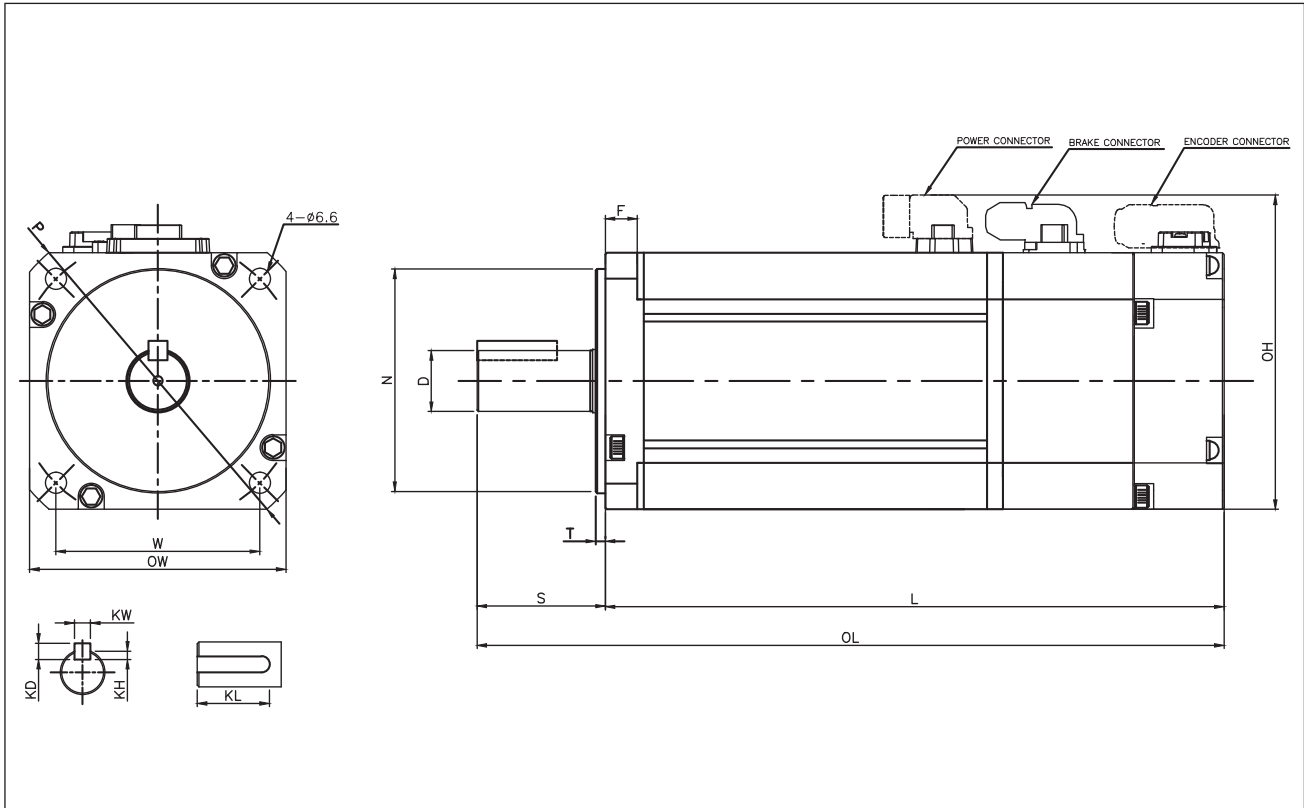
P Series Servo Motors

FCL Specifications

		PM-FCL04AM	PM-FCL06AM	PM-FCL08AM	PM-FCL10AM	
Rated Output Power	Watts	400	600	800	1000	
Rated Torque	N-m	1.27	1.91	2.39	3.18	
	in-lb	11.2	16.9	21.2	28.1	
Instantaneous Peak Torque	N-m	3.82	5.73	7.16	9.55	
	in-lb	33.8	50.7	63.4	84.5	
Rated Speed	rpm	3000	3000	3000	3000	
Peak Speed	rpm	5000	5000	5000	5000	
Rated Current	Arms	2.58	3.81	5.02	5.83	
Peak Current	Arms	7.75	11.42	15.07	17.50	
Inductance	mH	7.45	3.86	2.31	2.28	
Resistance	ohms	1.75	0.66	0.40	0.33	
Torque Constant	Nm/Arms	0.52	0.53	0.50	0.58	
Moment of Inertia	kg-m ² x 10 ⁻⁴	0.5	0.88	1.25	1.62	
	in-lb-sec ² x 10 ⁻⁴	4.4	7.8	11.1	14.3	
Allowable Moment of Load Inertia	Motor Inertia x 15					
Position Feedback	BiSS-C Interface – 19bit 524,288ppr 4096 revs					
Weight	kg	1.56	2.18	2.72	3.8	
	lb	3.4	4.8	6.0	8.4	
Standards	CE (EMC, LVD), UL (pending)					
Protection	IP67 (body and connectors, not shaft)					
Environmental						
	Temperature	0 - 40 °C				
	Humidity	20-80% non-condensing				
	Shock / Vibration	5G (49m/s ²)				



FCL Dimensions



(Unit: mm)

	OW	OH	OL	L	N	W	D	F	S	T	KW	KH	KD	KL	P
PM-FCL04AMK	80	98	138.7	98.7	70	63.6**	14	10	40	3	5	3	5	25	105
PM-FCL06AMK			156.7	116.7			19				6	3.5	6		
PM-FCL08AMK			174.7	134.7			19				6	3.5	6		
PM-FCL10AMK			192.7	152.7			14				5	3	5		
PM-FCL04AMK2*			179	139			14				5	3	5		
PM-FCL06AMK2*			197	157			19				6	3.5	6		
PM-FCL08AMK2*			215	175			19				6	3.5	6		
PM-FCL10AMK2*			233	193			19				6	3.5	6		

Notes

- * Includes Static Brake
- **Bolt Circle Diameter =90mm

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P Series Ordering Information

Select an option from each numbered field to create a complete model order code.

Drive

Order Example : ① ② ③

P D	-	04	C
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① Series	② Frame Size	③ Interface
PD	04 - 400W	C - EtherCAT P - Pulse/Indexer
	10 - 1000W	
	35 - 3500W	

Motor

Order Example : ① ② ③ ④ ⑤ ⑥ ⑦

P M	-	FBL	04	A	M	K	2
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① Series	② Frame Size	③ Rated Power	④ Winding	⑤ Feedback	⑥ Key	⑦ Options
PM	FAL - 40mm	R5 -50W	A - 3000rpm	M8 -18bit BiSS-C	N - none	[] - None
		01 -100W				[] - None 2 - Brake
		15 -150W				[] - None
	FBL - 62mm	01 -100W		M - 19bit BiSS-C	K - keyway	[] - None 2 - Brake
		02 -200W				
		04 -400W				
	FCL - 80mm	04 -400W				
		06 -600W				
		08 -800W				
		10 -1000W				

Accessories

	Part Number	Description
Motor Power Cables	APCS-PN03LS	Motor Power Cable, 3 meters
	APCS-PNxxLS	xx=Length in meters : 05, 10, 20
Encoder Cables	APCS-EN03ES	Encoder Cable, 3meters
	APCS-ENxxES	xx=Length in meters : 05, 10, 20
	APCS-EN03ES1	Encoder Cable, Multi-Turn w/Battery, 3 meters
	APCS-ENxxES1	xx=Length in meters : 05, 10, 20
Brake Cables	APCS-BN03QS	Brake Cable, 3 meters (Motor power cable is required)
	APCS-BNxxQS	xx=Length in meters : 05, 10, 20
Connectors and I/O Cables	APC-CN102A	I/O Cable, 50-pin,Flying Lead, 2m long for PD-xxP
	APC-CN105A	I/O Cable, 50-pin,Flying Lead, 5m long for PD-xxP
	APCS-CN102A	I/O Cable, 20-pin,Flying Lead, 2m long for PD-xxC
	APCS-CN105A	I/O Cable, 20-pin,Flying Lead, 5m long for PD-xxC
	APC-CN1NNA	I/O Connector, 50-pin for PD-xxP
	APC-CN2NNA	I/O Connector, 20-pin for PD-xxC
	APC-CN3NNA	Drive Feedback Connector, 14-pin
	APCS-CN6J	STO Jumper, 8-pin
	APC-VSCN1T	I/O Breakout Board, 50-pin for PD-xxP
	APCS-CN5L7U	USB Communication Cable
Brake Resistors	APCS-140R50	Brake Resistor 400W
	APCS-300R30	Brake Resistor 1kW
	APC-600R30	Brake Resistor 3.5kW

Notes:

Brake Cables are separate from the motor power cables.

Cables exit toward the front of the motor. Rear exit cables are also possible, consult factory for availability.

Cable Drawings Available for Download parkermotion.com/pseries



EM Sales Offices

Australia

Parker Hannifin (Australia) Pty Ltd.

9 Carrington Road
Castle Hill NSW 2154
Australia
Tel: +61 (0) 2 9634-7777
Fax: +61 (0) 2 9634 3749

Brazil

Parker Hannifin Ind. Com Ltda.

Av. Lucas Nogueira Garcez 2181
Esperança
12325-900 Jacareí, SP
Tel: 12 3954 5100
Fax: 12 3954 5262
Email: automation.brazil@parker.com

Canada

Parker Hannifin (Canada) Inc.

160 Chisholm Dr
Milton, Ontario L9T 3G9
Tel: 905-693-3000
Fax: 905-876-1958
Email: miltoncustservice@parker.com

China

Parker Hannifin Motion & Control (Shanghai) Co., Ltd

280 Yunqiao Rd. Jin Qiao Export
Processing Zone
Shanghai 201206, China
Tel: (86-21) 50312525
Fax: (86-21) 64459717

France

Parker SSD Parvex

8 avenue du Lac
B.P. 249
F-21007 Dijon Cedex
Tel: +33 (0) 3 80 42 41 40
Fax: +33 (0) 3 80 42 41 23

Germany

Electromechanical Europe Parker Hannifin GmbH & Co KG

Robert-Bosch-Strasse 22
D-77656 Offenburg
Germany
Tel: +49 (0) 781 509 0
Fax: +49 (0) 781 509 98176
Email: em-motion@parker.com

India

Parker Hannifin India Pvt. Ltd Automation Group-SSD Drives Div.

133 & 151 Developed Plots Estate
Perungudi, Chennai 600 096
Tel: 044-4391-0799
Fax: 044-4391-0700

Italy

Parker Hannifin SpA

Via Gounod 1
20092 Cinsello Balsamo
Milano, Italy
Tel: +39 02 361081
Fax: +39 02 36108400
Email: em-motion@parker.com

Korea

Sales Office

Ga San Office, 822-6344-0100
Parker Hannifin Korea Automation Office
13F Jei Platz B/D , 459-11 Gasan-dong,
Geumcheon-gu, Seoul

Automation Division

Jang An Plant, 82 31-359-0700
Parker Korea Ltd.
759-10 Geumui-ri, Jangan-myeon,
Hwaseong-si, Gyeonggi-do, 445-941,
Korea

Mexico

Parker Hannifin de Mexico

Eje uno Norte No.100
Parque Industrial Toluca 2000
Toluca, CP 50100 México
Tel: 52-722-275-4200
Fax: 52-722-279-0316

Singapore

Parker Hannifin Singapore Pte Ltd

11, Fourth Chin Bee Road
Singapore 619702
Tel: (65) 6887 6300
Fax: (65) 6265 5125/6261 4929

Taiwan

Parker Hannifin Taiwan Co., Ltd

Parker Hannifin Taiwan Co., Ltd.
No.19, Wu Chiuan 2nd Road,
Wuku Industrial Park, New Taipei
City, Taiwan 248

ROC

Tel: 886 2 2298 8987
Fax: 886 2 2298 8982

Thailand

Parker Hannifin (Thailand) Co., Ltd.

1265 Rama 9 Road
Suanluang, Bangkok 10250
Thailand
Tel: (66) 2 186 7000
Fax: (66) 2 374 1645

UK

Parker Hannifin Ltd.

Tachbrook Park Drive
Tachbrook Park
Warwick CV34 6TU
Tel: +44 (0) 1926 317970
Fax: +44 (0) 1926 317980

USA

Parker Hannifin Electromechanical Automation Division

5500 Business Park Drive
Rohnert Park, CA 94928 USA
Tel: 707-584-7558
800-358-9070
Fax: 707-584-8015
Email: emn_support@parker.com

